

[SWCON253] Machine Learning – Lec.**06**

Linear Regression + α

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References

- *Machine Learning* by Andrew Ng, Coursera (<https://www.coursera.org/learn/machine-learning>)

1. Linear Regression

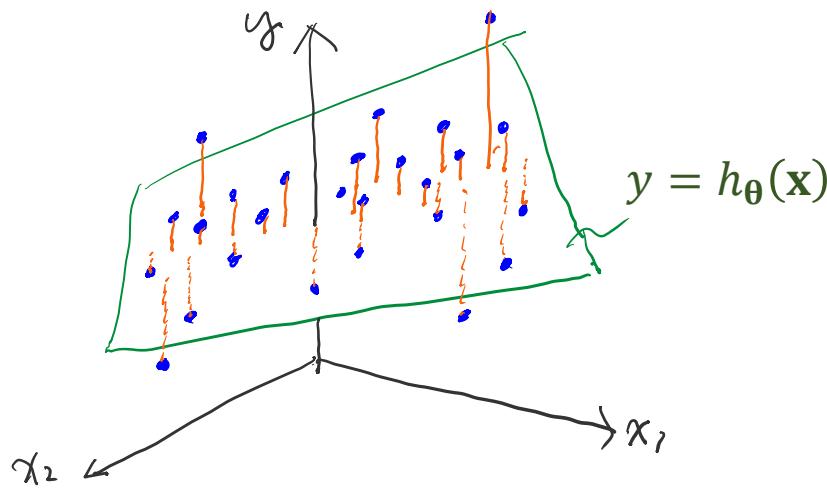
- ✓ Multivariate Linear Regression
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- ✓ Parameter Update (by Gradient Descent)

0. Multivariate Linear Regression

◆ Find the best linear function h_{θ} for the given training dataset \mathbb{D} with **multiple(n)-features**

- A feature vector: $\mathbf{x} = [x_1, \dots, x_n]^T$
- Training dataset: $\mathbb{D} = \{(\mathbf{x}^{(i)}, y^{(i)})\}_{i=1}^M = \{(\mathbf{x}^{(1)}, y^{(1)}), \dots, (\mathbf{x}^{(M)}, y^{(M)})\}$
- **Linear model:**

$$\begin{aligned} h_{\theta}(\mathbf{x}) &= h_{\theta}(x_1, \dots, x_n) \\ &= \theta_0 + \theta_1 x_1 + \dots + \theta_n x_n \end{aligned}$$



Ex) Housing Price Prediction

- **Multiple features:** size, # bedrooms, # floors, age
- **Single output:** the price of a house

→ Size (feet ²) x_1	Number of bedrooms x_2	Number of floors x_3	Age of home (years) x_4	Price (\$1000) y
2104	5	1	45	460
1416	3	2	40	232
1534	3	2	30	315
852	2	1	36	178
...

- n = number of features $n=4$
→ $x^{(i)}$ = input (features) of i^{th} training example.
→ $x_j^{(i)}$ = value of feature j in i^{th} training example.

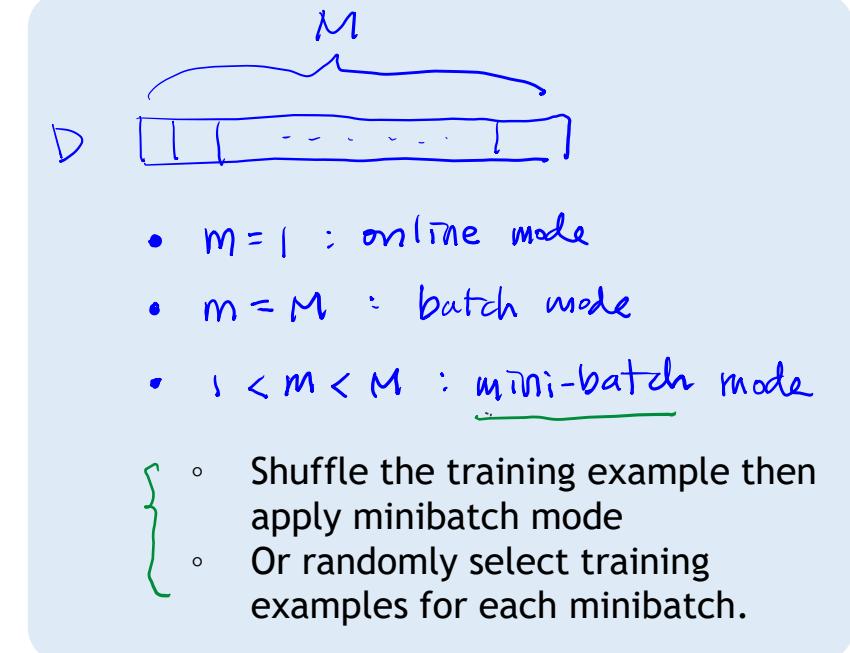
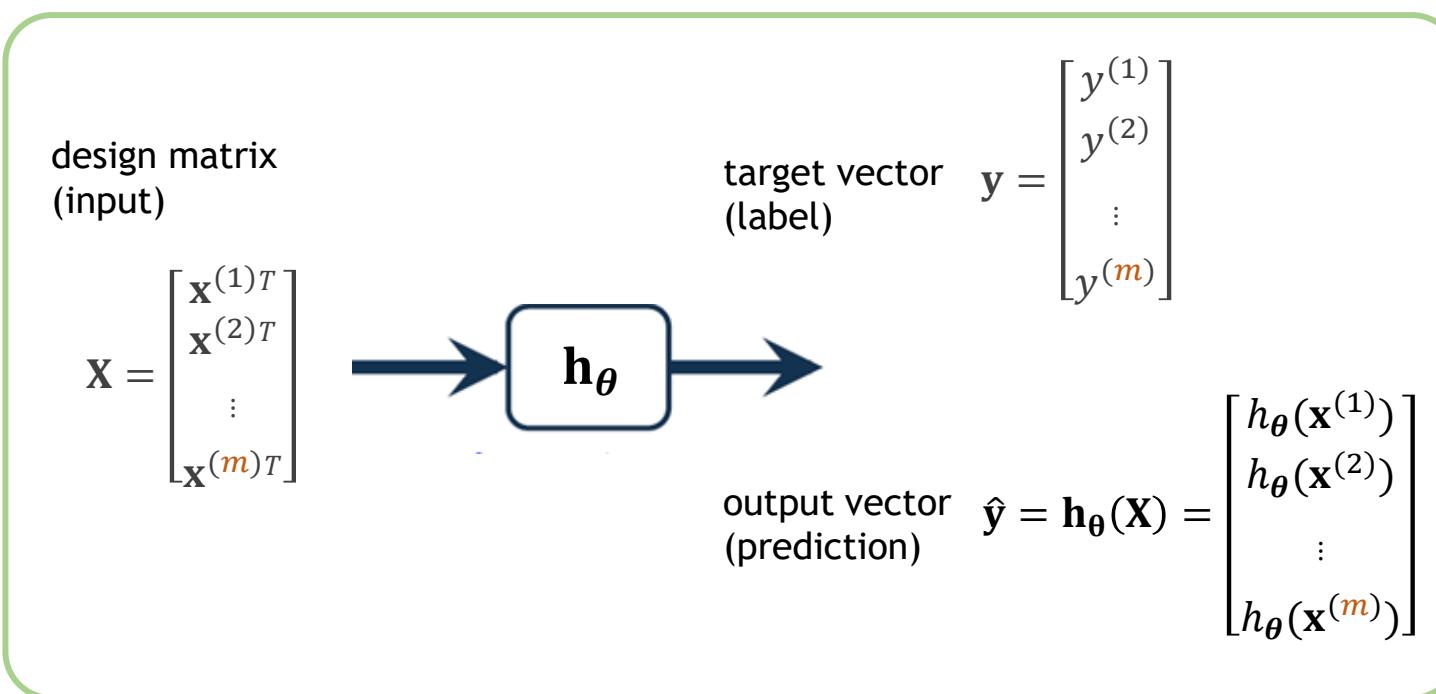
1. Data Representation

◆ Data with Multiple Features

- A feature vector: $\mathbf{x} = [x_1, \dots, x_n]^T$
- Training dataset: $\mathbb{D} = \{(\mathbf{x}^{(i)}, y^{(i)})\}_{i=1}^M = \{(\mathbf{x}^{(1)}, y^{(1)}), \dots, (\mathbf{x}^{(M)}, y^{(M)})\}$

◆ For batch processing

- (mini-)batch size: $1 \leq m \leq M$



2. Linear Model Representation

◆ Representation 1

- Let $\mathbf{x} \triangleq [x_0, x_1, \dots, x_n]^T$, $\boldsymbol{\theta} \triangleq [\theta_0, \theta_1, \dots, \theta_n]^T$
★ where $x_0 = 1$.
- Then, for a single training example (i.e., $\mathbf{x}^{(i)}$):

$$h_{\boldsymbol{\theta}}(\underline{x}) = \theta_0 + \theta_1 x_1 + \theta_2 x_2 + \dots + \theta_n x_n$$
$$= [\theta_0 \quad \theta_1 \quad \dots \quad \theta_n] \begin{bmatrix} x_0 \\ x_1 \\ \vdots \\ x_n \end{bmatrix} = \underline{\boldsymbol{\theta}}^T \underline{x}$$

- and for a batch of training examples (i.e., \mathbf{X}):

$$\mathbf{h}_{\boldsymbol{\theta}}(\mathbf{X}) = \begin{bmatrix} \boldsymbol{\theta}^T \mathbf{x}^{(1)} \\ \boldsymbol{\theta}^T \mathbf{x}^{(2)} \\ \vdots \\ \boldsymbol{\theta}^T \mathbf{x}^{(m)} \end{bmatrix} = \mathbf{X}\boldsymbol{\theta}$$

◆ Representation 2 (weight & bias)

- Let $\mathbf{x} \triangleq [x_1, \dots, x_n]^T$, $\boldsymbol{\theta} \triangleq [\theta_1, \dots, \theta_n]^T$
- Then, for a single training example

$$h_{\boldsymbol{\theta}}(\underline{x}) = \underline{\boldsymbol{\theta}}^T \underline{x} + \theta_0$$

$$(h_w(\underline{x}) = \underline{w}^T \underline{x} + b)$$

- and, for a batch of training example

$$h_{\boldsymbol{\theta}}(\mathbf{X}) = \mathbf{X}\underline{\boldsymbol{\theta}} + \theta_0 \begin{bmatrix} 1 \\ \vdots \\ 1 \end{bmatrix}$$

$$(h_w(\mathbf{X}) = \mathbf{X}\underline{w} + \underline{b})$$

2. Linear Model Representation (cont'd)

◆ Summary of Input, Output, & Model

$$\mathbf{X} = \begin{bmatrix} \mathbf{x}^{(1)T} \\ \mathbf{x}^{(2)T} \\ \vdots \\ \mathbf{x}^{(m)T} \end{bmatrix} \rightarrow \boxed{h_{\theta}} \rightarrow \mathbf{y} = \begin{bmatrix} y^{(1)} \\ y^{(2)} \\ \vdots \\ y^{(m)} \end{bmatrix}$$
$$h_{\theta}(\mathbf{X}) = \begin{bmatrix} h_{\theta}(\mathbf{x}^{(1)}) \\ h_{\theta}(\mathbf{x}^{(2)}) \\ \vdots \\ h_{\theta}(\mathbf{x}^{(m)}) \end{bmatrix} = \boxed{\begin{bmatrix} \theta^T \mathbf{x}^{(1)} \\ \theta^T \mathbf{x}^{(2)} \\ \vdots \\ \theta^T \mathbf{x}^{(m)} \end{bmatrix} = \mathbf{X}\theta}$$

Linear Model

3. MSE Cost for Linear Model

◆ MSE Cost

- Classic form:

$$\begin{aligned} J(\boldsymbol{\theta}) &= \frac{1}{2m} \sum_{i=1}^m (h_{\boldsymbol{\theta}}(\mathbf{x}^{(i)}) - y^{(i)})^2 \\ &= \frac{1}{2m} \sum_{i=1}^m (\boldsymbol{\theta}^T \mathbf{x}^{(i)} - y^{(i)})^2 \end{aligned}$$

- Vector form

$$\begin{aligned} J(\boldsymbol{\theta}) &= \frac{1}{2m} \|\mathbf{h}_{\boldsymbol{\theta}}(\mathbf{X}) - \mathbf{y}\|_2^2 \\ &= \frac{1}{2m} \|\mathbf{X}\boldsymbol{\theta} - \mathbf{y}\|_2^2 \\ &= \frac{1}{2m} (\mathbf{X}\boldsymbol{\theta} - \mathbf{y})^T (\mathbf{X}\boldsymbol{\theta} - \mathbf{y}) \end{aligned}$$



유도과정:
다음 슬라이드

◆ Gradient of the MSE Cost

- Classic form:

For $j=0, \dots, n$:

$$\frac{\partial J(\boldsymbol{\theta})}{\partial \theta_j} = \frac{1}{m} \sum_{i=1}^m (\boldsymbol{\theta}^T \mathbf{x}^{(i)} - y^{(i)}) x_j^{(i)}$$

- Vector form

$$\begin{aligned} \nabla J(\boldsymbol{\theta}) &= \frac{1}{m} \sum_{i=1}^m (\boldsymbol{\theta}^T \mathbf{x}^{(i)} - y^{(i)}) \mathbf{x}^{(i)} \\ &= \frac{1}{m} \mathbf{X}^T (\mathbf{X}\boldsymbol{\theta} - \mathbf{y}) \end{aligned}$$

3. MSE Cost for Linear Model (cont'd)

◆ $\nabla_{\theta} \|X\theta - y\|_2^2$?

$$\begin{aligned}\|X\theta - y\|_2^2 &= (X\theta - y)^T (X\theta - y) \stackrel{\textcircled{1}}{=} (\underline{\theta}^T \underline{x}^T - \underline{y}^T)(X\theta - y) \\ &= \underline{\theta}^T \underline{x}^T X\theta - \underline{y}^T X\theta - \underline{\theta}^T \underline{x}^T \underline{y} + \underline{y}^T \underline{y} \\ \stackrel{\textcircled{2}}{=} &\underline{\theta}^T \underline{x}^T X\theta - 2\underline{y}^T X\theta + \underline{y}^T \underline{y}\end{aligned}$$

$$\begin{cases} \textcircled{1} \quad (\underline{a} - \underline{b})^T = \underline{a}^T - \underline{b}^T \\ (\underline{A}\underline{x})^T = \underline{x}^T \underline{A}^T \end{cases}$$

$$\textcircled{2} \quad \underline{\theta}^T \underline{x}^T \underline{y} = (\underline{X}\underline{\theta})^T \underline{y} = \underline{y}^T \underline{X}\underline{\theta}$$

$$\begin{aligned}\Rightarrow \nabla_{\theta} \|X\theta - y\|_2^2 &= \nabla_{\theta} (\underline{\theta}^T \underline{x}^T \underline{X}\underline{\theta}) - 2 \nabla (\underline{y}^T \underline{X}\underline{\theta}) \\ \stackrel{\textcircled{3}}{=} &2 \underline{x}^T \underline{X}\underline{\theta} - 2 \underline{x}^T \underline{y} \\ &= 2 \underline{x}^T (X\theta - y)\end{aligned}$$

$$\begin{cases} \textcircled{3} \quad \begin{aligned} \nabla_{\underline{x}} (\underline{x}^T \underline{A}^T \underline{A} \underline{x}) &= 2 \underline{A}^T \underline{A} \underline{x} \\ \nabla_{\underline{x}} (\underline{b}^T \underline{A} \underline{x}) &= \nabla_{\underline{x}} \underline{c}^T \underline{x} = \underline{c} \end{aligned} \\ \text{symmetric} \\ \text{a row vector} \\ \equiv \underline{c}^T \\ &= (\underline{b}^T \underline{A})^T \\ &= \underline{A}^T \underline{b} \end{cases}$$

4. Parameter Update by GD (for Linear Model)

◆ Gradient Descent for *Linear Regression* with *MSE Cost*

● Classic form:

Repeat until convergence {

 Update $\forall \theta_j$'s *simultaneously*:

$$\theta_j := \theta_j - \alpha \frac{\partial J(\theta)}{\partial \theta_j} = \theta_j - \alpha \frac{1}{m} \sum_{i=1}^m (\theta^T \mathbf{x}^{(i)} - y^{(i)}) x_j^{(i)}$$

}

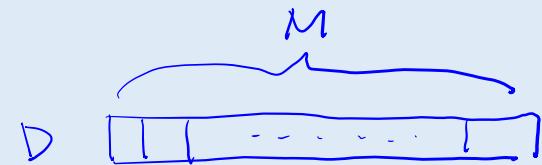
● Vector form

Repeat until convergence {

$$\theta := \theta - \alpha \nabla J(\theta) = \theta - \alpha \frac{1}{m} \mathbf{X}^T (\mathbf{X}\theta - \mathbf{y})$$

}

Learning Modes (Recap.)



- $m=1$: *online mode*

- $m=M$: *batch mode*

- $1 < m < M$: *mini-batch mode*

- }
 - Shuffle the training example then apply minibatch mode
 - Or randomly select training examples for each minibatch.

2. Normal Equation

- ✓ Normal Equation
- ✓ Gradient Descent vs. Normal Equation

Normal Equations

◆ Analytic Solution to *Linear Regression with MSE Loss*

$$\nabla J(\theta) = \frac{1}{m} \mathbf{X}^T (\mathbf{X}\theta - \mathbf{y}) = \mathbf{0}$$

→ $\theta^* = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y}$

$X\theta - y = 0$ (즉, $\theta^* = X^{-1}y$)로 구하지 않은 이유는?

주어진 문제에서 X 는 design matrix이고 차원이 대략 $m \times n$ (m 은 training example 개수, n 은 feature 차원)이 되므로 square 행렬이 아닐 수 있습니다.

역행렬은 square 행렬의 경우만 존재하므로 일반적인 $m \times n$ 행렬은 역행렬을 구할 수 없습니다.

반면에, $X^T X$ 나 $X X^T$ 형태로 만들면 square가 되어 역행렬을 구할 수 있습니다.

Examples: $m = 4$.

	x_0	x_1	x_2	x_3	x_4	y
1	2104	5	1	45	460	
1	1416	3	2	40	232	
1	1534	3	2	30	315	
1	852	2	1	36	178	

$X = \begin{bmatrix} 1 & 2104 & 5 & 1 & 45 \\ 1 & 1416 & 3 & 2 & 40 \\ 1 & 1534 & 3 & 2 & 30 \\ 1 & 852 & 2 & 1 & 36 \end{bmatrix}$ $m \times (n+1)$

$y = \begin{bmatrix} 460 \\ 232 \\ 315 \\ 178 \end{bmatrix}$ m -dimensional vector

$\theta = (X^T X)^{-1} X^T y$

Gradient Descent vs. Normal Equation

$$\nabla J(\theta) = \frac{1}{m} \mathbf{X}^T (\mathbf{X}\theta - \mathbf{y})$$

$$\theta^* = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y}$$

Gradient Descent	Normal Equation
Need to choose alpha	No need to choose alpha
Needs many iterations	No need to iterate
$O(kn^2)$	$O(n^3)$, need to calculate inverse of $\mathbf{X}^T \mathbf{X}$
Works well when n is large	Slow if n is very large

$$\mathbf{X} = \begin{pmatrix} & n \\ m & \begin{matrix} \vdash \\ \vdash \\ \vdash \\ \vdash \end{matrix} \end{pmatrix}$$

$$\begin{aligned} \mathbf{X}^T \mathbf{X} &\rightarrow (n \times n) \\ (n \times m) \cdot (m \times n) \end{aligned}$$

- With the normal equation, computing the inversion has complexity $O(n^3)$.
 - ★ So if we have a very large number of features (i.e., large n), the normal equation will be slow.
 - ★ In practice, when n exceeds 10,000 it might be a good time *to go to an iterative process*.

3. Polynomial Regression

Polynomial Regression

◆ Polynomial Regression can be solved by Linear Regression

- Linear Regression 문제로

환원하여 풀 수 있음:

$$x_1 = (\text{size})$$

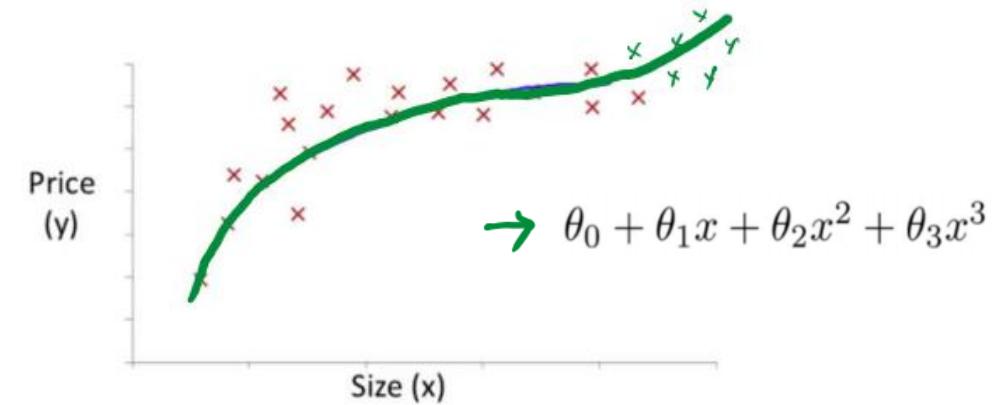
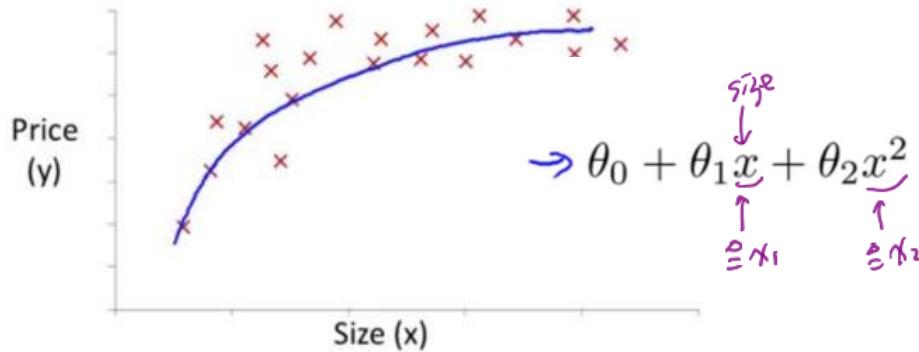
$$x_2 = (\text{size})^2$$

$$x_3 = (\text{size})^3$$

- 이때 feature scaling이 중요해 짐

$$h_{\theta}(x) = \theta_0 + \theta_1 x_1 + \theta_2 x_2 + \theta_3 x_3$$

● Ex) Housing Price Prediction



◆ Polynomial이외의 Nonlinear Function의 경우는?

- 마찬가지 방법(변수 치환)을 통해 선형회귀로 바꾸어 풀 수 있음!

$$h_{\theta}(x) = \theta_0 + \theta_1 \sqrt{x_1} + \theta_2 \cos(x_2 + \pi)$$

4. For Better Results

- ✓ Feature Normalization
- ✓ Learning Rate Selection

Feature Normalization

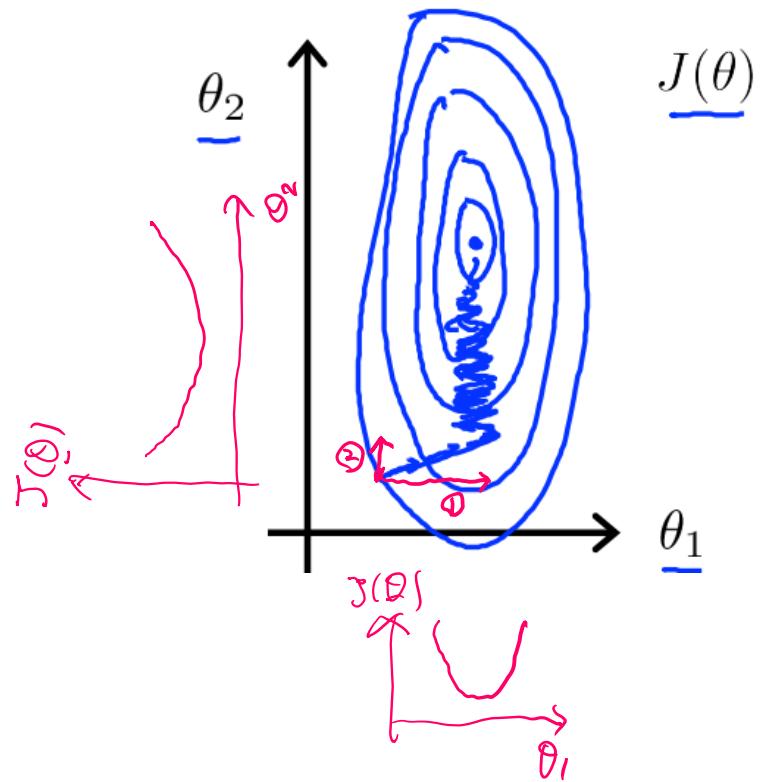
◆ Feature Scaling (Range Normalization)

- Make sure features are on a similar scale

E.g. $x_1 = \text{size } (0\text{-}2000 \text{ feet}^2) \leftarrow$
 $x_2 = \text{number of bedrooms } (1\text{-}5) \leftarrow$



$$\rightarrow x_1 = \frac{\text{size (feet}^2)}{2000}$$
$$\rightarrow x_2 = \frac{\text{number of bedrooms}}{5}$$



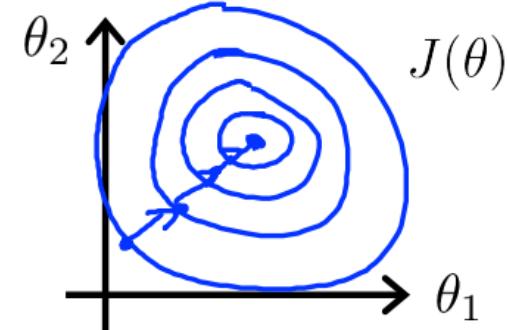
$$h_{\theta}(x) = \theta_0 + \theta_1 x_1 + \theta_2 x_2$$

$$J(\theta) = \frac{1}{2m} \sum_i (h_{\theta}(x^{(i)}) - y^{(i)})^2$$

$$\textcircled{1} \quad \frac{\partial J(\theta)}{\partial \theta_1} = \frac{1}{m} \sum_i (h_{\theta}(x^{(i)}) - y^{(i)}) \cdot x_1^{(i)}$$

$$\textcircled{2} \quad \frac{\partial J(\theta)}{\partial \theta_2} = \frac{1}{m} \sum_i (h_{\theta}(x^{(i)}) - y^{(i)}) \cdot x_2^{(i)}$$

$$0 \leq x_1 \leq 1 \quad 0 \leq x_2 \leq 1$$



∴ Converge faster!

Feature Normalization (cont'd)

◆ Mean Normalization (Mean Shifting)

- Replace x_j with $x_j - \mu_j$ to make features have approximately zero mean.

◆ Feature Normalization = Range Normalization + Mean Normalization

E.g. $\rightarrow x_1 = \frac{\text{size} - 1000}{2000}$

$$x_2 = \frac{\#\text{bedrooms} - 2}{5}$$

$$\rightarrow [-0.5 \leq x_1 \leq 0.5, -0.5 \leq x_2 \leq 0.5]$$

Feature Normalization (cont'd)

◆ Feature Normalization Summary

- Mean shifting:

$$x_j'^{(i)} = x_j^{(i)} - \mu_j \quad (\text{i.e., } \mathbf{x}'^{(i)} = \mathbf{x}^{(i)} - \boldsymbol{\mu})$$

- With Scaling Method 1: Use **range** ($R = \max |x_j|$) to normalize

$$x_j'^{(i)} = \frac{x_j^{(i)} - \mu_j}{\max |x_j|} \quad (\text{i.e., } \mathbf{x}'^{(i)} = \frac{\mathbf{x}^{(i)} - \boldsymbol{\mu}}{\max |\mathbf{x}^{(i)}|})$$

→ Normalized range: $-1 \leq x_j' \leq 1$ (strictly)

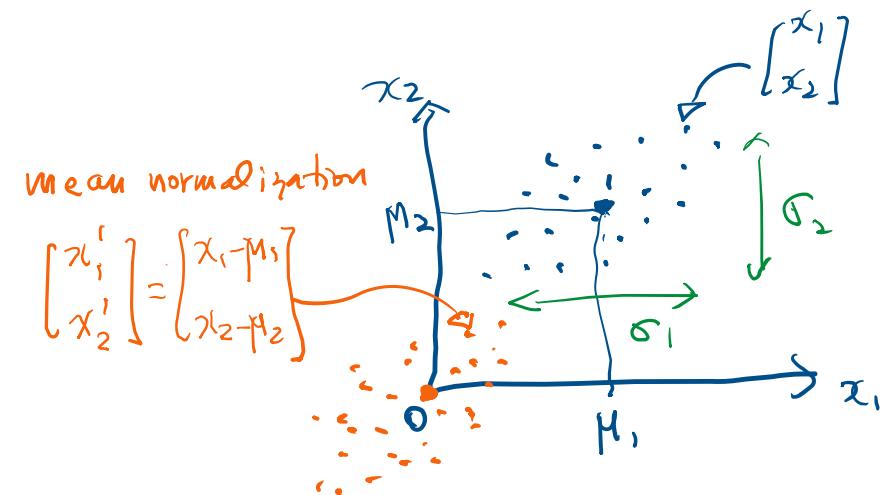
- With Scaling Method 2: Use **standard deviation** () to normalize

$$x_j'^{(i)} = \frac{x_j^{(i)} - \mu_j}{\sigma_j} \quad (\text{i.e., } \mathbf{x}'^{(i)} = \frac{\mathbf{x}^{(i)} - \boldsymbol{\mu}}{\boldsymbol{\sigma}})$$

→ Normalized range: $-1 \leq x_j' \leq 1$ (roughly)

◆ Caution:

- Do not normalize $x_0 = 1$.
- There is **no** need to do feature normalization with the **normal equation**.

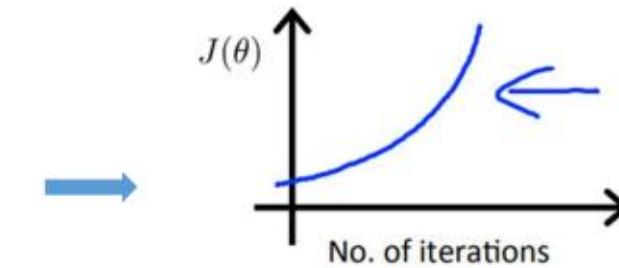
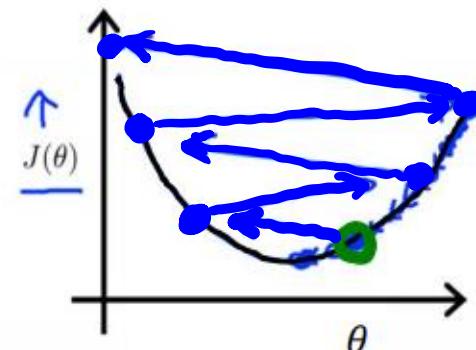


feature normalization: $x_j' = \frac{x_j - \mu_j}{\sigma_j}$
($x_j = \sigma_j x_j' + \mu_j$)

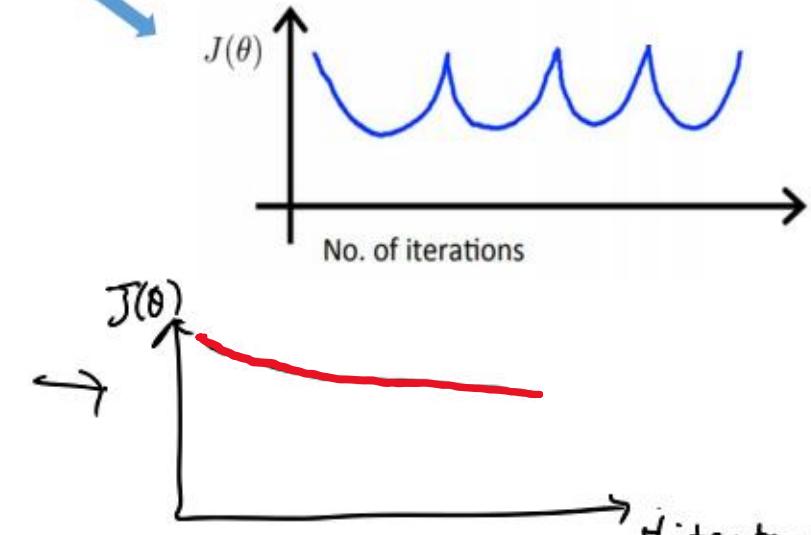
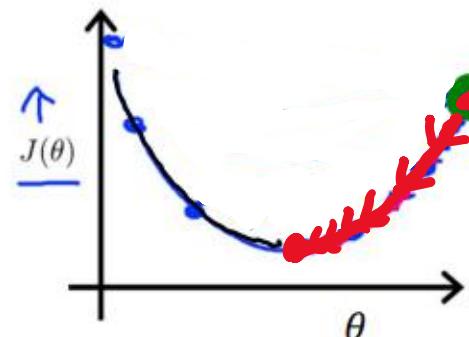
Learning Rate Selection

◆ How to Choose Learning Rate α ?

- Too large α : may not converge



- Too small α : slow convergence



- Rule of thumb:

★ Try ..., 0.001, ..., 0.01, ..., 0.1, ..., 1, ...
then try the in-betweens if not satisfactory

- Learning Rate Scheduling

★ Starts with some large α , and then decrease α according to a schedule

Q & A

본 강의 영상(자료)는 경희대학교 수업목적으로 제작·제공된 것으로 수업목적 외 용도로 사용할 수 없으며, 무단으로 복제, 배포, 전송 또는 판매하는 행위를 금합니다. 이를 위반 시 민·형사상 법적 책임은 행위자 본인에게 있습니다.