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ROB 501 Handout: Grizzle

Matrix Representation of a Linear Operator

Definition: Let $(\mathcal{X}, \mathcal{F})$ and $(\mathcal{Y}, \mathcal{F})$ be finite dimensional vector spaces. A function $L : \mathcal{X} \to \mathcal{Y}$ is a **linear operator** if for each x and z in \mathcal{X} , and α and β in \mathcal{F} ,

$$L(\alpha x + \beta z) = \alpha L(x) + \beta L(z)$$

Definition: Let $(\mathcal{X}, \mathcal{F})$ and $(\mathcal{Y}, \mathcal{F})$ be finite dimensional vector spaces, and let $L: \mathcal{X} \to \mathcal{Y}$ be a linear operator. A **matrix representation of** L with respect to the bases $\{u\} = \{u^1, \dots, u^m\}$ for \mathcal{X} and $\{v\} = \{v^1, \dots, v^n\}$ for \mathcal{Y} is a matrix A with coefficients in \mathcal{F} satisfying for every $x \in \mathcal{X}$,

$$[L(x)]_v = A[x]_u$$

Theorem: Let $(\mathcal{X}, \mathcal{F})$ and $(\mathcal{Y}, \mathcal{F})$ be finite dimensional vector spaces, and let $L : \mathcal{X} \to \mathcal{Y}$ be a linear operator. Then L has a matrix representation A, moreover,

$$A = [A_1|A_2|\cdots|A_m],$$

where A_i , the *i*-th column of A, is given by

$$A_i = \left[L\left(u^i\right)\right]_{\{v\}}$$

Proof: Let $x \in \mathcal{X}$, and write $x = \alpha_1 u^1 + \ldots + \alpha_m u^m$ so that

$$[x]_{\{u\}} = \left[\begin{array}{c} \alpha_1 \\ \vdots \\ \alpha_m \end{array} \right].$$

Then

$$L(x) = L(\alpha_1 u^1 + \ldots + \alpha_m u^m)$$

= $\alpha_1 L(u^1) + \ldots + \alpha_m L(u^m)$

$$[L(x)]_{\{v\}} = \left[\alpha_1 L(u^1) + \ldots + \alpha_m L(u^m)\right]_{\{v\}}$$

$$= \alpha_1 \left[L(u^1)\right]_{\{v\}} + \ldots + \alpha_m \left[L(u^m)\right]_{\{v\}}$$

$$= \left[\left[L(u^1)\right]_{\{v\}} \cdots \left[L(u^m)\right]_{\{v\}}\right] \begin{bmatrix} \alpha_1 \\ \vdots \\ \alpha_m \end{bmatrix}$$

$$= A \begin{bmatrix} \alpha_1 \\ \vdots \\ \alpha_m \end{bmatrix}$$

$$= A [x]_{\{u\}}$$

End of Proof.

Key Point: The *i*-th column of
$$A$$
 is given by $A_i = \begin{bmatrix} a_{1i} \\ \vdots \\ a_{ni} \end{bmatrix} = [L(u^i)]_{\{v^1, \dots, v^n\}}$

Useful Exercise: Let A be an $n \times n$ matrix with coefficients in a given field \mathcal{F} .

- 1. Let e_1, \dots, e_n denote the natural basis for $(\mathcal{F}^n, \mathcal{F})$. Show that $Ae_i = A_i$, where A_i is the *i*-th column of A.
- 2. Show that $L: \mathcal{F}^n \to \mathcal{F}^n$ by, for $x \in \mathcal{F}^n$, L(x) = Ax, is a linear operator.
- 3. Let e_1, \dots, e_n denote again the natural basis for $(\mathcal{F}^n, \mathcal{F})$. Find the matrix representation of L with respect to e_1, \dots, e_n . Note: In this case, the bases $\{u\}$ and $\{v\}$ are the same and equal to the natural basis.

Remark: The above exercise can be extended to a non-square matrix, say $n \times m$. In that case, $L: \mathcal{F}^m \to \mathcal{F}^n$. If you take the natural bases on both \mathcal{F}^m and \mathcal{F}^n , you will get the same result as part (3) of the exercise [namely, the matrix representation of L is A itself.]

A Worked Example of Matrix Representations

Let $(\mathcal{X}, \mathcal{F}) = (\mathbb{R}^2, \mathbb{R})$, and define $L : \mathbb{R}^2 \to \mathbb{R}^2$ by $L(e_1) = 3e_1 + 4e_2$, $L(e_2) = -e_1 + 6e_2$, where $e_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$ and $e_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$ are the canonical basis elements.

1. What is the matrix representation of L with respect to $\{e_1, e_2\}$?

2. What is the matrix representation of L with respect to $\{v^1, v^2\}$ where $v^1 = e_1 + e_2, v^2 = 3e_1 - 4e_2$?

Solution:

1. Let A = matrix representation of L. Then the i^{th} column of $A = [L(e_i)]_{\{e_1,e_2\}}$.

$$\therefore [L(e_1)]_{\{e_1,e_2\}} = \begin{bmatrix} 3\\4 \end{bmatrix}, [L(e_2)]_{\{e_1,e_2\}} = \begin{bmatrix} -1\\6 \end{bmatrix}$$

$$\implies A = \begin{bmatrix} 3 & -1\\4 & 6 \end{bmatrix}$$

2. Let P be the change of coordinates from $\{e_1, e_2\}$ to $\{v^1, v^2\}$, and \bar{P} be the change of coordinates from $\{v^1, v^2\}$ to $\{e_1, e_2\}$. Note that the i^{th} column of \bar{P} is just the representation of v^i in $\{e_1, e_2\}$. That is,

$$\bar{P} = \begin{bmatrix} 1 & 3 \\ 1 & -4 \end{bmatrix}.$$

Recall that $\bar{P} = P^{-1}$, so

$$P = (\bar{P})^{-1} = \frac{-1}{7} \begin{bmatrix} -4 & -3 \\ -1 & 1 \end{bmatrix} = \frac{1}{7} \begin{bmatrix} 4 & 3 \\ 1 & -1 \end{bmatrix}.$$

Therefore, if \bar{A} is the representation of L in $\{v^1, v^2\}$, then

$$\bar{A} = PAP^{-1} = \frac{1}{7} \begin{bmatrix} 4 & 3 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} 3 & -1 \\ 4 & 6 \end{bmatrix} \begin{bmatrix} 1 & 3 \\ 1 & -4 \end{bmatrix} = \frac{1}{7} \begin{bmatrix} -38 & 16 \\ -8 & 25 \end{bmatrix}.$$

Note: \bar{P} was readily available, not P, as you may have guessed!! 3. Just to check, let's do thing the "long way":

$$L(v^{1}) = L(e_{1} + e_{2})$$

$$= L(e_{1}) + L(e_{2})$$

$$= (3e_{1} + 4e_{2}) + (-e_{1} + 6e_{2})$$

$$= 2e_{1} + 10e_{2}$$

$$L(v^{2}) = L(3e_{1} - 4e_{2})$$

$$= 3L(e_{1}) - 4L(e_{2})$$

$$= 3(3e_{1} + 4e_{2}) - 4(-e_{1} + 6e_{2})$$

$$13e_{1} - 12e_{2}$$

 $\left[L\left(v^{1}\right)\right]_{\left\{v^{1},v^{2}\right\}}=$? To find it, write

$$\begin{bmatrix} 2\\10 \end{bmatrix} = \bar{a}_{11} \underbrace{\begin{bmatrix} 1\\1\\1 \end{bmatrix}}_{v^1} + \bar{a}_{21} \underbrace{\begin{bmatrix} 3\\-4 \end{bmatrix}}_{v^2} = \begin{bmatrix} 1 & 3\\1 & -4 \end{bmatrix} \begin{bmatrix} \bar{a}_{11}\\\bar{a}_{12} \end{bmatrix}$$

$$\implies \begin{bmatrix} \bar{a}_{11}\\\bar{a}_{12} \end{bmatrix} = \frac{1}{7} \begin{bmatrix} 38\\-18 \end{bmatrix}$$

Similarly

$$\begin{bmatrix} 13 \\ -12 \end{bmatrix} = \bar{a}_{12} \begin{bmatrix} 1 \\ 1 \end{bmatrix} + \bar{a}_{22} \begin{bmatrix} 3 \\ -4 \end{bmatrix}$$

$$\implies \begin{bmatrix} \bar{a}_{12} \\ \bar{a}_{22} \end{bmatrix} = \frac{1}{7} \begin{bmatrix} 16 \\ 25 \end{bmatrix}$$

$$\therefore \bar{A} = \frac{1}{7} \begin{bmatrix} 38 & 16 \\ -8 & 25 \end{bmatrix}$$