

11 Oct. 2018

Review • A real, $A=A^T \Rightarrow \lambda_i(A)$ real, $v_i \neq 0$ $Av_i = \lambda_i v_i$, $1 \leq i \leq n$
 $\{\lambda_1, \dots, \lambda_n\}$ distinct $\Rightarrow \langle v_i, v_j \rangle = (v_i)^T v_j = 0$ $i \neq j$.
HW6 treats the general case of repeated e-values.

Thm $A=A^T$ and real $\Rightarrow \exists Q$ orthogonal [$Q^T Q = I$]
such that $Q^T A Q = \Lambda = \text{diag}(\lambda_1, \dots, \lambda_n)$.
 $\therefore A = Q \Lambda Q^T$

$$\bullet x^T M x = x^T \left[\frac{M+M^T}{2} \right] x \quad \text{"Symmetric Part of } M \text{"}$$

Def. $P=P^T$ is positive definite if
 $\forall x \in \mathbb{R}^n$, $x \neq 0 \Rightarrow x^T P x > 0$

HW#2 Prob 7: If $P=P^T$, then $\forall x \in \mathbb{R}^n$,
 $\lambda_{\min}(P) x^T x \leq x^T P x \leq \lambda_{\max}(P) x^T x$

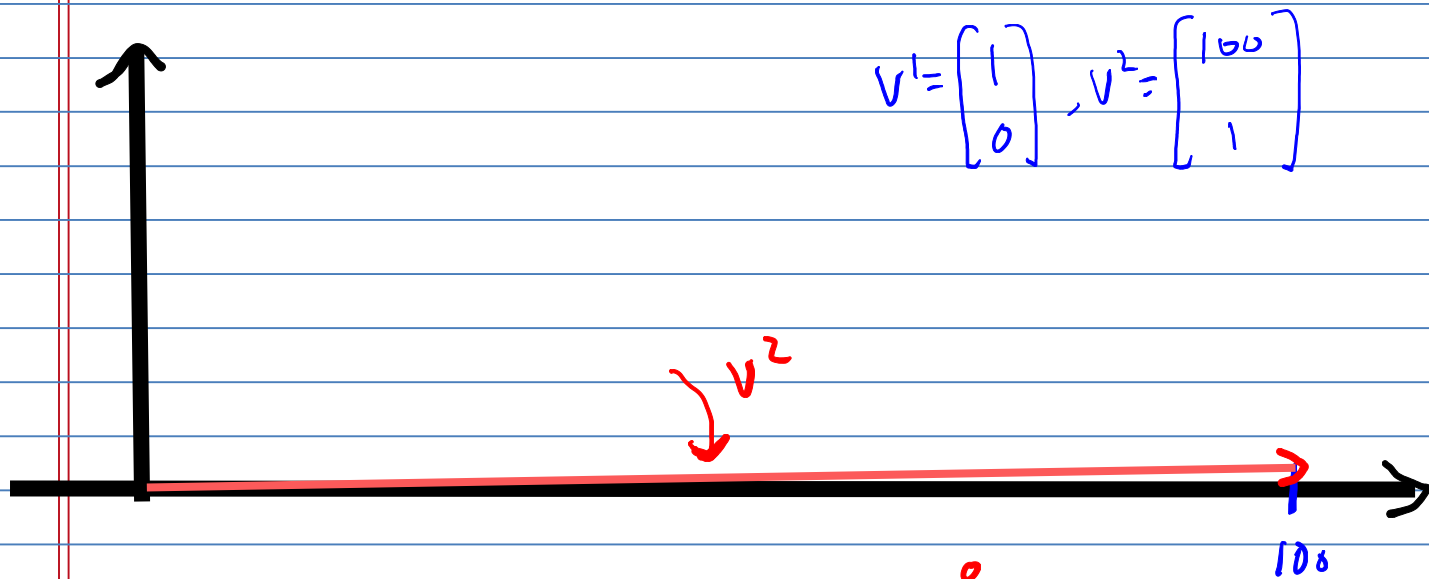
Thm P is pos. def $\Leftrightarrow \lambda_{\min}(P) > 0$

$$A = \begin{bmatrix} 1 & 100 \\ 0 & 1 \end{bmatrix} \Rightarrow A^T A = \begin{bmatrix} 1 & 100 \\ 100 & 10,001 \end{bmatrix}$$

$$A^T A = \begin{bmatrix} -6.01 & -1 \\ -1 & 0.01 \end{bmatrix} \begin{bmatrix} 10,002 & 0 \\ 0 & -0.00009998 \end{bmatrix} \begin{bmatrix} -0.01 & -1 \\ -1 & 0.01 \end{bmatrix}$$

$$\frac{\lambda_{\max}(A^T A)}{\lambda_{\min}(A^T A)} \approx 10^8$$

→ is really $-\sqrt{1-10^{-4}} = -0.999?$



angle of v^2 w.r.t. $v^1 \approx 0.57^\circ$

Later: Check the "numerical" rank of a matrix and the "numerical linear independence" of sets of vectors.

Today

Exercise: Show

$$P = \begin{bmatrix} 2 & -1 \\ -1 & 2 \end{bmatrix} \succ 0$$

Symbol for
pos. def.
Also see \succ

Important

Check
 $P = \begin{bmatrix} 2 & 3 \\ 3 & 2 \end{bmatrix}$ is not pos. def.

Definition: $P = P^\top$ is positive semidefinite if $x^\top P x \geq 0$ for all $x \neq 0$.

Theorem: P is positive semidefinite if and only if all eigenvalues of P are non-negative. (Notation: $P \geq 0$ or $P \succcurlyeq 0$.)

Definition: N is a square root of a symmetric matrix P if $N^\top N = P$.

Note: $N^\top N = (N^\top N)^\top \Rightarrow N^\top N$ is always symmetric.

Interesting

Theorem: $P \geq 0 \Leftrightarrow \exists N$ such that $N^\top N = P$.

Proof:

1. Suppose $N^\top N = P$, and let $x \in \mathbb{R}^n$.

$$x^\top P x = x^\top N^\top N x = (Nx)^\top (Nx) = \|Nx\|^2 \geq 0.$$

2. Now suppose $P \geq 0$. To show $\exists N$ such that $N^\top N = P$.

Since P is symmetric, there exists an orthogonal matrix O such that

$$P = O^\top \Lambda O$$

where $\Lambda = \text{diag}(\lambda_1, \lambda_2, \dots, \lambda_n)$.

Since $P \geq 0$, $\lambda_i \geq 0$ for all $i = 1, 2, \dots, n$.

Define $\Lambda^{1/2} := \text{diag}(\sqrt{\lambda_1}, \sqrt{\lambda_2}, \dots, \sqrt{\lambda_n})$,

$$\Lambda = (\Lambda^{1/2})^\top \Lambda^{1/2} = \Lambda^{1/2} \Lambda^{1/2}.$$

Let $N = \Lambda^{1/2} O$, then

$$N^\top N = O^\top (\Lambda^{1/2})^\top \Lambda^{1/2} O = O^\top \Lambda O = P.$$

$$\therefore N^\top N = P. \square$$

Schur Complement Thm

- Means for checking if a matrix is positive definite
- It shows up when we study conditional Gaussian Random Vectors !!!

Thm Suppose $A = n \times n$, $B = n \times m$, and C is $m \times m$ and that

$$M = \begin{bmatrix} A & B \\ B^T & C \end{bmatrix} \text{ is symmetric.}$$

$[A = A^T, C = C^T]$ Then TFAE:

a) $M > 0$

b) $A > 0$ and $C - B^T A^{-1} B > 0$

Schur complement of A in M

c) $C > 0$ and $A - B C^{-1} B^T > 0$

Schur complement of C in M

Proof Will show (a) \Leftrightarrow (b) and skip (a) \Leftrightarrow (c) because the proof is nearly identical.

a) \Rightarrow b) $M = \begin{bmatrix} A & B \\ B^T & C \end{bmatrix} > 0$. Hence, for

$$\text{all } \begin{bmatrix} x \\ y \end{bmatrix} \neq 0 \quad \begin{bmatrix} x \\ y \end{bmatrix}^T \begin{bmatrix} A & B \\ B^T & C \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} > 0.$$

Claim 1 Let $x \neq 0$ be otherwise arbitrary and set $y = 0$. Then

$$0 < \begin{bmatrix} x \\ 0 \end{bmatrix}^T \begin{bmatrix} A & B \\ B^T & C \end{bmatrix} \begin{bmatrix} x \\ 0 \end{bmatrix} = \begin{bmatrix} x \\ 0 \end{bmatrix}^T \begin{bmatrix} Ax \\ B^T x \end{bmatrix} = \\ = x^T A x \quad \therefore A > 0.$$

Claim 2 $C - B^T A^{-1} B > 0$

Pf. We let $y \neq 0$ be otherwise arbitrary and we make a clever choice of x

$$Ax + By = 0$$

$$\therefore x = -A^{-1}By \quad (\text{can do because } A > 0)$$

Because $y \neq 0$, $\begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} -A^{-1}By \\ y \end{bmatrix} \neq 0$

$$\therefore 0 < \begin{bmatrix} x \\ y \end{bmatrix}^T \begin{bmatrix} A & B \\ B^T & C \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$$

$$= \begin{bmatrix} x \\ y \end{bmatrix}^T \begin{bmatrix} 0 \\ B^T x + Cy \end{bmatrix}$$

$$= y^T B^T x + y^T C y$$

$$= y^T [B^T A^{-1} B y + C y]$$

$$= y^T [C - B^T A^{-1} B] y$$

$$\therefore (C - B^T A^{-1} B) > 0$$

□

$$(b) \Rightarrow (a) \quad A > 0 \text{ and } (C - B^T A^{-1} B) > 0$$

$$\Rightarrow M = \begin{bmatrix} A & B \\ B^T & C \end{bmatrix} > 0.$$

Claim 3 $(v^1 + v^2)^T M (v^1 + v^2) =$
 $= (v^1)^T M v^1 + 2 (v^1)^T M v^2 + (v^2)^T M v^2$

Recall $\langle x+y, x+y \rangle = \langle x, x \rangle + 2\langle x, y \rangle + \langle y, y \rangle$

Pf. Exercise.

Claim 4 Define $\tilde{x} = x + A^{-1}By$.

Then $\begin{bmatrix} \tilde{x} \\ y \end{bmatrix} \neq 0 \Leftrightarrow \begin{bmatrix} x \\ y \end{bmatrix} \neq 0$.

Pf.

If $y \neq 0$, then the result is obvious.

If $y = 0$, then $\tilde{x} = x$ and the result is also obvious.

Claim 5

$$\begin{bmatrix} x \\ y \end{bmatrix}^T \begin{bmatrix} A & B \\ B^T & c \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \underbrace{\tilde{x}^T A \tilde{x}}_{>0} + y^T \underbrace{(c - B^T A^{-1} B)}_{>0} y$$

Pf. Multiply out LHS = RHS.

Too boring for a ROB501 lecture.

□

Examples

$$a) M = \begin{bmatrix} a & b \\ b & c \end{bmatrix}_{2 \times 2} > 0 \Leftrightarrow \begin{matrix} a > 0 & \& \\ c - b(a)^{-1}b > 0 \end{matrix}$$

$$\Leftrightarrow a > 0 \& \quad ac - b^2 > 0$$

$$\Leftrightarrow a > 0 \& \det(M) > 0.$$

$$\begin{bmatrix} 3 & -2 \\ -2 & 3 \end{bmatrix} > 0 ?$$

$$\begin{bmatrix} 2 & 3 \\ 3 & 2 \end{bmatrix} > 0 ?$$

$$b) M = \begin{bmatrix} 2 & \vdots & 1 & \vdots & 1 \\ 1 & \vdots & 2 & \vdots & 1 \\ 1 & \vdots & 1 & \vdots & 3 \end{bmatrix} \quad \begin{matrix} A=2 & B=[1 \ 1] \\ C=\begin{bmatrix} 2 & 1 \\ 1 & 3 \end{bmatrix} \end{matrix}$$

$M > 0$? We check $A=2 > 0$ ✓ and

we check $C - B^T A^{-1} B =$

$$\begin{bmatrix} 2 & 1 \\ 1 & 3 \end{bmatrix} - \begin{bmatrix} 1 \\ 1 \end{bmatrix} \frac{1}{2} \begin{bmatrix} 1 & 1 \end{bmatrix} =$$

$$= \begin{bmatrix} 2 & 1 \\ 1 & 3 \end{bmatrix} - \frac{1}{2} \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 3\frac{1}{2} & 1\frac{1}{2} \\ 1\frac{1}{2} & 5\frac{1}{2} \end{bmatrix} > 0 \quad \checkmark$$

$\therefore M > 0.$

Rob 501 Handout: Grizzle Weighted Least Squares

Let M be an $n \times n$ positive definite matrix ($M \succ 0$) We revisit the over determined system of equations,

$$A\alpha = b,$$

where $A = n \times m, n \geq m, \text{rank}(A) = m, \alpha \in \mathbb{R}^m$, and $b \in \mathbb{R}^n$.

We seek $\hat{\alpha}$ such that

$$\|A\hat{\alpha} - b\| = \min_{\alpha \in \mathbb{R}^m} \|A\alpha - b\|$$

where $\|x\| := (x^\top M x)^{1/2}$ and $M > 0$.

Solution: Define an appropriate inner product space $\mathcal{X} = \mathbb{R}^n, \mathcal{F} = \mathbb{R}, \langle x, y \rangle := x^\top M y$ and decompose A into its columns

$$A = [A_1 \mid A_2 \mid \cdots \mid A_m]$$

We seek

$$\hat{x} := \underset{x \in \text{span}\{A_1, \dots, A_m\}}{\text{argmin}} \|x - b\|^2$$

Normal Equations:

$$\hat{x} = \hat{\alpha}_1 A_1 + \hat{\alpha}_2 A_2 + \cdots + \hat{\alpha}_m A_m$$

$$G^\top \hat{\alpha} = \beta, \text{ with } G = G^\top$$

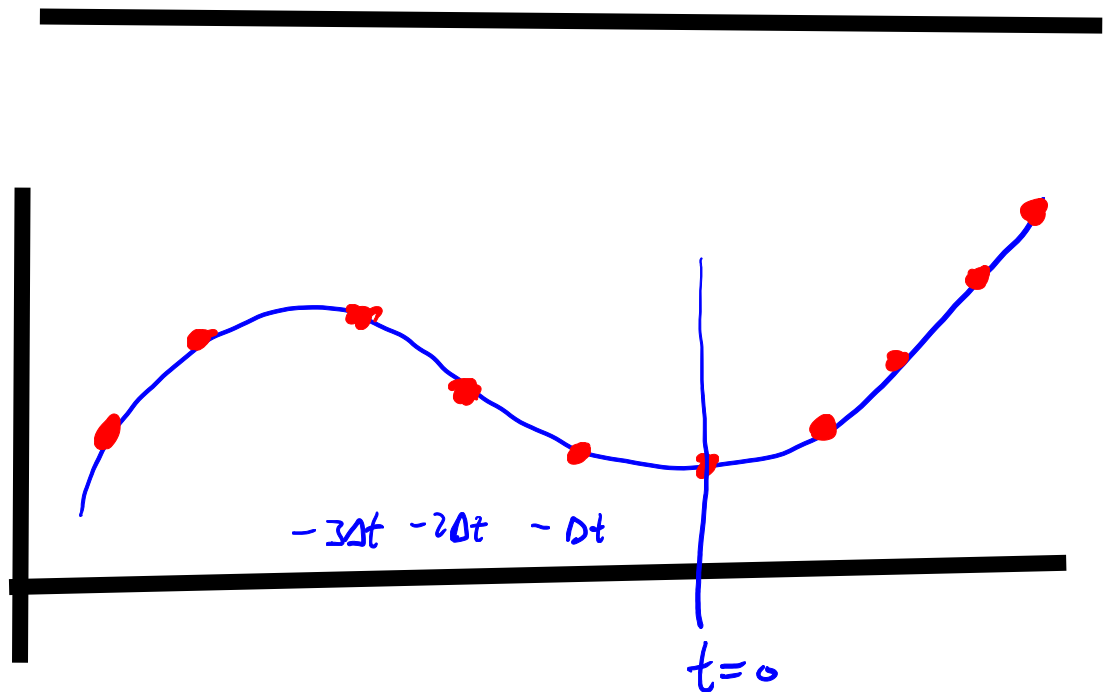
$$[G^\top]_{ij} = [G]_{ij} = \langle A_i, A_j \rangle = A_i^\top M A_j = [A^\top M A]_{ij}$$

$$\beta_i = \langle b, A_i \rangle = b^\top M A_i = A_i^\top M b = [A^\top M b]_i.$$

$$\therefore A^T M A \hat{\alpha} = A^T M b.$$

Because $\text{rank}(A) = m$, its columns are linearly independent and thus the Gram matrix is invertible. Hence, we conclude that

$$\hat{\alpha} = (A^T M A)^{-1} A^T M b.$$



$$y = a_0 + a_1 t, \quad y$$

$$Y = \begin{bmatrix} y_4 \\ y_3 \\ y_2 \\ y_1 \end{bmatrix}, \quad A = \begin{bmatrix} 1 & 0 \\ 1 & -\Delta t \\ 1 & -2\Delta t \\ 1 & -3\Delta t \end{bmatrix}, \quad \alpha = \begin{bmatrix} a_0 \\ a_1 \end{bmatrix}$$

$$\dot{y} \Big|_{t=0} = a_1 = \alpha(2)$$

$$\hat{\alpha} = (A^T A)^{-1} A^T Y$$

$$\dot{y} = \frac{y(t_k) - y(t_{k-1})}{\Delta t}$$