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#### ROB 501 Handout: Grizzle

#### **Inner Product Spaces**

**Definition:** Let  $(X, \mathbb{C})$  be a vector space. A function

$$\langle \cdot, \cdot \rangle : X \times X \to \mathbb{C}$$

is an **inner product** if

- (a)  $\langle x, y \rangle = \overline{\langle y, x \rangle}$
- (b)  $< \alpha_1 x_1 + \alpha_2 x_2, y > = \alpha_1 < x_1, y > +\alpha_2 < x_2, y >$  (i.e., linear in the left argument)
  - (c)  $\langle x, x \rangle \ge 0$  for any  $x \in X$ , and  $\langle x, x \rangle = 0 \Leftrightarrow x = 0$ .

In the case of a real vector space  $(X, \mathbb{R})$ , replace (a) with

(a'):  $\langle x, y \rangle = \langle y, x \rangle$ . It is easy to show that we then have linearity in both the left and right sides.

# **Examples:**

- (a)  $(\mathbb{C}^n, \mathbb{C})$   $\langle x, y \rangle = x^{\top} \overline{y}$
- (b)  $(\mathbb{R}^n, \mathbb{R})$   $\langle x, y \rangle = x^\top y$
- (c) The field is the real numbers  $\mathbb R$  and the vector space is the set of  $n\times m$  real matrices

$$X = \{A \mid A \text{ real } n \times m \text{ matrix}\},\$$

with inner product

$$\langle A, B \rangle = \operatorname{tr}(\mathbf{A}^{\top} \mathbf{B})$$

(d) X = C[a, b] = space of continuous real-valued functions on [a, b]

$$\langle f, g \rangle = \int_a^b f(t)g(t)dt$$

**Theorem:** [Cauchy-Schwarz Inequality] Suppose that  $\mathcal{F} = \mathbb{R}$  or  $\mathbb{C}$ . Let  $(X, \mathcal{F}, \langle \cdot, \cdot \rangle)$  be an **inner product space** (i.e.  $(X, \mathcal{F})$  is a vector space and  $\langle \cdot, \cdot \rangle$  is an inner product on X). Then, for all  $x, y \in X$ ,

$$|\langle x, y \rangle| \le \langle x, x \rangle^{1/2} \cdot \langle y, y \rangle^{1/2}$$
.

**Proof:** If y = 0, the result is obviously true. Hence, assume  $y \neq 0$ . For all scalars  $\lambda$  we have that

$$0 \le \langle x - \lambda y, x - \lambda y \rangle = \langle x, x \rangle - \lambda \langle y, x \rangle - \overline{\lambda} \langle x, y \rangle + |\lambda|^2 \langle x, y \rangle,$$

because the inner product of a vector with itself is a non-negative real number. For the particular choice  $\lambda = \frac{\langle x,y \rangle}{\langle y,y \rangle}$ , direct calculation shows

$$0 \le < x, x > -\frac{|< x, y > |^2}{< y, y >},$$

which gives

$$|\langle x, y \rangle| \le \sqrt{\langle x, x \rangle \langle y, y \rangle} = \langle x, x \rangle^{1/2} \cdot \langle y, y \rangle^{1/2}$$
.

Corollary: Let  $(X, \mathcal{F}, \langle \cdot, \cdot \rangle)$  be an inner product space. Then

$$||x|| := \langle x, x \rangle^{1/2}$$

is a norm on X.

**Proof:** The main thing to establish is the triangle inequality:

$$||x + y|| \le ||x|| + ||y||.$$

This is equivalent to showing:

$$||x + y||^2 \le ||x||^2 + 2||x|| ||y|| + ||y||^2$$
.

Brute force computation:

$$||x + y||^{2} = \langle x + y, x + y \rangle$$

$$= \langle x, x + y \rangle + \langle y, x + y \rangle$$

$$= \overline{\langle x + y, x \rangle} + \overline{\langle x + y, y \rangle}$$

$$= \overline{\langle x, x \rangle} + \overline{\langle x, y \rangle} + \overline{\langle x, y \rangle} + \overline{\langle y, y \rangle}$$

$$= \langle x, x \rangle + \langle x, y \rangle + \overline{\langle x, y \rangle} + \langle y, y \rangle$$

$$= ||x||^{2} + ||y||^{2} + 2\operatorname{Re}\{\langle x, y \rangle\}$$

where Re{< x, y >} denotes the real part of the complex number < x, y >. However, for any complex number  $\alpha$ , Re{ $\alpha$ }  $\le |\alpha|$ , and thus we have

$$||x + y||^2 = ||x||^2 + ||y||^2 + 2\operatorname{Re}\{\langle x, y \rangle\}$$

$$\leq ||x||^2 + ||y||^2 + 2|\langle x, y \rangle|$$

$$\leq ||x||^2 + ||y||^2 + 2||x|| ||y||,$$

where the last inequality is from the Cauchy-Schwarz Inequality.

## **Definition:**

- (a) Two vectors x and y are **orthogonal** if  $\langle x, y \rangle = 0$ . **Notation:**  $x \perp y$ .
- (b) A set of vectors S is orthogonal if

$$\forall x, y \in S, \quad x \neq y, \langle x, y \rangle = 0 \text{ (i.e. } x \perp y).$$

(c) If in addition  $||x|| = 1 \ \forall x \in S, S$  is an **orthonormal set**.

#### How to Construct Orthonormal Sets?

Gram-Schmidt Process: First orthogonalize, then normalize.

Let  $\{y_i \mid i = 1, ..., n\}$  be a *linearly independent* set of vectors. Define a set of vectors  $\{v_i \mid i = 1, ..., n\}$  recursively by

Step 1: Set

$$v_1 = y_1$$
.

Then clearly Span  $\{v_1\}$  = Span $\{y_1\}$ . From the linear independence of  $\{y_1\}$ , we see that  $\{v_1\}$  is linearly independent and hence  $v_1$  is nonzero.

Step 2: Set

$$v_2 = y_2 - a_{21}v_1,$$

and **choose**  $a_{21}$  so that  $\langle v_2, v_1 \rangle = 0$ .

$$0 = \langle v_2, v_1 \rangle = \langle y_2 - a_{21}v_1, v_1 \rangle$$

$$= \langle y_2, v_1 \rangle - a_{21} \langle v_1, v_1 \rangle$$

$$\therefore a_{21} = \frac{\langle y_2, v_1 \rangle}{\|v_1\|^2}$$

where we could divide by  $||v_1||^2$  because we know that  $v_1 \neq 0$ .

Claim Span  $\{v_1, v_2\} = \text{Span}\{y_1, y_2\}$  and  $v_1 \perp v_2$ .

**Proof of the claim:** The orthogonality is by construction. Because we have Span  $\{v_1\}$  = Span $\{y_1\}$ , in order to show Span  $\{v_1, v_2\}$  = Span $\{y_1, y_2\}$ , it is enough to show that  $v_2 \in \text{Span}\{y_1, y_2\}$  and  $y_2 \in \text{Span}\{v_1, v_2\}$ , which both follow from  $v_2 = y_2 - a_{21}v_1$ . Indeed,

$$y_2 = v_2 + a_{21}v_1$$

shows  $y_2 \in \text{Span}\{v_1, v_2\}$ , and

$$v_2 = y_2 - a_{21}v_1 = y_2 - a_{21}y_1$$

shows that  $v_2 \in \text{Span}\{y_1, y_2\}.$ 

From the linear independence of  $\{y_1, y_2\}$ , we see that the set  $\{v_1, v_2\}$  is linearly independent and hence  $v_1$  and  $v_2$  are nonzero. We could pass to the induction step now, but just to be extra clear, let's do one more:

**Step 3:** Write 
$$v_3 = y_3 - a_{31}v_1 - a_{32}v_2$$

$$0 = \langle v_3, v_1 \rangle = \langle y_3 - a_{31}v_1 - a_{32}v_2, v_1 \rangle$$

$$= \langle y_3, v_1, \rangle - a_{31} \langle v_1, v_1 \rangle - a_{32} \underbrace{\langle v_2, v_1 \rangle}_{=0}$$

$$\therefore a_{31} = \frac{\langle y_3, v_1 \rangle}{\|v_1\|^2}$$

$$0 = \langle v_3, v_2 \rangle = \langle y_3 - a_{31}v_1 - a_{32}v_2, v_2 \rangle$$

$$= \langle y_3, v_2 \rangle - a_{31} \underbrace{\langle v_1, v_2 \rangle}_{=0} - a_{32} \langle v_2, v_2 \rangle$$

$$\therefore a_{32} = \frac{\langle y_3, v_2 \rangle}{\|v_2\|^2}$$

**Step k:** In general, one obtains:

$$v_k = y_k - \sum_{j=1}^{k-1} \frac{\langle y_k, v_j \rangle}{\|v_j\|^2} \cdot v_j.$$

By construction, for each  $1 \le k \le n$ ,  $\{v_1, \dots, v_k\}$  is an **orthogonal** set.

**Normalization:** Define:  $\tilde{v}_i = \frac{v_i}{\|v_i\|} \Rightarrow \{\tilde{v}_1, \dots, \tilde{v}_k\}$  is **orthonormal**.

Remark: At each step, we need to prove that

$$\operatorname{Span} \{v_1, \cdots, v_k\} = \operatorname{Span} \{y_1, \cdots, y_k\}.$$

In this way we will have that the  $v_i$  are non-zero, and thus each step in the Gram-Schmidt process is well defined. First an example, then a proof.

**Example:** Construct a set of orthonormal vectors from

$$y_1^T = \begin{bmatrix} 1 & 0 & 1 \end{bmatrix}, \quad y_2^T = \begin{bmatrix} -1 & 2 & 1 \end{bmatrix}, \quad y_3^T = \begin{bmatrix} 0 & 1 & 2 \end{bmatrix}$$

The vectors are easily checked to be linearly independent.

# Orthogonalize: Let

$$v_1 = y_1 = \begin{bmatrix} 1 & 0 & 1 \end{bmatrix}^T$$
  
 $v_2 = y_2 - \frac{\langle y_2, v_1 \rangle}{\langle v_1, v_1 \rangle} v_1 = y_2$ , (because  $\langle y_2, v_1, \rangle = 0$ )

In this case  $y_1$  and  $y_2$  were already orthogonal, so there was nothing to do. Continuing,

$$v_3 = y_3 - \frac{\langle y_3, v_1 \rangle}{\langle v_1, v_1 \rangle} v_1 - \frac{\langle y_3, v_2, \rangle}{\langle v_2, v_2 \rangle} v_2 \tag{1}$$

$$=y_3 - \frac{2}{2}v_1 - \frac{4}{6}v_2 \tag{2}$$

$$= \begin{bmatrix} -\frac{1}{3} & -\frac{1}{3} & \frac{1}{3} \end{bmatrix}^T \tag{3}$$

**Normalize:** Normalize  $v_i$  to get  $\tilde{v}_i$ :

$$\tilde{v}_1 = \frac{v_1}{\|v_1\|} = \frac{1}{\sqrt{2}} \begin{bmatrix} 1\\0\\1 \end{bmatrix}, \ \tilde{v}_2 = \frac{v_2}{\|v_2\|} = \frac{1}{\sqrt{6}} \begin{bmatrix} -1\\2\\1 \end{bmatrix}, \ \tilde{v}_3 = \frac{v_1}{\|v_3\|} = \frac{1}{\sqrt{3}} \begin{bmatrix} -1\\-1\\1 \end{bmatrix}.$$

**Proposition:** Let  $\{y_1, \dots, y_k\}$  be a linearly independent set and suppose the set  $\{v_1, \dots, v_{k-1}\}$  is orthogonal and

$$\operatorname{span}\{v_1, \cdots, v_{k-1}\} = \operatorname{span}\{y_1, \cdots, y_{k-1}\}.$$

Define

$$v_k = y_k - \sum_{j=1}^{k-1} \frac{\langle y_k, v_j \rangle}{\|v_j\|^2} \cdot v_j$$
 (4)

Then,  $\{v_1, \dots, v_k\}$  is orthogonal and

$$span\{v_1, \cdots, v_k\} = span\{y_1, \cdots, y_k\}$$

**Proof:** The orthogonality is by construction. We will show that  $y_k \in \text{span}\{v_1, \dots, v_k\}$  and  $v_k \in \text{span}\{y_1, \dots, y_k\}$ .

From (4),

$$y_k = v_k + \sum_{j=1}^{k-1} \frac{\langle y_k, v_j \rangle}{\|v_j\|^2} \cdot v_j \implies y_k \in \text{span}\{v_1, \dots, v_k\}.$$

Left to show:  $v_k \in \text{span}\{y_1, \dots, y_k\}$ . By hypothesis,

$$v_j \in \operatorname{span}\{y_1, \cdots, y_{k-1}\}\ \text{for all } 1 \leqslant j \leqslant k-1,$$

SO

$$\sum_{j=1}^{k-1} \left( \frac{\langle v_j, y_k \rangle}{\|v_j\|^2} \right) v_j \in \text{span}\{y_1, \dots, y_{k-1}\} \subset \text{span}\{y_1, \dots, y_k\}.$$

Clearly,  $y_k \in \text{span}\{y_1, \cdots, y_k\}$ .

$$\therefore v_k = y_k - \sum_{j=1}^{k-1} \left( \frac{\langle v_j, y_k \rangle}{\|v_j\|^2} \right) v_j \in \text{span}\{y_1, \dots, y_k\}$$

because span $\{y_1, \dots, y_k\}$  is a subspace.

**Definition:**  $x \perp y \Leftrightarrow \langle x, y \rangle = 0$ ;  $x \perp S \Leftrightarrow \forall y \in S, \langle x, y \rangle = 0$ .

Claim: Suppose that  $x \perp \{y_1, \dots, y_k\}$  (i.e.  $\langle x, y_i \rangle = 0, 1 \leq i \leq k$ ). Then x is  $\perp$  to span $\{y_1, \dots, y_k\}$ , i.e.,  $\langle w, x \rangle = 0 \ \forall \ w \in \text{span}\{y_1, \dots, y_k\}$ .

Proof of the claim: 
$$\langle \sum_{i=1}^k \alpha_i y_i, x, \rangle = \sum_{i=1}^k \alpha_i \langle y_i, x, \rangle = 0$$

Claim: Let  $\{v_1, \dots, v_n\}$  be an **orthonormal basis** for a inner product space X. Then the representation of  $x \in X$  with respect to  $\{v_1, \dots, v_n\}$  is

$$x = \sum_{i=1}^{n} \langle x, v_i \rangle v_i$$

**Proof of the claim:**  $\{v_1, \dots, v_n\}$  a basis  $\Rightarrow \exists ! \text{ coeff. } \alpha_1, \dots, \alpha_n \text{ such that } x = \alpha_1 v_1 + \alpha_2 v_2 + \dots + \alpha_n v_n.$ 

Now,

$$\langle x, v_i \rangle = \langle \sum_{k=1}^n \alpha_k v_k, v_i \rangle$$

$$= \sum_{k=1}^n \alpha_k \underbrace{\langle v_k, v_i \rangle}_{0 \ k \neq i}$$

$$= \alpha_i$$

$$\therefore \alpha_i = \langle x, v_i \rangle$$

#### RECIPROCAL BASIS VECTORS

**Proposition:** Let  $(X, \mathbb{R}, \langle \cdot, \cdot \rangle)$  be an *n*-dim. inner product space, and let  $\{v_1, \dots, v_n\}$  be a basis for X (not necessarily orthonormal). Show that for each  $i = 1, 2, \dots, n, \exists r_i \in X$  such that

$$\langle r_i, v_j \rangle = \begin{cases} 1 & j = i \\ 0 & j \neq i \end{cases}$$
 (5)

**Solution:** Suffices to prove this for i = 1. Apply the Gram-Schmidt process to the linearly independent set  $\{v_2, v_3, \dots, v_n, v_1\}$ . Note that  $v_1$  has been permuted to the end. (To compute  $r_3$  for example, you would permute  $v_3$  to the end and apply the same procedure.) The Gram-Schmidt process will produce n orthogonal vectors  $\{w_2, w_3, \dots, w_n, w_1\}$ , such that

$$span\{w_2, w_3, \dots, w_n\} = span\{v_2, v_3, \dots, v_n\}$$

By construction,  $\langle w_1, w_j \rangle = 0, j = 2, \dots, n$ , which implies that

$$w_1 \perp \operatorname{span}\{w_2, \cdots, w_n\},$$
 (6)

and thus

$$w_1 \perp \operatorname{span}\{v_2, \cdots, v_n\}.$$
 (7)

From the Gram-Schmidt Process,

$$w_1 = v_1 - \sum_{j=2}^{n} \frac{\langle w_j, v_1 \rangle}{\|w_j\|^2} w_j.$$

Therefore,  $v_1 = w_1 + \sum_{j=2}^{n} \frac{\langle w_j, v_1 \rangle}{\|w_j\|^2} w_j$ , and hence,

$$< w_1, v_1 > = < w_1, w_1 >$$
 by (6) and (7).

 $\therefore$  If we choose  $r_1 = \frac{w_1}{\|w_1\|^2}$ , we have

$$\langle r_1, v_j \rangle = \begin{cases} 1 & j = 1 \\ 0 & j \neq 1 \end{cases}$$
 as desired.

**Remarks:** (a)  $\{r_1, \dots, r_n\}$  satisfying (5) is called a **reciprocal basis**. (b) In order to find  $r_k$ , simply rotate  $v_k$  to back as in  $\{v_1, \dots, v_{k-1}, v_{k+1}, \dots, v_n, v_k\}$  and apply the Gram-Schmidt procedure as above.

**Problem:**[4] Let  $(X, \mathbb{R}, <\cdot, \cdot>)$  be an *n*-dim. inner product space, let  $\{v_1, \cdots, v_n\}$  be a basis for X, and let  $\{r_1, \cdots, r_n\}$  be the corresponding reciprocal basis. Show that for all  $x \in X$ ,

$$x = \sum_{i=1}^{n} \langle r_i, x \rangle v_i \tag{8}$$

In other words, determining the representation of x with respect to  $\{v_1, \dots, v_n\}$  can be accomplished by computing inner products!

**Solution:** Because  $\{v_1, \dots, v_n\}$  is a basis, there exist unique  $\alpha_i \in \mathbb{R}$  such that

$$x = \sum_{i=1}^{n} \alpha_i v_i \tag{9}$$

Hence,

$$\langle r_i, x \rangle = \langle r_i, \sum_{k=1}^n \alpha_k v_k \rangle \tag{10}$$

$$= \sum_{k=1}^{n} \alpha_k \langle r_i, v_k \rangle \tag{11}$$

$$=\alpha_i \tag{12}$$

because  $\langle r_i, v_k \rangle$  equals one if i = k and zero otherwise. This proves (8).

# Inner Products: Example Computation for $(\mathbb{R}^3, \mathbb{R})$ Given data:

$$\langle p, q \rangle = p^{T}q = \sum_{i=1}^{3} p_{i}q_{i}$$

$$\{y_{1}, y_{2}, y_{3}\} = \left\{ \begin{bmatrix} 1\\1\\0 \end{bmatrix}, \begin{bmatrix} 1\\2\\3 \end{bmatrix}, \begin{bmatrix} 0\\1\\1 \end{bmatrix} \right\}$$

# Apply Gram-Schmidt to Produce an Orthogonal Basis:

$$\begin{aligned} v_1 &= y_1 = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} \\ \|v_1\|^2 &= (v_1)^T v_1 = 2; \\ v_2 &= y_2 - \frac{\langle v_1, y_2 \rangle}{\|v_1\|^2} v_1 \\ &= \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} - \underbrace{\begin{bmatrix} 1 & 1 & 0 \end{bmatrix}}_{3} \underbrace{\begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}}_{\frac{1}{2}} \underbrace{\begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}}_{0} = \underbrace{\begin{bmatrix} -\frac{1}{2} \\ \frac{1}{2} \\ 3 \end{bmatrix}}_{\frac{1}{2}} \\ \|v_2\|^2 &= 9\frac{1}{2} = \frac{19}{2}; \\ v_3 &= y_3 - \frac{\langle v_1, y_3 \rangle}{\|v_1\|^2} v_1 - \frac{\langle v_2, y_3 \rangle}{\|v_2\|^2} v_2 \\ &= \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} - \underbrace{\begin{bmatrix} 1 & 1 & 0 \end{bmatrix}}_{1} \underbrace{\begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}}_{\frac{1}{2}} \underbrace{\begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}}_{\frac{1}{2}} - \underbrace{\begin{bmatrix} -\frac{1}{2} \\ \frac{1}{2} \\ 3 \end{bmatrix}}_{\frac{19}{2}} \underbrace{\begin{bmatrix} -\frac{1}{2} \\ \frac{1}{2} \\ 3 \end{bmatrix}}_{\frac{19}{2}} \\ &= \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} - \underbrace{\begin{bmatrix} \frac{1}{2} \\ \frac{1}{2} \\ 0 \end{bmatrix}}_{\frac{1}{2}} - \underbrace{\begin{bmatrix} -\frac{7}{38} \\ \frac{11}{20} \end{bmatrix}}_{\frac{19}{2}} = \underbrace{\begin{bmatrix} -\frac{6}{19} \\ \frac{6}{19} \\ -\frac{2}{10} \end{bmatrix}}_{\frac{1}{2}}. \end{aligned}$$

#### Normalize to obtain Orthonormal Basis:

$$\tilde{v}_{1} = \frac{v_{1}}{\|v_{1}\|} = \begin{bmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \\ 0 \end{bmatrix}$$

$$\tilde{v}_{2} = \frac{v_{2}}{\|v_{2}\|} = \begin{bmatrix} \frac{-1}{\sqrt{38}} \\ \frac{1}{\sqrt{38}} \\ 3\sqrt{\frac{2}{19}} \end{bmatrix}$$

$$\tilde{v}_{3} = \frac{v_{3}}{\|v_{3}\|} = \frac{19}{\sqrt{76}} \begin{bmatrix} -\frac{6}{19} \\ \frac{6}{19} \\ -\frac{2}{19} \end{bmatrix}$$

# **Obtain Reciprocal Basis:**

We seek a basis  $\{r_1, r_2, r_3\}$  such that  $\langle r_i, y_j \rangle = \delta_{ij}$ . Step 1:  $r_1$  is found by applying the Gram-Schmidt process to  $\{y_2, y_3, y_1\}$ .

$$v_{1}^{1} := y_{2} = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$$

$$v_{1}^{2} := y_{3} - \frac{\langle v_{1}^{1}, y_{3} \rangle}{\|v_{1}^{1}\|^{2}} v_{1}^{1} = \begin{bmatrix} -\frac{5}{14} \\ \frac{2}{7} \\ -\frac{1}{14} \end{bmatrix}$$

$$v_{1}^{3} := y_{1} - \frac{\langle v_{1}^{1}, y_{1} \rangle}{\|v_{1}^{1}\|^{2}} v_{1}^{1} - \frac{\langle v_{1}^{2}, y_{1} \rangle}{\|v_{1}^{2}\|^{2}} v_{1}^{2} = \begin{bmatrix} \frac{2}{3} \\ \frac{2}{3} \\ -\frac{2}{3} \end{bmatrix}$$

$$r_{1} := \frac{v_{1}^{3}}{\|v_{1}^{3}\|^{2}} = \begin{bmatrix} \frac{1}{2} \\ \frac{1}{2} \\ -\frac{1}{2} \end{bmatrix}$$

Step 2:  $r_2$  is found by applying the Gram-Schmidt process to  $\{y_3, y_1, y_2\}$ .

$$v_{2}^{1} := y_{3} = \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}$$

$$v_{2}^{2} := y_{1} - \frac{\langle v_{1}^{1}, y_{1} \rangle}{\|v_{1}^{1}\|^{2}} v_{1}^{1} = \begin{bmatrix} 1 \\ \frac{1}{2} \\ -\frac{1}{2} \end{bmatrix}$$

$$v_{2}^{3} := y_{2} - \frac{\langle v_{1}^{1}, y_{2} \rangle}{\|v_{1}^{1}\|^{2}} v_{1}^{1} - \frac{\langle v_{1}^{2}, y_{1} \rangle}{\|v_{1}^{2}\|^{2}} v_{1}^{2} = \begin{bmatrix} \frac{2}{3} \\ -\frac{2}{3} \\ \frac{2}{3} \end{bmatrix}$$

$$r_{2} := \frac{v_{2}^{3}}{\|v_{2}^{3}\|^{2}} = \begin{bmatrix} \frac{1}{2} \\ -\frac{1}{2} \\ \frac{1}{2} \end{bmatrix}$$

Step 3:  $r_3$  is found by applying the Gram-Schmidt process to  $\{y_1, y_2, y_3\}$ .

$$v_{3}^{1} := y_{1} = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$$

$$v_{3}^{2} := y_{2} - \frac{\langle v_{1}^{1}, y_{2} \rangle}{\|v_{1}^{1}\|^{2}} v_{1}^{1} = \begin{bmatrix} -\frac{1}{2} \\ \frac{1}{2} \\ 3 \end{bmatrix}$$

$$v_{3}^{3} := y_{3} - \frac{\langle v_{1}^{1}, y_{3} \rangle}{\|v_{1}^{1}\|^{2}} v_{1}^{1} - \frac{\langle v_{1}^{2}, y_{3} \rangle}{\|v_{1}^{2}\|^{2}} v_{1}^{2} = \begin{bmatrix} -\frac{6}{19} \\ \frac{6}{19} \\ -\frac{2}{19} \end{bmatrix}$$

$$r_{3} := \frac{v_{3}^{3}}{\|v_{3}^{3}\|^{2}} = \begin{bmatrix} -\frac{3}{2} \\ \frac{3}{2} \\ -\frac{1}{2} \end{bmatrix}$$

Inner Products: Example Computation for  $(C[0,1],\mathbb{R})$ Given data:

$$C[0,1] = \{f : [0,1] \to \mathbb{R} \mid f \text{ continuous}\}, < f, g > = \int_0^1 f(\tau)g(\tau)d\tau$$

$${y_1, y_2, y_3} = {1, t, t^2}$$

# Apply Gram-Schmidt to Produce an Orthogonal Basis:

$$\begin{aligned} v_1 &= y_1 = 1 \\ \|v_1\|^2 &= \int_0^1 (1)^2 d\tau = 1; \\ v_2 &= y_2 - \frac{\langle v_1, y_2 \rangle}{\|v_1\|^2} v_1 \\ &= t - \underbrace{\int_0^1 1 \cdot \tau d\tau}_{\frac{1}{2}} \cdot \frac{1}{1} \cdot 1 = t - \frac{1}{2} \\ \|v_2\|^2 &= \int_0^1 (\tau - \frac{1}{2})^2 d\tau = \frac{1}{12}; \\ v_3 &= y_3 - \frac{\langle v_1, y_3 \rangle}{\|v_1\|^2} v_1 - \frac{\langle v_2, y_3 \rangle}{\|v_2\|^2} v_2 \\ &= t^2 - \underbrace{\int_0^1 1 \cdot \tau^2 d\tau}_{\frac{1}{3}} \cdot \frac{1}{1} \cdot 1 - \underbrace{\int_0^1 (\tau - \frac{1}{2})\tau^2 d\tau}_{\frac{1}{12}} \left(\frac{1}{\frac{1}{12}}\right) \left(t - \frac{1}{2}\right) \\ &= t^2 - \frac{1}{3} - \left(t - \frac{1}{2}\right) \\ &= t^2 - t + \frac{1}{6}. \end{aligned}$$

### Doing Inner products on C[a, b] in MATLAB

```
>> clear *
>> syms t % declare to be a symbolic variable
>> % INT(S,a,b) is the definite integral of S with respect to
   \% its symbolic variable from a to b. a and b are each
   % double or symbolic scalars.
>> y1=1+0*t % Otherwise MATLAB is too dumb to realize
            % that y1 is a trivial function of the symbolic
            % variable t
y1 = 1
>> y2=t;
>> y3=t^2;
% Start the G-S Procedure. Here we assume C[0,1], that is
% C[a,b], with [a,b]=[0,1]
>> v1=y1
v1 = 1
\Rightarrow v2=y2-int(v1*y2,0,1)*v1/int(v1^2,0,1)
v2=t-1/2
>> v3=y3-int(v1*y3,0,1)*v1/int(v1^2,0,1)-
int(v2*y3,0,1)*v2/int(v2^2,0,1)
v3=t^2+1/6-t
% Next, normalize to length one
v1_tilde=v1/int(v1^2,0,1)^.5
```

$$v2_{tilde}=(t-1/2)*12^(1/2)$$

ans=
$$(2*t-1)*3^(1/2)$$

$$v3_{tilde}=(6*t^2+1-6*t)*5^(1/2)$$