Rob 501 Handout: Grizzle

The SVD and Numerical Rank of a Matrix (Based on a handout of Prof. Freudenberg)

Motivation: In abstract linear algebra, a set of vectors is either linearly independent or not. There is nothing in between. For example, the set of vectors

$$\left\{ v^1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}, v^2 = \begin{bmatrix} 0.999 \\ 1 \end{bmatrix} \right\}$$

is linearly independent. In this case, you look at it and say, yes, BUT, the vectors are "almost" dependent because when I take the determinant

$$\det \begin{bmatrix} 1 & 0.999 \\ 1 & 1 \end{bmatrix} = 0.001,$$

I get something pretty small, so I am OK with calling them dependent. Well, what about the set

$$\left\{ v^1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}, v^2 = \begin{bmatrix} 10^4 \\ 1 \end{bmatrix} \right\}?$$

When you form the matrix and check the determinant, you get

$$\det \begin{bmatrix} 1 & 10^4 \\ 0 & 1 \end{bmatrix} = 1,$$

which seems pretty far from zero. So are these vectors "adequately" linearly independent?

Maybe not! Let's note that

$$\begin{bmatrix} 1 & 10^4 \\ 0 & 1 \end{bmatrix} + \begin{bmatrix} 0 & 0 \\ 10^{-4} & 0 \end{bmatrix} = \begin{bmatrix} 1 & 10^4 \\ 10^{-4} & 1 \end{bmatrix},$$

is clearly singular! Hence, we can add a very small perturbation to our vectors and make them dependent! This cannot be good! :(

Question: How to quantify the statement,"the rank is *nearly* 1" or more generally, how to quantify that a set of vectors is *nearly* linearly dependent?

Answer: The Singular Value Decomposition (**SVD**).

A good reference on numerical linear algebra is G. H. Golub and C. F. van Loan, *Matrix Computations*, The Johns Hopkins University Press, 1983.

Remark: In practice, you may have a need to deal with matrices that have complex entries, so the end of the handout also does things for $\mathbb{C}^{m\times n}$. The generalization of a real *symmetric* matrix is called a *Hermitian* matrix. And the generalization of a real *orthogonal* matrix is called a *unitary matrix.* These will not be on any ROB 501 exam.

Def. An $m \times n$ matrix Σ is rectangular diagonal if $\Sigma_{ij} = 0$ for $i \neq j$. The diagonal of Σ is

$$\mathrm{diag}\,(\Sigma) = (\Sigma_{11},\ \Sigma_{22},\ \cdots,\ \Sigma_{pp})$$

where $p := \min(m,\ n)$.

Examples Consider rectangular matrices

$$\Sigma_1 = \begin{bmatrix} 3 & 0 & 0 & 0 \\ 0 & 4 & 0 & 0 \\ 0 & 0 & -1 & 0 \end{bmatrix} \quad \text{and} \quad \Sigma_2 = \begin{bmatrix} 1 & 0 \\ 0 & -6 \\ 0 & 0 \end{bmatrix}$$

Then,

$$\mathrm{diag}\,(\Sigma_1) = \begin{bmatrix} 3 & 4 & -1 \end{bmatrix} \quad \text{and} \quad \mathrm{diag}\,(\Sigma_2) = \begin{bmatrix} 1 & -6 \end{bmatrix}$$

SVD Theorem: Any $m \times n$ real matrix A can be factored as

$$A = U\Sigma V^\top$$

where

$$\begin{aligned} U &= m \times m \text{ orthogonal matrix} \\ V &= n \times n \text{ orthogonal matrix} \\ \Sigma &= m \times n \text{ rectangular diagonal matrix} \end{aligned}$$

and $\text{diag}(\Sigma) = [\sigma_1,\ \sigma_2,\ \cdots,\ \sigma_p]$ satisfies $\sigma_1 \geq \sigma_2 \geq \cdots \geq \sigma_p \geq 0$ where $p = \min(m,\ n)$. Moreover, the columns of U are eigenvectors of $AA^\top$, the columns of V are eigenvectors of $A^\top A$, and the $(\sigma_i)^2$ are eigenvalues of both $AA^\top$ and $A^\top A$.

Remark: The entries of diag(Σ) are called singular values of A. We refer to σ_i as the i'th singular value, to u_i as the i'th left singular vector, and to v_i as the i'th right singular vector. The proof of the theorem is on page 12.

```
 SVD  Singular value decomposition.
  [U,S,V] = SVD(X) produces a diagonal matrix S, of the same
  dimension as X and with non-negative diagonal elements in
  decreasing order, and unitary matrices U and V so that
  X = U*S*V'.

   By itself, SVD(X) returns a vector containing diag(S).

A =[
    0.8038    0.1788    0.0960
    0.8576    0.6365    0.6991
    0.1107    0.6680    0.8653
    0.9522    0.6690    0.7041
    0.6551    0.7961    0.9283];

>> [U,S,V]=svd(A)

U =
   -0.2439   -0.6486    0.1591   -0.6821   -0.1711
   -0.4940   -0.1655    0.7006    0.4508    0.1859
   -0.3688    0.6649    0.2370   -0.3156   -0.5159
   -0.5236   -0.2418   -0.5645    0.3955   -0.4385
   -0.5350    0.2268   -0.3303   -0.2747    0.6912

S =
    2.5686         0         0
         0    0.8370         0
         0         0    0.0100
         0         0         0
         0         0         0
```

```
V =
   -0.5877   -0.8020    0.1065
   -0.5375    0.2886   -0.7923
   -0.6047    0.5229    0.6007

>> U*U'

ans =
    1.0000    0.0000    0.0000   -0.0000    0.0000
    0.0000    1.0000   -0.0000    0.0000   -0.0000
    0.0000   -0.0000    1.0000   -0.0000   -0.0000
   -0.0000    0.0000   -0.0000    1.0000   -0.0000
    0.0000   -0.0000   -0.0000   -0.0000    1.0000

>> A-U*S*V'

ans =
   1.0e-15 *
         0    0.0278   -0.8327
   -0.3331         0    0.1110
   -0.2220         0    0.2220
   -0.2220    0.2220   -0.2220
   -0.1110    0.2220         0
```

Theorem: rank(A) = number of nonzero singular values.

Fact: The numerical rank of A is the number of singular values that are larger than a given threshold. Often the threshold is chosen as a percentage of the largest singular value.

Example: 5×5 **matrix**

$$A = \begin{bmatrix} -32.57514 & -3.89996 & -6.30185 & -5.67305 & -26.21851 \\ -36.21632 & -11.13521 & -38.80726 & -16.86330 & -1.42786 \\ -5.07732 & -21.86599 & -38.27045 & -36.61390 & -33.95078 \\ -36.51955 & -38.28404 & -19.40680 & -31.67486 & -37.34390 \\ -25.28365 & -38.57919 & -31.99765 & -38.36343 & -27.13790 \end{bmatrix}$$

```
[U,Sigma,V]=svd(A);
```

$$\Sigma = \begin{bmatrix} 132.459 & 0.00000 & 0.00000 & 0.00000 & 0.00000 \\ 0.00000 & 37.70811 & 0.00000 & 0.00000 & 0.00000 \\ 0.00000 & 0.00000 & 33.41836 & 0.00000 & 0.00000 \\ 0.00000 & 0.00000 & 0.00000 & 19.34060 & 0.00000 \\ 0.00000 & 0.00000 & 0.00000 & 0.00000 & 0.79164 \end{bmatrix}$$

Because the **smallest singular value** $\sigma_5 = 0.79164$ **is less than** 1% **of the largest singular value** $\sigma_1 = 132.459$, in many cases, one might say that the numerical rank of A was 4 instead of 5.

This notion of numerical rank can be formalized by asking the following question: Suppose $\text{rank}(A) = r$. How far away is A from a matrix of rank strictly less than r?

The numerical rank of a matrix is based on the expansion

$$A = U\Sigma V^\top = \sum_{i=1}^{p} \sigma_i u_i v_i^\top = \sigma_1 u_1 v_1^\top + \sigma_2 u_2 v_2^\top + \cdots + \sigma_p u_p v_p^\top$$

where $p = \min\{m, n\}$, and once again, the singular values are ordered such that $\sigma_1 \geq \sigma_2 \geq \cdots \geq \sigma_p$. Each term $u_i v_i^\top$ is a rank-one matrix. The following exercises will help you understand the expansion.

Exercises: Suppose that A is $m \times n$, B is $n \times m$, and that $A = U\Sigma V^\top$ is the singular value decomposition of A.

- Partition A by columns, that is, $A = [A_1 \mid A_2 \mid \cdots \mid A_n]$ and B by rows, that is, $B^\top = \left[B_1^\top \mid B_2^\top \mid \cdots \mid B_n^\top\right]$. Show that

  $$AB = \sum_{k=1}^{n} A_k B_k.$$

  Hint: Show that $[A_k B_k]_{ij} = a_{ik} b_{kj}$ and recall the formula for $[AB]_{ij}$
- For here and the following, let $m = n$. $U\Sigma = [\sigma_1 u_1 \mid \sigma_2 u_2 \mid \cdots \mid \sigma_m u_m]$
- $A = U\Sigma V^\top = \sum_{i=1}^{m} \sigma_i u_i v_i^\top$
- $\forall\ 1 \leq j \leq m,\ \left[u_i v_i^\top\right] v_j = \begin{cases} u_i & j = i \\ 0 & j \neq i \end{cases}$
- $A^\top A = V\Sigma^2 V^\top$
- $A^\top A = V\Sigma^2 V^\top = \sum_{i=1}^{m} (\sigma_i)^2 v_i v_i^\top$
- The e-values of $v_i v_i^\top$ are $\lambda_1 = 1$ and the rest are zero. **Hint:** Show that

  $$\left[v_i v_i^\top\right] v_j = \begin{cases} v_i & j = i \\ 0 & j \neq i \end{cases}$$

Recall from HW For a symmetric real matrix M,

$$\max_{x^\top x=1} x^\top M x = \lambda_{\max}(M)$$

Def. (Induced matrix norm) Given $A \in \mathbb{R}^{m\times n}$. Then the *matrix norm induced by the Euclidean vector norm* is given by:

$$\begin{aligned} ||A||_2 := & \max_{x^\top x=1} ||Ax|| && (1)\\ = & \max_{x^\top x=1} \sqrt{x^\top A^\top A x} && (2)\\ = & \sqrt{\max_{x^\top x=1} x^\top A^\top A x} && (3)\\ = & \sqrt{\lambda_{\max}(A^\top A)} && (4) \end{aligned}$$

where $\lambda_{\max}(A^\top A)$ denotes the largest eigenvalue of the matrix $A^\top A$. **(Recall that we proved in lecture that all the eigenvalues of a matrix having the form $A^\top A$ are real and non-negative.)(Also, recall HW 2)**

Fact: Suppose that $\mathrm{rank}(A) = r$, so that σ_r is the smallest non-zero singular value. Then

(i) if an $n \times m$ matrix E satisfies $||E|| < \sigma_r$, then $\mathrm{rank}(A + E) \geq r$.

(ii) there exists E with $||E|| = \sigma_r$ and $\mathrm{rank}(A + E) < r$.

(iii) In fact, for $E = -\sigma_r u_r v_r^\top$, $\mathrm{rank}(A + E) = r - 1$.

(iv) Moreover, for $E = -\sigma_r u_r v_r^\top - \sigma_{r-1} u_{r-1} v_{r-1}^\top$, $\mathrm{rank}(A + E) = r - 2$.

Corollary: Suppose A is square and invertible. Then σ_r measures the distance from A to the nearest singular matrix.

Example: Using A above

```
>> d=diag(Sigma);
>> d(end)=0;
>> D=diag(d);
>> B=U*D*V';
>> E=A-B;
```

$$E = \begin{bmatrix} -0.04169 & 0.12122 & 0.09818 & -0.21886 & 0.05458 \\ 0.02031 & -0.05906 & -0.04784 & 0.10663 & -0.02659 \\ 0.01966 & -0.05716 & -0.04629 & 0.10320 & -0.02574 \\ 0.07041 & -0.20476 & -0.16584 & 0.36968 & -0.09220 \\ -0.08160 & 0.23728 & 0.19218 & -0.42839 & 0.10684 \end{bmatrix}$$

```
>> max(sqrt(eig(E'*E)))

 0.7916

 >> [U,Sigma,V]=svd(A-E);
```

$$\Sigma = \begin{bmatrix} 132.45977 & 0.00000 & 0.00000 & 0.00000 & 0.00000 \\ 0.00000 & 37.70811 & 0.00000 & 0.00000 & 0.00000 \\ 0.00000 & 0.00000 & 33.41836 & 0.00000 & 0.00000 \\ 0.00000 & 0.00000 & 0.00000 & 19.34060 & 0.00000 \\ 0.00000 & 0.00000 & 0.00000 & 0.00000 & 0.00000 \end{bmatrix}$$

I added a matrix with norm 0.7916 and made the (exact) rank drop from 4 to 5! How cool is that? It really shows that the matrix was close to a singular matrix.

Another Example:

```
>> N=100;A=[1,N;0,1]; [U,S,V]=svd(A); A,S

A =

     1   100
     0     1


S =

  100.0100          0
         0     0.0100
```

Hence, yeah, the SVD captures the fact that A is nearly singular.

Interesting and Useful Facts not on any ROB 501 Exam:

(a) We have not had the time to do anything with the nullspace and range of an $m \times n$ matrix A; they are important subspaces.

Nullspace: $\mathbf{N}(A) := \{x \in \mathbb{R}^n \mid Ax = 0\}$

Range: $\mathbf{R}(A) := \{y \in \mathbb{R}^m \mid \exists x \in \mathbb{C}^n \text{ such that } y = Ax\}$

(b) **Fact:** Let $[U, \Sigma, V] = \mathtt{svd}(A)$; Then the columns of U corresponding to non-zero singular values are a basis for $\mathbf{R}(A)$ and the columns of V corresponding to zero singular values are a basis for $\mathbf{N}(A)$.

(c) The SVD can also be used to compute an "effective" range and an "effective" nullspace of a matrix.

(d) Suppose that $\sigma_1 \geq ... \geq \sigma_r > \epsilon \geq \sigma_{r+1} \geq ...\sigma_n \geq 0$, so that r is the "effective" or numerical rank of A. (Note the ϵ inserted between σ_r and σ_{r+1} to denote the break point.)

(e) Let $\mathbf{R}_{\text{eff}}(A)$ and $\mathbf{N}_{\text{eff}}(A)$ denote the effective range and effective nullspace of A, respectively. Then we can calculate bases for these subspaces by choosing appropriate singular vectors:

$$\mathbf{R}_{\text{eff}}(A) := \text{span}\{u_1, ..., u_r\} \text{ and } \mathbf{N}_{\text{eff}}(A) := \text{span}\{v_{r+1}, ..., v_n\}.$$

The SVD for Real Matrices

Def. An $m \times n$ matrix Σ is rectangular diagonal if $\Sigma_{ij} = 0$ for $i \neq j$. The diagonal of Σ is

$$\operatorname{diag}(\Sigma) = (\Sigma_{11},\ \Sigma_{22},\ \cdots,\ \Sigma_{kk})$$

where $k = \min(m,\ n)$.

Examples Consider rectangular matrices

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Then,

$$\operatorname{diag}(\Sigma_1) = \begin{bmatrix} 3 & 4 & -1 \end{bmatrix} \quad \text{and} \quad \operatorname{diag}(\Sigma_2) = \begin{bmatrix} 1 & -6 \end{bmatrix}$$

SVD Theorem: Any $m \times n$ real matrix A can be factored as

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where

$$\begin{aligned} U &= m \times m \text{ orthogonal matrix} \\ V &= n \times n \text{ orthogonal matrix} \\ \Sigma &= m \times n \text{ rectangular diagonal matrix} \end{aligned}$$

and $\operatorname{diag}(\Sigma) = [\sigma_1,\ \sigma_2,\ \cdots,\ \sigma_p]$ satisfies $\sigma_1 \geq \sigma_2 \geq \cdots \geq \sigma_p \geq 0$ where $p = \min(m,\ n)$. Moreover, the columns of U are eigenvectors of $AA^\top$, the columns of V are eigenvectors of $A^\top A$, and the $(\sigma_i)^2$ are eigenvalues of both $AA^\top$ and $A^\top A$.

Remark: The entries of $\operatorname{diag}(\Sigma)$ are called singular values of A.

Proof of the theorem: $A^\top A$ is $n \times n$, real, and symmetric. Hence, there exist orthonormal eigenvectors $\{v^1, \cdots, v^n\}$ such that $A^\top A v^j = \lambda_j v^j$. Without loss of generality, we can assume that

$$\lambda_1 \geq \lambda_2 \geq \cdots \geq \lambda_n \geq 0$$

If not, we simply re-order the v^i's to make it so.

For $\lambda_j > 0$, say $1 \leq j \leq r$, we define

$$\sigma_j = \sqrt{\lambda_j}$$

and

$$q^j = \frac{1}{\sigma_j} A v^j \in \mathbb{R}^m$$

<u>Claim:</u> $\left(q^i\right)^\top q^j = \delta_{ij} = \begin{cases} 1 & i = j \\ 0 & 1 \neq j \end{cases}$ for $1 \leq i,\ j \leq r$.

<u>Proof of Claim:</u>

$$\begin{aligned} \left(q^i\right)^\top q^j &= \frac{1}{\sigma_i}\frac{1}{\sigma_j}\left(v^i\right)^\top A^\top A v^j \\ &= \frac{\lambda_j}{\sigma_i \sigma_j}\left(v^i\right)^\top v^j \\ &= \begin{cases} \frac{\lambda_j}{(\sigma_i)^2} & i = j \\ 0 & i \neq j \end{cases} \\ &= \begin{cases} 1 & i = j \\ 0 & 1 \neq j \end{cases} \end{aligned}$$

<u>End of proof of Claim.</u>

If $r < m$, we can extend the q^i's to an orthonormal basis for $\mathbb{R}^m$. Define

$$U = [q^1 \mid q^2 \mid \cdots \mid q^m]$$
$$V = [v^1 \mid v^2 \mid \cdots \mid v^n]$$

and define $\Sigma = m \times n$ by

$$\Sigma_{ij} = \begin{cases} \sigma_i \delta_{ij} & 1 \leq i,\ j \leq r \\ 0 & \text{otherwise} \end{cases}$$

Then, Σ is rectangular diagonal with

$$\operatorname{diag}(\Sigma) = [\sigma_1,\ \sigma_2,\ \cdots,\ \sigma_r,\ 0,\ \cdots,\ 0]$$

To complete the proof of the theorem, it is enough to show that $U^\top AV = \Sigma$. We note that the ij element of this matrix is

$$(U^\top AV)_{ij} = q_i^\top Av^j$$

If $j > r$, then $Av^j = 0$, and thus $q_i^\top Av^j = 0$, as required. If $i > r$, then q^i was selected to be orthogonal to

$$\{q^1,\ \cdots,\ q^r\} = \{\frac{1}{\sigma_1}Av^1,\ \frac{1}{\sigma_2}Av^2,\ \cdots,\ \frac{1}{\sigma_r}Av^r\}$$

and thus $\left(q^i\right)^\top Av^j = 0$.

Hence we now consider $1 \leq i,\ j \leq r$ and compute that

$$\begin{aligned} \left(U^\top AV\right)_{ij} &= \frac{1}{\sigma_i}\left(v^i\right)^\top A^\top Av^j \\ &= \frac{\lambda_j}{\sigma_i}\left(v^i\right)^\top v^j \\ &= \sigma_i \delta_{ij} \end{aligned}$$

as required. **End of Proof**.

SVD for Complex Matrices
(not on ROB 501 Final Exam)

Hermitian: Consider $x \in \mathbb{C}^n$. Then we define the vector "x Hermitian" by $x^H := \bar{x}^\top$. That is, x^H is the complex conjugate transpose of x. Similarly, for a matrix $A \in \mathbb{C}^{m\times n}$, we define $A^H \in \mathbb{C}^{n\times m}$ by $\bar{A}^\top$. We say that a square matrix $A \in \mathbb{C}^{n\times n}$ is a *Hermitian matrix* if $A = A^H$.

Important things to note:

- Similar to $A^\top A$ for real matrices, when A is complex, $A^H A$ has e-values that are real and non-negative. The proof is similar to things we have done in lecture; if you care to see it, you can find it online.
- In MATLAB, $A' = A^H$. Yikes! It is not the ordinary transpose? No, it is the complex conjugate transpose. If you want the ordinary transpose, use `transpose(A)`.

```
>> A=[j,0;0,-j]

A =

        0 + 1.0000i         0
        0                   0 - 1.0000i

>> A'

ans =

        0 - 1.0000i         0
        0                   0 + 1.0000i
```

Inner product on $\mathbb{C}^n$: Given $x, y \in \mathbb{C}^n$. Let the elements x and y be noted

$$x = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} \quad \text{and} \quad y = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{bmatrix}.$$

Then the Euclidean inner product is defined as

$$\begin{aligned} < x, y >: &= x^H y && (5) \\ &= \bar{x}_1 y_1 + \bar{x}_2 y_2 + \cdots + \bar{x}_n y_n && (6) \end{aligned}$$

We note that this puts the linearity on the right side of the "bracket", but as we have noted in HW, both definitions are common.

Euclidean vector norm: As in class, the vector norm associated with this inner product is given by

$$\begin{aligned} ||x||_2 : &= \sqrt{< x, x >} && (7) \\ &= \sqrt{\sum_{i=1}^{n} |x_i|^2} && (8) \end{aligned}$$

We often omit the subscript "2" when we are discussing the Euclidean norm (or "2-norm") exclusively.

Euclidean matrix norm: Given $A \in \mathbb{C}^{m \times n}$. Then the *matrix norm induced by* *the Euclidean vector norm* is given by:

$$
\begin{aligned}
||A||_2 := & \max_{x^H x=1} ||Ax|| && (9)\\
= & \max_{x^H x=1} \sqrt{x^H A^H A x} && (10)\\
= & \sqrt{\max_{x^H x=1} x^H A^H A x} && (11)\\
= & \sqrt{\lambda_{\max}(A^H A)} && (12)
\end{aligned}
$$

where $\lambda_{\max}(A^H A)$ denotes the largest eigenvalue of the matrix $A^H A$. **(As noted above, all the eigenvalues of a matrix having the form $A^H A$ are real and non-negative.)(Also, recall HW 2)**

<u>Orthogonality:</u> Two vectors $x, y \in \mathbb{C}^n$ are *orthogonal* if $< x, y >= 0$.

<u>Orthonormal Set:</u> A collection of vectors $\{x_1, x_2, \cdots, x_m\} \in \mathbb{C}^n$ is said to be an *orthonormal set* if

$$< x_i, x_j >= \begin{cases} 0, & i \neq j \\ 1, & i = j \end{cases} \qquad \text{(Hence } ||x_i|| = 1, \forall\ i.\text{)}$$

<u>**Unitary Matrix:**</u> A matrix $U \in \mathbb{C}^{n\times n}$ is *unitary* if $U^H U = UU^H = I_n$.

Fact: If U is a unitary matrix, then the columns of U form an orthonormal basis (ONB) for $\mathbb{C}^n$.

Proof of Fact: Denote the columns of U as $U = \begin{bmatrix} u_1 & u_2 & \cdots & u_n \end{bmatrix}$. Then

$$U^H U = \begin{bmatrix} u_1^H \\ u_2^H \\ \vdots \\ u_n^H \end{bmatrix} \begin{bmatrix} u_1 & u_2 & \cdots & u_n \end{bmatrix} = \begin{bmatrix} u_1^H u_1 & u_1^H u_2 & \cdots & u_1^H u_n \\ u_2^H u_1 & u_2^H u_2 & \cdots & u_2^H u_n \\ \vdots & \vdots & \ddots & \vdots \\ u_n^H u_1 & u_n^H u_2 & \cdots & u_n^H u_n \end{bmatrix} = \begin{bmatrix} 1 & 0 & \cdots & 0 \\ 0 & 1 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & 1 \end{bmatrix}$$

For real matrices, unitary is the same thing as orthogonal.

Example:

```
U =

    0.1259    0.9920
    0.9920   -0.1259

>>U*U'

ans =

    1.0000    0.0000
    0.0000    1.0000
```

Unitary matrices are effectively rotation matrices: they do not change the length of a vector, nor the angle between two vectors. Indeed,

1) From $U^H U = UU^H = I_n$, it follows that $U^{-1} = U^H$

2) Let's compute the inner product of Ux and Uy:

$$< Ux, Uy > := (Ux)^H Uy = x^H U^H Uy = x^H y =: < x, y >$$

3) It follows that
(a) norm of Ux equals the norm of x:

$$||Ux||^2 := < Ux, Ux > = < x, x > =: ||x||^2$$

(b) angle between x and y is the same as the angle between Ux and Uy:

$$\cos(\angle(x, y)) := \frac{< x, y >}{||x|| \; ||y||} = \frac{< Ux, Uy >}{||Ux|| \; ||Uy||} =: \cos(\angle(Ux, Uy))$$

4) All of the e-values of U have magnitude 1. Indeed, suppose that λ is an e-value with e-vector v: $Uv = \lambda v$

Applying norms to both sides of the above yields: $||Uv|| = ||\lambda v||$

But, by item (3) above and properties of norms:

$$||Uv|| = ||v|| \text{ and } ||\lambda v|| = |\lambda| \; ||v||$$

which, with the above, implies $|\lambda| = 1$.

Theorem (SVD for Complex matrices: Consider $A \in \mathbb{C}^{m \times n}$. Then there exist unitary matrices

$$U = \begin{bmatrix} u_1 & u_2 & \cdots & u_m \end{bmatrix}$$
$$V = \begin{bmatrix} v_1 & v_2 & \cdots & v_n \end{bmatrix}$$

such that

$$A = \begin{cases} U \begin{bmatrix} \Sigma \\ \\ 0 \end{bmatrix} V^H, & m \geq n \\ U \begin{bmatrix} \Sigma & 0 \end{bmatrix} V^H, & m \leq n \end{cases}$$

where

$$\Sigma = \begin{bmatrix} \sigma_1 & 0 & \cdots & 0 \\ 0 & \sigma_2 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & \sigma_p \end{bmatrix}, \; p = \min(m, n)$$

and

$$\sigma_1 \geq \sigma_2 \geq \cdots \sigma_p \geq 0$$

<u>Terminology:</u> We refer to σ_i as the i'th singular value, to u_i as the i'th left singular vector, and to v_i as the i'th right singular vector.