

13 Sept 2018

Review: \mathbb{F} = Field \longleftrightarrow 7 Axioms

Examples: \mathbb{R} , \mathbb{C} , \mathbb{Q}

Non-examples: \mathbb{Z} (integers) (No multiplicative inverses)
 \mathbb{I} (irrational numbers) (No zero = 0,
No one = unit = 1)

(V, \mathbb{F}) or (X, \mathbb{F}) Vector Space \longleftrightarrow 10 Axioms

Examples: $(\mathbb{R}^2, \mathbb{R})$, $(\mathbb{F}^n, \mathbb{F})$, $(\mathbb{F}^{n \times m}, \mathbb{F})$

(X, \mathbb{R}) where $X = \{f: D \rightarrow \mathbb{R}\}$ functions

(\mathbb{C}, \mathbb{R}) but (\mathbb{R}, \mathbb{C}) is not a vector space.

Subspaces

Def. Let (X, \mathbb{F}) be a vector space

and $Y \subset X$. Then Y is a subspace of X [or of (X, \mathbb{F})] if (Y, \mathbb{F}) is

a vector space when using the rules of vector addition and scalar times

Remarks: (a) In principle, must check all 10 axioms!

(b) 0 must be an element of y .

TODAY

Proposition (TFAE) The Following Are Equivalent for a vector space (X, \mathcal{F}) and $y \subset X$ a subset:

- y is a subspace of X
- $\forall v^1, v^2 \in y, v^1 + v^2 \in y$ and $\forall \alpha \in \mathcal{F}$,
 $\forall v \in y, \alpha \cdot v \in y$.
- $\forall \alpha \in \mathcal{F}$ and $\forall v^1, v^2 \in y, \alpha \cdot v^1 + v^2 \in y$
- $\forall \alpha_1, \alpha_2 \in \mathcal{F}$, and $\forall v^1, v^2 \in y$,
 $\alpha_1 \cdot v^1 + \alpha_2 \cdot v^2 \in y$.

]

Examples

1) $(X, \mathcal{F}) = (\mathbb{R}^2, \mathbb{R})$, $y = \left\{ \begin{bmatrix} \beta \\ 2\beta \end{bmatrix} \mid \beta \in \mathbb{R} \right\}$

$$\underbrace{\begin{bmatrix} \beta_1 \\ z\beta_1 \end{bmatrix}}_{V'} + \underbrace{\begin{bmatrix} \beta_2 \\ z\beta_2 \end{bmatrix}}_{V^2} = \begin{bmatrix} \beta_1 + \beta_2 \\ z(\beta_1 + \beta_2) \end{bmatrix} \in Y$$

$$\alpha \in \mathbb{R}, \quad \alpha \underbrace{\begin{bmatrix} \beta \\ z\beta \end{bmatrix}}_V = \begin{bmatrix} \alpha\beta \\ z(\alpha\beta) \end{bmatrix} \in Y$$

∴ Subspace.

2) $\mathcal{F} = \mathbb{R}$, $X = \{f: \mathbb{R} \rightarrow \mathbb{R}\}$

$Y := P(t) := \{ \text{polynomials in } t \text{ with real coefficients} \}$. Is a subspace by checking the proposition.

$$\tilde{Y} := \{ f: \mathbb{R} \rightarrow \mathbb{R}, f \text{ differentiable and } \frac{df}{dt} \equiv 0 \}. \subset X$$

Also subspace.

Non-example

$$(X, \mathcal{F}) = (\mathbb{R}^2, \mathbb{R})$$

$$Y = \left\{ \begin{bmatrix} \beta \\ z\beta \end{bmatrix} + \begin{bmatrix} 1 \\ 0 \end{bmatrix} \mid \beta \in \mathbb{R} \right\}$$

$0 \notin Y$. Not a subspace.

$\sigma = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$ in this case.

Linear Combinations and Linear Independence

Let (X, \mathbb{F}) be a vector space.

Def. A linear combination is any finite sum of the form

$$\alpha_1 v^1 + \alpha_2 v^2 + \dots + \alpha_n v^n$$

where $n \geq 1$, $\alpha_i \in \mathbb{F}$, $v^i \in X$, $1 \leq i \leq n$. \square

Note $\sum_{i=1}^{\infty} \alpha_i v^i$ is not a linear combination.

Why? $\sum_{i=1}^{\infty} \alpha_i v^i \triangleq \lim_{n \rightarrow \infty} \sum_{i=1}^n \alpha_i v^i$

Without additional structure, we cannot define what it means to converge to something; i.e., has a limit. \square

Mindset Let A be an $n \times n$

real matrix. Let $x \in \mathbb{R}^n$.

Fact: A is invertible \Leftrightarrow the only solution to $Ax = 0$ is $x = 0$. \square

$$A = [A_1 | A_2 | \dots | A_n], \quad x = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}$$

Exercise: $Ax = x_1 A_1 + x_2 A_2 + \dots + x_n A_n$

Def. A finite set of vectors

$\{v^1, \dots, v^k\} \subset X$ is linearly dependent if there exist $\alpha_1, \dots, \alpha_k \in \mathbb{F}$ **NOT**

ALL ZERO such that

$$\alpha_1 v^1 + \alpha_2 v^2 + \dots + \alpha_k v^k = 0.$$

Otherwise $\{v^1, \dots, v^k\}$ is linearly independent

[The only solution to
 $\alpha_1 v^1 + \alpha_2 v^2 + \dots + \alpha_k v^k = 0$
is the trivial solution,
 $\alpha_1 = \alpha_2 = \dots = \alpha_k = 0$] \square

Def. An arbitrary set of vectors is linearly independent if every finite subset of vectors is linearly independent.

Examples $(\mathbb{X}, \mathbb{F}) = (\mathbb{R}^2, \mathbb{R})$

$v^1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$ and $v^2 = \begin{bmatrix} 4 \\ 0 \end{bmatrix}$. Is the set $\{v^1, v^2\}$ linearly independent?

Let $\alpha_1, \alpha_2 \in \mathbb{R}$ be arbitrary.

$$\alpha_1 v^1 + \alpha_2 v^2 = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$



$$\alpha_1 \begin{bmatrix} 1 \\ 1 \end{bmatrix} + \alpha_2 \begin{bmatrix} 4 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$



$$\begin{bmatrix} \alpha_1 + 4\alpha_2 \\ \alpha_1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$\alpha_1 = \alpha_2 = 0$ is the only solution

\therefore Linearly independent.

$$X = \mathbb{R}^{2 \times 3}$$

$$F = \mathbb{R}$$

$$A_1 = \begin{bmatrix} 1 & 0 & 4 \\ 3 & -1 & 2 \end{bmatrix}$$

$$A_2 = \begin{bmatrix} 4 & 1 & 0 \\ 6 & 0 & 6 \end{bmatrix}$$

Independent?

$$\alpha_1 A_1 + \alpha_2 A_2 = ?$$

$$\alpha_1 A_1 + \alpha_2 A_2 = \begin{bmatrix} \alpha_1 + 4\alpha_2 & \alpha_2 & 4\alpha_1 \\ 3\alpha_1 + 6\alpha_2 & -\alpha_1 & 2\alpha_1 + 6\alpha_2 \end{bmatrix}$$

$$= \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \Leftrightarrow$$

$$\alpha_1 + 4\alpha_2 = 0$$

$$\alpha_2 = 0$$

$$4\alpha_1 = 0$$

$$3\alpha_1 + 6\alpha_2 = 0$$

$$-\alpha_1 = 0$$

$$2\alpha_1 + 6\alpha_2 = 0$$

$$\Leftrightarrow \alpha_1 = \alpha_2 = 0$$

∴ Linearly independent.

Example $(P(t), \mathbb{R}) = (\mathcal{X}, \mathcal{Y})$.

$S = \{1, t, t^2, t^3, \dots\} =$
all monomials.

Claim S is linearly independent.

Pf. (Lazy Induction) (Sketch of Proof)

Take an arbitrary, but finite, combination of elements of S

$$p(t) = a_0 + a_1 t + a_2 t^2 + \dots + a_k t^k$$

To show: $p(t) = 0$ vector $\Leftrightarrow a_0 = a_1 = \dots = a_k = 0$.

Important: $p(t) = 0$ vector $\Leftrightarrow \forall t \in \mathbb{R}$,
 $p(t) = 0$.

Observe $p(0) = 0 \Leftrightarrow a_0 = 0$.

"The trick" $p \equiv 0 \Rightarrow \frac{d}{dt} p \equiv 0$

$$\frac{d}{dt} p(t) = a_1 + 2a_2 t + \dots + k a_k t^{k-1}$$

$$\therefore \alpha = \frac{d}{dt} p(t) \Rightarrow p'(t) = 0 \Rightarrow a_1 = 0$$

Continue by induction. \square

Proof: Correct Proof by Induction: Let $k \geq 0$, and define the property $\mathcal{P}(k)$ by

$\mathcal{P}(k)$: The set $\{1, t, \dots, t^k\}$ is linearly independent

Base Case: $\mathcal{P}(0)$ is true; that is, the set $\{1\}$ is linearly independent. (You can work this out at home).

Induction Step: For $k \geq 0$, we assume that $\mathcal{P}(k)$ is true and we must show that $\mathcal{P}(k+1)$ is true, that is,

$\{1, t, \dots, t^{k+1}\}$ is linearly independent

Assume $p_{k+1}(t) := \alpha_0 + \alpha_1 t + \dots + \alpha_{k+1} t^{k+1} = 0$, the zero polynomial, and hence, is zero for all t . Then,

$$0 = \frac{d^{k+1} p_{k+1}}{dt^{k+1}}|_{t=0} = (k+1)! \alpha_{k+1}$$

and hence $\alpha_{k+1} = 0$. It follows that

$$p_{k+1}(t) := \alpha_0 + \alpha_1 t + \dots + \alpha_k t^k = 0.$$

By the induction step, this implies that

$$\alpha_0 = 0, \alpha_1 = 0, \dots, \alpha_k = 0,$$

and thus we are done.

\square

Def. Let $S \subset X$, (X, \mathcal{F})
 a vector space. The **Span** of S
 denoted $\text{Span}\{S\}$ or $\text{span } S$

is the set of all possible linear combinations of S . \square

$$\text{Span}\{S\} = \left\{ x \in X \mid \exists k \geq 1, \alpha_1, \dots, \alpha_k \in \mathbb{F}, v_1, \dots, v_k \in S \text{ such that } x = \alpha_1 v_1 + \dots + \alpha_k v_k \right\}$$

$\text{Span}\{S\}$ is always a subspace of X . { closed under vector addition and scalar times vector multiplication. }

Examples

$$\mathbb{F} = \mathbb{R}, X = \{ f: \mathbb{R} \rightarrow \mathbb{R} \},$$

$$S = \{ 1, t, t^2, \dots \}.$$

$$\text{Span}\{S\} = \text{TP}(t)$$

Question: Is $e^t \in \text{span}\{S\}$?

No only linear combinations
(finite sums).

$$\mathcal{F} = \mathbb{R}^{2 \times 4}, \quad A_1 = \begin{bmatrix} 1 & 2 & 3 & 5 \\ 0 & 0 & 4 & 0 \end{bmatrix}$$

$$A_2 = \begin{bmatrix} 0 & 0 & 0 & 4 \\ 1 & 1 & 1 & 5 \end{bmatrix}$$

$\text{span}\{A_1, A_2\} = \text{exercise!}$

