

Qualitative Spatial Reasoning over Line-Region Relations

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Knowledge Representation
Seminar Presentation

Agenda

Motivation

9-Intersection

Snapshot Model

Smooth-Transition Model

Evaluation

Summary

Motivation

- ▶ Modeling spatial relations
- ▶ How do humans conceptualize spatial relations?
- ▶ Strong correlation between Perceptual space and Language Space
- ▶ Understanding cognitive perceptual groupings

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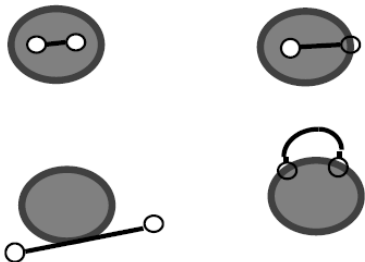
Summary

9-Intersection

Goal

A computational model to describe conceptual neighborhoods and enable the definition of a similarity metric for line region relations.

Conceptual Similarity: Which pairs of relationships are similar?



Formal Definitions

Line

A sequence of $1 \dots n$ connected 1-cells between two geometrically independent 0-cells such that they neither cross each other nor form cycles.

- Interior, Boundary, Exterior

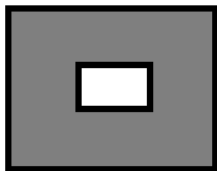


Formal Definitions(contd.,)

Region

A region is defined as a connected, homogeneously 2-dimensional 2-cell. Its boundary forms a Jordan curve separating the region's exterior from its interior.

- Interior, Boundary, Exterior



Adjacency

Topological adjacency

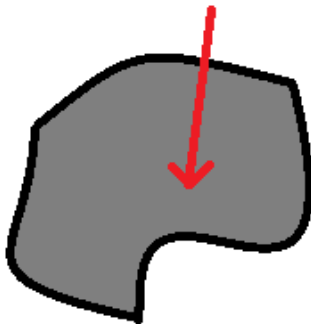
- ▶ $\text{Adjacent}(\text{Interior } A^0) = \partial A$
- ▶ $\text{Adjacent}(\text{Boundary } \partial A) = A^0 \text{ and } A^-$
- ▶ $\text{Adjacent}(\text{Exterior } A^-) = \partial A$



Adjacency

Topological adjacency

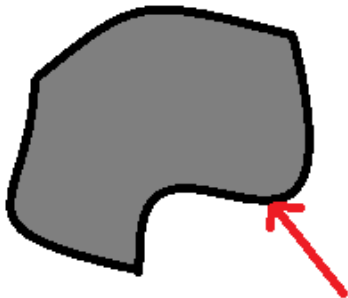
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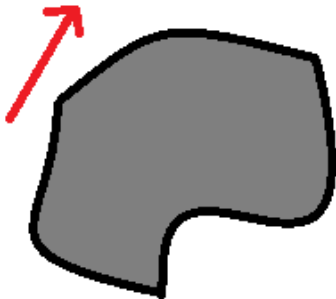
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9-Intersection(contd..)

Topological adjacency

- 9 intersections between the different topological parts of a line and a region

The 9-intersection Matrix(M)

$$\begin{pmatrix} L^0 \cap R^0 & L^0 \cap \partial R & L^0 \cap R^- \\ \partial L \cap R^0 & \partial L \cap \partial R & \partial L \cap R^- \\ L^- \cap R^0 & L^- \cap \partial R & L^- \cap R^- \end{pmatrix}$$

9-Intersection(contd..)

- ▶ Binary assignment to intersections($\emptyset, -\emptyset$)
- ▶ **512** possible instances of M
- ▶ **19** of 512 instances can actually be realized.

Example



$$\begin{pmatrix} L^0 \cap R^0 & L^0 \cap \partial R & L^0 \cap R^- \\ \partial L \cap R^0 & \partial L \cap \partial R & \partial L \cap R^- \\ L^- \cap R^0 & L^- \cap \partial R & L^- \cap R^- \end{pmatrix}$$

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Compute the values of the matrix...

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Snapshot Model

- ▶ A model of conceptual neighborhood among topological relations between a line and a region.

Characteristics

- ▶ No prior knowledge of the potential transformations that could lead from one configuration to the other.
- ▶ Comparison on the basis of a pre-defined distance metric

Differences of Intersections($\emptyset = 0$, $\neg\emptyset = 1$)

$$\begin{array}{rclcl} \emptyset & - & \emptyset & = & 0 \\ \neg\emptyset & - & \neg\emptyset & = & 0 \\ \emptyset & - & \neg\emptyset & = & -1 \\ \neg\emptyset & - & \emptyset & = & 1 \end{array}$$

Defining topological neighbors

Distance between any two relationships r_A, r_B is given by:

$$T_{r_A, r_B} = \sum_{i=0}^{-} \sum_{j=0}^{-} |M_A[i, j] - M_B[i, j]| \quad (1)$$

- ▶ It is the count of differences of empty/non empty entries of corresponding elements in the 9 intersections.
- ▶ Shortest Nonzero distance between relations is 1
- ▶ Spatial relations with the shortest non zero distance are considered topological neighbors.

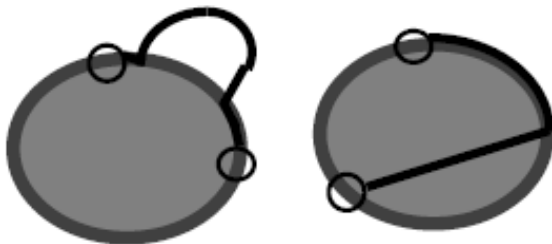
Example 1

Are these relations neighbors according to the snapshot model?

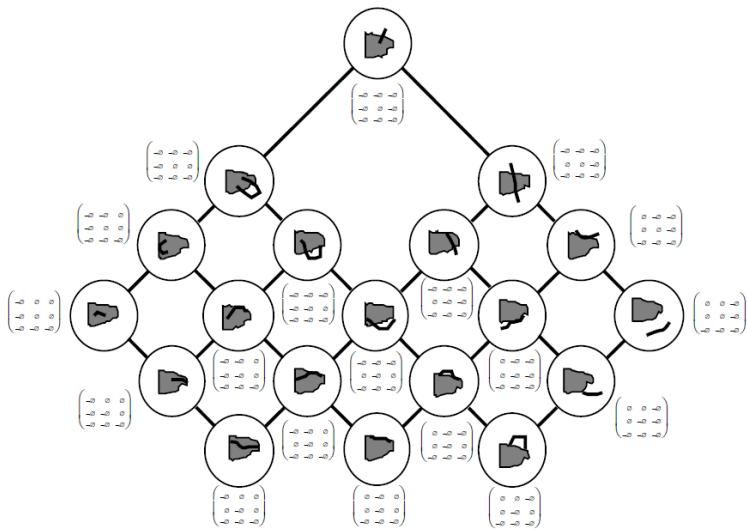


Example 2

Another example... Are these relations topological neighbors ?



Conceptual neighborhoods derived from the snapshot model



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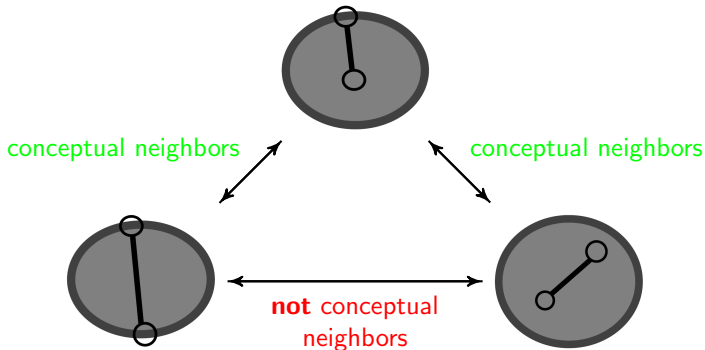
Summary

Smooth-Transition Model

Smooth Transition

An infinitesimally small deformation that changes the topological relation between the line and the region

Examples and Counterexamples



Formalization

A smooth transition occurs by moving around the line's

1. boundary nodes

Q: Do they intersect with the same region part?

Transition Rule 1 **if** Yes

Transition Rule 2 **if** No

2. interior

Transition Rule 3 **to** extend the intersection area *and*

Transition Rule 4 **to** reduce it

What this means for the 9-intersection:

An entry or its adjacent entries gets changed from \emptyset to $\neg\emptyset$ or v.v.

One More Thing...

Definition (Extent of a line part i)

- ▶ Denoted by $\#M[i, -]$
- ▶ Count of intersections betw. line part i and the region parts
- ▶ $\#M[i, -]$ in the interval $[0 \dots 3]$

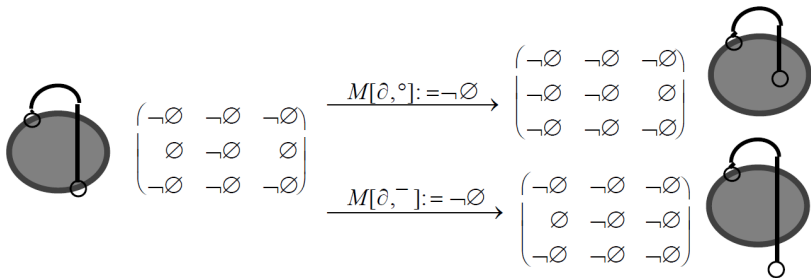
Examples

- ▶ extent of the line's boundary is either 1 (if both nodes are located in the same region part) or 2 (if the nodes are located in different parts of the region)
- ▶ extent of a line's exterior is always 3

Transition Rule 1

If the line's two boundaries intersect with the **same** region part, then extend the intersection to either of the adjacent region parts:

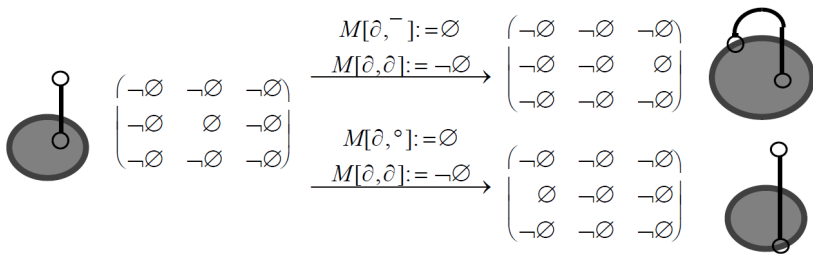
$$\#M[\delta, _]=1 \Rightarrow \forall i(M[\delta, i] = \neg\emptyset) : M_N[\delta, \text{adjacent}(i)] := \neg\emptyset$$



Transition Rule 2

If the line's two boundaries intersect with two **different** region parts then move either intersection to the adjacent region part:

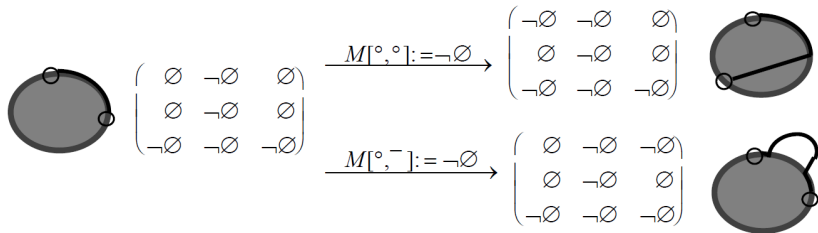
$$\begin{aligned} \#M[\delta, _] = 2 &\implies \forall i (M[\delta, i] = \neg\emptyset) : \\ M_N[\delta, i] &:= \emptyset \wedge M_N[\delta, \text{adjacent}(i)] := \neg\emptyset \end{aligned}$$



Transition Rule 3

Extend the line's interior-intersection to either of the adjacent region parts:

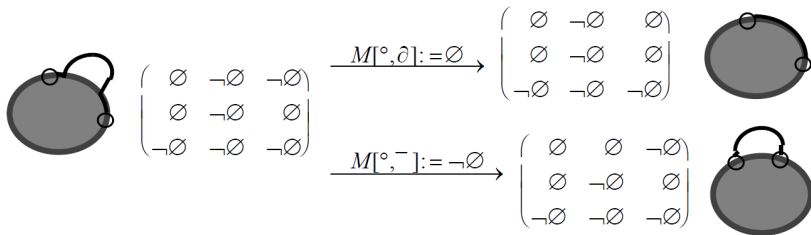
$$\forall i (M[\circ, i] = \neg\emptyset) : M_N[\circ, \text{adjacent}(i)] := \neg\emptyset$$



Transition Rule 4

Reduce the line's interior intersection on either of the adjacent region parts.

$$\begin{aligned} \#M[^\circ, _] = 2 &\implies \forall i (M[^\circ, i] = \neg\emptyset) : M_N[^\circ, i] := \emptyset \\ \#M[^\circ, _] = 3 &\implies \forall i (i \neq \delta) : M_N[^\circ, i] := \emptyset \end{aligned}$$



Additional Consistency Constraints

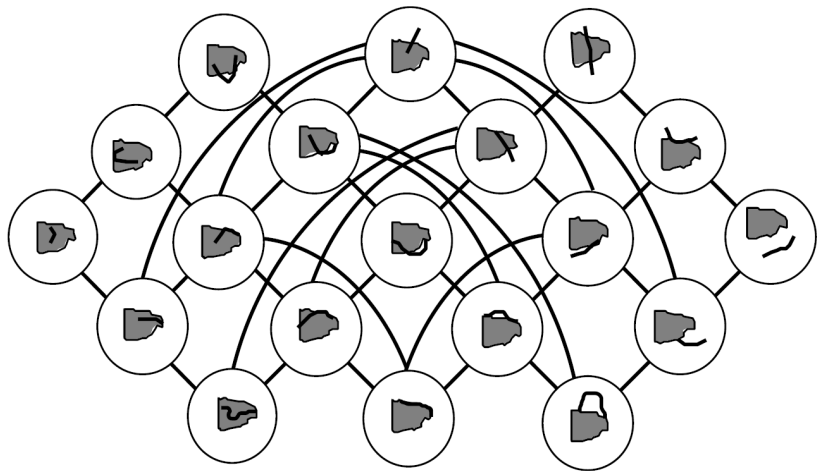
1. If the line's interior intersects with the region's interior *and* exterior, then the line's interior must also intersect with the region's boundary.

$$M[^\circ, ^\circ] = \neg\emptyset \wedge M[^\circ, ^-] = \neg\emptyset \implies M[^\circ, \delta] := \neg\emptyset$$

2. If the line's boundary intersects with the region's interior (exterior) then the line's interior must intersect with the region's interior (exterior) as well.

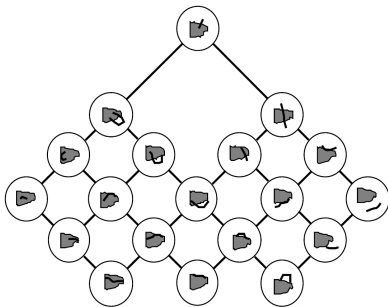
$$\begin{aligned} M[\delta, ^\circ] = \neg\emptyset &\implies M[^\circ, ^\circ] := \neg\emptyset \\ M[\delta, ^-] = \neg\emptyset &\implies M[^\circ, ^-] := \neg\emptyset \end{aligned}$$

Resulting Neighborhood Graph

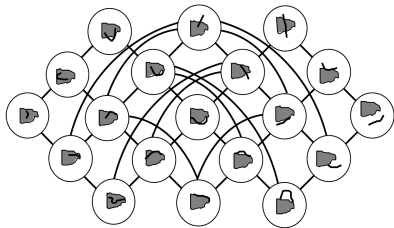


Comparison

Snapshot Model



Smooth-Transition Model



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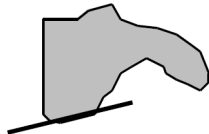
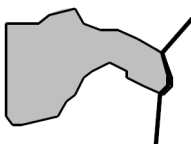
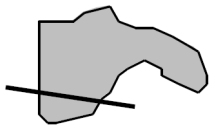
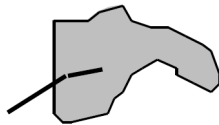
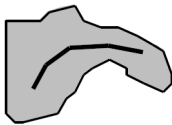
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Setup

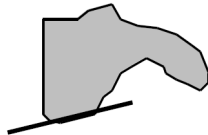
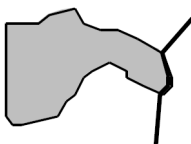
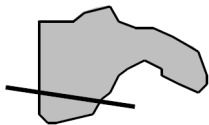
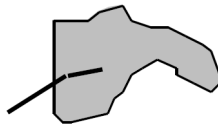
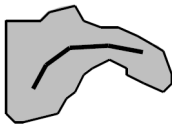
- ▶ **2** geometrically distinct placements of the line for each of the **19** topologically distinct relations
- ▶ a total of **38** diagrams each showing a line and a region
- ▶ line → road, region → park
- ▶ parks in all diagrams same size and shape
- ▶ 28 participants

Setup (cont.)



Q: Find the pair that is topologically identical from among all geometrically distinct diagrams.

Setup (cont.)



Q: Find the pair that is topologically identical from among all geometrically distinct diagrams.

A: The right and middle examples in the lower row.

Task

- ▶ arrange the sketches into several groups, such that you would use the same verbal description for the spatial relationship between the road and the park for every sketch in each group

Goal

Goal

- ▶ analyse how the subjects formed groups of similar relations
- ▶ check similarity with presented conceptual neighborhood models

Results

Each spatial relation could be grouped as many as 112 times (4 pairs times 28 subjects) with each other relation.

Number of times conceptual neighbors are grouped:

	... ¹	<i>min</i>	<i>max</i>	<i>mean</i>	% ²
snapshot model only	2	10	16	13.0	11.6
smooth-transition model only	12	0	66	17.3	15.4
both models	26	0	78	33.6	29.5
neither model	131	-	-	6.0	5.3

¹Number of relations that are conceptual neighbors

²percentage = mean / 112

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Two Conceptual Neighborhood Models:

1. Snapshot Model
2. Smooth-Transition Model

Finding: *Almost* identical Conceptual-Neighborhood Graphs

Findings from the Human-Subject Experiment:

- ▶ models correspond largely to the way humans conceptualize similarity about line-region relations
- ▶ smooth-transition model captures more aspects of the similarity of topological line-region relations than the snapshot model

References

- ▶ Egenhofer, Max J., and David M. Mark. "Modelling conceptual neighbourhoods of topological line-region relations." *International journal of geographical information systems* 9.5 (1995): 555-565.
- ▶ Mark, David M., and Max J. Egenhofer. "Modeling spatial relations between lines and regions: combining formal mathematical models and human subjects testing." *Cartography and geographic information systems* 21.4 (1994): 195-212.
- ▶ Egenhofer, Max J., and A. Rashid Shariff. "Metric details for natural-language spatial relations." *ACM Transactions on Information Systems (TOIS)* 16.4 (1998): 295-321.
- ▶ Talmy, Leonard. *How language structures space*. Springer US, 1983.
- ▶ Moore, Timothy E. "Cognitive Development and the Acquisition of Language." (1973).