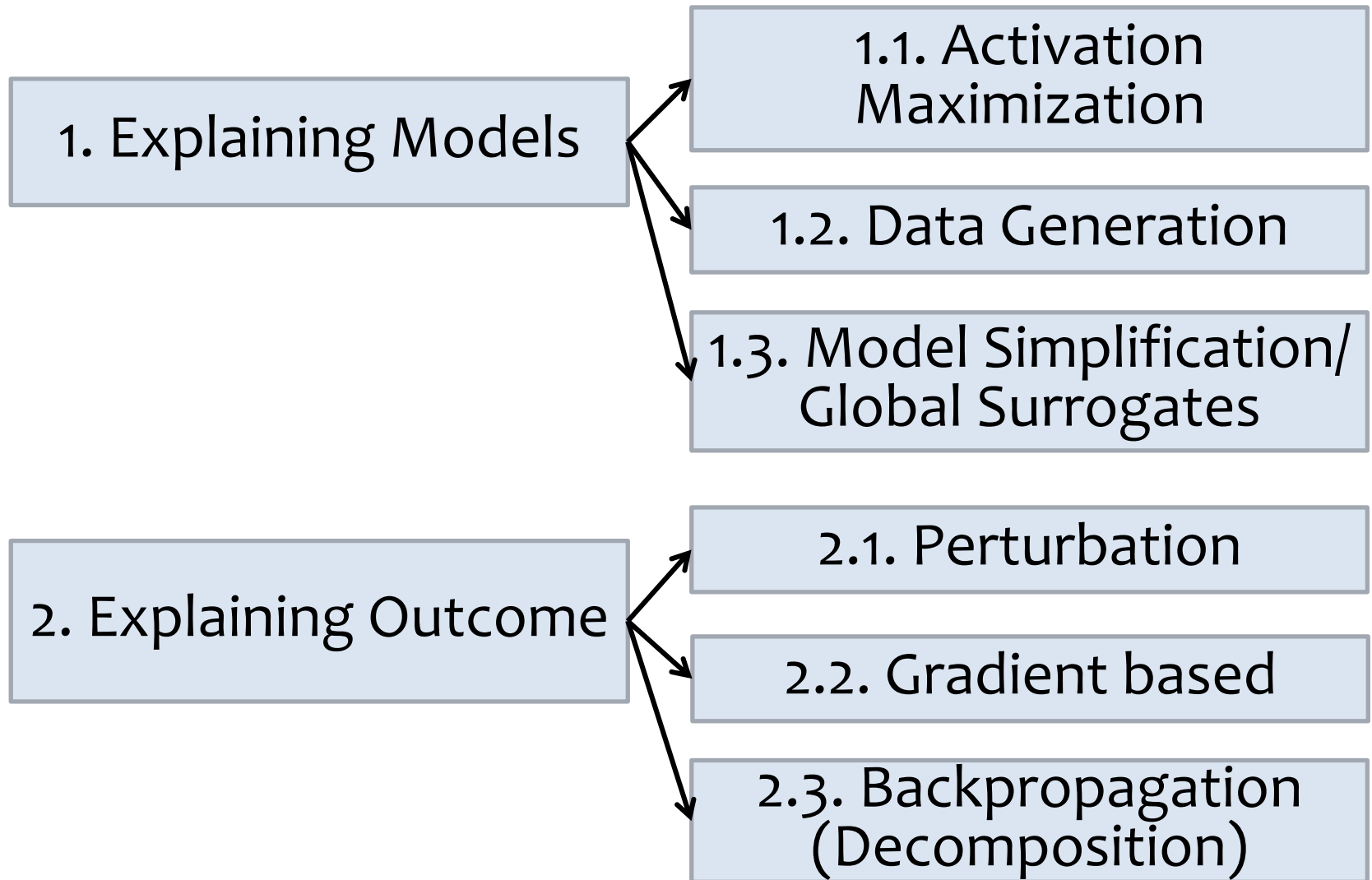


Explaining Deep Learning Methods



Part 3: Interpretable Deep Learning

- **Explaining Models (EM)**
- Explaining Outcome (EO)

* Most of the slides comes in this section comes from

- ICASSP 2017 Tutorial and CVPR'18 Tutorial by W. Samek, G. Montavon and K.R. Müller [ICASSP 2017 Tutorial] [CVPR'18 Tutorial]
- G. Montavon, et al. "Methods for interpreting and understanding deep neural networks," *Digit. Signal Process.*, vol. 73, pp. 1–15, 2018.
- R. Guidotti et al., "A Survey of Methods for Explaining Black Box Models," *ACM Comput. Surv.*, vol. 51, no. 5, pp. 1–42, Aug. 2018.

Class Prototypes (CP)

- “How does a goose typically look like according to the neural network?”

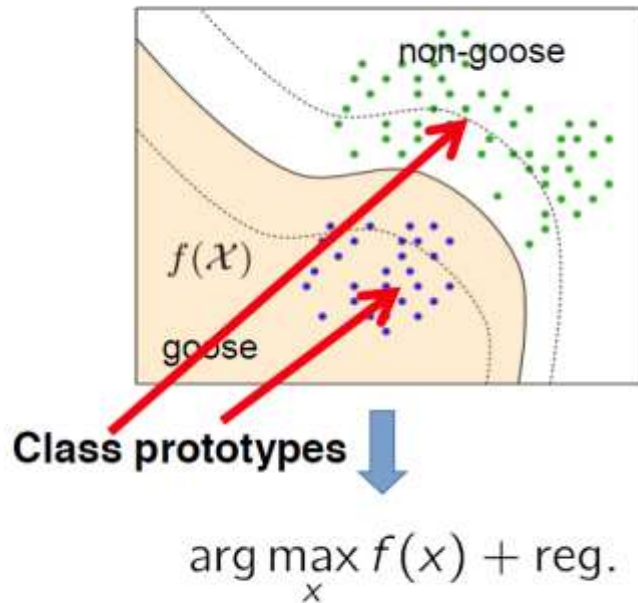
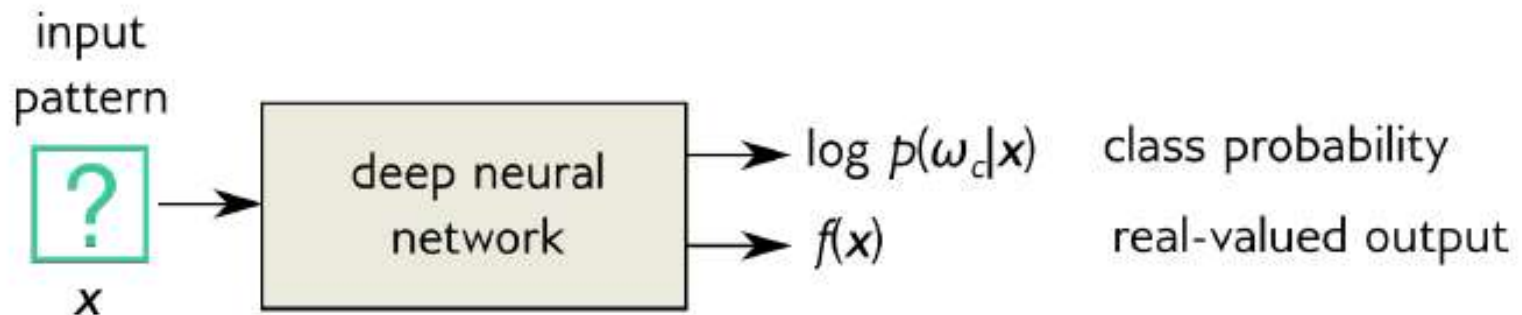


Image from Symonians'13

[CVPR'18 Tutorial]

Activation Maximization (AM)

Interpreting concepts predicted by a deep neural net via activation maximization



□ Example :

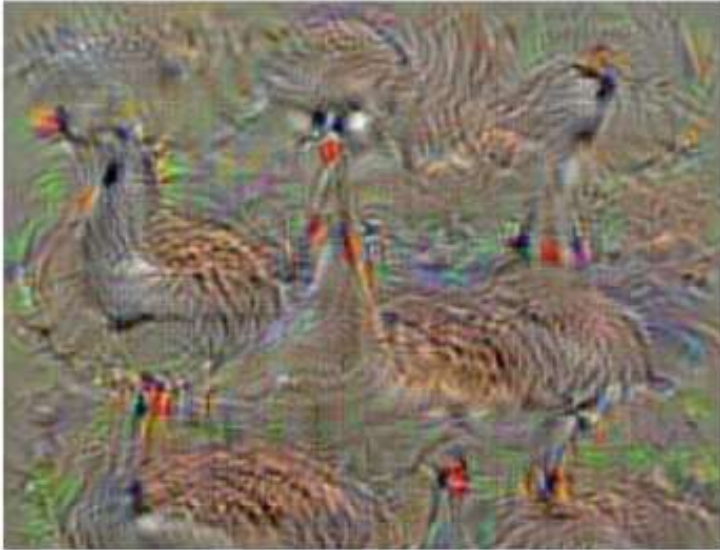
- Creating class prototype: $\operatorname{argmax}_{x \in \mathcal{X}} \log p(w_c|x)$
- Synthesizing extreme case: $\operatorname{argmax}_{x \in \mathcal{X}} f(x)$

Activation Maximization

- ❑ [Erhan et al. 2010] – Find image that maximize neuron activity in of interest in Deep Belief Network
- ❑ [Le et al. 2012] – Visualize class model in Autoencoder
- ❑ [Simonyan et al. 2014] – Saliency map of CNN
- ❑ [Nguyen et al. 2016]
- ❑ ...

Saliency Map via AM

goose



ostrich



Saliency map of goose and ostrich from **Simonyan et al. 2013**

Problem: Saliency map obtained by AM

- 1) often not resembling true data,
- 2) can be uninterpretable to humans

Improving Activation Maximization

- ❑ **Idea:** Force the features learned to match the data more closely.
- ❑ Now the optimization problem become

Finding the input pattern that maximizes **class probability**. $p(w|x)$

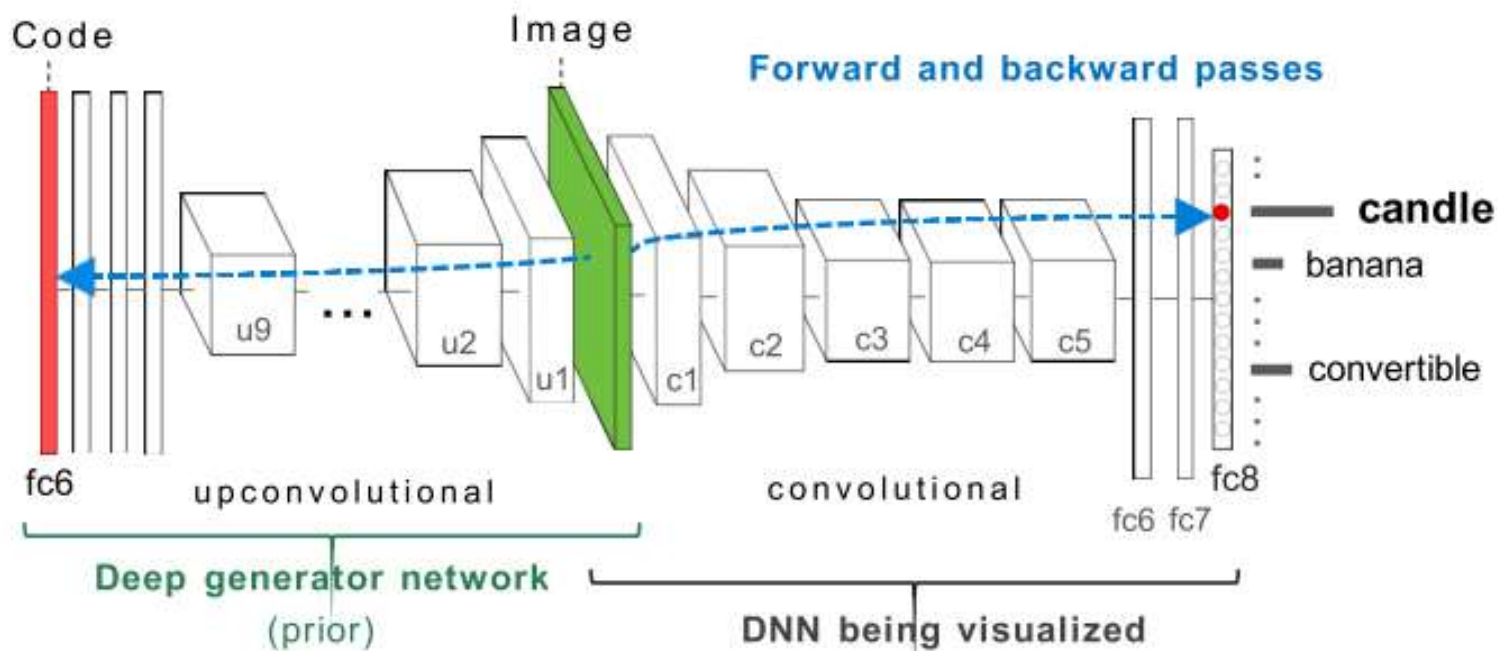


Find the **most likely input pattern** for a given class. $p(x|w)$

Data Generation

Problem: Activation maximization problem as finding a code \mathbf{y}^l such that:

$$\hat{\mathbf{y}}^l = \arg \max_{\mathbf{y}^l} \Phi_h \left(G_l(\mathbf{y}^l) \right) - \lambda \|\mathbf{y}^l\|$$



Deep generator network proposed by Nguyen et al. 2016

Model Simplification/ Global Surrogates

- ❑ Model Simplification – AKA Model Compression
 - Applied more for embedded programming than to interpretation
- ❑ Global Surrogates – Simple models often fails for DNN cases.

Modular Representation

- ❑ Trained network
- ❑ Trained network
- ❑ Community structure
- ❑ Modular representation
 - bundled connections are defined that summarize multiple connections between pairs of detected communities

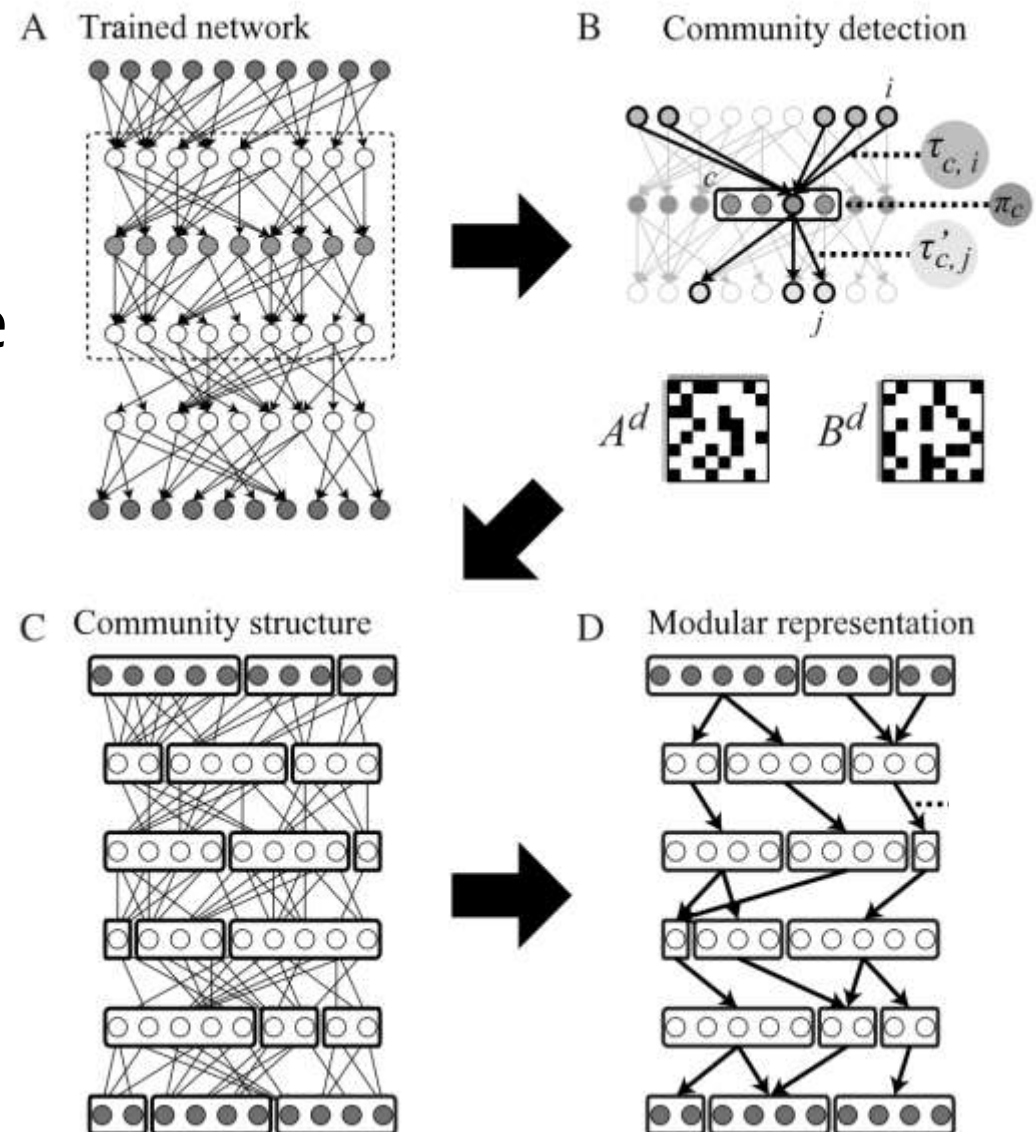


Fig 1. of Watanabe et al. 2018

Part 3: Interpretable Deep Learning

- Explaining Models (EM)
- **Explaining Outcome (EO)**

* Most of the slides comes in this section comes from

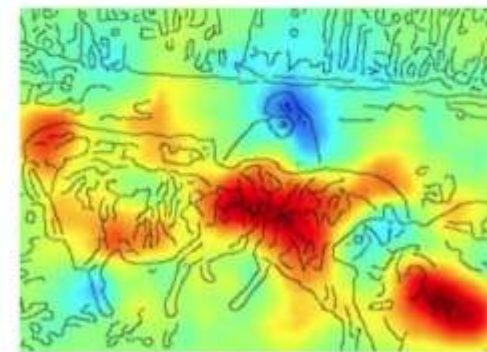
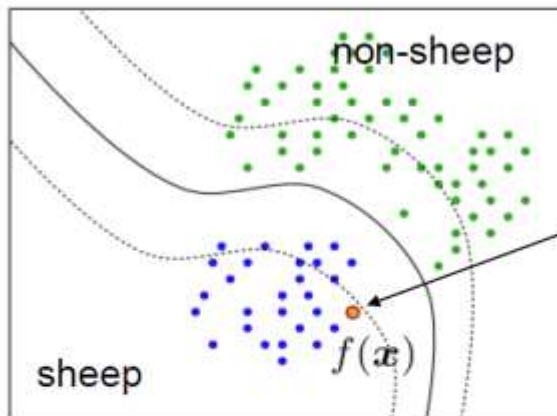
- ICASSP 2017 Tutorial and CVPR'18 Tutorial by W. Samek, G. Montavon and K.R. Müller [ICASSP 2017 Tutorial] [CVPR'18 Tutorial]
- G. Montavon, et al. "Methods for interpreting and understanding deep neural networks," *Digit. Signal Process.*, vol. 73, pp. 1–15, 2018.
- R. Guidotti et al., "A Survey of Methods for Explaining Black Box Models," *ACM Comput. Surv.*, vol. 51, no. 5, pp. 1–42, Aug. 2018.

Explaining Outcome

- ❑ **Goal:** Determine the relevance of each (set of) input feature for a given decision on an instance, by assigning to these variables a **scores to each (set of) feature.**
- ❑ Important for **Personalized Healthcare**
- ❑ Most DNN explained via a **Saliency Mask**
 - Feature importance that is presented in a visual form to show subset of the original input which is mainly responsible for the prediction.

Explaining Individual Outcome

- ❑ *EX* > “Why is a given image classified as a sheep?”



$$\text{heatmap} = LRP(x, f)$$

Images from **Lapuschkin'16**

Saliency Map Examples

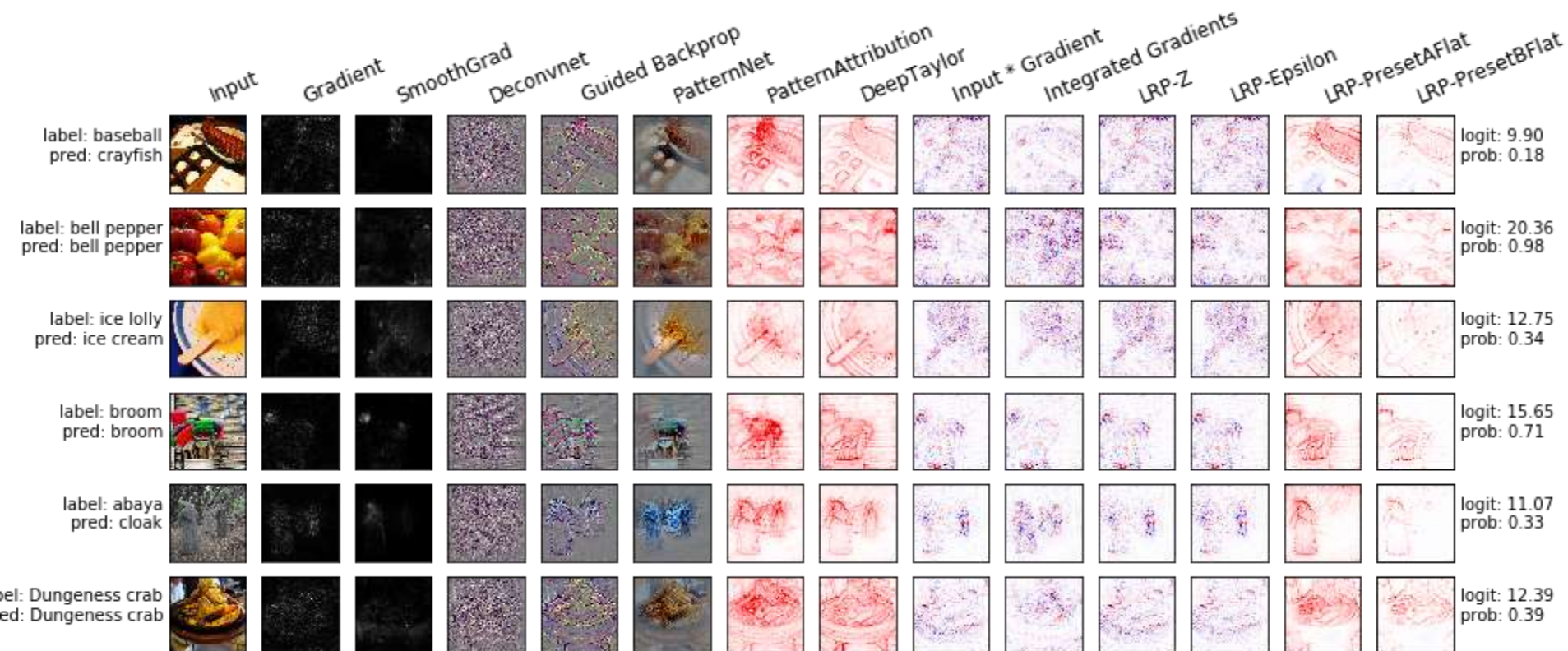


Figure from <https://github.com/albermax/innvestigate>

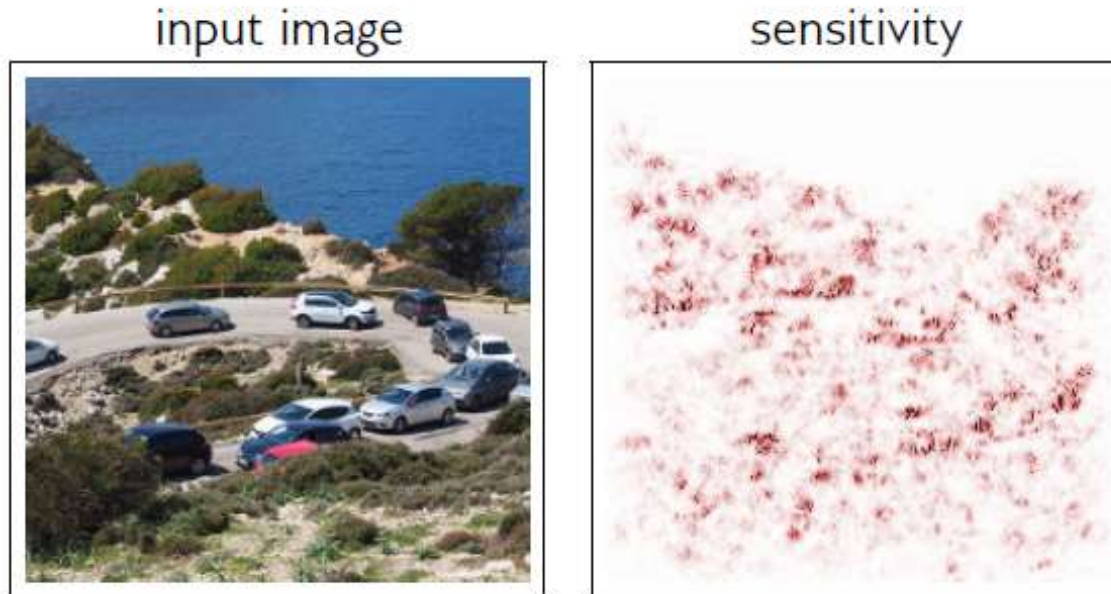
Explaining by Sensitivity Analysis

Given prediction function $f(x_1, x_2, \dots, x_d)$ on d dimensional input data $\mathbf{x} = (x_1, x_2, \dots, x_d)$,

Sensitivity analysis is the measure of local variation of the prediction function f along each input dimension

$$R_i = \left(\frac{\partial f}{\partial x_i} \Big|_{\mathbf{x}=\mathbf{x}} \right)^2$$

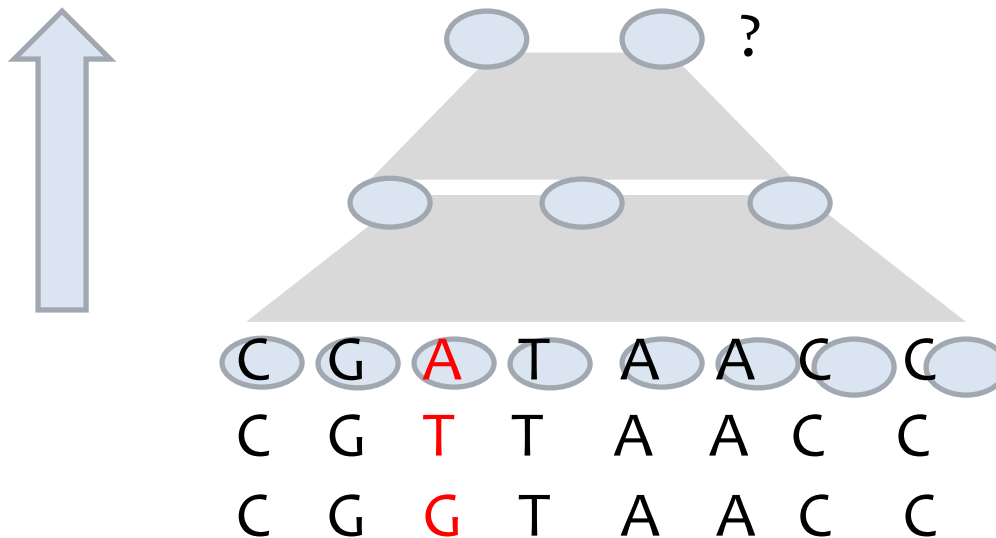
Sensitivity Analysis



- ❑ Easy to implement
 - Requires access to the **gradient** of the decision function
 - May not explain the prediction well

Perturbation Approaches

- ❑ Make perturbation to input and observe the difference in the output
- ❑ 😞 Every time you make a perturbation output needs to be recomputed



Meaningful Perturbation

The aim of saliency is to identify which regions of an image x are used by the black box to produce the output value $f(x)$ by “deleting” different regions R of x



“deletions”:



Class Activation Mapping (CAM)

- linear combination of a late layer's activations and class-specific weights

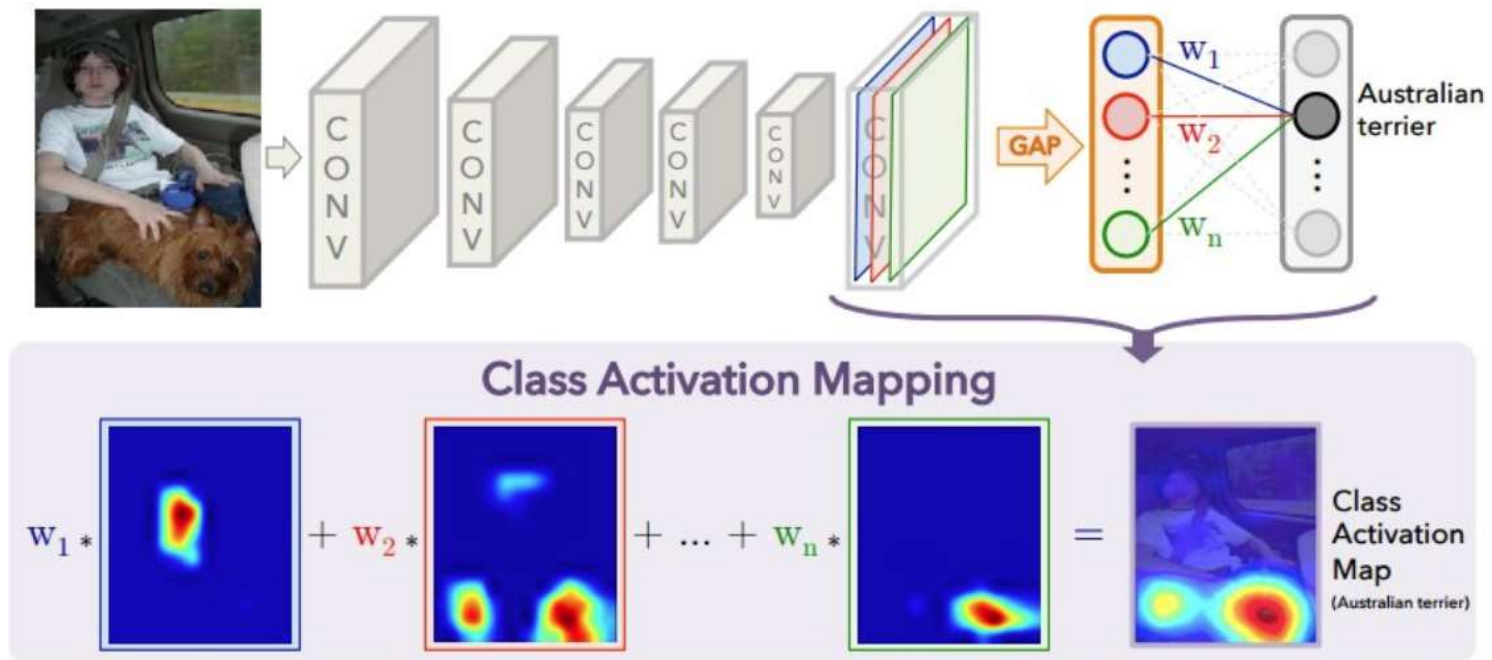


Figure from <http://cnnlocalization.csail.mit.edu/>

Gradient-Weighted CAM (Grad-CAM)

- Linear combination of a late layer's activations and class-specific gradients

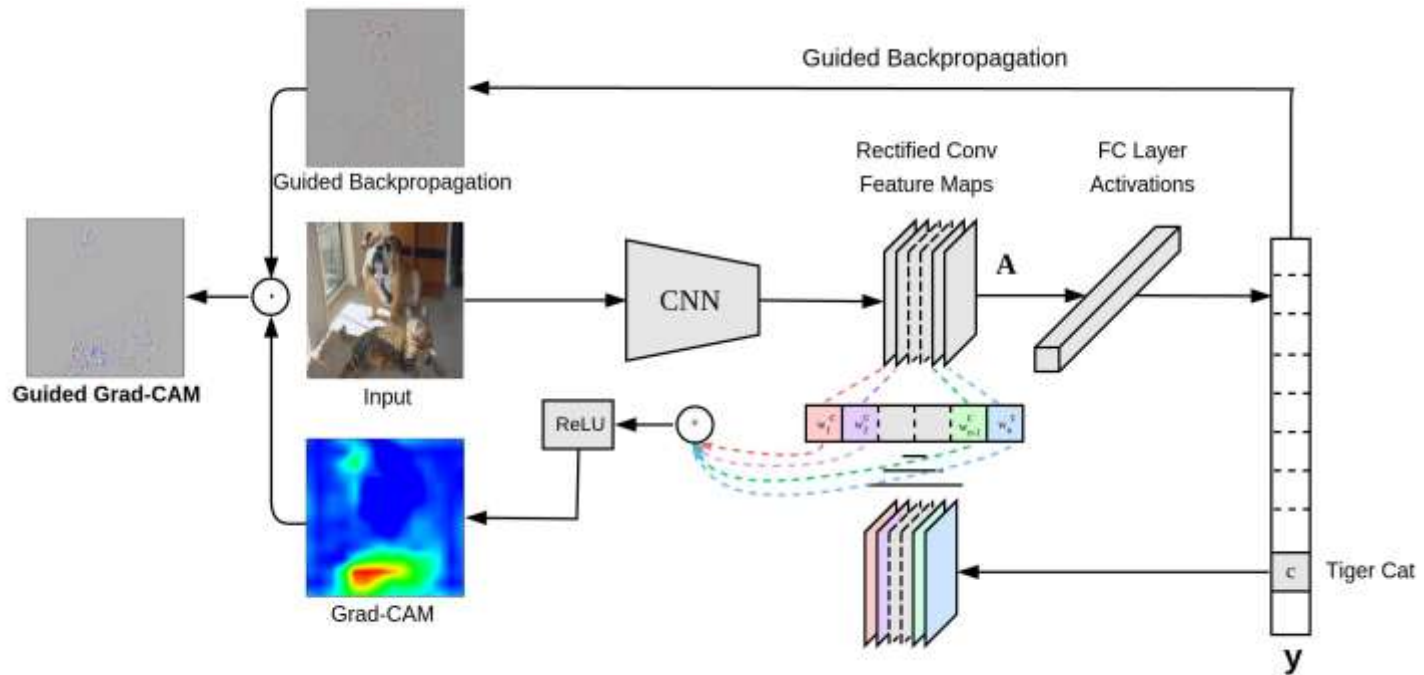
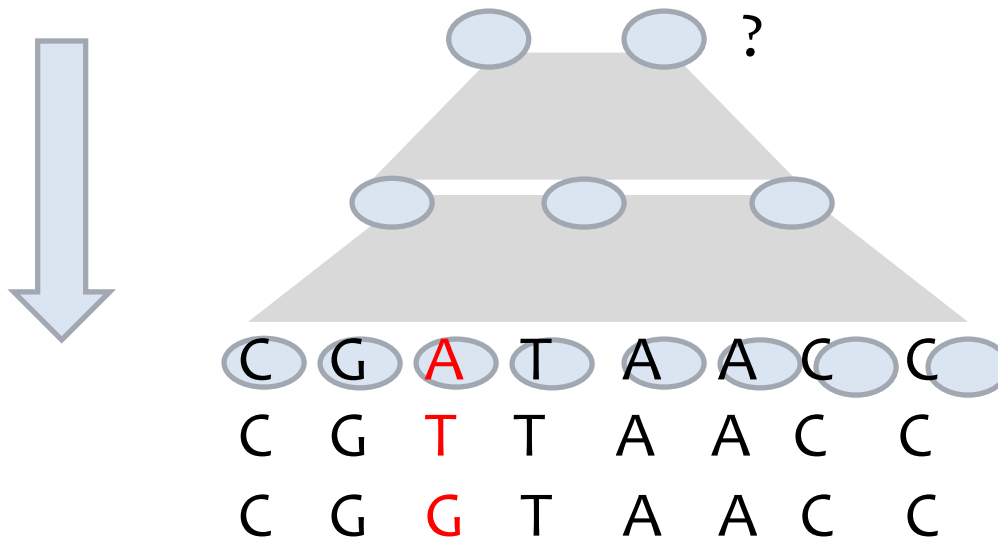


Figure from Selvaraju et al.

Backpropagation methods

- ❑ Sensitivity analysis
- ❑ Layer-wise relevance propagation (Deep Tylor)
- ❑ DeepLIFT



Explaining by Decomposing

Decomposition methods decompose prediction value $f(x)$ to **relevance scores** R_i such that

$$\sum_i R_i = f(x_1, \dots, x_d)$$

Decomposition **explains the function value** itself.

Sensitivity Analysis in Decomposition View

❑ Decomposition: $\sum_i R_i = f(x_1, \dots, x_d)$

❑ Sensitivity Analysis:

$$R_i = \left(\frac{\partial f}{\partial x_i} \Big|_{x=x} \right)^2$$

$$\sum_i R_i = \|\nabla_x f\|^2$$

- Sensitivity analysis **explains a variation** of the function.

Decomposition on Shallow Nets

- Taylor decomposition of function $f(x_1, \dots, x_d)$

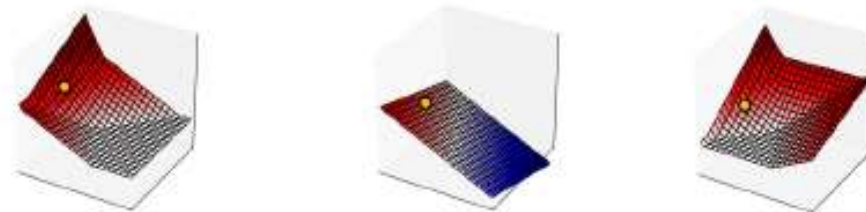
$$f(\mathbf{x}) = \underbrace{f(\tilde{\mathbf{x}})}_0 + \sum_{i=1}^d \underbrace{\frac{\partial f}{\partial x_i} \Big|_{\mathbf{x}=\tilde{\mathbf{x}}}}_{R_i} (x_i - \tilde{x}_i) + \underbrace{O(\mathbf{x}\mathbf{x}^T)}_0$$

- Can it be applied on Deep Learning?
 - Doesn't work well on DNN
 - Also subjected to gradient noise

Deep Taylor Decomposition

Taylor
decomposition
(TD)

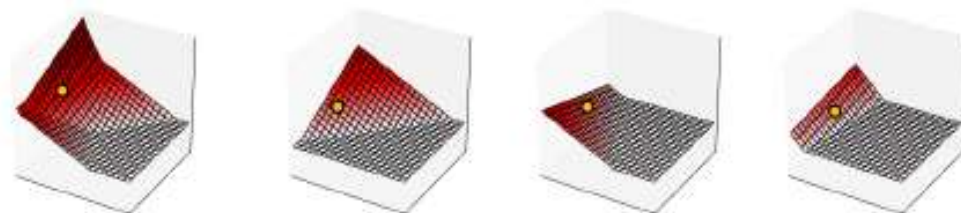
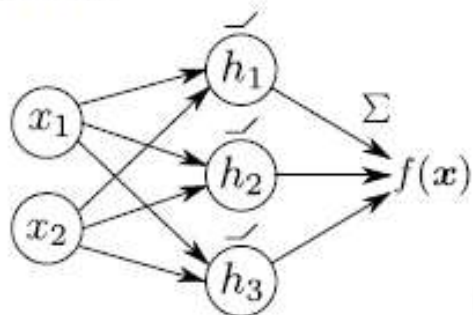
$$f(\mathbf{x}), \nabla f, \dots$$



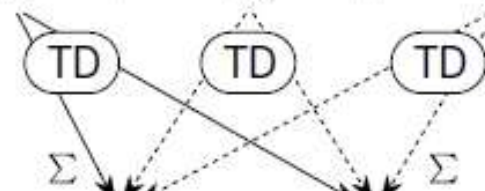
$$f(\mathbf{x}) = \nabla f|_{\mathbf{x}=\tilde{\mathbf{x}}}^T \cdot (\mathbf{x} - \tilde{\mathbf{x}}) + \varepsilon$$

$$f(\mathbf{x}) = R_1 + R_2 + \varepsilon$$

deep Taylor
decomposition
(DTD)

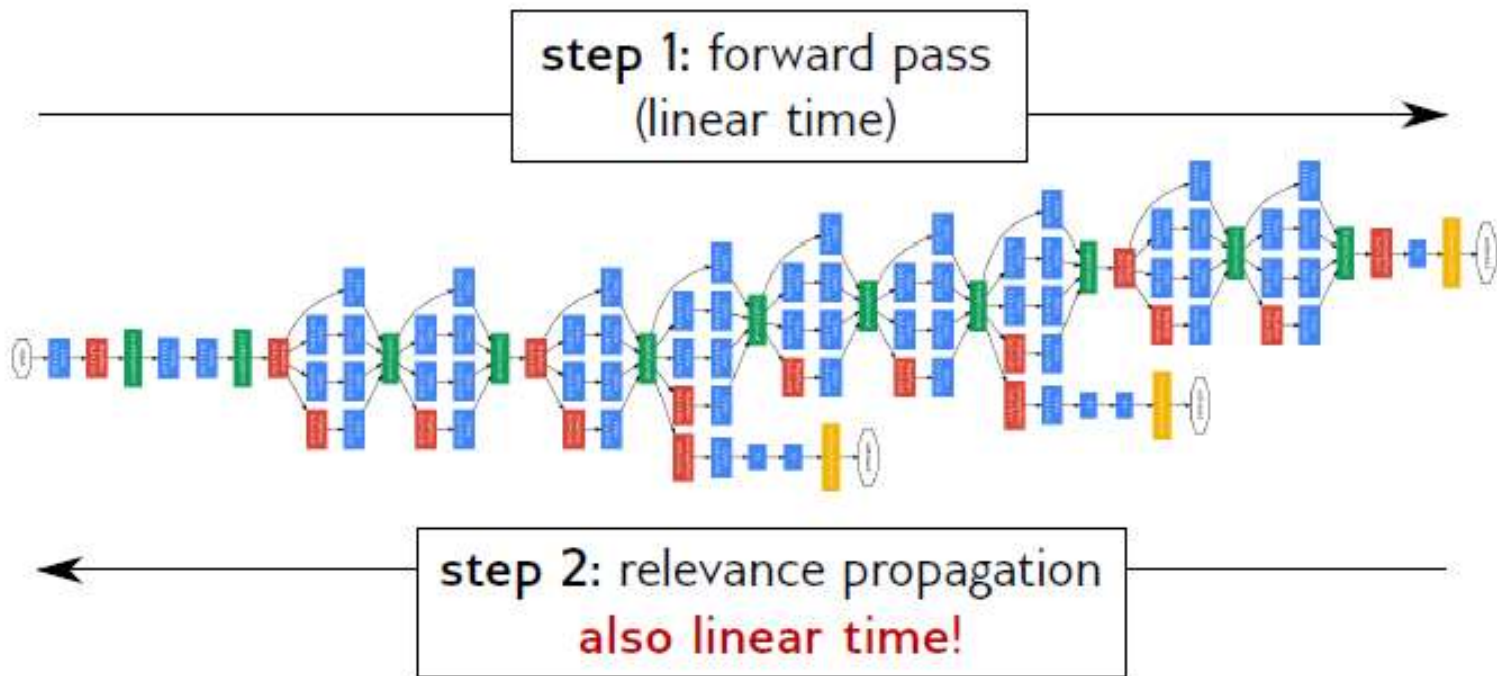


$$f(\mathbf{x}) = h_1 + h_2 + h_3$$



$$f(\mathbf{x}) = R_1 + R_2$$

Layer-Wise Relevance Propagation (LRP)



Propagation rule:

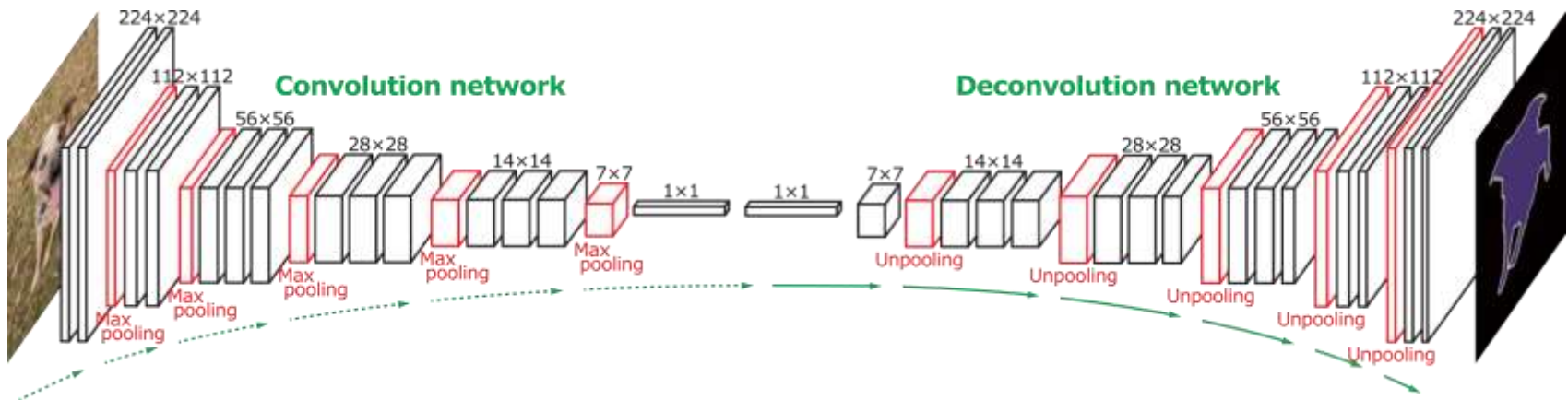
$$R_i = \sum_j q_{ij} R_j \quad \sum_j q_{ij} = 1$$

DeepLIFT

- ❑ DeepLIFT explains the difference in output from some 'reference' output in terms of the difference of the input from some 'reference' input.
- ❑ The 'reference' input represents some default or 'neutral' input that is chosen according to what is appropriate for the problem at hand
- ❑ **Activation difference** propagated down to input
- ❑ Capable to propagate relevance down even when the gradient is zero. (solves saturation problem)

DeConvNet

- ❑ Outputs **probability map** that indicate probability of each pixel belonging to one of the classes



- Convolution Network extract features
- Deconvolution Network generate probability map (same size as the input)

Figure from [Noh et al. ICCV'15]

Summary – What We Have Discussed

- ❑ Interpretable ML
- ❑ Agonistics methods
- ❑ Model-specific methods
- ❑ Interpretability in deep learning

Discussion – Current Limitations

- ❑ What we have not discussed
 - Interpretable recurrent neural nets
 - Interpretable reinforcement learning
 - Interpretable unsupervised learning models

Reference

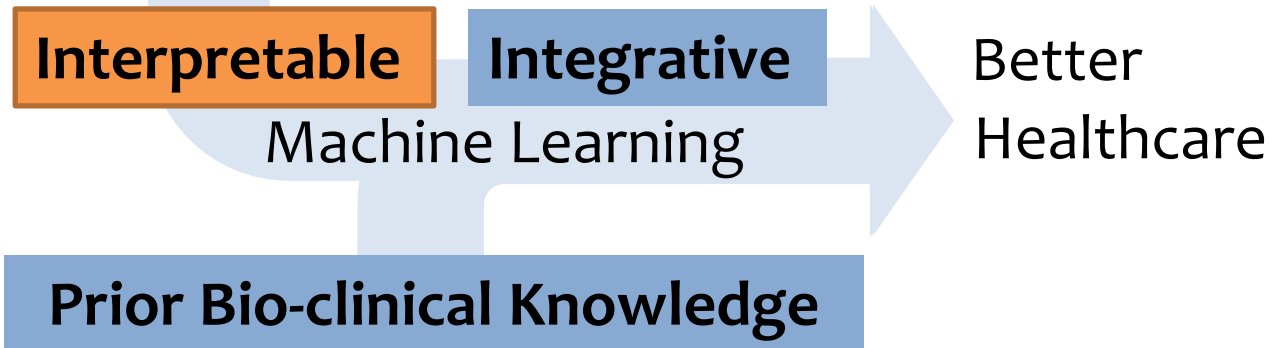
- ❑ G. Montavon, W. Samek, and K. Müller, “Methods for interpreting and understanding deep neural networks,” *Digit. Signal Process.*, vol. 73, pp. 1–15, 2018.
- ❑ W. Samek, G. Montavon & K.-R. Müller “Tutorial on Methods for Interpreting and Understanding Deep Neural Networks.” ICASSP 2017 Tutorial.
- ❑ David Baehrens, Timon Schroeter, Stefan Harmeling, Motoaki Kawanabe, Katja Hansen, and Klaus-Robert Müller. How to explain individual classification decisions. volume 11, pages 1803–1831, 2010.
- ❑ Wojciech Samek, Alexander Binder, Grégoire Montavon, Sebastian Lapuschkin, and Klaus Robert Muller. 2016. Evaluating the Visualization of What a Deep Neural Network Has Learned. *IEEE Transactions on Neural Networks and Learning Systems*: 1–13.
- ❑ Grégoire Montavon, Sebastian Lapuschkin, Alexander Binder, Wojciech Samek, and Klaus Robert Müller. 2017. Explaining nonlinear classification decisions with deep Taylor decomposition. *Pattern Recognition* 65, August 2016: 211–222.
- ❑ Sebastian Bach, Alexander Binder, Grégoire Montavon, Frederick Klauschen, Klaus-Robert Müller, and Wojciech Samek. On pixel-wise explanations for non-linear classifier decisions by layer-wise relevance propagation. volume 10, page e0130140, 2015.

Reference cont.

- ❑ Karen Simonyan, Andrea Vedaldi, and Andrew Zisserman. 2014. Deep Inside Convolutional Networks: Visualising Image Classification Models and Saliency Maps. In *Workshop at International Conference on Learning Representations*, 1–8.
- ❑ Korattikara A, Rathod V, Murphy K, Welling M. Bayesian Dark Knowledge. arXiv preprint arXiv:1506.04416. 2015;.
- ❑ Zachary C Lipton. 2016. The Mythos of Model Interpretability. *ICML Workshop on Human Interpretability in Machine Learning*.
- ❑ D. Erhan, Y. Bengio, A. Courville, and P. Vincent. Visualizing higher-layer features of a deep network. Technical Report 1341, University of Montreal, Jun 2009.
- ❑ M. D. Zeiler and R. Fergus. Visualizing and understanding convolutional networks. CoRR, abs/1311.2901v3, 2013.
- ❑ Q. Le, M. Ranzato, R. Monga, M. Devin, K. Chen, G. Corrado, J. Dean, and A. Ng. Building high-level features using large scale unsupervised learning. In *Proc. ICML*, 2012.
- ❑ Anh Nguyen, Alexey Dosovitskiy, Jason Yosinski, Thomas Brox, and Jeff Clune. 2016. Synthesizing the preferred inputs for neurons in neural networks via deep generator networks. In *29th Conference on Neural Information Processing Systems (NIPS 2016)*, 1–29.
- ❑ Avanti Shrikumar, Peyton Greenside, and Anshul Kundaje. 2017. Learning Important Features Through Propagating Activation Differences. In *CVPR*.

Thank you!

Omics Data + Clinical Data



<https://leesael.github.io/>