

Automated Exhaustive Test Case Generation for Safety-critical Software

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INTRODUCTION

As existing nuclear power plants (NPPs) are employing digital technologies in both safety-critical and safety-related systems, an issue of incorporating the software reliability to NPP probabilistic risk assessment (PRA) model revealed the importance of the reliability quantification of safety-critical software. In response, various quantitative software reliability methods (QSRMs) such as software reliability growth model (SRGM) [1], Bayesian belief network (BBN) model [2], and test-based method [3, 4] have been proposed and adopted in the nuclear field. However, the limitations of current state-of-the-art methods include: 1) the uncertainty in estimating model parameters, 2) a long testing time for each test case, and 3) and the limitation on demonstrating the test inputs match to the actual operation profile.

By its nature, the software is a logical matter and determines the function of hardware in the digital system. The space that digitalized inputs and internal variables construct is considered as the domain that the software may encounter during its operation, which may be very large but not infinite. For many safety-critical systems, the number of software variables is limited, and they have limited resolution. Therefore, if we can perform the testing over the whole space, the issues related to input selection and model parameter estimation can be resolved.

This paper proposes an automated exhaustive test case generation framework for NPP safety-critical software testing. From the viewpoint of NPP safety, the testing of NPP safety software needs to focus on the failure of its dedicated safety function when demand comes (i.e., failure-on-demand). As the software output is determined by the combinations of the states of software input and internal variables, the exhaustive test case generation for safety software can be considered as a problem of finding the solutions that satisfy its on-demand situation, i.e. Satisfiability Modulo Theories (SMT) problem [5]. The proposed framework formally translates the function block diagram (FBD) program into a semantically-equivalent SMT formula and generates exhaustive test cases by iteratively solving the translated SMT formula using SMT solver.

METHODS

Translation of FBD into SMT formula

FBD program is a network of function blocks executed sequentially according to their predefined execution order [6]. To generate exhaustive test cases for FBD program, we first formally define the FBDs based on the ideas discussed in previous studies [7] and translate FBD to semantically-equivalent SMT formula to be later solved by SMT solver given test requirement. Fig. 1 shows an overview of the translation algorithm in the flowchart form. The translation starts with generating SMT formulas for individual function blocks (FBs) used in the FBD program and continues for component FBD and system FBD.

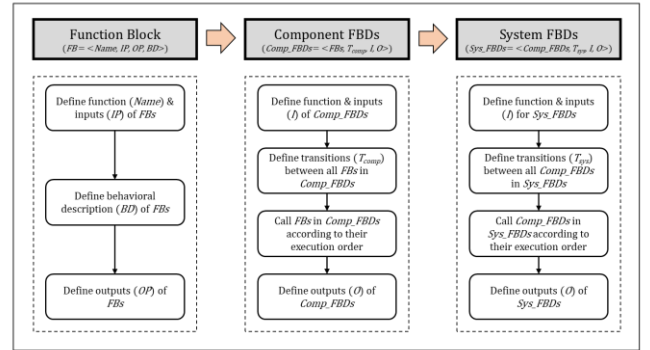


Fig. 1. An overview of FBD-to-SMT translation scheme.

Function Block Translation

A FB is the basic program organizing unit that has assigned input parameters and static variables [6]. A FB is defined as a tuple composed of a name (*Name*), input ports (*IP*), output ports (*OP*), and its behavior description (*BD*). Fig. 2 shows an example of how a FB can be translated into an equivalent SMT formula. First, the components of FB including its *Name*, *IP*, and *OP* are declared, and the value of the output variable is determined by its specific *BD* according to their types (e.g., arithmetic and logical, selection, comparison operation). Finally, a function definition ends with returning the outputs of FBs.

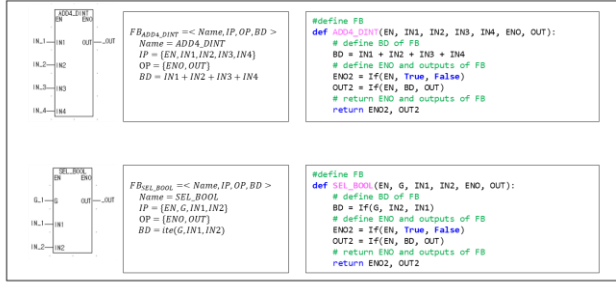


Fig. 2. FBD-to-SMT translation for function blocks.

Component FBD Translation

A component FBD (*Comp_FBD*) is a logical block that is composed of FBs according to their sequential execution orders. It is defined as a tuple consisting of a set of function blocks (*FBs*), a set of transitions (T_{comp}) between the function blocks, a set of input ports (*I*), and a set of output ports (*O*). Fig. 3 shows an example of translation for component FBDs composed of four FBs with three transition relations. First, the elements of component FBD, including the name of *Comp_FBD*, *I* and *O*, are defined. As the behavior of component FBD is defined as sequential calls of function blocks described in T_{comp} , the program flow is defined by calling *FBs* according to their execution order. Here, the temporary variables that store the value of output ports of FBs in *Comp_FBD* or the ladder connections at each rung are defined to model a set of transitions between FBs. The definition ends by returning its outputs.

System FBD Translation

The system FBD (*Sys_FBD*) is a set of component FBDs connected according to their sequential execution orders. It is defined as a tuple of component FBDs (*Comp_FBD*), a set of transition between component FBDs (T_{sys}), a set of input ports (*I*), and a set of output ports (*O*).

The translation rules for system FBDs are similar to those of component FBDs while it is composed of sequential function calls of component FBDs instead of FBs and uses temporary variables to model a set of transitions between *Comp_FBDs*. The output of component FBDs are used as inputs to other component FBDs according to the transitions (T_{sys}), and they are called in *Sys_FBD* according to their execution orders. In this study, the whole NPP safety software is considered as one system FBD, and the enables of system FBD (*EN* and *ENO*) are not defined in the translation since the programmable logic controller (PLC) operates a system FBD periodically with specific scan cycle.

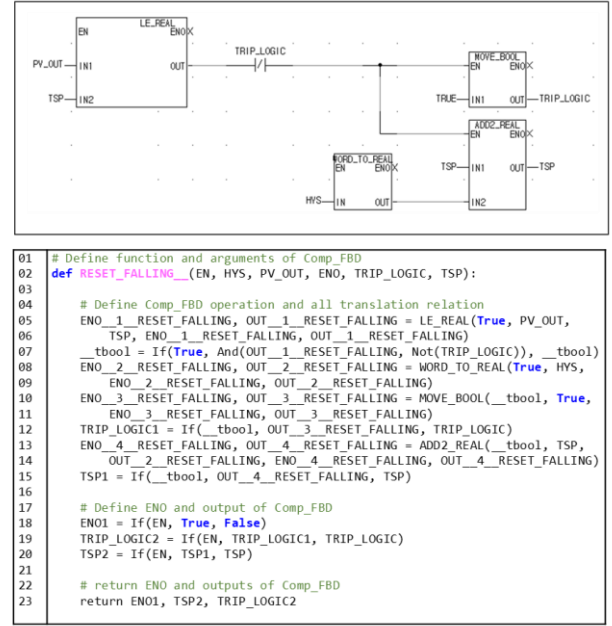


Fig. 3. FBD-to-SMT translation for component FBDs.

Exhaustive Test Case Generation for FBD Program

Given the SMT formulas translated from FBD program, a test case can be generated by finding the states of input and internal variables of the FBD program that satisfy the selected test requirement. In this study, an FBD exhaustive test case generation (*FBDET*) algorithm is developed which checks the satisfiability of the translated FBD program and retrieve the models for software input and internal variables given certain software output. Generating exhaustive test cases for FBD program consists of three steps: 1) defining the FBD program and variables under test, 2) defining the test requirements, and 3) retrieving the model for FBD variables that satisfies the test requirements. Fig. 4 shows an overview of the exhaustive test case generation scheme.

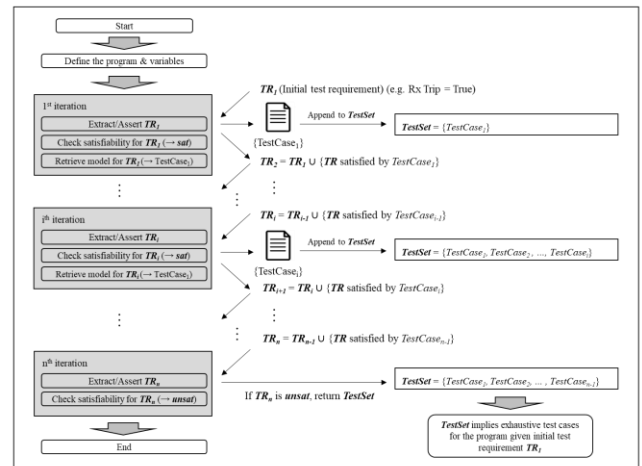


Fig. 4. Test case generation procedure for FBD program.

In the case study, the desired software output was set to be the PZR_PR_LO trip signal, and 35 variables among a total of 612 variables defined in BP software were identified as the input and internal variables that contribute to generating the PZR_PR_LO trip signal. The exhaustive test cases that represent the trip generation by the FBD program were generated for the target scenario that: 1) the software is running in normal operation, 2) there are no errors in BP hardware and heartbeat signal, 3) operators do not request trip bypass or trip set-point reset. Based on the available software specification documents [11], the possible states of program input and internal variable were identified and defined in the test module shown in Fig. 5-(d).

After the software variables are defined, the test module generates the test cases for the target scenario based on the *FBDet* algorithm. The initial test requirement was set to be the desired software output, which is the PZR_PR_LO trip signal generation ($QX0_3_2 = \text{True}$). Fig. 6 shows the generated exhaustive test cases from the *FBDet* execution. Each line at Fig. 6-(b) shows a single test case which describes the states of software input and internal variables that makes the software output to be true. In result, a total of 147,694,036 test cases were generated as exhaustive test cases for the target scenario.

An important characteristic of the proposed framework includes: 1) the number test sets for exhaustive testing of the safety-critical software can be quantitatively derived, 2) combining the proposed method with the software test-bed [12] can enable effective testing to demonstrate the completeness of the software in terms of its safety function.

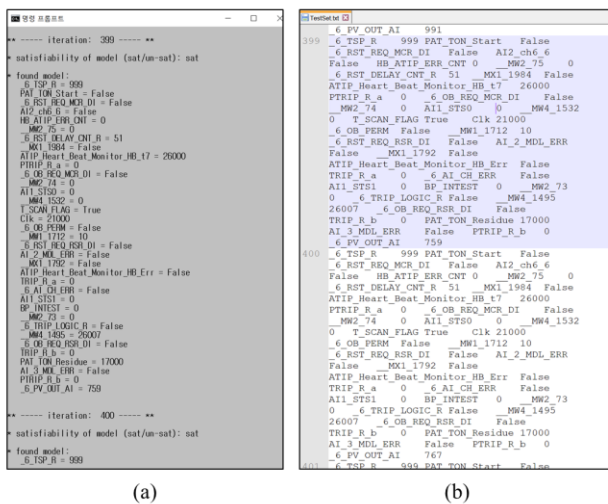


Fig. 6. Exhaustive test case generation for BP PZR_PR_LO trip logic: (a) Screenshot of the test module execution, (b) A part of generated exhaustive test cases for target scenario.

CONCLUSION

This paper proposed a novel automated exhaustive test case generation framework for the FBD programs. The proposed framework formally translates the FBD program to SMT formula and implements the *FBD_{DET}* algorithm developed for exhaustive test case generation. As an application of the proposed software test method, the exhaustive test cases for the PZR_PR_LO trip of KNICS IDiPS-RPS BP trip logic software were derived.

The contribution of the proposed framework are as follows: First, the translation rules from FBD to SMT formula is developed based on the FBD formal semantics and implemented to the FBD-to-SMT translator. Second, the proposed test case generation framework provides a method to generate the exhaustive test cases of NPP safety software that can prove that the software error-free for its

safety function. As a future work, we plan to develop a tool suite which supports and automates the entire process of proposed software test method from translating the FBD program of NPP safety software to test result generation.

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