

# CV / VLM

Unit 2: Introduction to Object  
Detection (OD)



# 2.1.1

## Overview of Object Detection

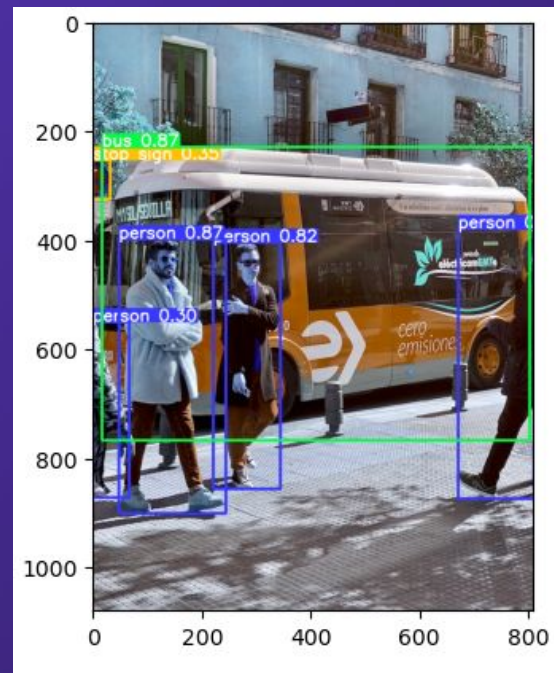
What is object detection?

# What is Object Detection?

Localizing and identifying objects within an image.

## Tasks:

- What **Classification:** Assigning a class label to the object (e.g. bus, person, dog).
- Where **Localization:** Pinpointing the bounding box (rectangular frame) around the detected object.
- Score **Confidence Score:** Indicating the model's certainty in the detection and classification.



# How Object Detection Works

## 1. Feature Extraction:

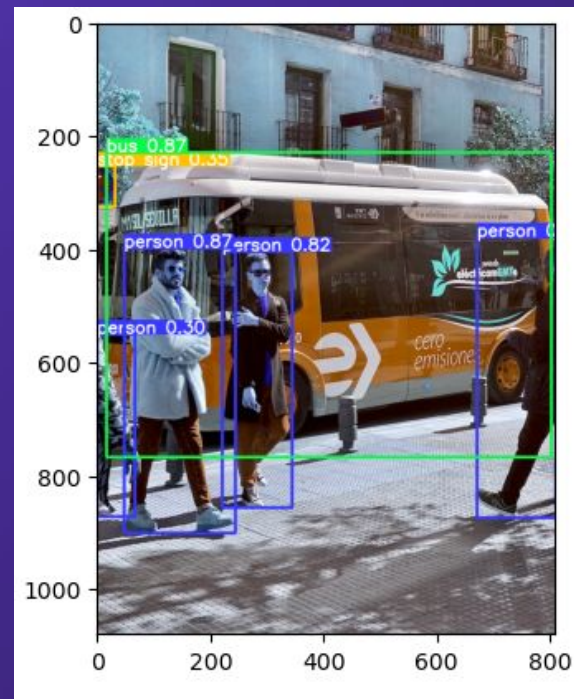
The model extracts relevant features from the image, like edges, shapes, and colors, often using convolutional neural networks (CNNs).

## 2. Bounding Box Prediction:

The bounding box model predicts bounding boxes for potential objects in the image.

## 3. Classification and Confidence Score:

The CNN model classifies the objects within the bounding boxes and assigns a confidence score for each detection.



# OD Algorithm Examples

There are many object detection algorithms available. We will discuss:

- Region-CNN (R-CNN)
- Single-Shot Detectors (SSD)
- You Only Look Once (YOLO)
- Vision Transformers (ViT)

Explored in  
Unit 6!

# Applications of OD

Object detection has a wide range of applications, including:

- **Self-driving cars:** Detecting pedestrians, vehicles, and traffic signs.
- **Video surveillance:** Tracking objects and monitoring activity.
- **Medical image analysis:** Detecting tumors and other abnormalities.
- **Robot navigation:** Identifying obstacles and objects in the environment.

