

BKM - zadaci na jarku

* $\sin^2 \theta \rightarrow \cos^2 \theta$? 4.

6 - bad se koristi formula za 1(4)?
- $\beta = v$??

(1.) $u(t) = \sin(4 \cdot 10^8 t) [V] \Rightarrow \omega = 10^8 \pi$

$v_p = 2 \cdot 10^8 \text{ m/s}$

$\beta \cdot x = \frac{\pi}{2}$

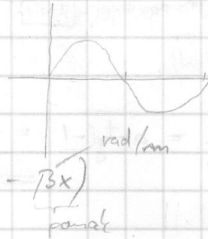
$x = \frac{\pi}{2\beta}$

$u(x) = u_0 \sin\left(\omega t - \frac{x}{v_p}\right) = u_0 \sin(\omega t - \beta x)$

$\beta = \frac{\omega}{v_p} \left[\frac{\text{rad/s}}{\text{m/s}} = \frac{\text{rad}}{\text{m}} \right]$

$\beta = \frac{10^8 \cdot \pi}{2 \cdot 10^8}$

$\beta \cdot x = \frac{\pi}{2} \Rightarrow x = \frac{\pi}{2\beta} = \frac{\pi}{2 \cdot 10^8 \cdot \pi} \cdot 2 \cdot 10^8 = 10^2 = 100 \text{ m}$



$\beta \cdot x = \frac{\pi}{2}$

$x = \frac{\pi}{2\beta}$

(2.) $f = 10^6 \text{ Hz} \Rightarrow \omega = 2\pi f$

$v_p = 200000 \text{ km/s} = 2 \cdot 10^8 \text{ m/s}$

$\alpha = 20 \text{ dB/km}$

$P = 2 \quad (\beta \cdot L = 2\pi) \Rightarrow L = \frac{2\pi}{\beta} = \frac{2\pi}{\omega} \cdot v_p = \frac{2\pi}{2\pi f} \cdot v_p = \frac{v_p}{f} = \frac{2 \cdot 10^8}{10^6} = 200$

$P_2 = ? / 10 = ?$

$L = 0.2 \text{ km}$

$\beta = \frac{\omega}{v_p}$

$P_2 = P_1 - A = P_1 - \alpha \cdot L$

$A = \alpha \cdot L = 2 \cdot 0.2 = 0.4 \text{ dB}$

(3.) f_0

$Z_s = 100 + j100 [\Omega] \Rightarrow Z_s^* = Z_s^* = 100 - j100$

$R_L = 150 [\Omega] \quad Z_L = R_L + jX_L$

učet za ak nagu $Z_s = Z_L$?

$P = \frac{Z_L - Z_s}{Z + Z_s} = \frac{150 - 100 - j100}{150 + 100 + j100} = \frac{50 + j100}{250 + j100} = \frac{50 \cdot 250 + 300 \cdot 100 - 100^2}{250^2 + 100^2}$

$= \frac{2500 + 30000j}{72500}$

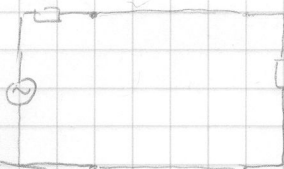
$= \frac{25}{725} + j\frac{300}{725}$

$|P| = \sqrt{\left(\frac{25}{725}\right)^2 + \left(\frac{300}{725}\right)^2} = 0.415229$

4.

$$Z_0 = 120 - j120$$

$$Z_{uk} = ?$$



$$Z_2 = 0 \rightarrow Z_{uk} = Z_0$$

$$Z_{uk} = Z_0 \quad \text{if } H(f) = 1$$

$$\angle(Z_{uk}) = \arctan \frac{\operatorname{Im} Z_{uk}}{\operatorname{Re} Z_{uk}} = \arctan(-1) = -\frac{\pi}{2}$$



$$x + jy \quad \arctan \frac{y}{x} = 0$$

5.

$$u(t) = \sin(\pi \cdot 10^5 t)$$

$$\omega = 10^5 \text{ rad/s}$$

$$v_p = 2 \cdot 10^8 \text{ m/s}$$

$$\beta = \frac{\omega}{v_p} = \frac{10^5}{2 \cdot 10^8} = \frac{1}{2} \cdot 10^{-3} \text{ rad/m}$$

$$= \frac{1}{2} \text{ rad/m}$$

6.

$$f = 2 \text{ km}$$

$$f > 10 \text{ kHz} \rightarrow Z_s = Z_L = Z_0$$

$$\rightarrow \text{Porter ideala zalkydena } Z_s = Z_0 \rightarrow \text{maximalna refleksija} \rightarrow V(x) = V_0 e^{+j\beta x} + \frac{V_0 e^{-j\beta x}}{0}$$

$$f = 100 \text{ kHz}$$

$$A = 20 \text{ dB}$$

$$\rightarrow \alpha = 10 \text{ dB/km} \approx 1.15 \text{ Np/km}$$

$$1 \text{ dB} = \frac{10}{20} \text{ [Np]} = \frac{1}{2} \log_{10} e \approx 0.115129 \text{ [Np]}$$

$$\omega = 2\pi f = 200 \cdot 10^3 \pi$$

$$\beta = \frac{\omega}{v_p}$$

$$\beta x = 2\pi$$

$$\beta = 0 \text{ ?}$$

$$\beta = \alpha + j\beta$$

$$\Rightarrow \beta = \alpha = 1.15 \text{ Np/km}$$

$$\text{prijemna } H(f) = \frac{V(d)}{V(0)} = \frac{1}{\cos(\beta d) + \frac{Z_0}{Z_0} \sin(\beta d)} = \frac{1}{\cos(1.15 \cdot 2) + \frac{Z_0}{Z_0} \sin(1.15 \cdot 2)} = 0.1$$

$$\text{amplitudna karakteristika } |H(f)| \Rightarrow |H(f)| = \sqrt{\operatorname{Re}\{H(f)\}^2 + \operatorname{Im}\{H(f)\}^2} = 0.1$$

7.

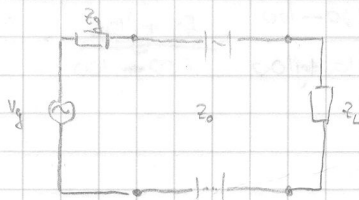
$$f_0 > 10 \text{ kHz}$$

$$\text{protok } Z_g = R + jX [\Omega]$$

$$Z_L = Z_g = Z_0 \quad \text{vred na max snagu}$$

$$R = 10X \Rightarrow X = \frac{10}{10}$$

$$P_L = ?$$



$$P_L = \frac{Z_L - Z_0}{Z_L + Z_0} = \frac{10X + jX - 10X + jX}{10X + jX + 10X - jX} = \frac{jX}{20X} = \frac{j}{20} = \frac{j}{10} = \frac{10j}{100} = 0.1j$$

8.

$$L = 20 \text{ dB}$$

$$L = 10 \log \frac{P_1}{P_2}$$

$$H(f) = \frac{U_2}{U_1}$$

$$= \sqrt{\frac{P_2}{P_1}}$$

$$= 0.1$$

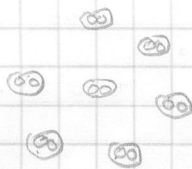
$$|H(f)| = \sqrt{0.1^2} = 0.1$$

$$P = \frac{1}{2} \left| \frac{U}{Z_0} \right|^2 \cdot R_L = \frac{1}{2} \left| \frac{U}{Z_0} \right|^2 \cdot R_L$$

$$P = \frac{U^2}{R} = U \cdot \sqrt{PR}$$

$$\frac{U}{\sqrt{2}} = \sqrt{\frac{P_1}{P_2}} = 10 = \sqrt{\frac{P_2}{P_1}} = 0.1$$

8.



10

$$A_0 = 10 \log \frac{P_{AP}}{P_{EP}}$$

$$|A_0| = 70 \text{ dB}$$

$$\text{substitue} \rightarrow < 0 \rightarrow A_0 = -70 \text{ dB}$$

$$10^{A_0} = \left(\frac{P_{AP}}{P_{EP}} \right)^{10} \rightarrow 10^{-7} = \frac{P_{AP}}{P_{EP}} = 10^{-7}$$

$$\text{NEXT} = 10 \log (6 \cdot 10^7) = \underline{\underline{-62.218 \text{ dB}}}$$

9.

$$f = 10^6 \text{ Hz}$$

$$d \rightarrow \infty$$

$$\lambda = 200 \text{ m}$$

$$v_p = ?$$

$$u(t) = \sin(\omega t + \frac{x}{v_p}) = \sin(\omega t - \beta x)$$

$$v_p = \frac{\omega}{\beta} = \frac{2\pi f \cdot 200}{2\pi}$$

$$x \cdot \beta = 2\pi$$

$$\beta = \frac{2\pi}{x} = \frac{2\pi}{200} = \frac{1}{100}$$

$$v_p = \frac{2 \cdot \omega}{2\pi} = \frac{200 \cdot 2\pi \cdot 10^6}{2\pi} = \underline{\underline{2 \cdot 10^8 \text{ m/s}}}$$

10.

$$v_s(t) = E \sin(\omega t)$$

$$d \rightarrow \infty$$

$$f_0 = 1 \text{ kHz} \rightarrow v_s(f_0) = 1 \text{ V}; \quad Z_s(f_0) = 100 + j100 [-2]; \quad \text{max. power: } Z_s = Z_L = \bar{Z}_0$$

$$= U_{\text{max}} = \bar{Z}_0 \cdot U_{\text{effekt}}$$

$$\bar{Z}_0 = 100 - j100$$

$$Z_L = \bar{Z}_0$$

$$P_s = ?$$

$$P(f) = \frac{1}{2} \text{Re}\{U \cdot I\} = \frac{1}{2} |I|^2 \cdot R_L = \frac{1}{2} \left| \frac{U}{Z_L} \right|^2 \cdot R_L = \frac{1}{2} \left| \frac{1/\sqrt{2}}{100 - j100} \right|^2 \cdot 100 = \frac{1}{2} \left(\frac{1/\sqrt{2}}{\sqrt{100^2 + 100^2}} \right)^2 \cdot 100$$

$$= 0.00125$$

11.

$$\text{Hals. Power} \rightarrow Z_L = Z_S = \bar{Z}_0$$

$$\bar{Z}_0 = 100 + j100 [-2]$$

$$P = \frac{Z_L - Z_0}{Z_L + Z_0} = \frac{100 + j100 - 100 + j100}{100 + j100 + 100 - j100} = \frac{j200}{200} = j$$

$$R_L = 10 \log_{10} \left(\frac{1}{|P|^2} \right) = 10 \log_{10} \frac{1}{1} = \underline{\underline{0 \text{ dB}}}$$

12.

$$l = 100 \text{ m} = 0.1 \text{ km}$$

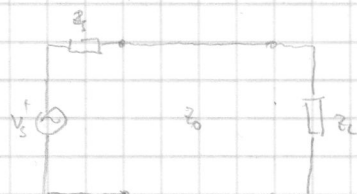
$$v_s(t) = 0.1 \sin(2\pi \cdot 10^3 t) \text{ [V]}$$

$$f = 10^3 \text{ Hz}$$

$$A_{\text{max}} = -45 \text{ dB}; \quad \text{ACR} = 50 \text{ dB}$$

$$\alpha = ?$$

$$Z_s = Z_L = \bar{Z}_0$$



$$A_{\text{max}} = 10 \log_{10} \left(\frac{P_1}{P_2} \right) \Rightarrow \frac{P_1}{P_2} = 10^{A_{\text{max}}/10}$$

$$\text{ACR} = 10 \log_{10} \frac{P_A}{P_i/P_2} \Rightarrow P_A = \frac{P_i}{P_2} \cdot 10^{A_{\text{CR}}/10}$$

$$P_A = 10^{A_{\text{max}}/10} \cdot 10^{A_{\text{CR}}/10}$$

$$P_A = 10^{-4.5} \cdot 10^5 = 10^{0.5}$$

$$A = \alpha \cdot l \Rightarrow A = 10 \log_{10} P_A = 10 \log_{10} 10^{0.5} = \underline{\underline{-5 \text{ dB}}}$$

$$\alpha = \frac{|A|}{l} = \frac{5}{0.1} = \underline{\underline{50 \text{ dB/km}}}$$

13. $10 \text{ Np} = ? \text{ dB}$

$$1 \text{ dB} = \frac{\ln 10}{20} \text{ Np} \Rightarrow 1 \text{ Np} = \frac{20}{\ln 10} \text{ dB} \cdot 10$$

$$10 \text{ Np} = \underline{\underline{86.86 \text{ dB}}}$$

14. $v_p = 2 \cdot 10^5 \text{ km/s} = 2 \cdot 10^8 \text{ m/s}$

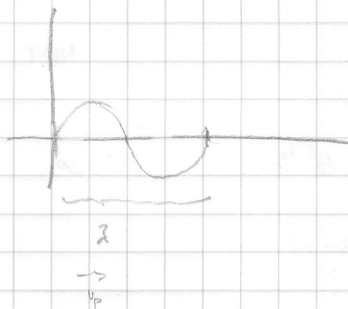
$$u = 5 \sin(10^6 t)$$

$$\Delta \varphi = ?$$

$$P = 200 \text{ mW}$$

$$\omega = 2\pi f \Rightarrow \frac{1}{f} = \frac{2\pi}{\omega} = \frac{2\pi}{10^6} \text{ s} = T$$

$$\lambda = \frac{2\pi}{\omega} \cdot v_p$$



$$v_p = \frac{\omega}{k}$$

$$v = \frac{\lambda}{T}$$

$$t_{\text{res}} = \frac{s}{v} = \frac{200}{2 \cdot 10^8} = 10^{-6} \text{ s}$$

$$\beta x = \frac{\omega}{v_p} \cdot x = \frac{10^6}{2 \cdot 10^8} \cdot 200 = \frac{10^6}{2 \cdot 10^8} \cdot 2 \cdot 10^2 = 1 \text{ rad}$$

$$\Delta u = ?$$

$$\Delta u = u(t_{\text{res}}) - u(0) = 5 (\sin(10^6 \cdot 10^{-6}) - \sin(0)) = 5 \cdot (\sin(1) - \sin(0))$$

$$\rightarrow \frac{\sin 1}{\sin 0}$$

15. $z_0(f)$

$$f_1; \quad z_0(f) = 10x + jX$$

$$z_1(f) = z_0(f_1)$$

$$z_2(f_1) = z_0(f_1)$$

$$RL = ?$$

$$RL = 10 \log \left(\frac{1}{|1 + \rho|^2} \right)$$

$$\rho = \frac{z_1 - z_0}{z_1 + z_0} = \frac{10x - jX - 10x - jX}{10x - jX + 10x + jX} = \frac{-2jX}{20x} = -\frac{j}{10}$$

$$RL = 10 \log \left(\frac{1}{1 + \frac{1}{100}} \right) = 10 \log 100 = \underline{\underline{20 \text{ dB}}}$$

16. $z_0(f_1) =$

$$z_1(f_1) = z_0(f_1)$$

$$z_2(f_1) = z_0(f_1)$$

$$\alpha_{f_1} = 5 \text{ dB/km}$$

$$A = 50 \text{ dB}$$

$$RL = \alpha \cdot l \Rightarrow l = \frac{A}{\alpha} = \underline{\underline{10 \text{ km}}}$$

17.

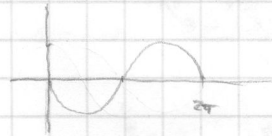
$$d \rightarrow \infty$$

$$f = 1000 \text{ Hz}$$

$$t = 0 \rightarrow \pi = \varphi = \beta \cdot x \quad u(t) = A \sin(\omega t + \varphi)$$

$$u(0) = A \sin(\pi)$$

$$\beta = 0.01 \pi \text{ rad/m}$$



$$\beta \cdot x = 2\pi$$

$$0.01\pi \cdot x = 2\pi$$

$$x = 2 \cdot 100 = 200 \text{ m}$$

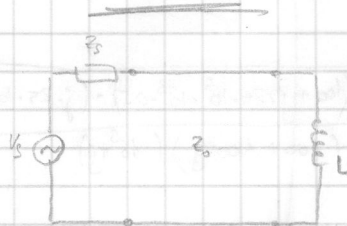
18.

$$f_0 = ? \quad d \rightarrow \infty$$

$$Z_L(f_0) = 100 \Omega$$

$$L = 1.5 \cdot 10^{-3} \text{ H}; \quad Z_L = j\omega L$$

$$\omega = 2\pi f$$



$$V_0^+ = 2V_0^-$$

$$V_0(f) = Z_L \cdot j\omega L$$

$$f_L = \frac{V_0}{2V_0} = \frac{Z_L \cdot Z_0}{Z_L + Z_0}$$

$$Z_L + Z_0 = 2(Z_L - Z_0)$$

$$j\omega L + 100 \Omega = 2j\omega L - 200 \Omega$$

$$+300 \Omega = j\omega L$$

$$\omega = \frac{300 \Omega}{L}$$

$$f = \frac{300 \Omega}{2\pi L} = 100000 \text{ Hz}$$

$$= 100 \text{ kHz}$$

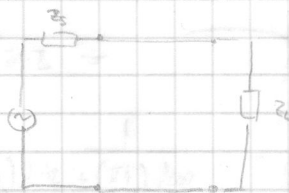
19.

$$E = 10 \sin(2\pi f_0 t)$$

$$Z_L(f_0) = Z_L(f_0) = Z_0(f) = 100 - j2$$

$$d = 4 \text{ km}$$

$$\alpha = 5 \text{ dB/km}$$



$$L = ?$$

$$L = d \cdot \alpha = 20 \text{ dB}$$

20.

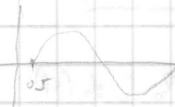
$$u(t) = U \sin(10^6 t + 0.5) \rightarrow \beta \cdot x = 2\pi$$

$$x = 1 \text{ km} = 1000 \text{ m}$$

$$V_0 = ?$$

$$\beta = \frac{2\pi}{1000}$$

$$\beta = \frac{\omega}{v} \rightarrow v = \frac{\omega}{\beta} = \frac{\omega}{2\pi} \cdot 1000 = \frac{10^8}{2\pi} = 159.155 \cdot 10^6 \text{ m/s}$$



21.

See graph

$$u_1(t) = 10 \sin(2\pi \cdot 10^6 t) \text{ [V]}$$

$$Z_1 = Z_2 = Z_0 = 100 - j2$$

$$L = 10^{-3} \text{ H/km}$$

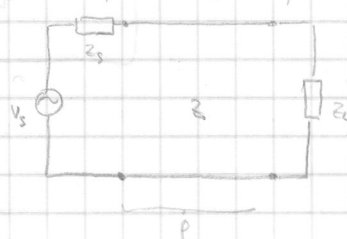
$$C = 10^{-9} \text{ F/km}$$

$$u_L(t) = ?$$

$$l = 0.5 \text{ km}$$

$$I_L = \frac{u}{Z_L + Z_0} = \frac{10}{200} = 0.05$$

$$u = I_L \cdot Z_L = 0.05 \cdot 100 = 5$$



$$f(f) = \frac{u_L}{u_1}$$

$$H(f) = \frac{1}{\cosh(\gamma l)}$$

$$\cosh(0) = 1$$

$$\beta = \sqrt{RZ + j\omega LC} \Rightarrow \beta = \omega \sqrt{LC}$$

$$(\beta \cdot x) = 2\pi \cdot 10^6 \cdot \sqrt{LC} \cdot 0.5 = \pi \text{ rad/km}$$

$$u(t) = 5 \sin(2\pi \cdot 10^6 t + \pi) = -5 \sin(2\pi \cdot 10^6 t)$$

$$22. \quad \begin{aligned} Z_0 &= 100j \, (\Omega) \\ Z_L &= \overline{Z_0} \\ Z_S &= Z_0 \end{aligned}$$

$$100 (\sin + j \cos)$$

$$u_L(t) = 10 \sin(25 \cdot 10^3 t)$$

$$I_L = ? = \frac{u_L}{Z_L}$$

$$\begin{aligned} &= \frac{10 \sin(25 \cdot 10^3 t)}{-j100} = \frac{10 \sin(25 \cdot 10^3 t + 0)}{100 \angle -90^\circ} = 0.1 \sin(25 \cdot 10^3 t + 0 - (-\frac{\pi}{2})) \\ &= 0.1 \sin(25 \cdot 10^3 t + \frac{\pi}{2}) \\ &= 0.1 \cos(25 \cdot 10^3 t) \end{aligned}$$

U

$$23. \quad u_S = 10 \sin(25 \cdot 10^3 t) \, [V]$$

$$Z_0 = 100 - j2$$

$$R = 100 - j2$$

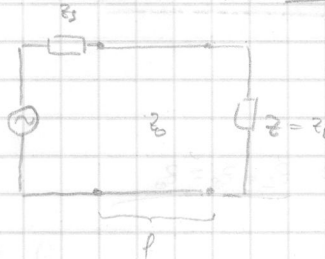
$$Z_0 = 100 - j2$$

$$\alpha = 1 \text{ dB/km}$$

$$l = 2 \text{ km}$$

$$K = ?$$

$$K = 2 \cdot l = 2 \text{ dB}$$



$$24. \quad P_m(f) = k_b \cdot f^{1.5}$$

$$\begin{aligned} \text{dA} &= |10 \log P_1 - 10 \log P_2| = |10 [\log(k_b f^{1.5}) - \log(k_b (2f)^{1.5})]| \\ &= |10 \log \frac{k_b f^{1.5}}{k_b 2^{1.5} f^{1.5}}| = |10 \log 2^{-1.5}| = |-15 \log 2| = 15 \log 2 = 4.5154 \end{aligned}$$

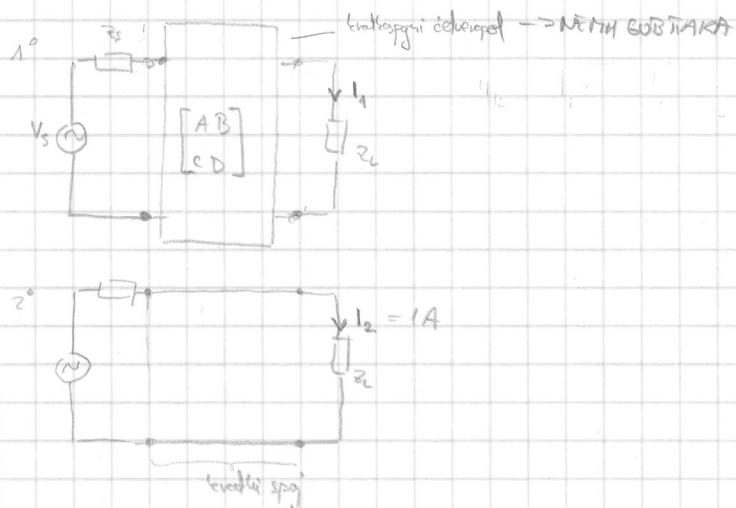
$$25. \quad u(t) = 2 \sin(\omega t) \, [V]$$

$$Z_S = Z_L = 1 - j2$$

26.

$$I_1 = I_2$$

$$u_2 = I_2 \cdot [Z_S + Z_L] = 2V$$



$$\begin{bmatrix} V_1 \\ V_2 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} I_1 \\ I_2 \end{bmatrix} \Rightarrow$$

jedinična
matrica

26.

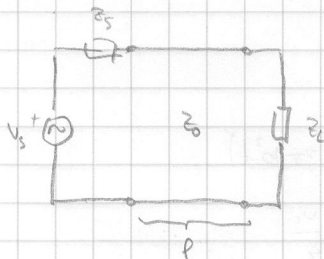
Antje bei gebildet

$$R' = 0 \text{ } \Omega/\text{km}$$

$$G' = 0$$

$$X = 0$$

$$l > 0$$



$$u(t) = 2 \sin(100t)$$

$$Z_s =$$

$$Z_L =$$

$$Z_0 = \sqrt{\frac{L'}{C'}} =$$

$$\beta^2(\omega) = \omega^2 L' C' \rightarrow \underline{\beta = \omega \sqrt{LC}} = 100 \sqrt{\quad} = \underline{0.01}$$

$$L' = 10^{-3} \text{ H/km}$$

$$C' = 10^{-5} \text{ F/km}$$

$$P_L = P_S = 0 = \frac{Z_L Z_0}{Z_L + Z_0} \Rightarrow \underline{Z_L = Z_S = Z_0}$$

a) $u_L(t) = ?$

b) $I = ?$

$$I = \frac{u_s}{Z + Z_s} = \frac{2}{2\sqrt{\frac{L}{C}}} = \sqrt{\frac{C}{L}}$$

$$u_L = I \cdot Z_L = \sqrt{\frac{C}{L}} \cdot \sqrt{\frac{L}{C}} = \underline{1 \text{ V}}$$

$$u_L = 1 \sin(100t)$$

$$\beta x = 24\pi$$

$$x = \frac{24\pi}{\beta} = \underline{\underline{24\pi \cdot 100}}$$