torch.Tensor.size

$$\frac{\sigma \vdash E \Rightarrow e, c}{\sigma \vdash E.\mathtt{size}() \Rightarrow shapeToTuple(e), c}$$

$$\begin{split} \sigma &\vdash E \Rightarrow e, c \\ k &= \mathtt{rank}(e) \\ \frac{c' = \{(k \geq 1) \land (0 \leq n < k)\}}{\sigma \vdash E.\mathtt{size}(n) \Rightarrow e[n+1], c \cup c'} \end{split}$$

torch.tensor

$$\frac{\sigma \vdash E \Rightarrow e, c}{\sigma \vdash \mathtt{tensor}(E) \Rightarrow e, c}$$

torch.Tensor.shape

$$\frac{\sigma \vdash E \Rightarrow e, c}{\sigma \vdash E.\mathtt{shape} \Rightarrow shapeToTuple(e), c}$$

torch.range

$$\begin{aligned} d \neq 0 \\ & (e-s)/d > 0 \\ & \overline{\sigma \vdash \mathtt{range}(s,e,d) \Rightarrow (1 + \lfloor (e-s)/d \rfloor), \emptyset} \end{aligned}$$

Default: s = 0, d = 1

torch.Tensor.item

$$\begin{split} \sigma \vdash E &\Rightarrow e, c \\ k &= \mathtt{rank}(e) \\ c' &= \{(k=1) \land (e[1]=1)\} \\ \hline \sigma \vdash E.\mathtt{item}() &\Rightarrow (), c \cup c' \end{split}$$

torch.split

$$\begin{split} \sigma &\vdash E \Rightarrow e, c \\ k &= \mathtt{rank}(e) \\ e_1 &= (n)@e[2:k] \\ e_2 &= (n)@e[2:k] \\ & \cdots \\ e_{l-1} &= (n)@e[2:k] \\ e_l &= (n')@e[2:k] \quad \text{where } e[1] = n(l-1) + n', \ 0 < n' \leq n \\ c' &= \{(k \geq 1)\} \\ \hline \sigma &\vdash \mathtt{split}(E, n) \Rightarrow (e_1, e_2, \dots, e_l), c \cup c' \end{split}$$

l-원소 tuple 형태로 반환

$$\begin{split} \sigma &\vdash E \Rightarrow e, c \\ k &= \mathtt{rank}(e) \\ e_1 &= (n_1)@e[2:k] \\ e_2 &= (n_2)@e[2:k] \\ & \cdots \\ e_l &= (n_l)@e[2:k] \\ & c' &= \{(k \geq 1) \wedge (e[1] = n_1 + n_2 + \cdots + n_l)\} \\ \hline \sigma &\vdash \mathtt{split}(E, [n_1, n_2, \dots, n_l]) \Rightarrow (e_1, e_2, \dots, e_l), c \cup c' \end{split}$$

l-원소 tuple 형태로 반환

$$\begin{split} \sigma &\vdash E \Rightarrow e, c \\ k &= \mathtt{rank}(e) \\ e_1 &= e[1:x]@(n)@e[x+2:k] \\ e_2 &= e[1:x]@(n)@e[x+2:k] \\ & \dots \\ e_{l-1} &= e[1:x]@(n)@e[x+2:k] \\ e_l &= e[1:x]@(n')@e[x+2:k] \quad \text{where } e[1] = n(l-1) + n', \ 0 < n' \le n \\ c' &= \{(k \ge 1) \land (0 \le x < k)\} \\ \hline \sigma &\vdash \mathtt{split}(E,n,x) \Rightarrow (e_1,e_2,\dots,e_l), c \cup c' \end{split}$$

l-원소 tuple 형태로 반환

$$\begin{split} \sigma &\vdash E \Rightarrow e, c \\ k &= \mathtt{rank}(e) \\ e_1 &= e[1{:}x]@(n_1)@e[x+2{:}k] \\ e_2 &= e[1{:}x]@(n_2)@e[x+2{:}k] \\ & \dots \\ e_l &= e[1{:}x]@(n_l)@e[x+2{:}k] \\ c' &= \{(k \geq 1) \land (0 \leq x < k) \land (e[x+1] = n_1 + n_2 + \dots + n_l)\} \\ \hline \sigma &\vdash \mathtt{split}(E, [n_1, n_2, \dots, n_l], x) \Rightarrow (e_1, e_2, \dots, e_l), c \cup c' \end{split}$$

l-원소 tuple 형태로 반환

torch.zeros, torch.rand, torch.randn

$$\forall \texttt{ft} \in \{\texttt{zeros}, \texttt{rand}, \texttt{randn}\}, \quad \frac{}{\sigma \vdash \texttt{ft}(t_1, t_2, \dots, t_l) \Rightarrow (t_1, t_2, \dots, t_l), \emptyset}$$

torch.mode

$$\begin{split} \sigma \vdash E &\Rightarrow e, c \\ k &= \mathtt{rank}(e) \\ e' &= e[1:k-1] \\ \underline{c' = \{(k \geq 1)\}} \\ \overline{\sigma \vdash \mathtt{mode}(E) \Rightarrow (e', e'), c \cup c'} \end{split}$$

tuple 형태로 반환

$$\begin{split} \sigma &\vdash E \Rightarrow e, c \\ k &= \mathtt{rank}(e) \\ e' &= e[1:n]@e[n+2:k] \\ \frac{c' = \{(k \geq 1) \land (0 \leq n < k)\}}{\sigma \vdash \mathtt{mode}(E, n) \Rightarrow (e', e'), c \cup c'} \end{split}$$

tuple 형태로 반환

$$\begin{split} \sigma \vdash E &\Rightarrow e, c \\ k &= \mathtt{rank}(e) \\ e' &= e[1:n]@(1)@e[n+2:k] \\ \frac{c' = \{(k \geq 1) \land (0 \leq n < k)\}}{\sigma \vdash \mathtt{mode}(E, n, True) \Rightarrow (e', e'), c \cup c'} \end{split}$$

tuple 형태로 반환

$$\frac{\sigma \vdash \mathtt{mode}(E, n) \Rightarrow (e, e), c}{\sigma \vdash \mathtt{mode}(E, n, False) \Rightarrow (e, e), c}$$

tuple 형태로 반환

torch.randint

$$\overline{\sigma \vdash \mathtt{randint}(low, high, e_s) \Rightarrow e_s, \emptyset}$$

$$\overline{\sigma \vdash \mathtt{randint}(high, e_s) \Rightarrow e_s, \emptyset}$$

torch.max

$$\frac{\sigma \vdash E \Rightarrow _, c}{\sigma \vdash \max(E) \Rightarrow (), c}$$

$$\begin{split} \sigma &\vdash E \Rightarrow e, c \\ k &= \mathtt{rank}(e) \\ e' &= e[1:n]@e[n+2:k] \\ \underline{c'} &= \{(k \geq 1) \land (0 \leq n < k)\} \\ \overline{\sigma} &\vdash \mathtt{max}(E, n) \Rightarrow (e', e'), c \cup c' \end{split}$$

tuple 형태로 반환

$$\begin{split} \sigma \vdash E &\Rightarrow e, c \\ k &= \mathtt{rank}(e) \\ e' &= e[1:n]@(1)@e[n+2:k] \\ \frac{c' = \{(k \geq 1) \land (0 \leq n < k)\}}{\sigma \vdash \mathtt{max}(E, n, True) \Rightarrow (e', e'), c \cup c'} \end{split}$$

tuple 형태로 반환

$$\frac{\sigma \vdash \max(E, n) \Rightarrow (e, e), c}{\sigma \vdash \max(E, n, False) \Rightarrow (e, e), c}$$

tuple 형태로 반환

$$\begin{split} \sigma \vdash E_1 \Rightarrow e_1, c_1 \\ \sigma \vdash E_2 \Rightarrow e_2, c_2 \\ \hline \sigma \vdash \max(E_1, E_2) \Rightarrow broadcast(e_1, e_2), c_1 \cup c_2 \cup broadcastable(e_1, e_2) \end{split}$$

torch.nn.Conv2d

$$\begin{split} \sigma &\vdash E \Rightarrow e, c \\ k = \mathsf{rank}(e) \\ w &= \left \lfloor \frac{e[3] + 2 \times padding[0] - dilation[0] \times (kernel_size[0] - 1) - 1}{stride[0]} \right \rfloor + 1 \\ h &= \left \lfloor \frac{e[4] + 2 \times padding[1] - dilation[1] \times (kernel_size[1] - 1) - 1}{stride[1]} \right \rfloor + 1 \\ e' &= (e[1], out, w, h) \\ c_{dim} &= \{(k = 4)\} \\ c_w &= \{(kernel_size[0] \le e[3] + 2 \times padding[0]\} \\ c_h &= \{(kernel_size[1] \le e[4] + 2 \times padding[1]\} \\ c_{group} &= \{(in\%groups = 0) \wedge (out\%groups = 0)\} \end{split}$$

 $\overline{\sigma \vdash \mathtt{Conv2d}(in, out, kernel_size, stride, padding, dilation, groups)(E) \Rightarrow e', c \cup c_{dim} \cup c_w \cup c_h \cup c_{group})}$

default values: stride=1, padding=0, dilation=1, groups=1 $kernel_size, stride, padding, dilation는 가로-세로별 2-tuple로도 들어갈 수 있음 이 경우를 위해 <math>stride[0], stride[1]$ 으로 표기함 만일 stride가 튜플이 아닌 스칼라라면 stride[0] 또는 [1]은 stride 값 자체를 의미