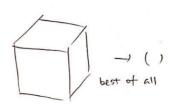
Statistics

torch.max, torch.min

torch.max(input) or .min



Require

Guarantees

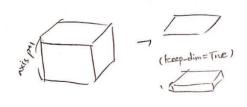
• |y| = ()

Comment

• 주어진 텐서에서 최대/최소 값을 ()-shape 텐서로 반환(스칼라 X)

$$\forall \mathtt{ft} \in \{\mathtt{min},\mathtt{max}\}, \quad \frac{\sigma \vdash E \Rightarrow _, c}{\sigma \vdash \mathtt{ft}(E) \Rightarrow (), c}$$

torch.max(input, dim, keep_dim=False, out=None) or .min



Require

- $|input| = (d_1, d_2, \dots, d_k)$
- $k \ge 1, \ 0 \le dim < k$

Guarantees

- $|y| = |z| = (d_1, d_2, \dots, d_{dim}, d_{dim+2}, \dots, d_k)$ 인 (y, z) 튜플 반환
- 세 번째 인자 $keep_dim$ 이 True이면 $|y|=|z|=(d_1,d_2,\ldots,d_{dim},1,d_{dim+2},\ldots,d_k)$ 로 처리

Comment

- 주어진 텐서에서 축 상의 최대/최소값과, 그에 해당하는 인덱스 번 호를 쌍으로 엮어 튜플로 반환
- out-텐서 인자가 있는 함수

$$\begin{split} \sigma \vdash E \Rightarrow e,c \\ k = \mathtt{rank}(e) \\ e' = e[1:n]@e[n+2:k] \\ \forall \mathtt{ft} \in \{\mathtt{min},\mathtt{max}\}, \quad & \frac{c' = \{(k \geq 1) \land (0 \leq n < k)\}}{\sigma \vdash \mathtt{ft}(E,n) \Rightarrow (e',e'),c \cup c'} \end{split}$$

tuple 형태로 반환

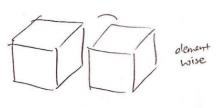
$$\begin{split} \sigma \vdash E \Rightarrow e,c \\ k = \mathtt{rank}(e) \\ e' = e[1:n]@(1)@e[n+2:k] \\ \forall \mathtt{ft} \in \{\mathtt{min},\mathtt{max}\}, \quad \frac{c' = \{(k \geq 1) \land (0 \leq n < k)\}}{\sigma \vdash \mathtt{ft}(E,n,True) \Rightarrow (e',e'),c \cup c'} \end{split}$$

tuple 형태로 반환

$$\forall \mathtt{ft} \in \{\mathtt{min},\mathtt{max}\}, \quad \frac{\sigma \vdash \mathtt{ft}(E,n) \Rightarrow (e,e), c}{\sigma \vdash \mathtt{ft}(E,n,False) \Rightarrow (e,e), c}$$

tuple 형태로 반환

torch.max(input,	other,	out=None)	or	.min



Require

 \bullet broadcastable(|input|, |other|)

Guarantees

 \bullet broadcast(|input|, |other|)

Comment

- 두 텐서의 elementwise 최대/최소
- out-텐서 인자가 있는 함수

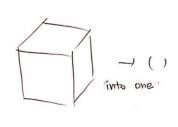
$$\sigma \vdash E_1 \Rightarrow e_1, c_1$$

$$\sigma \vdash E_2 \Rightarrow e_2, c_2$$

$$\forall \texttt{ft} \in \{\texttt{min}, \texttt{max}\}, \quad \frac{\sigma \vdash E_2 \Rightarrow e_2, c_2}{\sigma \vdash \texttt{ft}(E_1, E_2) \Rightarrow broadcast(e_1, e_2), c_1 \cup c_2 \cup broadcastable(e_1, e_2)}$$

torch.sum, torch.mean

torch.sum(input, dtype=None) or .mean



Require

• .mean에 대해서는 텐서 타입이 floating이어야 함

Guarantees

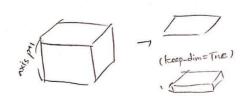
• |y| = ()

Comment

ullet 주어진 텐서의 합계/평균값을 ()-shape 텐서로 반환(스칼라 X)

$$\forall \mathtt{ft} \in \{\mathtt{sum},\mathtt{mean}\}, \quad \frac{\sigma \vdash E \Rightarrow _, c}{\sigma \vdash \mathtt{ft}(E) \Rightarrow (), c}$$

torch.sum(input, dim, keep_dim=False, dtype=None) or .mean



Require

- $|input| = (d_1, d_2, \dots, d_k)$
- k > 1, 0 < dim < k
- .mean에 대해서는 텐서 타입이 floating이어야 함

Guarantees

- $|y| = (d_1, d_2, \dots, d_{dim}, d_{dim+2}, \dots, d_k)$
- 세 번째 인자 $keep_dim$ 이 True이면 $|y|=(d_1,d_2,\ldots,d_{dim},1,d_{dim+2},\ldots,d_k)$

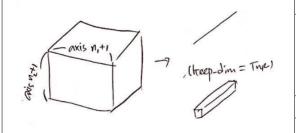
Comment

• 주어진 텐서에서 축 상의 합/평균을 반환

$$\begin{split} \sigma \vdash E \Rightarrow e, c \\ k = \mathrm{rank}(e) \\ e' = e[1:n]@e[n+2:k] \\ \hline \sigma \vdash \mathrm{ft}(E,n) \Rightarrow e', c \cup c' \end{split}$$

$$\begin{split} \sigma \vdash E \Rightarrow e,c \\ k = \mathtt{rank}(e) \\ e' = e[1:n]@(1)@e[n+2:k] \\ \forall \mathtt{ft} \in \{\mathtt{sum},\mathtt{mean}\}, \quad \frac{c' = \{(k \geq 1) \land (0 \leq n < k)\}}{\sigma \vdash \mathtt{ft}(E,n,True) \Rightarrow e',c \cup c'} \end{split}$$

torch.sum(input, [n1, n2, ..., n1], keep_dim=False, dtype=None) or .mean



Require

- $|x| = (d_1, d_2, \dots, d_k)$
- $k \ge 1, \ 0 \le n_1, n_2, \dots, n_l < k$
- .mean에 대해서는 텐서 타입이 floating이어야 함

Guarantees

- $|y|=(d_{i_1},d_{i_2},\dots,d_{i_{k-l}})$ $-1,2,\dots,k$ 에서 n_1+1,n_2+1,\dots,n_l+1 번째 항이 지워진 shape
- 세 번째 인자 keep_dim이 True이면 n₁ + 1, n₂ + 1,..., n_l + 1번째 항은 삭제되지 않고 1로 남음

Comment

- 주어진 텐서에서 여러 축을 통합한 합/평균을 반환
- $[n_1, n_2, \ldots, n_l]$ 에 중복된 원소가 들어가도 상관없이 잘 작동함

$$\sigma \vdash E \Rightarrow e, c \\ k = \operatorname{rank}(e) \\ e_1 = \operatorname{if} \ 0 \in \{n_1, n_2, \dots, n_r\} \ \operatorname{then} \ () \ \operatorname{else} \ (e[1]) \\ e_2 = \operatorname{if} \ 1 \in \{n_1, n_2, \dots, n_r\} \ \operatorname{then} \ () \ \operatorname{else} \ (e[2]) \\ \dots \\ e_k = \operatorname{if} \ k - 1 \in \{n_1, n_2, \dots, n_r\} \ \operatorname{then} \ () \ \operatorname{else} \ (e[k]) \\ e' = e_1@e_2@ \cdots @e_k \\ c' = \{(k \geq 1) \land (\forall i = 1, 2, \dots, r, \ 0 \leq n_i < k)\} \\ \hline \sigma \vdash \operatorname{ft}(E, (n_1, n_2, \dots, n_r)) \Rightarrow e', c \cup c' \\ \\ \sigma \vdash E \Rightarrow e, c \\ k = \operatorname{rank}(e) \\ e_1 = \operatorname{if} \ 0 \in \{n_1, n_2, \dots, n_r\} \ \operatorname{then} \ (1) \ \operatorname{else} \ (e[1]) \\ e_2 = \operatorname{if} \ 1 \in \{n_1, n_2, \dots, n_r\} \ \operatorname{then} \ (1) \ \operatorname{else} \ (e[2])$$

 $e_k = \text{if } k - 1 \in \{n_1, n_2, \dots, n_r\} \text{ then } (1) \text{ else } (e[k])$

$$\forall \mathtt{ft} \in \{\mathtt{sum}, \mathtt{mean}\}, \qquad \frac{c' = \{(k \geq 1) \land (\forall i = 1, 2, \dots, r, \ 0 \leq n_i < k)\}}{\sigma \vdash \mathtt{ft}(E, (n_1, n_2, \dots, n_r), True) \Rightarrow e', c \cup c'}$$

 $e' = e_1@e_2@\cdots@e_k$

torch.prod

torch.prod(input, dtype=None),
torch.prod(input, dim, keepdim=False, dtype=None)

Comment

- 대부분 sum과 똑같음
- 하지만, dim 부분에 튜플값이 들어갈 수 없음. 즉 여러 축에 대한 곱을 계산할 수 없음

$$\frac{\sigma \vdash E \Rightarrow _, c}{\sigma \vdash \mathtt{prod}(E) \Rightarrow (), c}$$

$$\begin{split} \sigma &\vdash E \Rightarrow e, c \\ k &= \mathtt{rank}(e) \\ e' &= e[1:n]@e[n+2:k] \\ c' &= \{(k \geq 1) \land (0 \leq n < k)\} \\ \hline \sigma &\vdash \mathtt{prod}(E, n) \Rightarrow e', c \cup c' \end{split}$$

$$\begin{split} \sigma \vdash E &\Rightarrow e, c \\ k &= \mathtt{rank}(e) \\ e' &= e[1:n]@(1)@e[n+2:k] \\ \underline{c'} &= \{(k \geq 1) \land (0 \leq n < k)\} \\ \overline{\sigma \vdash \mathtt{prod}(E, n, True)} &\Rightarrow e', c \cup c' \end{split}$$

torch.var, torch.std

torch.var(input, unbiased=True) or .std	
	Require
	• 텐서 타입이 floating이어야 함
	Guarantees
	$\bullet y = ()$
	Comment
	• 주어진 텐서의 분산/표준편차를 ()-shape 텐서로 반환(스칼라 X)

$$\forall \mathtt{ft} \in \{\mathtt{var},\mathtt{std}\}, \quad \frac{\sigma \vdash E \Rightarrow \neg, c}{\sigma \vdash \mathtt{ft}(E) \Rightarrow (), c}$$

torch.var(input,	dim,	keepdim=False,	unbiased=None,	out=None)	or
<pre>torch.std(input,</pre>	dim,	unbiased=True,	keepdim=False,	out=None)	

Require

- $|input| = (d_1, d_2, \dots, d_k)$
- $k \ge 1, 0 \le dim < k$
- 텐서 타입이 floating이어야 함

Guarantees

- $|y| = (d_1, d_2, \dots, d_{dim}, d_{dim+2}, \dots, d_k)$
- $keepdim \circ | True \circ | \mathfrak{P} | | y | = (d_1, d_2, \dots, d_{dim}, 1, d_{dim+2}, \dots, d_k)$

Comment

- 주어진 텐서에서 축 상의 분산/표준편차를 반환
- sum, mean과 마찬가지로 dim 부분은 튜플로 쓰일 수도 있음 (여러 축에 대한 분산/표춘편차)

$$\sigma \vdash E \Rightarrow e, c$$

$$k = \operatorname{rank}(e)$$

$$e' = e[1:n]@e[n+2:k]$$

$$\frac{c' = \{(k \geq 1) \land (0 \leq n < k)\}}{\sigma \vdash \operatorname{ft}(E, n) \Rightarrow e', c \cup c'}$$

$$\sigma \vdash E \Rightarrow e, c$$

$$k = \operatorname{rank}(e)$$

$$e' = e[1:n]@(1)@e[n+2:k]$$

$$\forall \operatorname{ft} \in \{\operatorname{var}, \operatorname{std}\}, \qquad \frac{c' = \{(k \geq 1) \land (0 \leq n < k)\}}{\sigma \vdash \operatorname{ft}(E, n, True) \Rightarrow e', c \cup c'}$$

keepdim이 True인 상황에 대한 proof tree

$$\sigma \vdash E \Rightarrow e,c$$

$$k = \operatorname{rank}(e)$$

$$e_1 = \operatorname{if} \ 0 \in \{n_1, n_2, \dots, n_r\} \ \operatorname{then} \ () \ \operatorname{else} \ (e[1])$$

$$e_2 = \operatorname{if} \ 1 \in \{n_1, n_2, \dots, n_r\} \ \operatorname{then} \ () \ \operatorname{else} \ (e[2])$$

$$\cdots$$

$$e_k = \operatorname{if} \ k - 1 \in \{n_1, n_2, \dots, n_r\} \ \operatorname{then} \ () \ \operatorname{else} \ (e[k])$$

$$e' = e_1@e_2@\cdots@e_k$$

$$\forall \operatorname{ft} \in \{\operatorname{var}, \operatorname{std}\},$$

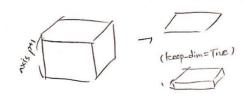
$$\frac{c' = \{(k \geq 1) \land (\forall i = 1, 2, \dots, r, \ 0 \leq n_i < k)\}}{\sigma \vdash \operatorname{ft}(E, (n_1, n_2, \dots, n_r)) \Rightarrow e', c \cup c'}$$

$$\begin{split} \sigma \vdash E \Rightarrow e, c \\ k = \text{rank}(e) \\ e_1 &= \text{if } 0 \in \{n_1, n_2, \dots, n_r\} \text{ then } (1) \text{ else } (e[1]) \\ e_2 &= \text{if } 1 \in \{n_1, n_2, \dots, n_r\} \text{ then } (1) \text{ else } (e[2]) \\ & \cdots \\ e_k &= \text{if } k - 1 \in \{n_1, n_2, \dots, n_r\} \text{ then } (1) \text{ else } (e[k]) \\ e' &= e_1@e_2@\cdots@e_k \\ \forall \text{ft} \in \{\text{var}, \text{std}\}, & \frac{c' = \{(k \geq 1) \land (\forall i = 1, 2, \dots, r, \ 0 \leq n_i < k)\}}{\sigma \vdash \text{ft}(E, (n_1, n_2, \dots, n_r), True) \Rightarrow e', c \cup c'} \end{split}$$

keepdim이 True인 상황에 대한 proof tree

torch.mode, torch.median

torch.mode(input, dim=-1, keep_dim=False, out=None) or torch.median



Require

- $|input| = (d_1, d_2, \dots, d_k)$
- *k* > 1
- $0 \le dim \le k \ (dim \leftarrow k 1 \ \text{if} \ dim = -1)$

Guarantees

- $|y| = |z| = (d_1, d_2, \dots, d_{dim}, d_{dim+2}, \dots, d_k)$ 인 (y, z) 튜플 반환
- 세 번째 인자 $keep_dim$ 이 True이면 $|y|=|z|=(d_1,d_2,\ldots,d_{dim},1,d_{dim+2},\ldots,d_k)$

Comment

- 입력받은 축을 기준으로한 통계적 최빈값/중간값 계산 함수
- (결과값, 인덱스) 튜플 형태로 반환하기 때문에, out인자도 들어가는 텐서도 2-원소 튜플 형태로 들어감

$$\sigma \vdash E \Rightarrow e,c$$

$$k = \operatorname{rank}(e)$$

$$e' = e[1:n]@e[n+2:k]$$

$$\forall \mathtt{ft} \in \{\mathtt{mode},\mathtt{median}\}, \qquad \frac{c' = \{(k \geq 1) \land (0 \leq n < k)\}}{\sigma \vdash \mathtt{ft}(E,n=-1,out=None) \Rightarrow (e',e'),c \cup c'}$$
 tuple 형태로 반환

$$\sigma \vdash E \Rightarrow e,c$$

$$k = \operatorname{rank}(e)$$

$$e' = e[1:n]@(1)@e[n+2:k]$$

$$\forall \mathtt{ft} \in \{\mathtt{mode},\mathtt{median}\}, \qquad \frac{c' = \{(k \geq 1) \land (0 \leq n < k)\}}{\sigma \vdash \mathtt{ft}(E,n=-1,True,out=None) \Rightarrow (e',e'),c \cup c'}$$
 tuple 형태로 반환

$$\forall \mathtt{ft} \in \{\mathtt{mode}, \mathtt{median}\}, \qquad \frac{\sigma \vdash \mathtt{ft}(E, n) \Rightarrow (e, e), c}{\sigma \vdash \mathtt{ft}(E, n = -1, False, out = None) \Rightarrow (e, e), c} \qquad \qquad \mathsf{tuple} \ \ \mathsf{형태로} \ \ \mathsf{반환}$$