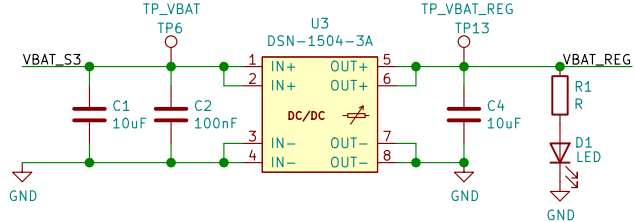


Figure 1: Schematic diagram of the power supply circuit. The circuit includes a Barrel Jack Mounting Pin connected to a 5V regulator, a Battery Connector connected to a 12.6V battery, and a Motor Connector connected to a motor. The 5V regulator is connected to the 5V pin of the Battery Connector. The 12.6V battery is connected to the 12.6V pin of the Battery Connector. The Motor Connector is connected to the motor. The schematic shows the connections between the power supply components and the motor.



STM32 - NUCLEO - F446RE			
<u>GPS_UART_RX</u>	1	PC10	SP13_SCLK / SERIAL3_TX
<u>GPS_UART_TX</u>	2	PC11	SERIAL3_RX / SP13_MISO
<u>GPS_RESET</u>	3	PC12	I2C2_SDA / SP13_MOSI / SERIAL5_TX
	4	PD2	SERIAL5_RX
from PSU -> <u>VBAT_REG</u>	5	VDD	SP12_SSEL / CAN12_TD / I2C1_SDA
	6	ESV	SERIAL3_RX / ADC
	7	BOOT0	AVDD
<u>LOGIC_GND</u>	8	GND	USV
	9	NC	GND
	10	NC	NC
	11	NC	NC
	12	IOREF	LED1 / SCL / DAC / PWM2_1 / ADC
	13	PA13	CAN1_TD
	14	RESET	SP13_MISO / PWM3_1 / ADC
<- to periphs <u>LOGIC_3V3</u>	15	PA14	PWM1_4 / CAN1_RX
	16	3V3	SP13_SCLK / PWM1_2 / SERIAL4_RX
<- to periphs <u>LOGIC_5V</u>	17	PA15	SP12_SSEL / PWM2_1
	18	5V0	SERIAL1_TX / CAN2_TD / PWM4_1 / I2C1_SCL
<u>LOGIC_GND</u>	19	GND	NC
<u>LOGIC_GND</u>	20	GND	GND
<u>LOGIC_GND</u>	21	PB7	I2C1_SDA / PWM4_2 / SERIAL1_RX
	22	GND	SP12_SCLK / PWM3_2 / SERIAL6_RX
	23	PC13	USER_BUTTON
MOTOR_MODE	24	VIN	PWM1_2 / I2C3_SCL
MOTOR1_P5	25	PC14	ADC / PWM1_3N
MOTOR2_P5	26	NC	SP12_SCLK / SERIAL3_TX / PWM2_3 / I2C2_SCL
MOTOR3_P5	27	PC15	PWM1_3N / SP12_MISO
	28	PA0	SP13_MISO / PWM3_1 / I2C3_SDA
	29	PH0	PWM1_2N / SP12_MISO
<u>MOTOR1_ENC_A</u>	30	PA1	SERIAL1_RX / PWM2_2 / ADC
<u>MOTOR1_ENC_B</u>	31	PH1	PWM1_1N / CAN2_TD / SP12_SCLK
<u>MOTOR2_ENC_A</u>	32	PA4	SP13_SSEL / ADC / DAC
<u>MOTOR2_ENC_B</u>	33	VBAT	AGND
<u>MOTOR3_ENC_A</u>	34	PB0	PWM1_2N / SP13_MOSI / ADC
<u>MOTOR3_ENC_B</u>	35	PC2	SP12_MISO / ADC
	36	PC1	SP12_MOSI / ADC
MOTOR1_INA	37	PC3	SP12_MOSI / ADC
MOTOR1_INB	38	PC0	ADC
MOTOR2_INA			
MOTOR2_INB			
MOTOR3_INA			
MOTOR3_INB			

[illegible]

LOGIC_3V3	TP7 TP_LOGIC_3V3
LOGIC_5V	TP8 TP_LOGIC_5V
LOGIC_GND	TP9 TP_LOGIC_GND
GPS_UART_RX	TP10TP_GPS_UART_RX
GPS_UART_TX	TP11TP_GPS_UART_TX
GPS_RESET	TP12TP_GPS_RESET

Motor1 Connections:

- Logic Power:** LOGIC_3V3 (1) to VCC, LOGIC_GND (2) to GND.
- Motor Power:** MOTOR1_VIN (5) to VCC, MOTOR1_GND (2) to GND.
- Control:** MOTOR1_INA (10) to IN+, MOTOR1_INB (11) to IN-, MOTOR1_A (3) to OUT+, MOTOR1_B (4) to OUT-.
- Motor Pins:** MOTOR1_PS (7) to PS, MOTOR1_MODE (12) to PWM, MOTOR1_TR1 (8) to TR1, MOTOR1_TR2 (9) to TR2.

Motor2 Connections:

- Logic Power:** LOGIC_3V3 (1) to VCC, LOGIC_GND (2) to GND.
- Motor Power:** MOTOR2_VIN (5) to VCC, MOTOR2_GND (2) to GND.
- Control:** MOTOR2_INA (10) to IN+, MOTOR2_INB (11) to IN-, MOTOR2_A (3) to OUT+, MOTOR2_B (4) to OUT-.
- Motor Pins:** MOTOR2_PS (7) to PS, MOTOR2_MODE (12) to PWM, MOTOR2_TR1 (8) to TR1, MOTOR2_TR2 (9) to TR2.

Motor3 Connections:

- Logic Power:** LOGIC_3V3 (1) to VCC, LOGIC_GND (2) to GND.
- Motor Power:** MOTOR3_VIN (5) to VCC, MOTOR3_GND (2) to GND.
- Control:** MOTOR3_INA (10) to IN+, MOTOR3_INB (11) to IN-, MOTOR3_A (3) to OUT+, MOTOR3_B (4) to OUT-.
- Motor Pins:** MOTOR3_PS (7) to PS, MOTOR3_MODE (12) to PWM, MOTOR3_TR1 (8) to TR1, MOTOR3_TR2 (9) to TR2.

Motor Driver Modules:

- U6 BD65496MUV:** Motor1 driver.
- U7 BD65496MUV:** Motor2 driver.
- U8 BD65496MUV:** Motor3 driver.

Motor Connector Details:

- JP1 (Motor1):** MOTOR1_A (1), MOTOR1_B (2), LOGIC_GND (3), LOGIC_3V3 (4), MOTOR1_ENC_A (5), MOTOR1_ENC_B (6).
- JP2 (Motor2):** MOTOR2_A (1), MOTOR2_B (2), LOGIC_GND (3), LOGIC_3V3 (4), MOTOR2_ENC_A (5), MOTOR2_ENC_B (6).
- JP3 (Motor3):** MOTOR3_A (1), MOTOR3_B (2), LOGIC_GND (3), LOGIC_3V3 (4), MOTOR3_ENC_A (5), MOTOR3_ENC_B (6).

Sheet: /
File: lego_robot.sch

Title:

Size: A4	Date:
KiCad E.D.A. kicad (5.1.10)-1	

Rev:
Id: 1/1