

# TROUBLESHOOTING

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There are troubleshooting sections in the sample answers

# PYTHONPATH

- Path errors: **ModuleNotFoundError**: (check spelling for **imports**, but otherwise you have set up problem).
- This is how Python finds the modules to import
- On the robot set at the Command Line
  - **export PYTHONPATH=/home/pi/robohat**

# PYTHONPATH: SIMULATOR

- PYTHONPATH should include the folder where the simulator is installed.

# STUDENT PROGRAMS

- PYTHONPATH also needs to point to wherever students store their programs.
- If they each have their own simulator/robot then this can be the simulator/robohat folder.
- Otherwise you are going to need to think about what instructions to give them - clear out old programs regularly.

# THE ROBOTS

- **Power:** The robots eat batteries. The most common cause of them just shutting down or the motors stopping working is power.
  - I recommend using a USB power bank as back-up power for the Raspberry Pi.
  - Use Eneloop Pro Rechargeable batteries (particularly for the Initio).

# ROBOT DOESN'T MOVE (BUT NO ERRORS)

- May be a power issue.
- If you are working from a file (not the command line) it may be that the command didn't have time to execute (check using the command line).

# PYTHON SIMULATOR

- Check you are in the right IDLE window.
- (On Macs) sometimes crashes with a memory error. Everything is programmed so that if you just restart and re-open the world everything should connect properly.
- Can be a bit laggy.

# FAILING TO INITIALISE

```
>>> initio.forward(10);
```

```
Traceback (most recent call last):
```

```
File "<pyshell#1>", line 1, in <module>
```

```
    initio.forward(10);
```

```
File "/Users/louisedennis/PiRovers/pirover_simulator/simclient/simrobot.py", line  
113, in forward
```

Similar errors can arise if you've called `cleanup()` and carried on working



# FOR MORE HELP: THIS IS ME

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