**Virtual Pi2Go Programming: Line Following**

**Exercise**: Write a program that will follow a line. You should use the same techniques you used to design and develop your obstacle avoidance program and use **line\_following.xml** world to test the program. Your program design should involve the robot moving forward when its line sensors are either side of the line and turning left or right as appropriate if one of the line sensors detects the line.

You may have to move the robot to a suitable starting position.



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