

Open Distributed Automation and Control with IEC 61499

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by:

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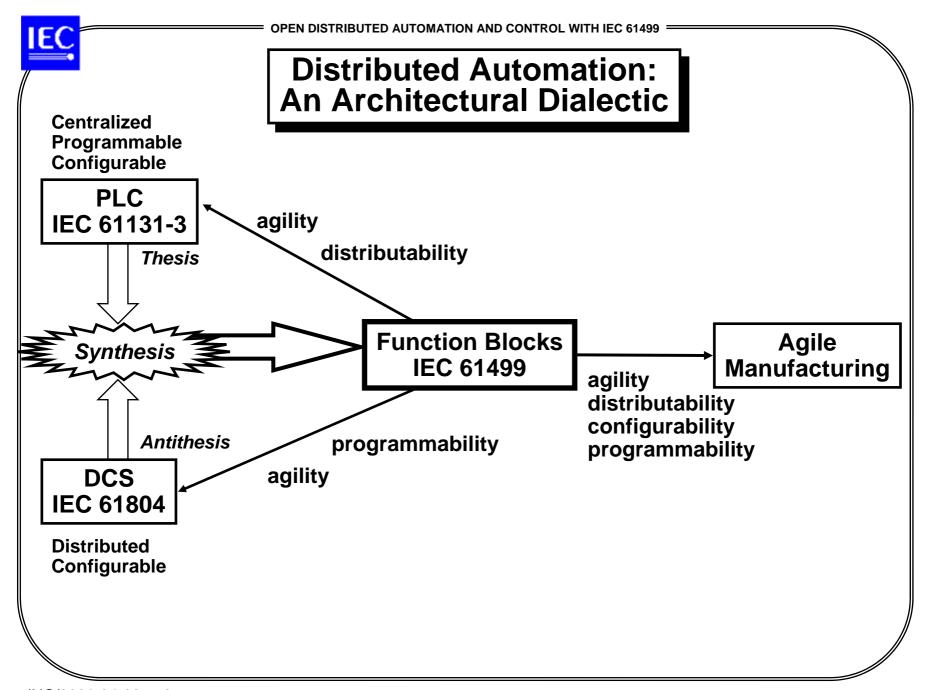
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Open Distributed Automation and Control with IEC 61499

- Background
- Architecture
- Object Models
- Software Tool Requirements
- Status and Future



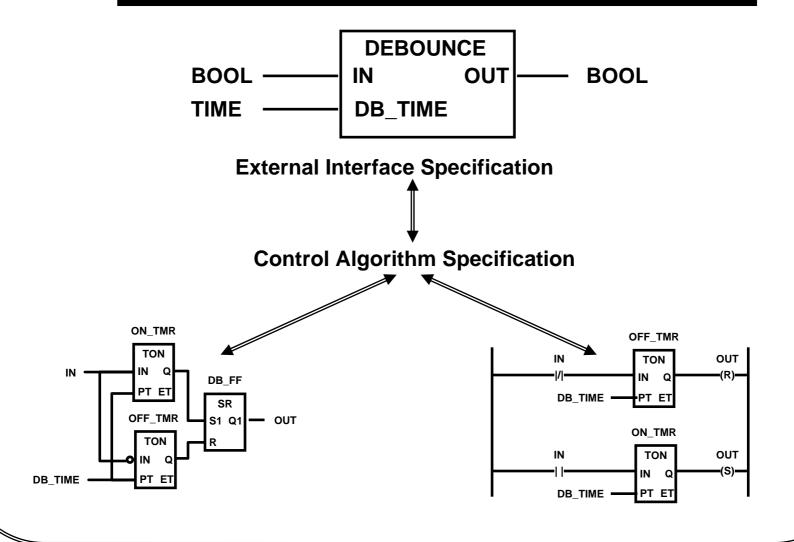


IEC 61131-3: Modern (1993) Software Engineering for Automation and Control

- Encapsulation/Reuse Mechanisms
 - Function Blocks, Functions, Data Types, Programs
- Application-adapted Languages
 - Ladder Diagram (LD) for logic control ("power flow")
 - Function Block Diagram (FBD) for regulatory control ("data flow")
 - Sequential Function Chart (SFC) for state-machine control
 - Structured Text (ST) for information processing
 - Instruction List (IL) for assembly-level programming
- A Mature, Internationally Adopted Standard
 - First edition: 1993
 - Second edition: 2001

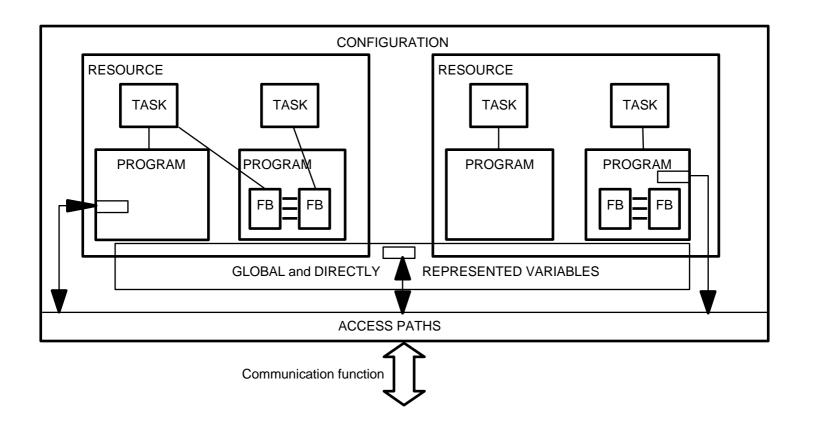


Function Blocks: Object-Oriented Encapsulation and Reuse in IEC 61131-3



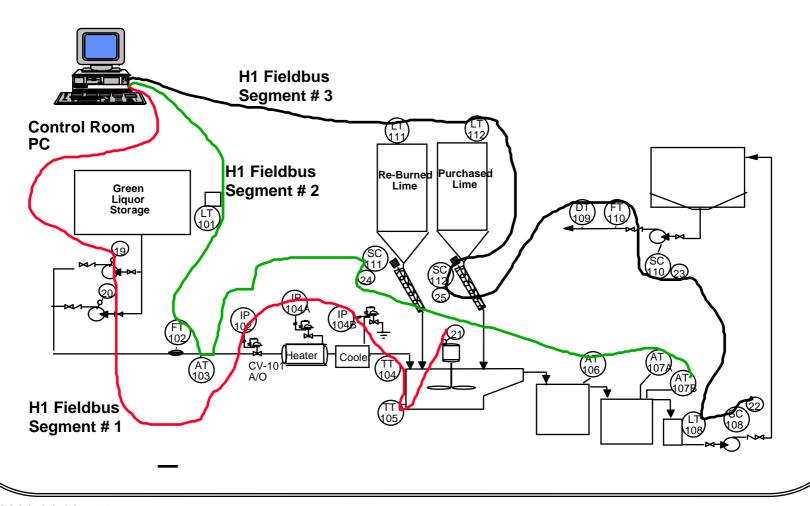


Centralized System Configuration in IEC 61131-3



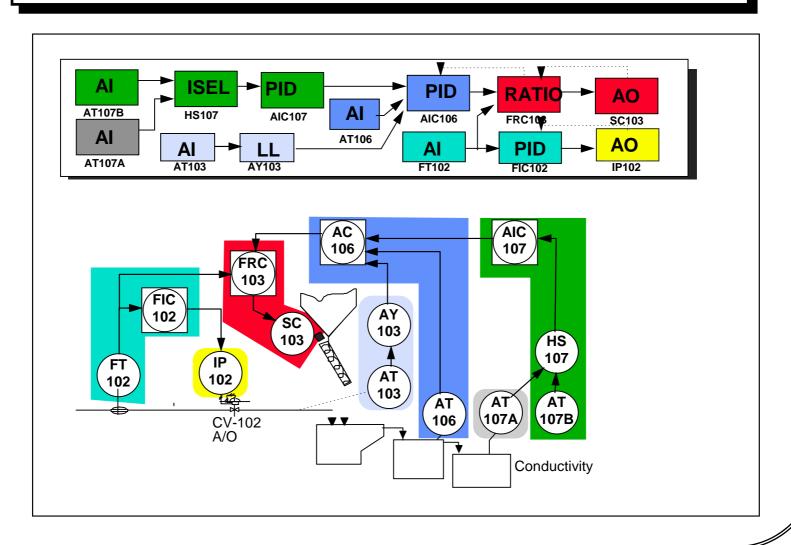


Distributed Configuration in Fieldbus Systems (Physical View)





Distributed Configuration in Fieldbus Systems (Logical View)



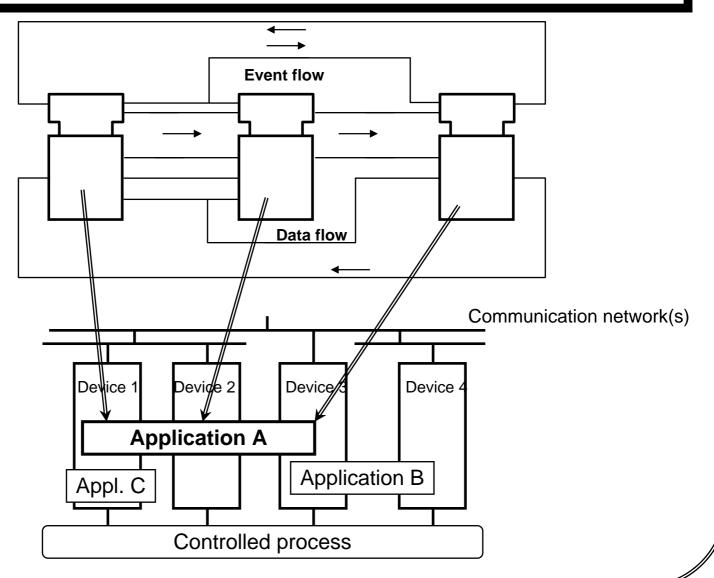


Basic Concepts of IEC 61499

- Distributed applications
- Object-oriented software encapsulation and reuse
- Event and data interfaces
- Event-driven state machines
- Service interfaces
- Management services
- Software portability



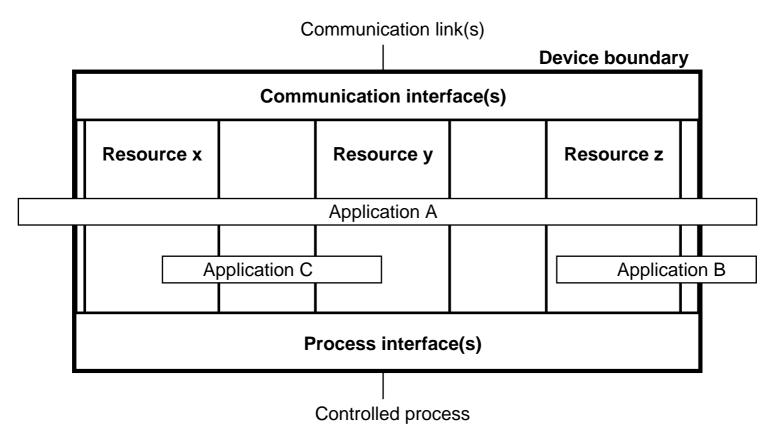
System Architecture for Distributed Applications





Device Architecture

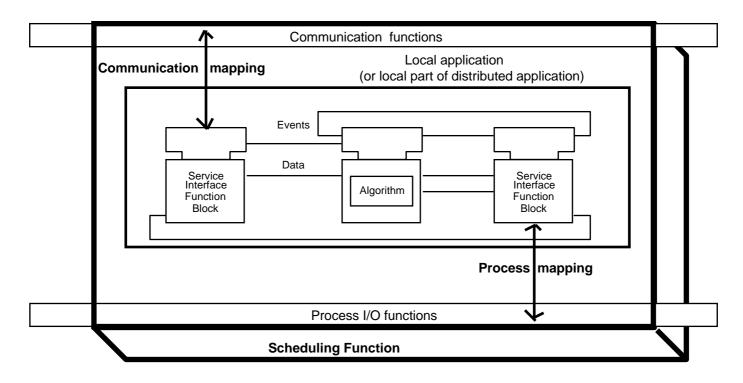
- Device = Container for Resources
- Device provides Communications & Process Interfaces





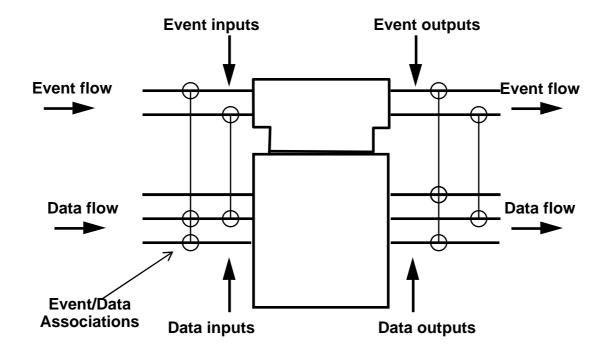
Resource Architecture

- Resource schedules & executes FB algorithms
- Resource maps Communications & Process I/O Functions to Service Interface Function Blocks



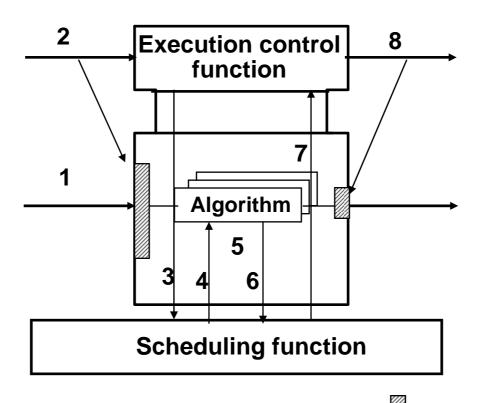


Event and Data Interfaces



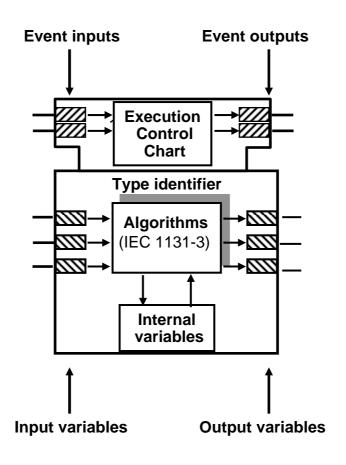


Event-Driven Execution Control





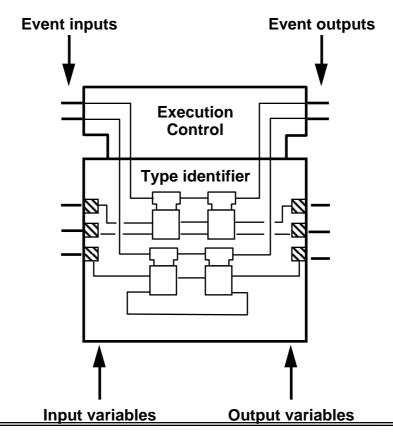
Encapsulation and Reuse: Basic Function Block Types





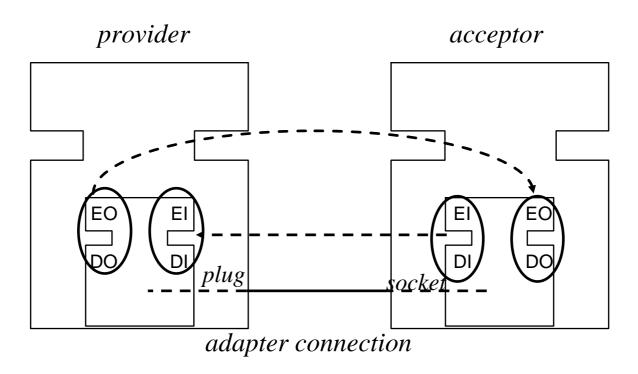
Software Encapsulation and Reuse: Composite Function Block Types

- Functional composition
- Reusable
- Atomic (not distributable)
 - "subapplications" are distributable





Adapter Interfaces



- Reduce diagram clutter
- Simplify transducer interface
- Capture patterns of interaction

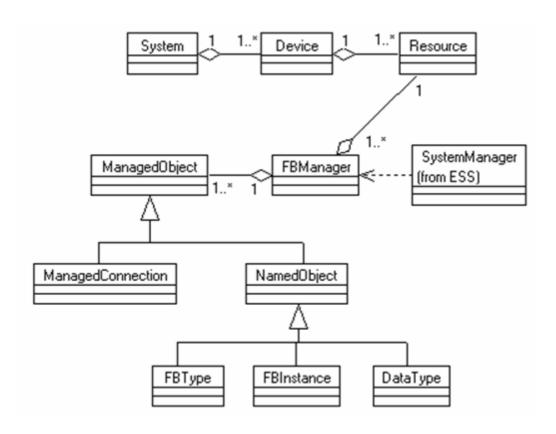


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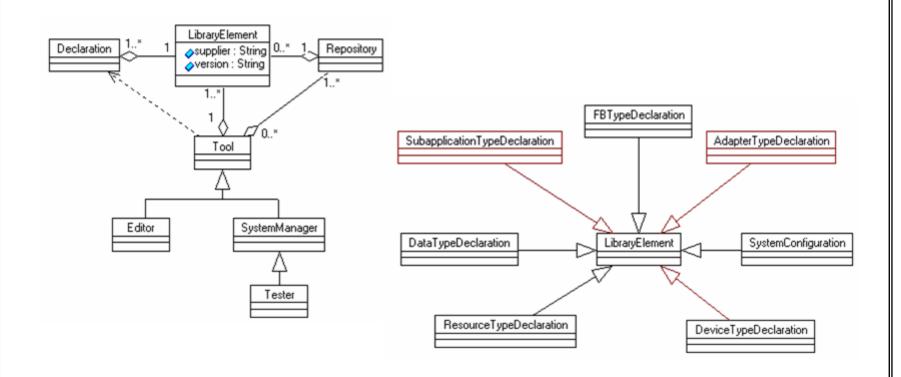


System Management Model



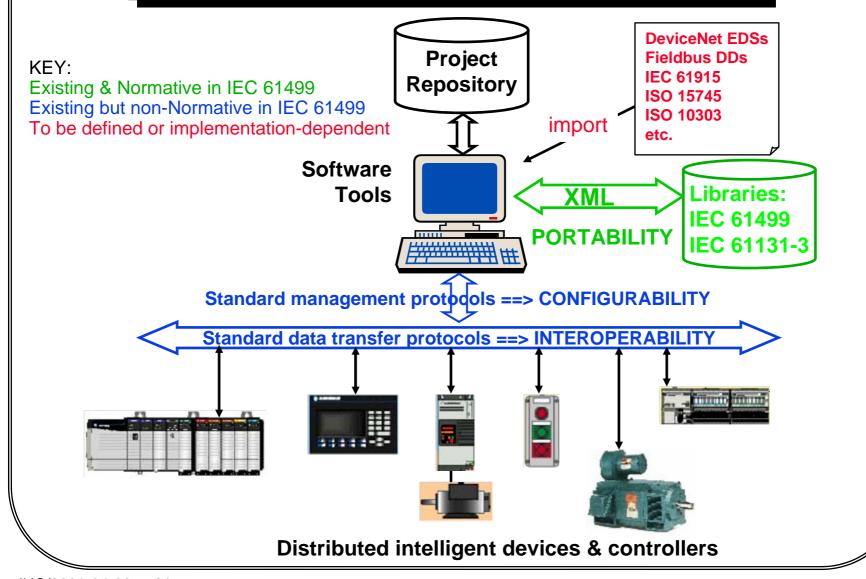


Software Tool Models





Open Distributed Systems: The IEC 61499 Vision





Software Tool Requirements (1)

- Information to be provided by tool supplier
 - Applicable library element type(s)
 - Engineering task(s) supported
- Exchange of library elements
 - via XML per defined DTDs for:
 - » data types
 - » other library elements
- Information to be provided by library element supplier
 - sufficient to enable the user to fully determine functionality
 - at a minimum, event + data interfaces + service specification
 - IP protection allowed when element implementation is provided
- Display of declarations
 - in a form appropriate to the engineering task
- Modification of declarations
 - as appropriate to the engineering task



Software Tool Requirements (2)

Validation of declarations

- as required by the associated engineering task
- examples:
 - » syntax checking
 - » semantic checking
 - » simulation and testing, individually and in combinations

Implementation of declarations

- as required by the associated engineering task
- examples:
 - » production of executable code ("firmware")
 - » creation and interconnection of function block instances in devices and resources

System operation, testing and maintenance

- as required by the associated engineering task
- examples:
 - » facilities described above
 - » configuration/operation of information interchange
 - » management services



IEC Project 61499 Status & Future

- PASs (Publicly Available Specifications)
 - IEC PAS 61499-1, Architecture
 - IEC PAS 61499-2, Software tool requirements
- Ongoing Work
 - 61499-3, Application guidelines
 - (to be proposed) 61499-4, Rules for compliance profiles
- 2-year trial use period
 - Incorporate lessons learned from trial implementations
 - Parts 1,2 CDVs projected: 2003-10-01



First Feasibility Demonstration: Kitakyushu City, Japan, 2000-10-20

