

$$\max_w \left\{ J(w) = \frac{w^T \zeta_B w}{w^T \zeta_w w} \right\}$$

$$\text{where } \zeta_B = (m_2 - m_1)(m_2 - m_1)^T$$

$$\begin{aligned} \zeta_w = & \sum_{n \in C_1} (x_n - m_1)(x_n - m_1)^T \\ & + \sum_{n \in C_2} (x_n - m_2)(x_n - m_2)^T \end{aligned}$$

Let's prove by constraint optimization.

$$\max_w \{ w^T \zeta_B w \} \quad \dots (1)$$

Since we are only interested in direction, length is not important.

$$\text{Therefore, } w^T \zeta_w w = 1 \quad \dots (2)$$

$$\max_w \{ w^T \zeta_B w \} \quad \text{s.t. } w^T \zeta_w w = 1 \quad (\because (1), (2))$$

$$\mathcal{L}(w; \mu) = w^T \zeta_B w - \mu (w^T \zeta_w w - 1)$$

$$\frac{\partial}{\partial w} \mathcal{L}(w; \mu) = 2\zeta_B w - 2\mu \zeta_w w$$

$$\therefore S_W^{-1} S_B \omega^* = \mu \omega^* \quad \dots (3)$$

Therefore,

μ and ω^* are the eigenvalues and eigenvectors of $S_W^{-1} S_B$. $(\because (3))$

$$\therefore S_W^{-1} (m_2 - m_1) \propto \omega \quad \boxed{\text{Q.E.D.}}$$