$$(\omega(n) = \underset{\omega}{\operatorname{arg min}} \left\| \begin{bmatrix} y(t) \\ \vdots \\ y(n) \end{bmatrix} - \begin{bmatrix} x(t) \\ \vdots \\ x(n) \end{bmatrix} \right\|^{2}$$

For
$$i=1$$
:
$$\omega(1) = \arg\min_{w} ||y(1) - X(1)w||^{2}$$

$$= (x^{T}(1)X(1))^{T}X^{T}(1)y(1) \quad (: L5 \text{ Solution.}) \quad (()$$
Let $P(1) = (X^{T}(1)X(1))^{T}$.

For
$$i=2$$
:

$$(\omega(2) = \operatorname{argmin} \left\| \begin{bmatrix} y(t) \\ y(2) \end{bmatrix} - \begin{bmatrix} x(t) \\ x(2) \end{bmatrix} \omega \right\|^{2}$$

$$= P(2) \begin{bmatrix} x(t) \\ x(2) \end{bmatrix}^{T} \begin{bmatrix} y(t) \\ y(2) \end{bmatrix}.$$

where
$$P(2) = \begin{bmatrix} x(t) \\ x(2) \end{bmatrix}^{T} \begin{bmatrix} x(t) \\ x(2) \end{bmatrix}$$

$$P(2) = \begin{bmatrix} x(t) \\ x(2) \end{bmatrix}^{T} \begin{bmatrix} x(t) \\ x(2) \end{bmatrix}$$

$$= X^{T}(1) X(1) + X^{T}(2) X(2)$$

$$= P^{T}(1) + X^{T}(2) X(2) \cdots (2)$$

$$\rho(2) = (\rho^{T}(1) + X^{T}(2)X(2))^{T} \\
= \rho(1) - \rho(1)X^{T}(2)(I + X(2)\rho(1)X^{T}(2))^{T}X(2)\rho(1) \\
C: (wodburg motion identity beams). ((3)$$

$$\begin{bmatrix}
X(1) \\
X(2)
\end{bmatrix}^{T} \begin{bmatrix} y_{(1)} \\
y_{(2)}
\end{bmatrix} = X^{T}(1)y_{(1)} + X^{T}(2)y_{(2)} \\
= \rho^{T}(1)w_{(1)} + X^{T}(2)y_{(2)} & C: (1) \\
= (\rho^{T}(2) - X^{T}(2)X(2))w_{(1)} + X^{T}(2)y_{(2)} \\
(: (2)) & (4)$$

$$(w(2) = \rho(2) \begin{bmatrix} X(1) \\
X(2)
\end{bmatrix}^{T} \begin{bmatrix} y_{(1)} \\
y_{(2)}
\end{bmatrix} \\
= \rho(2) \left(\rho^{T}(2) - X^{T}(2)X(2) \right) w_{(1)} + X^{T}(2)y_{(2)} \\
= (w(1) - \rho(2)X^{T}(2)X(2)w_{(1)} + \rho(2)X^{T}(2)y_{(2)} \\
= (w(1) + \rho(2)X^{T}(2)(y_{(2)} - X(2)w_{(1)}) & (5)$$

Therefore,

$$i = 2$$
, $w(i) = w(i-1) - P(i) \times^{T}(i) (y(i) - X(i)) w(i-1)$ where $P(i) = P(i-1) - P(i-1) \times^{T}(i) (I + X(i)P(i-1)X^{T}(i))^{T}$ $X(i)P(i-1) - P(i-1) \times^{T}(i) (I + X(i)P(i-1)X^{T}(i))^{T}$ $X(i)P(i-1) - P(i) \times^{T}(i) (I + X(i)P(i-1)X^{T}(i))^{T}$ $Y(i) = w(i-1) - P(i) \times^{T}(i) (y(i) - X(i)) w(i-1)$ where $P(i) = P(i-1) - P(i-1)X^{T}(i) (I + X(i)P(i-1)X^{T}(i))^{T}$ $X(i)P(i-1)$