

d) 4 Euler steps with $\frac{\pi}{4}$ $X(t_0) = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$ $a = \begin{pmatrix} \cos t \\ \sin t \end{pmatrix}$

$$\vec{V}_{t+1} = \vec{V}_t + \Delta t \vec{a}$$

$$\vec{X}_{t+1} = \vec{X}_t + \Delta t \cdot \vec{V}_{t+1}$$

$$\vec{X}_{t+1} = \vec{X}_t + \Delta t \cdot \vec{V}_t + \Delta t^2 \cdot \vec{a}_t$$

$$t = 0, \frac{\pi}{4}, \frac{\pi}{2}, \frac{3\pi}{4}, \pi \quad \Delta t = \frac{\pi}{4}$$

$$\vec{V}_1 = \begin{pmatrix} 0 \\ 0 \end{pmatrix} + \frac{\pi}{4} \cdot \begin{pmatrix} \cos \frac{\pi}{4} \\ \sin \frac{\pi}{4} \end{pmatrix}$$

$$\begin{aligned} \vec{X}_1 &= \begin{pmatrix} 0 \\ 0 \end{pmatrix} + \frac{\pi}{4} \cdot \frac{\pi}{4} \begin{pmatrix} \cos \frac{\pi}{4} \\ \sin \frac{\pi}{4} \end{pmatrix} + \frac{\pi^2}{16} \cdot \begin{pmatrix} \cos \frac{\pi}{4} \\ \sin \frac{\pi}{4} \end{pmatrix} \\ &= \frac{\pi^2}{16} \cdot \begin{pmatrix} \sqrt{2} \\ \sqrt{2} \end{pmatrix} \end{aligned}$$

$$\begin{aligned} \vec{V}_2 &= \frac{\pi}{4} \cdot \begin{pmatrix} \cos \frac{\pi}{4} \\ \sin \frac{\pi}{4} \end{pmatrix} + \frac{\pi}{4} \cdot \begin{pmatrix} \cos \frac{\pi}{2} \\ \sin \frac{\pi}{2} \end{pmatrix} \\ &= \frac{\pi}{4} \cdot \begin{pmatrix} \cos \frac{\pi}{4} \\ \sin(\frac{\pi}{4}) + 1 \end{pmatrix} \end{aligned}$$

$$\begin{aligned} \vec{X}_2 &= \frac{\pi^2}{16} \cdot \begin{pmatrix} \sqrt{2} \\ \sqrt{2} \end{pmatrix} + \frac{\pi}{4} \cdot \frac{\pi}{4} \cdot \begin{pmatrix} \cos(\frac{\pi}{4}) \\ 1 + \sin(\frac{\pi}{4}) \end{pmatrix} \\ &= \frac{\pi^2}{16} \cdot \begin{pmatrix} \sqrt{2} + \cos \frac{\pi}{4} \\ \sqrt{2} + 1 + \sin \frac{\pi}{4} \end{pmatrix} \end{aligned}$$

$$\begin{aligned} \vec{V}_3 &= \frac{\pi}{4} \begin{pmatrix} \cos \frac{\pi}{4} \\ 1 + \sin \frac{\pi}{4} \end{pmatrix} + \frac{\pi}{4} \cdot \begin{pmatrix} \cos \frac{3}{4}\pi \\ \sin \frac{3}{4}\pi \end{pmatrix} \\ &= \frac{\pi}{4} \begin{pmatrix} 0 \\ 1 + \sqrt{2} \end{pmatrix} \end{aligned}$$

$$\begin{aligned} \vec{X}_3 &= \frac{\pi^2}{16} \cdot \begin{pmatrix} \sqrt{2} + \cos \frac{\pi}{4} \\ \sqrt{2} + 1 + \sin \frac{\pi}{4} \end{pmatrix} + \frac{\pi}{4} \cdot \frac{\pi}{4} \begin{pmatrix} 0 \\ 1 + \sqrt{2} \end{pmatrix} \\ &= \frac{\pi^2}{16} \cdot \begin{pmatrix} \sqrt{2} + \cos \frac{\pi}{4} \\ 2\sqrt{2} + 2 + \sin \frac{\pi}{4} \end{pmatrix} \end{aligned}$$

$$\vec{v}_4 = \frac{\pi}{4} \begin{pmatrix} 0 \\ 1+\sqrt{2} \end{pmatrix} + \frac{\pi}{4} \cdot \begin{pmatrix} -1 \\ 0 \end{pmatrix} \leftarrow \text{eventuell minus} \\ \text{minus } \Delta t \text{ davor nehmen?}$$

$$\vec{x}_4 = \frac{\pi^2}{16} \cdot \begin{pmatrix} \sqrt{2} + \cos \frac{\pi}{4} \\ 2\sqrt{2} + 2 + \sin \frac{\pi}{4} \end{pmatrix} + \frac{\pi}{4} \cdot \frac{\pi}{4} \begin{pmatrix} -1 \\ 1+\sqrt{2} \end{pmatrix}$$

$$= \frac{\pi^2}{16} \begin{pmatrix} \sqrt{2} - 1 + \cos \frac{\pi}{4} \\ 3\sqrt{2} + 3 + \sin \frac{\pi}{4} \end{pmatrix}$$
