

## Sheet 1 - Transformations

Please upload your solutions to  
<https://uni-bonn.sciebo.de/s/XfRkWhpwDEeR8Y7>  
by

**Sun, 20.10.2019.**

Make sure to **list all group members** on all pages / source files.  
Theoretical solutions must be texed or scanned, **photos will not be accepted.**

### Practical Part

#### Assignment 1) Transformations

(1+1+2=4Pts)

- a) Download the framework and run **Transformations.py**. It will display a monkey head. Set the limits of all three axes to  $[-2, \dots, 2]$  so that the mesh is properly centered.
- b) Scale up the model so that it appears 2 times larger and translate the mesh by  $t = (1, 0, 0)^T$  and display the result.
- c) Rotate the model from task a) by  $\pi/2$  around the z-axis by using matrix/vector multiplication. In addition rotate the model from task b) by  $\pi/4$  around an axis parallel to the z-axis passing the point  $p = (1, 0, 0)^T$  and display the results of both rotations in a single coordinate frame.

### Theoretical Part

#### Assignment 2) Cross and Dot Product

(1+1+2+1+1=6Pts)

Let  $\mathbf{a}, \mathbf{b}, \mathbf{c} \in \mathbb{R}^3$ .

- a) Show that  $\mathbf{a} \times (\mathbf{b} + \mathbf{c}) = \mathbf{a} \times \mathbf{b} + \mathbf{a} \times \mathbf{c}$ .
- b) Show that  $\mathbf{a} \cdot (\mathbf{a} \times \mathbf{b}) = 0$ .
- c) A vector  $\mathbf{a}$  is defined by  $a = a_1 e_x + a_2 e_y + a_3 e_z$  and  $\mathbf{b} = b_1 e_x + b_2 e_y + b_3 e_z$ . Show that

$$|\mathbf{a} \times \mathbf{b}| = \left| \begin{vmatrix} a_2 & a_3 \\ b_2 & b_3 \end{vmatrix} \cdot e_x - \begin{vmatrix} a_1 & a_3 \\ b_1 & b_3 \end{vmatrix} \cdot e_y + \begin{vmatrix} a_1 & a_2 \\ b_1 & b_2 \end{vmatrix} \cdot e_z \right|$$

Explain why the following definition is correct for the formal case.

$$\mathbf{a} \times \mathbf{b} = \begin{vmatrix} e_x & e_y & e_z \\ a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \end{vmatrix}$$

- d) Show that  $\mathbf{a} \cdot (\mathbf{b} \times \mathbf{c}) = \mathbf{b} \cdot (\mathbf{c} \times \mathbf{a}) = \mathbf{c} \cdot (\mathbf{a} \times \mathbf{b})$ . (It is sufficient to show only one of the equations).
- e) Show that  $\mathbf{a} \cdot (\mathbf{b} \times \mathbf{c})$  represents the volume  $V$  of the parallelepiped (Fig. 1) defined by the three vector  $\mathbf{a}$ ,  $\mathbf{b}$  and  $\mathbf{c}$ .

**Good luck!**

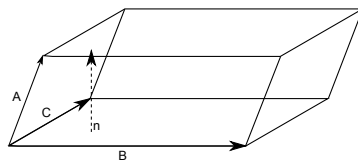


Figure 1: Parallelepiped with Volume  $V$