

KingstVIS Analyzer Developer Guide

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Contents

I. Setting up an Analyzer Project	3 -
1. General description	3 -
2. Setting project	3 -
2.1 Windows	3 -
2.2 Linux	7 -
2.3 Mac	8 -
II. Writing your Analyzer's Code	9 -
1. Analyzer Settings	10 -
1.1 {YourName} AnalyzerSettings.h	10 -
1.2 {YourName} AnalyzerSettings.cpp	13 -
2. SimulationDataGenerator	22 -
2.1 {YourName}SimulationDataGenerator.h	23 -
2.2 {YourName}SimulationDataGenerator.cpp	24 -
3. AnalyzerResults	32 -
3.1 {YourName} AnalyzerResults.h	33 -
3.2 {YourName} AnalyzerResults.cpp	34 -
4.Analyzer	43 -
4.1 {YourName}Analyzer.h	43 -
4.2 {YourName} Analyzer cpn	- 45 -

I. Setting up an Analyzer Project

1. General description

The Kingst logic analyzer software supports user-defined protocol parsing.

This document is mainly divided into two parts. The first part is the steps of establishing protocol parsing engineering, and introduces how to generate the final dynamic Link Library on Windows, Linux, Mac system. The second part is the related content of coding, mainly introduces the usage of basic classes and member functions and the points needing attention in use.

2. Setting project

Before starting the next step, you should make sure that you have KingstVIS_Analyzer_SDK provided by us.

There are *inc*, *lib* folders and the sample *Uart Analyzer* in the root of *KingstVIS_Analyzer_SDK* folder. Base class header file is stored in the *Inc* folder. There are four folders of *Win32*, *Win64*, *Linux* and *Mac* in the *lib* folder, The 32-bit and 64-bit *Analizer.lib* and the Analyzer.dll are stored in the *Win32* and *Win64* folders, respectively. *libAnalyzer.dylib* is stored in *Mac*. The *UartAnalyzer* folder holds the project for the Uart Analyzer, and in the *UartAnalyzer* folder there are four folders, *SRC* and *vs2013*, *Linux*, *Mac*, and the source code for the Analyzer in the *SRC* folder; *vs2013* store the project that need to build by vs2013, you can use the project in Windows system to generate parsing required dynamic Link Library files; in Linux system, you can use *makefile* file to generate the required dynamic Link Library, which stored in the *Linux* folder; in Mac system, same to Linux, you can use *makefile* generates the required dynamic Link Library, which stored in *Mac*.

2.1 Windows

1. Take the example of generating dynamic Link Library which use to parse the Spi protocol, you can modify the project to get the Spi parser directly from the sample *Uart Analyzer*. If you want to keep the sample, you can copy it in the same directory as Figure 1, and then modify it on the "Uart Analyzer - copy";

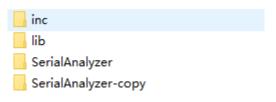


Fig.1

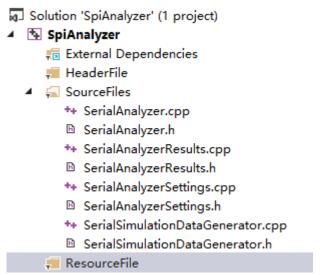
2. First, change the name of the folder, refer to the sample, change the name of the folder to Spi

Analyzer, then open the folder, replace the source file in the *src* folder with the source file suitable for parsing the Spi, we will discuss how to build the specific source file in the next chapter. and then open *vs2013* Folder, modify the two files as shown in Figure 2

- SpiAnalyzer.vcxproj
- SpiAnalyzer.vcxproj.filters

Fig.2

3. Click the *SpiAnalyzer*: *vcxproj* file shown in Figure 2 to open the project, click Source File, as shown in Figure 3, remove the existing files under the Source File. Right click the files you choose, and then Click remove, as shown in Figure 4, click in the pop-up dialog box to confirm.



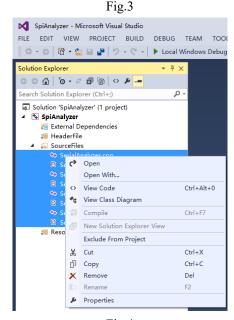


Fig.4

4. Right click on Source Files and choose Add->ExistingItem as shown in Figure 5, then open

src, make sure the c++ source files and header files to be added are all checked and then click add, as shown in Figure 6.

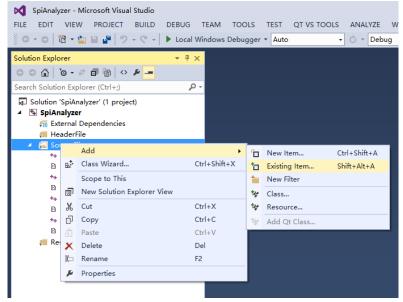


Fig.5

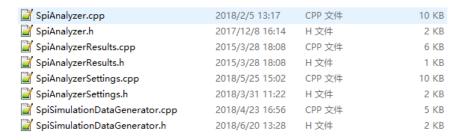


Fig.6

5. After completing the above steps, the project is set up, and the next step is to generate a 32-bit or 64-bit DLL file in Relesse mode, you can use logic analyzer software to determine which one you need, if you are using 64-bit software You need to generate 64 bits and vice versa 32 bits. You can set the DLL file's name by right click the project name ,then click Properties in the menu that appears, as shown in Figure 7 and change file name in Target file name ,as shown in Figure 8. When generating a 32-bit DLL file, firstly, configure it in Release and x86 mode, as shown in Figure 9, and then select Generate -> Generate Solution in the menu bar, as shown in Figure 9, and then select Generate -> Generate Solution in the menu bar.

- 5 -

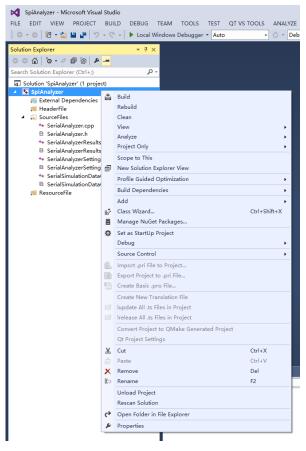


Fig.7

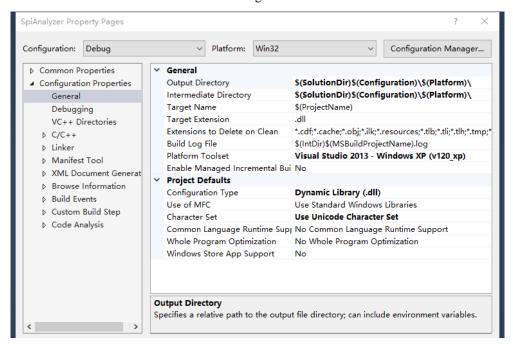


Fig.8

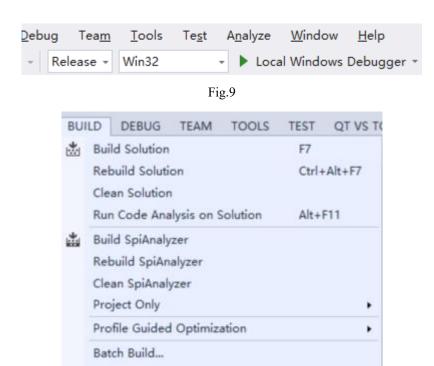


Fig.10

Configuration Manager...

- 6. After the DLL file is generated, a *Win32* folder will appear in the *Release* folder, which is in the *vs2013* folder if the 32-bit DLL file is generated; and a "x64" folder will appear in the "Release" folder if the 64-bit DLL file is generated. Copy the DLL file to the *Analyzer* folder, which was in the Logic Analyzer software installation directory. When you open the Logic Analyzer software again, the parser you write will appear in the parser list.
- 7. When you click the Save All button in the vs2013 software or close the project, you will be reminded to save a file with the suffix .sln in the vs2013 folder. When you want to open the project again, you can click this file to open it.

2.2 Linux

- 1. Take the dynamic library that generates the parsing Spi protocol as an example to explain, we can modify the project to get Spi parser directly on the basis of the sample *Uart Analyzer*. If we want to keep this sample, we can copy the sample in the same directory, and then modify it in the copied folder.
- 2. First, change the folder name to *Spi Analyzer*, then opening this folder, replacing the source file in the *src* folder with the source file suitable for parsing Spi, and then opening the *Linux* folder, open the *makefile* file, change *libUART*. so to the name you want, here to *libSPI.so*.
- 3. Open the terminal and go to the *Linux* directory, type make instructions on the terminal, then press the Enter key, in the *Linux* folder will generate the *libSPI.so* DLL file. The terminal will give a hint if you write the source code have some trouble, just modify it according to the hint.

4. Copy the generated *libSPI.so* file to the Analyzer directory of the KingstVIS software installation package, and your own parser will appear in the parser list when you open the software again.

2.3 Mac

- 1. Take the dynamic library that generates the parsing Spi protocol as an example to explain, we can modify the project to get Spi parser directly on the basis of the sample *Uart Analyzer*. If we want to keep this sample, we can copy the sample in the same directory, and then modify it in the copied folder.
- 2. First, change the folder name to *Spi Analyzer*, then opening this folder, replacing the source file in the *src* folder with the source file suitable for parsing Spi, and then opening the *MAC* folder, open the *makefile* file, change *libUART*. *so* to the name you want, here to *libSPI.so*.
- 3. Open the terminal and go to the *MAC* directory, type make instructions on the terminal, then press the Enter key, in the *MAC* folder will generate the *libSPI.so* DLL file. The terminal will give a hint if you write the source code have some trouble, just modify it according to the hint.
- 4. Copy the generated *libSPI.so* file to the Analyzer directory of the KingstVIS software installation package, and your own parser will appear in the parser list when you open the software again.

II. Writing your Analyzer's Code

There are 4 c++ files and 4 header files that you will implement to create your analyzer. You can modify the source files of the samples in the SDK package to simplify the operation.

Conceptually, the analyzer can be broken into 4 main parts – the 4 c++ files. Working on them in a particular order is highly recommended, and this document describes the procedure in this order.

First you'll work on the AnalyzerSettings-derived class. You'll define the settings your analyzer needs, and create interfaces that'll allow the Logic software to display a GUI for the settings. You'll also implement serialization for these settings so they can be saved and recalled from disk.

Next you implement the SimulationDataGenerator class. Here you'll generate simulated data that can be later to test your analyzer, or provide an example of what your analyzer expects.

Third you'll create your AnalyzerResults-derived class. This class translates saved results into text for a variety of uses. Here you'll start thinking about the format your results will be saved in. You probably will revisit your file after implementing your Analyzer.

Lastly, you'll implement your Analyzer-derived class. The main thing you'll do here is translate data streams into results, based on your protocol.

Let's get started!

To write serial protocol (such as UART) parser, for example, first create 4. CPP and 4. h files. four .cpp files are <code>SerialAnalyzer.cpp</code>, <code>SerialAnalyzerResults.cpp</code>, <code>SerialAnalyzerSettings.cpp</code>, <code>SerialSimulationDataGenerator.cpp</code>, four .h files are <code>SerialAnalyzer.h</code>, <code>SerialAnalyzerResults.h</code>, <code>SerialAnalyzerSettings.h</code>, <code>SerialSimulationDataGenerator.h</code>. Let these files be empty first, and then implement them one by one later. When writing your own parser, it is also recommended to create the file according to this naming method.

1. Analyzer Settings

Add the created 4. CPP files and 4. h files to the created project, so that a project on the parser is completed, and the next step is to complete the 8 empty files one by one.

1.1 {YourName} Analyzer Settings.h

The first thing to implement is a derived class of the Analyzer Settings class. The code to implement this derived class is written in *SerialAnalyzerSettings.cpp* and *SerialAnalyzerSettings.h*, the name of this derived class could be named SerialAnalyzerSettings, This class must inherit from *AnalyzerSettings*, and should include the *AnalyzerSettings.h* header file.

The code of SerialAnalyzerSettings.h shown as follows:

```
#ifndef SERIAL_ANALYZER_SETTINGS
#define SERIAL_ANALYZER_SETTINGS

#include <AnalyzerSettings.h>

class SerialAnalyzerSettings : public AnalyzerSettings

{
   public:
        SerialAnalyzerSettings();
        virtual ~SerialAnalyzerSettings();

        virtual bool SetSettingsFromInterfaces();
        void UpdateInterfacesFromSettings();
        virtual void LoadSettings(const char *settings);
        virtual const char *SaveSettings();
};

#endif //SERIAL ANALYZER SETTINGS
```

- 10 *2019-2-12*

In addition, your header will define two sets of variables:

1.1.1 User-modifiable settings

This will always include at least one variable of the type Channel – so the user can specify which input channel to use. This cannot be hard coded, and must be exposed as a setting. (Channel isn't just an index, it also specifies which Logic device the channel is from). Other possible settings depend on your protocol, and might include:

- Bit rate
- Bits per transfer
- Bit ordering (MSB first, LSB first)
- Clock edge (rising, falling) to use
- Enable line polarity

The variable types can be whatever you like -std::string, double, int, enum, etc. Note that these variables will need to be serialized (saved for later, to a file) so when in doubt, stick to simple types (rather than custom classes or structs). The SDK provides a means to serialize and store your variables.

The setting variables added to the SerialAnalyserSettings class are as follows:

```
Channel mInputChannel;
U32 mBitRate;
U32 mBitsPerTransfer;
AnalyzerEnums::ShiftOrder mShiftOrder;
double mStopBits;
AnalyzerEnums::Parity mParity;
bool mInverted;
bool mUseAutobaud;
SerialAnalyzerEnums::Mode mSerialMode;
```

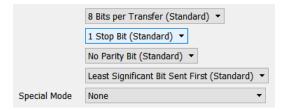
1.1.2 Analyzer Settings Interfaces

One of the services the Analyzer SDK provides is a means for users to edit your settings, with a GUI, with minimal work on your part. To make this possible, each of your settings variables must have a corresponding interface object. Here are the available *AnalyzerSettingsInterface* types:

AnalyzerSettingInterfaceChannelData: Used exclusivly for input channel selection.



AnalyzerSettingInterfaceNumberList: Provides a list of numeric options that users can select



AnalyzerSettingInterfaceInteger: For the user to enter an integer.



AnalyzerSettingInterfaceText: For the user to enter some description information words.

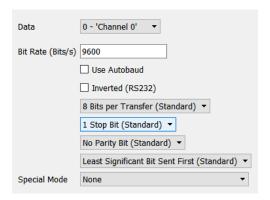
AnalyzerSettingInterfaceBool: Single box.



AnalyzerSettingInterfaceChannelData, AnalyzerSettingInterfaceNumberList,

AnalyzerSettingInterfaceInteger, AnalyzerSettingInterfaceText, AnalyzerSettingInterfaceBool all inherit from AnalyzerSettingsInterface, smart pointer was used when creating object pointers using these five classes.

For Serial, the GUI setup interface we want to implement is shown in the following figure.



So you should add the following code to the SerialAnalyserSettings class:

```
std::auto_ptr< AnalyzerSettingInterfaceChannel > mInputChannelInterface;
std::auto_ptr< AnalyzerSettingInterfaceInteger > mBitRateInterface;
std::auto_ptr< AnalyzerSettingInterfaceBool > mInvertedInterface;
std::auto_ptr< AnalyzerSettingInterfaceBool > mUseAutobaudInterface;
std::auto_ptr< AnalyzerSettingInterfaceNumberList> mBitsPerTransferInterface;
std::auto_ptr< AnalyzerSettingInterfaceNumberList > mShiftOrderInterface;
std::auto_ptr< AnalyzerSettingInterfaceNumberList > mStopBitsInterface;
```

```
std::auto_ptr< AnalyzerSettingInterfaceNumberList > mParityInterface;
std::auto_ptr< AnalyzerSettingInterfaceNumberList > mSerialModeInterface;
```

After adding the above code to the SerialAnalyserSettings class, the code in *SerialAnalyserSettings.h* is written.

1.2 {YourName}AnalyzerSettings.cpp

After completing the contents of the *SerialAnalyserSettings.h* file, you need to complete the *SerialAnalyserSettings.cpp* file, which is to implement the constructors, destructors, etc. in the SerialAnalyserSettings class.

1.2.1 The Constructor

First of all, we need to complete the compilation of the constructor. In the constructor, we need to initialize the variable. For the parser Serial, the code for initializing the variable is written as follows:

```
SerialAnalyzerSettings::SerialAnalyzerSettings()
: mInputChannel(UNDEFINED_CHANNEL),
    mBitRate(9600),
    mBitsPerTransfer(8),
    mStopBits(1.0),
    mParity(AnalyzerEnums::None),
    mShiftOrder(AnalyzerEnums::LsbFirst),
    mInverted(false),
    mUseAutobaud(false),
    mSerialMode(SerialAnalyzerEnums::Normal)
    {
    }
}
```

After initializing the variable, the member function reset is called to complete the creation of the interface.

AnalyzerSettingInterfaceChannelData

```
mInputChannelInterface.reset(new AnalyzerSettingInterfaceChannel());
```

Next, we call the member function SetTitleAndTooltip. The title will appear to the left of the input element. Note that often times you won't need a title, but you should use one for Channels. The tooltip shows up when hovering over the input element.

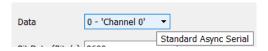
```
void SetTitleAndTooltip(const char *title, const char *tooltip)
```

Kingst VIS Analyzer SDK

For example, for the serial channel setting interface, the following settings can be made.

```
mInputChannelInterface->SetTitleAndTooltip("Data", "Standard Async Serial");
```

The interface name is Data and the prompt message is Standard Async Serial.



Next, we use the SetChannel function to set the channel.

```
void SetChannel(const Channel &channel);
mInputChannelInterface->SetChannel(mInputChannel);
```

And we can use GetChannel function to get channel number;

```
Channel GetChannel();
```

Sometimes the channel can be set to None, means that it can not be connected to one channel of the logic analyzer. This situation will only occurs under multiple channels, and an input channel must be set when the protocol is single line.

For example, when parsing SPI protocol, set channel selection, as shown in the following figure



This means "enable" may not be connected to the logic analyzer.

We'll want to specify the allowable options. This depends on the type of interface.

```
void SetSelectionOfNoneIsAllowed(bool is_allowed);
```

You can get whether the channel is allowed to be set to none by calling the getSelectionOfNoneISallowed function.

```
void GetSelectionOfNoneIsAllowed(bool is_allowed);
```

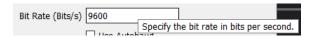
AnalyzerSettingInterfaceInteger

```
mBitRateInterface.reset(new AnalyzerSettingInterfaceInteger());
```

Call the SetitLeandToolTip function to set the interface name and prompt information

```
mBitRateInterface->SetTitleAndTooltip("Bit Rate (Bits/s)", "Specify the bit rate in bits per
```

```
second.");
```



This number to be entered must be an integer. You can set the range of input numbers by calling the SetMax and SetMin functions.

```
void SetMax(int max);
void SetMin(int min);
mBitRateInterface->SetMax(100000000);
mBitRateInterface->SetMin(1);
```

With the above settings, the input data range is limited to an integer between 10000000 and 1. Setting the input data can be achieved by calling Set Integer.

```
void SetInteger(int integer);
mBitRateInterface->SetInteger(mBitRate);
```

Input data can be obtained by calling the Get Integer function.

```
int GetInteger();
```

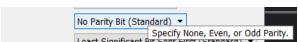
AnalyzerSettingInterfaceNumberList

Explains the use of the Analyzer SettingInterfaceNumberList class with how to set parity in the Serial parser.

```
mParityInterface.reset(new AnalyzerSettingInterfaceNumberList());
```

Then set the interface name and prompt information, and also call SetitLeandToolTip.

```
mParityInterface->SetTitleAndTooltip("", "Specify None, Even, or Odd Parity.");
```



Add a selection to the interface drop-down list by calling Add Number.

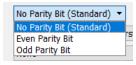
```
void AddNumber(double number, const char *str, const char *tooltip);
```

This function has three input parameters, Number is associated with the selection and will not be displayed to the user. STR is the name of the selection and will appear in the list; Tooltip is a prompt message that will appear when the mouse hovers over the selection item. This function has not been implemented in the current software, so you can not enter a prompt message.

```
mParityInterface->AddNumber(AnalyzerEnums::None, "No Parity Bit (Standard)", "");
mParityInterface->AddNumber(AnalyzerEnums::Even, "Even Parity Bit", "");
mParityInterface->AddNumber(AnalyzerEnums::Odd, "Odd Parity Bit", "");
```

When the selection item you want to set is selected in the list, the set number is saved by calling the setnumber function.

mParityInterface->SetNumber(mParity);



The value set by setnumber can be obtained by the getnumber function.

```
double GetNumber();
```

AnalyzerSettingInterfaceBool

Here is an example of setting whether the serial parser enables the automatic baud rate to show how to use the AnalyzerSettingInterfaceBool class, which is also to first create a pointer to the AnalyzerSettingInterFacebool and call the reset function.

```
mUseAutobaudInterface.reset(new AnalyzerSettingInterfaceBool());
```

Set the interface name and prompt information.

```
mUseAutobaudInterface->SetTitleAndTooltip("", "Automatically find the minimum pulse width and
calculate the baud rate according to this pulse width.");
```

You can call the SetCheckBoxText function to give the selection box a name, and the name set by the SetCheckBoxText function is displayed on the right side of the selection box.

```
void SetCheckBoxText(const char *text);
mUseAutobaudInterface->SetCheckBoxText("Use Autobaud");
```

Call the setvalue function to enable this radio box setting item.

```
void SetValue(bool value);
mUseAutobaudInterface->SetValue(mUseAutobaud);
```

The GetValue function can be used to obtain whether to enable the selection box setting item.

```
bool GetValue();
```

After creating our interfaces (with new), giving them a titles, settings their values, and specifying their allowed options, we need to expose them to the API. We do that with function AddInterface.

```
void AddInterface(AnalyzerSettingInterface *analyzer_setting_interface);
```

The following parameters need to be passed

```
AddInterface(mInputChannelInterface.get());
AddInterface(mBitRateInterface.get());
AddInterface(mUseAutobaudInterface.get());
AddInterface(mInvertedInterface.get());
AddInterface(mBitsPerTransferInterface.get());
AddInterface(mStopBitsInterface.get());
AddInterface(mParityInterface.get());
AddInterface(mShiftOrderInterface.get());
AddInterface(mShiftOrderInterface.get());
```

Specifing the export options

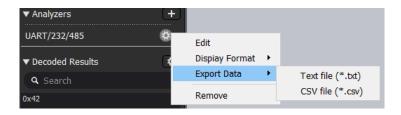
Analyzers can offer more than one export type. For example txt or csv, or even a wav file or bitmap. If these need special settings, they can be specified as analyzer variables/interfaces as we've discussed.

Export options are assigned an ID. Later, when your function for generating export data is called, this ID will be provided. There are two functions you'll need to call to specify an export type. Be sure to specify at least one export type (tyically text/csv).

```
void AddExportOption(U32 user_id, const char *menu_text);
void AddExportExtension(U32 user_id, const char *extension_description, const char *extension);
```

user_id means a specify ID, extension_description means the output file's type that we want, extension means Suffix.

```
AddExportOption(0, "Export as text/csv file");
AddExportExtension(0, "Text file", "txt");
AddExportExtension(0, "CSV file", "csv");
```



Specifying which channels are in use

The analyzer must indicate which channel(s) it is using. This is done with the AddChannel function. Every time the channel changes (such as when the user changes the channel) the reported channel

must be updated. To clear any previous channels that have been set, call ClearChannels.

```
void ClearChannels();
void AddChannel(Channel &channel, const char *channel_label, bool is_used);
ClearChannels();
AddChannel(mInputChannel, CHANNEL_NAME, false);
```

Note that in the constructor, we have set *is_used* to false. This is because by defualt our channel is set to *UNDEFINED_CHANNEL*. After the user has set the channel to something other that *UNDEFINED_CHANNEL*, we would specify true. It would always be true, unless the channel was optional, in which case you will need to examine the channel value, and specify false if the channel is set to *UNDEFINED CHANNEL*. We'll discuss this later as it comes up.

1.2.2 The Destructor

Generally you won't need to do anything in your AnalyzerSettings-derived class's destructo.

1.2.3 bool {YourName} AnalyzerSettings::SetSettingsFromInterfaces()

As the name implies, in this function we will copy the values saved in our interface objects to our settings variables. This function will be called if the user updates the settings.

We can also examine the values saved in the interface (the user's selections) and choose to reject combinations we don't want to allow. If you want to reject a particular selection, do not assign the values in the interfaces to your settings variables – use temporary variables so you can choose not to assign them at the last moment. To reject a user's selections, return false; otherwise return true. If you return false (reject the user's settings), you also need to call *SetErrorText* to indicate why. This will be presented to the user in a popup dialog.

```
void SetErrorText(const char *error_text);
```

For example, when using more than one channel, you would typically want to make sure that all the channels are different. You can use the AnalyzerHelpers::DoChannelsOverlap function to make that easier if you like.

For your analyzer, it's quite possible that all possible user selections are valid. In that case you can ignore the above.

After assigning the interface values to your settings variables, you also need to update the channel(s) the analyzer will report as being used. Below is an example from *SimpleSerialAnalyzerSettings*.

```
bool SerialAnalyzerSettings::SetSettingsFromInterfaces()
{
    if( AnalyzerEnums::Parity(U32(mParityInterface->GetNumber())) != AnalyzerEnums::None)
    if( SerialAnalyzerEnums::Mode(U32( mSerialModeInterface->GetNumber())) !=
```

1.2.4 void {YourName} AnalyzerSettings::UpdateInterfacesFromSettings()

UpdateInterfacesFromSettings goes in the opposite direction. In this function, update all your interfaces with the values from your settings variables. Below is an example from SimpleSerialAnalyzerSettings.

```
void SerialAnalyzerSettings::UpdateInterfacesFromSettings()
{
    mInputChannelInterface->SetChannel(mInputChannel);
    mBitRateInterface->SetInteger(mBitRate);
    mBitsPerTransferInterface->SetNumber(mBitsPerTransfer);
    mStopBitsInterface->SetNumber(mStopBits);
    mParityInterface->SetNumber(mParity);
    mShiftOrderInterface->SetNumber(mShiftOrder);
    mInvertedInterface->SetValue(mInverted);
    mUseAutobaudInterface->SetValue(mUseAutobaud);
    mSerialModeInterface->SetNumber(mSerialMode);
}
```

1.2.5 void {YourName} AnalyzerSettings::LoadSettings(const char *settings)

In the last to functions of your AnalyzerSettings-derived class, you'll implement serialization (persistence) of your settings. It's pretty straightforward. Your settings are saved in, and loaded from, a single string. You can technically serialize all of your variables into a string anyway you like, including third part libraries like boost, but to keep things simple we provided a mechanism to serialize your variables. We'll discuss that here.

First, you'll need a *SimpleArchive* object. This will perform serialization for us. Use *SetString* to provide the archive with our settings string. This string is passed in as a parameter to *LoadSettings*.

```
struct SimpleArchiveData;
class LOGICAPI SimpleArchive
public:
     SimpleArchive();
     ~SimpleArchive();
     void SetString(const char *archive_string);
     const char *GetString();
     bool operator<<(U64 data);</pre>
     bool operator<<(U32 data);</pre>
     bool operator<<(S64 data);</pre>
     bool operator<<(S32 data);</pre>
     bool operator<<(double data);</pre>
     bool operator<<(bool data);</pre>
     bool operator<<(const char *data);</pre>
     bool operator<<(Channel &data);</pre>
     bool operator>>(U64 &data);
     bool operator>>(U32 &data);
     bool operator>>(S64 &data);
     bool operator>>(S32 &data);
     bool operator>>(double &data);
     bool operator>>(bool &data);
     bool operator>>(char const **data);
     bool operator>>(Channel &data);
protected:
     struct SimpleArchiveData *mData;
```

- 20 *2019-2-12*

};

Next we will use the archive to loaf all of our settings variables, using the overloaded >> operator.

Since our channel values may have changed, we will also need to update the channels we're reporting as using. We need to do this every times settings change.

Lastly, call *UpdateInterfacesFromSettings*. This will update all our interfaces to reflect the newly loaded values.

Below is an example from SimpleSerialAnalzerSettings.

```
void SerialAnalyzerSettings::LoadSettings(const char *settings)
{
     SimpleArchive text_archive;
     text_archive.SetString(settings);
     const char *name_string;
     text_archive >> &name_string;
     if(strcmp(name_string, "KingstUartAnalyzer") != 0)
           AnalyzerHelpers::Assert("KingstUartAnalyzer: Provided with a settings string that
  doesn't belong to us;");
     text_archive >> mInputChannel;
     text_archive >> mBitRate;
     text_archive >> mBitsPerTransfer;
     text_archive >> mStopBits;
     text_archive >> *(U32*)&mParity;
     text_archive >> *(U32*)&mShiftOrder;
     text_archive >> mInverted;
     bool use_autobaud;
     if(text_archive >> use_autobaud)
           mUseAutobaud = use autobaud;
     SerialAnalyzerEnums::Mode mode;
     if(text_archive >> *(U32*)&mode)
           mSerialMode = mode;
     ClearChannels();
     AddChannel(mInputChannel, CHANNEL_NAME, true);
```

- 21 *2019-2-12*

```
UpdateInterfacesFromSettings();
}
```

1.2.6 void {YourName} AnalyzerSettings::SaveSettings()

Our last function will save all of our settings variables into a single string. We'll use SimpleArchive to serialize them.

The order in which we serialize our settings variables must be exactly the same order as we extract them, in LoadSettings.

When returning, use the SetReturnString function, as this will provide a pointer to a string that will not go out of scope when the function ends.

Bellow is an example from SimpleSerialAnalyzerSettings: .

```
const char *SerialAnalyzerSettings::SaveSettings()
{
    SimpleArchive text_archive;

    text_archive << "KingstUartAnalyzer";
    text_archive << mInputChannel;
    text_archive << mBitRate;
    text_archive << mBitsPerTransfer;
    text_archive << mStopBits;
    text_archive << mParity;
    text_archive << mInverted;
    text_archive << mInverted;
    text_archive << mUseAutobaud;
    text_archive << mSerialMode;

return SetReturnString(text_archive.GetString());
}</pre>
```

2. Simulation Data Generator

The next step after creating your {YourName}AnalyzerSettings files, is to create your SimulationDataGenerator class, and you need to complete { YourName } SimulationDataGenerator.h and { YourName } SimulationDataGenerator.cpp.

Your SimulationDataGenerator class provides simulated data so that you can test your analyzer against controlled, predictable waveforms. Generally you should make the simulated data match the user settings, so you can easily test under a variety of expected conditions. In addition, simulated data gives end users an example of what to expect when using your analyzer, as well as examples of what the

waveforms should look like.

2.1 {YourName}SimulationDataGenerator.h

Besides the constructor and destructor, there are only two required functions, and two required variables. Other functions and variables can be added, to help implement your simulated data. Here is an example starting point, from *SimpleSerialSimulationDataGenerator.h.*

```
#ifndef SERIAL_SIMULATION_DATA_GENERATOR
#define SERIAL_SIMULATION_DATA_GENERATOR
#include <AnalyzerHelpers.h>
class SerialAnalyzerSettings;
class SerialSimulationDataGenerator
public:
     SerialSimulationDataGenerator();
     ~SerialSimulationDataGenerator();
     void Initialize(U32 simulation_sample_rate, SerialAnalyzerSettings *settings);
     U32 GenerateSimulationData(U64 newest_sample_requested, U32 sample_rate,
           SimulationChannelDescriptor **simulation_channelss);
protected:
     SerialAnalyzerSettings *mSettings;
     U32 mSimulationSampleRateHz;
     BitState mBitLow;
     BitState mBitHigh;
     U64 mValue;
     U64 mMpModeAddressMask;
     U64 mMpModeDataMask;
     U64 mNumBitsMask;
protected: //Serial specific
     void CreateSerialByte(U64 value);
```

```
ClockGenerator mClockGenerator;
    SimulationChannelDescriptor mSerialSimulationData;
};
#endif //UNIO_SIMULATION_DATA_GENERATOR
```

The key to the SimulationDataGenerator is the class SimulationChannelDescriptor. You will need one of these for every channel you will be simulated (serial, for example, only needs to simulate on one channel). When your GenerateSimulationData function is called, your job will be to generate additional simulated data, up to the amount requested. When complete, you provide the caller with a pointer to an array of your SimulationChannelDescriptor objects.

2.2 {YourName}SimulationDataGenerator.cpp

2.2.1 Constructor / Destructor

You may or may not need anything in your constructor or destructor. For now at least, leave them empty. At the time we're constructed, we really have no idea what the settings are or anything else, so there's not much we can do at this point.

2.2.2 void {YourName}SimulationDataGenerator::Initialize(U32 simulation_sample_rate, {YourName}AnalyzerSettings *settings)

This function provides you with the state of things as they are going to be when we start simulating. We'll need to save this information.

First, save simulation_sample_rate and settings to member variables. Notice that we now have a pointer to our AnalyzerSettings-derived class. This is good, now we know what all the settings will be for our simulation – which channel(s) it will be on, as well as any other settings we might need – like if the signal is inverted, etc.

Next, we'll want to initialize the state of our SimulationChannelDescriptor objects – we need to set what channel it's for, the sample rate, and the initial bit state (high or low).

At this point we'll need to take a step back and discuss some key concepts.

BitState

BitState is a type used often in the SDK. It can be either BIT_LOW or BIT_HIGH, and represents a channel's logic state.

Sample Rate (samples per second)

Sample Rate refers to how many samples per second the data is. Typically it refers to how fast we're collecting data, but for simulation, it refers to how fast we're generating sample data.

Sample Number

This is the absolute sample number, starting at sample 0. When a data collection starts, the first sample collected is Sample Number 0. The next sample collected is Sample Number 1, etc. This is the same in simulation. The first sample we'll provide is Sample Number 0, and so on.

SimulationChannelDescriptor

We need this object to describe a single channel of data, and what its waveform looks like. We do this in a very simple way:

We provide the initial state of the channel (BIT LOW, or BIT HIGH)

We move forward some number of samples, and then toggle the channel.

The initial bit state of the channel never changes. The state (high or low) of a particular sample number can be determined by knowing how many times it has toggled up to that point (an even or odd number of times).

Put another way:

- In the very beginning, we specify the initial state (BIT_LOW or BIT_HIGH). This is the state of Sample Number 0.
- Then, we move forward (advance) some number of samples. 20 samples, for example.
- Then, we toggle the channel (low becomes high, high becomes low).
- Then we move forward (advance) some more. Maybe 100 samples this time.
- Then we toggle again.
- Then we move forward again, and then we toggle again, etc.

Let's explore the functions used to do this:

```
void Advance(U32 num_samples_to_advance);
```

As you might guess, this is how we move forward in our simulated waveform. Internally, the object keeps track of what its Sample Number is. The Sample Number starts at 0. After calling Advance (10) x3 times, the Sample Number will be 30.

```
void Transition();
```

This toggles the channel. BIT_LOW becomes BIT_HIGH, BIT_HIGH becomes BIT_LOW. The current Sample Number will become the new BitState (BIT_LOW or BIT_HIGH), and all samples after that will also be the new BitState, untill we toggle again.

```
void TransitionIfNeeded(BitState bit_state);
```

Often we don't want to keep track of the current BitState, which toggles every time we call Transition.

TransitionIfNeeded checks the current BitState, and only transitions if the current BitState doesn't match the one we provide. In other words "Change to this bit state, if we're not already".

```
BitState GetCurrentBitState();
```

This function lets you directly ask what the current BitState is.

```
U64 GetCurrentSampleNumber();
```

This function lets you ask what the current SampleNumber is.

ClockGenerator

ClockGenerator is a class provided in *AnalyzerHelpers.h* which will let you enter time values, rather than numbers-of-samples.

First, create an object using the ClockGenerator class, and then call the init function to initialize it

```
void Init(double target_frequency, U32 sample_rate_hz);
```

You'll need to call this before using the class. For sample_rate_hz, enter the sample rate we'll be generating data at. For target_frequency, enter the frequency (in hz) you will most commonly be using. For example, the bit rate of a SPI clock, etc.

```
U32 AdvanceByHalfPeriod(double multiple = 1.0);
```

This function returns how many samples are needed to move forward by one half of the period (for example, the low time for a perfect square wave). You can also enter a multiple. For exaple, to get the number of samples to move forward for a full period, enter 2.0.

```
U32 AdvanceByTimeS(double time_s);
```

This functions provides number of samples needed to advance by the arbitrary time, *time_s*. Note that this is in seconds, so enter 1E-6 for for one microsecond, etc.

Let's take a look at an example in SerialSimulationDataGenerator.cpp

```
void SerialSimulationDataGenerator::Initialize(U32 simulation_sample_rate, SerialAnalyzerSettings
*settings)

{
    mSimulationSampleRateHz = simulation_sample_rate;
    mSettings = settings;

mClockGenerator.Init(mSettings->mBitRate, simulation_sample_rate);
    mSerialSimulationData.SetChannel(mSettings->mInputChannel);
    mSerialSimulationData.SetSampleRate(simulation_sample_rate);

if(mSettings->mInverted == false) {
```

```
mBitLow = BIT_LOW;
           mBitHigh = BIT_HIGH;
     } else {
           mBitLow = BIT_HIGH;
           mBitHigh = BIT_LOW;
     }
     mSerialSimulationData.SetInitialBitState(mBitHigh);
     mSerialSimulationData.Advance(mClockGenerator.AdvanceByHalfPeriod(10.0));
//insert 10 bit-periods of idle
     mValue = 0;
     mMpModeAddressMask = 0;
     mMpModeDataMask = 0;
     mNumBitsMask = 0;
     U32 num bits = mSettings->mBitsPerTransfer;
     for(U32 i = 0; i < num_bits; i++) {</pre>
           mNumBitsMask <<= 1;
           mNumBitsMask |= 0x1;
     }
     if( mSettings->mSerialMode == SerialAnalyzerEnums::MpModeMsbOneMeansAddress )
           mMpModeAddressMask = 0x1ull << (mSettings->mBitsPerTransfer);
     if( mSettings->mSerialMode == SerialAnalyzerEnums::MpModeMsbZeroMeansAddress )
           mMpModeDataMask = 0x1ull << (mSettings->mBitsPerTransfer);
}
2.2.3 U32 {YourName}SimulationDataGenerator::GenerateSimulationData(U64
largest_sample_requested, U32sample_rate, SimulationChannelDescriptor
**simulation_channels)
```

This function is repeatedly called to request more simulated data. When it's called, just keep going where you left off. In addition, you can generate more data that requested, to make things easy -- that way you don't have to stop half way in the middle of something and try to pick it back up later exactly where you left off.

When we leave the function, our Sample Number - in our SimulationChannelDecriptor object(s) must be

equal to or larger than largest_sample_requested. Actually, this number needs to first be adjusted (for technical reasons related to future compatibility). Use the helper function AdjustSimulationTargetSample to do this, as we'll see in a moment.

The parameter *simulation_channels* is to provide the caller with a pointer to an array of your *SimulationChannelDecriptor* objects. We'll set this pointer at the end of the function. The return value is the number of elements in the array – the number of channels.

The following is an example of SerialSimulationDataGenerator.cpp:

```
U32 SerialSimulationDataGenerator::GenerateSimulationData(U64 largest_sample_requested, U32
sample rate, SimulationChannelDescriptor **simulation channels)
          U64 adjusted_largest_sample_requested =
mSimulationSampleRateHz);
       while(mSerialSimulationData.GetCurrentSampleNumber() < adjusted_largest_sample_requested) {</pre>
               if(mSettings->mSerialMode == SerialAnalyzerEnums::Normal) {
                     CreateSerialByte( mValue++ );
                mSerialSimulationData.Advance(mClockGenerator.AdvanceByHalfPeriod(10.0));
     //insert 10 bit-periods of idle
               } else {
                    U64 address = 0x1 | mMpModeAddressMask;
                     CreateSerialByte(address);
                     for(U32 i=0; i<4; i++) {</pre>
                          \verb|mSerialSimulationData.Advance(mClockGenerator.AdvanceByHalfPeriod(2.0));|\\
//insert 2 bit-periods of idle
                          CreateSerialByte((mValue++ & mNumBitsMask) | mMpModeDataMask);
                     };
                    mSerialSimulationData.Advance(mClockGenerator.AdvanceByHalfPeriod(20.0));
//insert 20 bit-periods of idle
                     address = 0x2 | mMpModeAddressMask;
                     CreateSerialByte(address);
                     for(U32 i=0; i<4; i++) {</pre>
```

```
\verb|mSerialSimulationData.Advance(mClockGenerator.AdvanceByHalfPeriod(2.0));|\\
//insert 2 bit-periods of idle
                           CreateSerialByte((mValue++ & mNumBitsMask) | mMpModeDataMask);
                      };
                      mSerialSimulationData.Advance(mClockGenerator.AdvanceByHalfPeriod(20.0));
//insert 20 bit-periods of idle
                }
           }
           *simulation_channels = &mSerialSimulationData;
           return 1; // we are retuning the size of the SimulationChannelDescriptor array. In
     our case, the "array" is length 1.
     void SerialSimulationDataGenerator::CreateSerialByte(U64 value)
     {
           //assume we start high
           mSerialSimulationData.Transition(); //low-going edge for start bit
           mSerialSimulationData.Advance(mClockGenerator.AdvanceByHalfPeriod()); //add
     start bit time
           if(mSettings->mInverted == true)
                value = ~value;
           U32 num_bits = mSettings->mBitsPerTransfer;
           if(mSettings->mSerialMode != SerialAnalyzerEnums::Normal)
                num_bits++;
           BitExtractor bit_extractor(value, mSettings->mShiftOrder, num_bits);
           for(U32 i=0; i<num bits; i++) {</pre>
                mSerialSimulationData.TransitionIfNeeded(bit_extractor.GetNextBit());
                mSerialSimulationData.Advance(mClockGenerator.AdvanceByHalfPeriod());
           }
           if(mSettings->mParity == AnalyzerEnums::Even) {
                if( AnalyzerHelpers::IsEven(AnalyzerHelpers::GetOnesCount(value)) == true)
                      mSerialSimulationData.TransitionIfNeeded(mBitLow); //we want to add a zero bit
```

- 29

There are a few things we could do to clean this up. First, we could save the *samples_per_bit* as a member variable, and compute it only once, in the *Initialize* function. If we wanted to be more accurate, we could use the *ClockGenerator* class to pre-populate an array of *samples_per_bit* values, so on average the timing would be perfect. We would use this as a lookup each time we *Advance* one bit. Another thing we could do is use the *DataExtractor* class to take care of the bit masking/testing. However, in our simple example what we have works well enough, and it has the advantage of being a bit more transparent.

2.2.4 Simulating Multiple Channels

Simulating multiple channels requires multiple *SimulationChannelDescriptors*, and they must be in an array. The best way to this is to use the helper class, *SimulationChannelDescriptorGroup*.

Here is an example of I2C (2 channels)—these are the member variable definitions in *I2cSimulationDataGenerator.h*:

```
SimulationChannelDescriptorGroup mI2cSimulationChannels;
SimulationChannelDescriptor *mSda;
SimulationChannelDescriptor *mScl;

Then, in the Initialize function:

mSda = mI2cSimulationChannels.Add(settings->mSdaChannel, mSimulationSampleRateHz, BIT_HIGH);
mScl = mI2cSimulationChannels.Add(settings->mSclChannel, mSimulationSampleRateHz, BIT_HIGH);
```

And to provide the array to the caller of GenerateSimulationData:

```
*simulation_channels = mI2cSimulationChannels.GetArray();
return mI2cSimulationChannels.GetCount();
```

You can use each *SimulationChannelDescriptor* object pointer separately, calling *Advance*, *Transition*, etc on each one, or you can manipulate them as a group, using the AdvanceAll method of the *SimulationChannelDescriptorGroup* object.

```
void AdvanceAll(U32 num_samples_to_advance);
```

Before returning from *GenerateSimulationData*, be sure that the Sample Number of *all* of your *SimulationChannelDescriptor* objects exceed *adjusted largest sample requested*.

Examples of generating simulation data:

```
U32 I2cSimulationDataGenerator::GenerateSimulationData(U64 largest_sample_requested, U32
sample_rate, SimulationChannelDescriptor **simulation_channels)
     {
            U64 adjusted_largest_sample_requested =
            AnalyzerHelpers::AdjustSimulationTargetSample(largest_sample_requested, sample_rate,
            mSimulationSampleRateHz);
          while(mScl->GetCurrentSampleNumber() < adjusted_largest_sample_requested) {</pre>
           mI2cSimulationChannels.AdvanceAll(mClockGenerator.AdvanceByHalfPeriod(500));
                if(rand() % 20 == 0) {
                     CreateStart();
                      CreateI2cByte(0x24, I2C_NAK);
                     CreateStop();
                     mI2cSimulationChannels.AdvanceAll(mClockGenerator.AdvanceByHalfPeriod(80));
                }
                CreateI2cTransaction(0xA0, I2C_WRITE, mValue++ + 12);
                mI2cSimulationChannels.AdvanceAll(mClockGenerator.AdvanceByHalfPeriod(80));
                CreateI2cTransaction(0xA0, I2C_READ, mValue++ - 43 + (rand() % 100 ));
                mI2cSimulationChannels.AdvanceAll(mClockGenerator.AdvanceByHalfPeriod(50));
                CreateI2cTransaction(0x24, I2C_READ, mValue++ + (rand() % 100));
                mI2cSimulationChannels.AdvanceAll(mClockGenerator.AdvanceByHalfPeriod(2000)); //insert
20 bit-periods of idle
```

- 31 *2019-2-12*

```
CreateI2cTransaction(0x24, I2C_READ, mValue++ + 16 + (rand() % 100 ));

mI2cSimulationChannels.AdvanceAll(mClockGenerator.AdvanceByHalfPeriod(100));

}

*simulation_channels = mI2cSimulationChannels.GetArray();
return mI2cSimulationChannels.GetCount();
}
```

Note that above we use a number of helper functions and classes. Let's discuss BitExtractor brie

BitExtractor

```
BitExtractor( U64 data, AnalyzerEnums::ShiftOrder shift_order, U32 num_bits );
BitState GetNextBit();
```

Some protocols have variable numbers of bits per word, and settings for if the most significant bit is first or last. This can be a pain to manage, so we made the *BitExtraxtor* class. This can be done by hand of course if you like, but this class tends to tidy up the code quite a bit in our experiece.

Similar, but reveresed, is the *DataBuilder* class, but as this generally used for collecting data, we'll talk more about it then.

AnalyzerHelpers

Some static helper functions that might be helpful, include:

```
static bool IsEven(U64 value);
Parity check
static bool IsOdd(U64 value);
Odd parity check
static U32 GetOnesCount(U64 value);
Get data bits
```

3. AnalyzerResults

After creating your SimulationDataGenerator class, working on your {YourName}AnalyzerResults files is the next step.

AnalyzerResults is what we use to transform our results into text for display and as well as exported files, etc.

Tip: You may end up finalizing may of the details about how your results are saved when you work

on your main Analyzer file – {YourName}Analyzer.cpp/.h; You can simply implement the bare minimum of the functions in your {YourName}AnalyzerResults.cpp file, and come back to it later.

3.1 {YourName} AnalyzerResults.h

In addition to the constructor and destructor, there are 5 functions we'll need to implement.

Here's the *SimpleSerialAnalyzerResults* header file. Yours will like very similar, with the only difference typically being the *enums* and/or *defines* you need.

```
ifndef SERIAL_ANALYZER_RESULTS
     #define SERIAL_ANALYZER_RESULTS
     #include <AnalyzerResults.h>
     #define FRAMING_ERROR_FLAG (1 << 0)
     #define PARITY_ERROR_FLAG (1 << 1)</pre>
     #define MP_MODE_ADDRESS_FLAG (1 << 2)</pre>
     class SerialAnalyzer;
     class SerialAnalyzerSettings;
     class SerialAnalyzerResults : public AnalyzerResults
     public:
           SerialAnalyzerResults(SerialAnalyzer *analyzer, SerialAnalyzerSettings *settings);
           virtual ~SerialAnalyzerResults();
           virtual void GenerateBubbleText(U64 frame_index, Channel &channel, DisplayBase
display_base);
           virtual void GenerateExportFile(const char *file, DisplayBase display_base, U32
export_type_user_id);
           virtual void GenerateFrameTabularText(U64 frame_index, DisplayBase display_base);
           virtual void GeneratePacketTabularText(U64 packet id, DisplayBase display base);
           virtual void GenerateTransactionTabularText(U64 transaction_id, DisplayBase display_base);
     protected: //functions
     protected: //vars
           SerialAnalyzerSettings *mSettings;
           SerialAnalyzer *mAnalyzer;
```

```
#endif //SERIAL_ANALYZER_RESULTS
```

3.2 {YourName} AnalyzerResults.cpp

3.2.1 Constructors and analytic functions

In your constructor, save copies of the Analyzer and Settings raw pointers provided. There's generally nothing else to do for the constructor or destructor. Below is an example from SimpleSerialAnalyzerResults.cpp:

```
SerialAnalyzerResults::SerialAnalyzerResults(SerialAnalyzer *analyzer, SerialAnalyzerSettings

*settings)

: AnalyzerResults(),
    mSettings(settings),
    mAnalyzer(analyzer)

{
  }
  SerialAnalyzerResults::~SerialAnalyzerResults()

{
  }
}
```

The basic result an analyzer generates is called a *Frame*. This could be byte of serial data, the header of a CAN packet, the MOSI and MISO values from 8-bit of SPI, etc. Smaller elements, such the Start and Stop events in I2C can be saved as *Frames*, are probably better saved as be graphical elements (called *Markers*) and otherwise ignored. *Collections* of Frames make up *Packets*, and collections of *Packets* make up *Transactions*.

95% of what you will be concerned about is *Frames*. What exactly a *Frame* represents is your choice, but unless your protocol is fairly complicated (such as USB, CAN, Ethernet) the best bet is to make the Frame your main result element.

We'll get into more detail regarding how to save your results when we describe to your *Analyzer-derived* class.

Frame

A *Frame* is an object, with fairly generic member variables which can be used to save results. Here is the definition of a *Frame*:

```
class LOGICAPI Frame
{
```

```
public:
    Frame();
    Frame( const Frame &frame );
    ~Frame();
    S64 mStartingSampleInclusive;
    S64 mEndingSampleInclusive;
    U64 mData1;
    U64 mData2;
    U8 mType;
    U8 mFlags;
};
```

A *Frame* represents a piece of information conveyed by your protocol over an expanse of time. The member variables *mStartingSampleInclusive* and *mEndingSampleInclusive* are the sample numbers for the beginning and end of the *Frame*. Note that Frames may not overlap; they cannot even share the same sample. For example, if a single clock edge ends one Frame, and starts a new Frame, then you'll need to add one (+1) to the *mStartingSampleInclusive* of the second frame.

In addition, the *Frame* can carry two 64-bit numbers as data. For example, in SPI, one of these is used for the MISO result, and the other for the MISO result. Often times you'll only use one of these variables.

The mType variable is intended to be used to save a custom-defined enum value, representing the type of Frame. For example, CAN can have many different types of frames – header, data, CRC, etc. Serial only has one type, and it doesn't use this member variable.

mFlags is intended to be a holder for custom flags which might apply to frame. Note that this is not intended for use with a custom an enum, but rather for individual bits that can be or'ed together. For example, in Serial, there is a flag for framing-error, and a flag for parity error.

```
#define FRAMING_ERROR_FLAG (1 << 0)
#define PARITY_ERROR_FLAG (1 << 1)</pre>
```

Two flags are reserved by the system, and will produce an error or warning indication on the bubble displaying the *Frame*.

```
#define DISPLAY_AS_ERROR_FLAG (1 << 7)
#define DISPLAY_AS_WARNING_FLAG (1 << 6)</pre>
```

3.2.2 void {YourName} AnalyzerResults::GenerateBubbleText(U64 frame_index, Channel &channel, DisplayBase display_base)

GenerateBubbleText exists to retrieve text to put in a bubble to be displayed on the screen. If you like you can leave this function empty, and return to it after implementing the rest of your analyzer.

The *frame_index* is the index to use to get the Frame itself – for example:

```
Frame frame = GetFrame(frame index);
```

Rarely, an analyzer needs to display results on more than one channel (SPI is the only example of this in an analyzer we make). If so, the channel which is requesting the bubble is specified in the channel parameter.

display_base specifies the radix (hex, decimal, binary) that any numerical values should be displayed in. There are some helper functions provided so you should never have to deal directly with this issue.

```
enum DisplayBase { Binary, Decimal, Hexadecimal, ASCII , AsciiHex};

AnalyzerHelpers::GetNumberString(U64 number, DisplayBase display_base, U32 num_data_bits, char
*result_string, U32 result_string_max_length);
```

In *GetNumberString*, above, note that *num_data_bits* is the number of bits which are actually part of your result. For sample, for I2C, this is always 8. It will depend on your protocol and possibly on user settings. Providing this will let *GetNumberString* produce a well-formatted number with the right amount of zero-padding for the type of value under consideration.

Bubbles can display different length strings, depending on how much room is available. You should generate several results strings. The simplest might simply indicate the type of contents ('D' for data, for example), longer ones might indicate the full number ("0xFF01"), and longer ones might be very verbose ("Left Channel Audio Data: 0xFF01").

To provide strings to the caller, use the AddStringResult function. This will make sure that the strings persist after the function has returned. Always call ClearResultStrings before adding any string results.

Note that to easily concatenate multiple strings, simply provide AddStringResult with more strings.

```
void ClearResultStrings();
void AddResultString(const char *str1, const char *str2 = NULL, const char *str3 = NULL,
const char *str4 = NULL, const char *str5 = NULL, const char *str6 = NULL);
```

Here's the Serial Analyzer's GenerateBubbleText function:

```
bool framing_error = false;
           if((frame.mFlags & FRAMING_ERROR_FLAG) != 0)
                framing_error = true;
           bool parity_error = false;
           if((frame.mFlags & PARITY_ERROR_FLAG) != 0)
                parity_error = true;
           U32 bits_per_transfer = mSettings->mBitsPerTransfer;
           if(mSettings->mSerialMode != SerialAnalyzerEnums::Normal)
                bits_per_transfer--;
           char number_str[128];
           AnalyzerHelpers::GetNumberString(frame.mData1, display_base, bits_per_transfer,
                                                                                             number_str,
128);
           char result_str[128];
           //MP mode address case:
           bool mp_mode_address_flag = false;
           if((frame.mFlags & MP_MODE_ADDRESS_FLAG) != 0) {
                mp_mode_address_flag = true;
                AddResultString("A");
                AddResultString("Addr");
                if(framing_error == false) {
                      snprintf(result_str, sizeof(result_str), "Addr: %s", number_str);
                      AddResultString(result_str);
                      snprintf(result_str, sizeof(result_str), "Address: %s", number_str);
                      AddResultString(result str);
                } else {
                      snprintf(result_str, sizeof(result_str), "Addr: %s (framing error)", number_str);
                      AddResultString(result_str);
                      snprintf(result_str, sizeof(result_str), "Address: %s (framing error)",
number_str);
                      AddResultString(result_str);
```

```
}
                return;
           }
           //normal case:
           if((parity_error == true ) || (framing_error == true)) {
                AddResultString("!");
                snprintf(result_str, sizeof(result_str), "%s (error)", number_str);
                AddResultString(result_str);
                if(parity_error == true && framing_error == false)
                      snprintf(result_str, sizeof(result_str), "%s (parity error)", number_str);
                else if (parity_error == false && framing_error == true)
                      snprintf(result_str, sizeof(result_str), "%s (framing error)", number_str);
                else
                      snprintf(result_str, sizeof(result_str), "%s (framing error & parity error)",
number str);
                AddResultString(result_str);
           } else {
                AddResultString(number_str);
           }
     }
```

3.2.3 void{YourName}AnalyzerResults::GenerateExportFile(const char* file,DisplayBase display_base, U32 export_type_user_id)

This function is called when the user tries to export the analyzer results to a file. If you like, you can leave this function empty, and come back to it after finalizing the rest of your analyzer design.

The *file* parameter is string containing the full path of the file you should create and write to with the analyzer results.

```
std::ofstream file stream(file, std::ios::out);
```

The display base parameter contains the radix which should be used to display numerical results.

The *export_type_user_id* parameter is the id associated with the export-type the user selected. You specify what these options are (there should be at least one) in the constructor of your *AnalyzerSettingsderived* class. If you only have one export option you can ignore this parameter.

Often times you'll want to print out the time (in seconds) associated with a particular result. To do this, use the *GetTimeString* helper function. You'll need the trigger sample number and the sample rate –

which can be obtained from your Analyzer object pointer.

```
U64 trigger_sample = mAnalyzer->GetTriggerSample();
U32 sample_rate = mAnalyzer->GetSampleRate();
static void AnalyzerHelpers::GetTimeString(U64 sample, U64 trigger_sample, U32sample_rate_hz,
char *result_string, U32 result_string_max_length);
```

Other than that, the implementation is pretty straightforward. Here is an example from SerialAnalyzerResults.cpp:

```
void SerialAnalyzerResults::GenerateExportFile(const char *file, DisplayBase display_base, U32
/*export_type_user_id*/)
           //export_type_user_id is only important if we have more than one export type.
           std::stringstream ss;
           U64 trigger_sample = mAnalyzer->GetTriggerSample();
           U32 sample_rate = mAnalyzer->GetSampleRate();
           U64 num_frames = GetNumFrames();
           void *f = AnalyzerHelpers::StartFile(file);
           if(mSettings->mSerialMode == SerialAnalyzerEnums::Normal) {
                 //Normal case -- not MP mode.
                 ss << "Time [s],Value,Parity Error,Framing Error" << std::endl;</pre>
                for(U32 i=0; i < num_frames; i++) {</pre>
                      Frame frame = GetFrame(i);
                      //static void GetTimeString( U64 sample, U64 trigger_sample, U32
           sample_rate_hz, char* result_string, U32 result_string_max_length );
                      char time_str[128];
                      AnalyzerHelpers::GetTimeString(frame.mStartingSampleInclusive, trigger_sample,
sample_rate, time_str, 128);
                      char number str[128];
                      AnalyzerHelpers::GetNumberString(frame.mData1, display_base,
mSettings->mBitsPerTransfer, number_str, 128);
                      ss << time_str << "," << number_str;</pre>
```

- 39

```
ss << ",Error,";
                      else
                            ss << ",,";
                      if((frame.mFlags & FRAMING_ERROR_FLAG) != 0)
                            ss << "Error";
                      ss << std::endl;</pre>
                      AnalyzerHelpers::AppendToFile((U8*)ss.str().c_str(), ss.str().length(), f);
                      ss.str(std::string());
                      if(UpdateExportProgressAndCheckForCancel(i, num_frames) == true) {
                            AnalyzerHelpers::EndFile(f);
                            return;
                      }
                 }
           } else {
                //MP mode.
                 ss << "Time [s],Packet ID,Address,Data,Framing Error" << std::endl;</pre>
                U64 address = 0;
                for(U32 i=0; i < num_frames; i++) {</pre>
                      Frame frame = GetFrame(i);
                      if((frame.mFlags & MP_MODE_ADDRESS_FLAG) != 0) {
                            address = frame.mData1;
                            continue;
                      }
                      U64 packet id = GetPacketContainingFrameSequential(i);
                      //static void GetTimeString( U64 sample, U64 trigger_sample, U32
           sample_rate_hz, char* result_string, U32 result_string_max_length );
                      char time_str[128];
                      AnalyzerHelpers::GetTimeString(frame.mStartingSampleInclusive, trigger_sample,
sample_rate, time_str, 128);
```

if((frame.mFlags & PARITY_ERROR_FLAG) != 0)

char address_str[128];

```
AnalyzerHelpers::GetNumberString(address, display_base,
mSettings->mBitsPerTransfer - 1, address_str, 128);
                char number_str[128];
                AnalyzerHelpers::GetNumberString(frame.mData1, display_base,
           mSettings->mBitsPerTransfer - 1, number_str, 128);
                if(packet id == INVALID RESULT INDEX)
                      ss << time_str << "," << "" << address_str << "," << number_str
     << ",";
                else
                      ss << time_str << "," << packet_id << "," << address_str << "," <<
     number_str << ",";</pre>
                if((frame.mFlags & FRAMING_ERROR_FLAG) != 0)
                      ss << "Error";
                ss << std::endl;</pre>
                AnalyzerHelpers::AppendToFile((U8*)ss.str().c_str(), ss.str().length(), f);
                ss.str(std::string());
                if(UpdateExportProgressAndCheckForCancel(i, num_frames) == true) {
                      AnalyzerHelpers::EndFile(f);
                      return;
                }
           }
     }
     UpdateExportProgressAndCheckForCancel(num_frames, num_frames);
     AnalyzerHelpers::EndFile(f);
```

3.2.4 void {YourName}AnalyzerResults::GenerateFrameTabularText(U64 frame_index, DisplayBase display_base)

GenerateFrameTabularText is for producing text for tabular display which is not yet implemented. You can safely leave it empty.

GenerateFrameTabularText is almost the same as GenerateBubbleText, except that you should generate only one text result. Ideally the string should be concise, and only be a couple inches long or less under normal (non error) circumstances.

Here is an example from SerialAnayzerResults.cpp:

```
void SerialAnalyzerResults::GenerateFrameTabularText(U64 frame_index, DisplayBase display_base)
     {
         ClearTabularText();
           Frame frame = GetFrame(frame_index);
           bool framing_error = false;
           if((frame.mFlags & FRAMING_ERROR_FLAG) != 0)
                framing_error = true;
           bool parity_error = false;
           if((frame.mFlags & PARITY_ERROR_FLAG) != 0)
                parity_error = true;
           U32 bits_per_transfer = mSettings->mBitsPerTransfer;
           if(mSettings->mSerialMode != SerialAnalyzerEnums::Normal)
                bits_per_transfer--;
           char number_str[128];
           AnalyzerHelpers::GetNumberString(frame.mData1, display_base, bits_per_transfer, number_str,
128);
           char result_str[128];
           //MP mode address case:
           bool mp_mode_address_flag = false;
           if((frame.mFlags & MP_MODE_ADDRESS_FLAG) != 0) {
                mp_mode_address_flag = true;
                if(framing_error == false) {
                      snprintf(result_str, sizeof(result_str), "Address: %s", number_str);
                      AddTabularText(result_str);
                } else {
                      snprintf(result_str, sizeof(result_str), "Address: %s (framing error)",
number_str);
                      AddTabularText(result_str);
                return;
```

3.2.5 void {YourName}AnalyzerResults::GeneratePacketTabularText(U64 packet_id, DisplayBase display base)

Temporary vacancy.

3.2.6 void {YourName} AnalyzerResults::GenerateTransactionTabularText(U64 transaction_id, DisplayBase display_base)

Temporary vacancy.

4.Analyzer

Your *Analyzer-derived* class is the heart of the analyzer. It's here were we analyze the bits coming in – in real time – and generate analyzer results. Other than a few other housekeeping things, that's it. Let's get started.

4.1 {YourName} Analyzer.h

In addition to the constructor and destructor, here are the functions you'll need to implement:

```
virtual void WorkerThread();
virtual U32 GenerateSimulationData(U64 newest_sample_requested, U32 sample_rate,
SimulationChannelDescriptor **simulation_channels);
virtual U32 GetMinimumSampleRateHz();
virtual const char *GetAnalyzerName() const;
```

```
virtual bool NeedsRerun();
extern "C" ANALYZER_EXPORT const char * __cdecl GetAnalyzerName();
extern "C" ANALYZER_EXPORT Analyzer * __cdecl CreateAnalyzer();
extern "C" ANALYZER_EXPORT void __cdecl DestroyAnalyzer(Analyzer *analyzer);
```

You'll also need these member variables:

```
std::auto_ptr< {YourName}AnalyzerSettings > mSettings;
std::auto_ptr< {YourName}AnalyzerResults > mResults;
{YourName}SimulationDataGenerator mSimulationDataGenerator;
bool mSimulationInitilized;
```

You'll also need one AnalyzerChannelData raw pointer for each input. For SerialAnalyzer, for example, we need

```
AnalyzerChannelData *mSerial;
```

As you develop your analyzer, you'll add additional member variables and helper functions depending on your analysis needs.

Here is an example of SerialAnalyzer.h:

```
#ifndef SERIAL_ANALYZER_H
#define SERIAL_ANALYZER_H

#include <analyzer.h>
#include "SerialAnalyzerResults.h"
#include "SerialSimulationDataGenerator.h"

class SerialAnalyzerSettings;
class ANALYZER_EXPORT SerialAnalyzer : public Analyzer
{
public:
    SerialAnalyzer();
    virtual ~SerialAnalyzer();
    virtual void SetupResults();
    virtual void WorkerThread();

    virtual U32 GenerateSimulationData(U64 newest_sample_requested, U32 sample_rate,
SimulationChannelDescriptor **simulation_channels);
    virtual U32 GetMinimumSampleRateHz();
```

```
virtual const char *GetAnalyzerName() const;
     virtual bool NeedsRerun();
#pragma warning(push)
#pragma warning(disable : 4251) //warning C4251: 'SerialAnalyzer::<...>' : class <...> needs to
have dll-interface to be used by clients of class
protected: //functions
     void ComputeSampleOffsets();
protected: //vars
     std::auto_ptr< SerialAnalyzerSettings > mSettings;
     std::auto_ptr< SerialAnalyzerResults > mResults;
     AnalyzerChannelData *mSerial;
     SerialSimulationDataGenerator mSimulationDataGenerator;
     bool mSimulationInitilized;
     //Serial analysis vars:
     U32 mSampleRateHz;
     std::vector<U32> mSampleOffsets;
     U32 mParityBitOffset;
     U32 mStartOfStopBitOffset;
     U32 mEndOfStopBitOffset;
     BitState mBitLow;
     BitState mBitHigh;
#pragma warning( pop )
};
extern "C" ANALYZER_EXPORT const char * __cdecl GetAnalyzerName();
extern "C" ANALYZER_EXPORT Analyzer * __cdecl CreateAnalyzer();
extern "C" ANALYZER_EXPORT void __cdecl DestroyAnalyzer(Analyzer *analyzer);
#endif //SERIAL_ANALYZER_H
```

4.2 {YourName}Analyzer.cpp

4.2.1 Constructor

Your constructor will look something like this

```
{YourName}Analyzer::{YourName}Analyzer()
: Analyzer(),
mSettings(new{YourName}AnalyzerSettings()),
mSimulationInitilized(false)
{
        SetAnalyzerSettings(mSettings.get());
}
```

Note that here you're calling the base class conststructor, *newing* your *AnalyzerSettings*-derived class, and providing the base class with a pointer to your *AnalyzerSettings*-derived object.

4.2.2 Destructor

This only thing your destructor must do is call KillThread.

4.2.3 void {YourName} Analyzer:: SetupResults()

in this function, you need to generate the *AnalyzerResults* derived class object, save the object pointer to the Analyzer derived class, and pass the channel display parsing result to the AnalyzerResults derived class

For example in Serial Analyzer.cpp:

```
void SerialAnalyzer::SetupResults()

{
    mResults.reset(new SerialAnalyzerResults(this, mSettings.get()));
    SetAnalyzerResults(mResults.get());
    mResults->AddChannelBubblesWillAppearOn(mSettings->mInputChannel);
}

在 SpiAnalyzer.cpp 中:
void SpiAnalyzer::SetupResults()
{
    mResults.reset(new SpiAnalyzerResults(this, mSettings.get()));
    SetAnalyzerResults(mResults.get());

    if(mSettings->mMosiChannel != UNDEFINED_CHANNEL)
        mResults->AddChannelBubblesWillAppearOn(mSettings->mMosiChannel);
    if(mSettings->mMisoChannel != UNDEFINED_CHANNEL)
        mResults->AddChannelBubblesWillAppearOn(mSettings->mMisoChannel);
}
```

4.2.4 void {YourName}Analyzer::WorkerThread()

This function the key to everything - it's where you'll decode the incoming data. Let's leave it empty for

now, and we'll discuss in detail once we complete the other housekeeping functions.

4.2.5 bool {YourName} Analyzer:: NeedsRerun()

Generally speaking, just return false in this function. For more detail, read on.

This function is called when your analyzer has finished analyzing the collected data (this condition is detected from outside your analyzer.)

This function gives you the opportunity to run the analyzer all over again, on the same data. To do this, simply return true. Otherwise, return false. The only thing this is currently used for is for our Serial analyzer, for "autobaud". When using autobaud, we don't know ahead of time what the serial bit rate will be. If the rate turns out to be significantly different from the rate we ran the analysis at, we return true to re-run the analysis.

If you return true, that's all there is to do. Your analyzer will be re-run automatically.

4.2.6 U32 {YourName}Analyzer::GenerateSimulationData(U64 Minimum_sample_index,U32device_sample_rate,SimulationChannelDescriptor**simulation_channels)

This is the function that gets called to obtain simulated data. We made a dedicated class for handling this earlier – we just need to do some housekeeping here to hook it up.

4.2.7 U32 {YourName}SerialAnalyzer::GetMinimumSampleRateHz()

This function is called to see if the user's selected sample rate is sufficient to get good results for this analyzer.

```
An example in SerialAnalyzer.cpp:

U32 SerialAnalyzer::GetMinimumSampleRateHz()

{
    return mSettings->mBitRate * 4;
```

}

If we set band rate as 9600, then the minim sampling frequency was suggested we be more than 9600*4=38400Hz.

4.2.8 const char *{YourName}Analyzer::GetAnalyzerName() const

Simply return the name you would like to see in the "Add Analyzer" drop down.

4.2.9 const char *GetAnalyzerName()

Return the same string as in the previous function.

4.2.10 Analyzer *CreateAnalyzer()

Return a pointer to a new instance of your Analyzer-derived class.

4.2.11 void DestroyAnalyzer (Analyzer *analyzer)

Simply call delete on the provided pointer.

4.2.12 Details

Ok, now that everything else is taken care of, let's look at the most important part of the analyer in detail.

First, we'll new our AnalyzerResults-derived object.

```
mResults.reset(new{YourName}AnalyzerResults( this, mSettings.get()));
```

Well provide a pointer to our results to the base class:

```
SetAnalyzerResults(mResults.get());
```

Let's indicate which channels we'll be displaying results on (in the form of bubbles). Usually this will only be one channel. (Except in the case of SPI, where we'll want to put bubbles on both the MISO and MISO lines.) Only indicate where we will display bubbles – other markup, like tick marks, arrows, etc, are not bubbles, and should not be reported here.

```
mResults->AddChannelBubblesWillAppearOn(mSettings->mInputChannel);
```

We'll probably want to know (and save in a member variable) the sample rate.

```
mSampleRateHz = GetSampleRate();
```

Now we need to get access to the data itself. We'll need to get pointers to AnalyzerChannelData objects for each channel we'll need data from. For Serial, we'll just need one. For SPI, we might need 4. Etc.

```
mSerial = GetAnalyzerChannelData(mSettings->mInputChannel);
```

We've now ready to start traversing the data, and recording results. We'll look at each of these tasks in turn.

First, a word of advice

A protocol is typically fairly straightforward, when it behaves exactly as it supposed to. The more your analyzer needs to deal with exceptions to the rule, the more sophisticated it'll need to be. The best bet is probably to start as simple as possible, and add more "gotchas" as they are discovered, rather than to try and design an elaborate, bulletproof analyzer from the start, especially when you're new to the API.

AnalyzerChannelData

AnalyzerChannelData is the class that will give us access to the data from a particular input. This will provide data in a serialized form – we will not have "random access" to any bit in the saved data. Rather, we will start at the beginning, and move forward as more data becomes available. In fact we'll never know when we're at the "end" of the data or not – attempts to move forward in the stream will block until more data becomes available. This will allow our analyzer to process data in a real-time manner. (It may backlog, of course, if it can't keep up – although generally the collection will end at some point and we'll be able to finish).

AnalyzerChannelData - State

If we're not sure where are in the stream, or if the input is currently high or low, we can just ask:

```
U64 GetSampleNumber();
BitState GetBitState();
```

AnalyzerChannelData - Basic Traversal

We'll need some ability to move forward in the stream. We have three basic ways to do this.

U32 Advance(U32 num samples);

We can move forward in the stream by a specific number of samples. This function will return how many times the input toggled (changed from a high to a low, or low to a high) to make this move.

U32 AdvanceToAbsPosition(U64 sample number);

If we want to move forward to a particular absolute position, we can use this function. It also returns the number of times the input changed during the move.

void AdvanceToNextEdge();

We also might want to move forward until the state changes. After calling this function you might want to call GetSampleNumber to find out how far you've come.

AnalyzerChannelData- Advanced Traversal (looking ahead without moving)

As you develop your analyzer(s) certain tasks may come up that call for more sophisticated traversal. Here are some ways of doing it.

U64 GetSampleOfNextEdge();

This function does not move your position in the stream. Remember, you can not move backward in the stream, so sometimes seeing what's up ahead without moving can be very important.

bool WouldAdvancingCauseTransition(U32 num samples);

This function does not move your position in the stream. Here you find out if moving forward a given number of samples would cause the bit state (low or high) to change.

bool WouldAdvancingToAbsPositionCauseTransition(U64 sample number);

This is the same as the prior function, except you provide the absolute position.

Filling in and saving Frames

Using the above AnalyzerChannelData class, we can now move through a channel's data and analyze it. Now let's discus how to store results.

We described Frames when talking about the AnalyzerResults-derived class. A Frame is the basic unit results are saved in. Frames have:

- starting and ending time (starting and ending sample number)
- x2 64-bit values to save results in
- an 8-bit type variable to specify the type of Frame
- an 8-bit flags variable to specify Yes/No types of results.

When we have analyzed far enough, and now have a complete Frame we would like to record, we do it like this:

First we make a Frame on the stack. Then we fill in all its values. If there's a value you don't need, to save time you can skip setting it. mFlags should always be set to zero, however, because certan predefined flags will cause the results bubble to indicate a warning or error (DISPLAY_AS_WARNING_FLAG, and DISPLAY AS ERROR FLAG).

Part of the Frame is expected to be filled in correctly because it's used automaticly by other systems. In particular,

- mStartingSampleInclusive
- mEndingSampleInclusive
- mFlags

To save a Frame, Use AddFrame from your AnalyzerResults-derived class. Note that frames must be added in-order, and must not overlap. In other words, you can't add a Frame from an earlier time (smaller sample number) after adding a Frame form a later time (larger sample number).

Immediately after adding a Frame, call CommitResults. This makes the Frame accessable to the external system.

Also call the Analyzer base class ReportProgress. Provide it with it the largest sample number you have processed.

Adding Markers

Makers are visual elements you can place on the waveform to highlight various waveform features as they relate to your protocol. For example, in our asynchronous serial analyzer, we place little white dots at the locations where we sample the input's state. You can also use markers to indicate where the protocol falls out of specification, a rising or falling clock edge, etc. You specify where to put the marker (the sample number), which channel to display it on, and which graphical symbol to use.

```
void AddMarker(U64 sample_number, MarkerType marker_type, Channel &channel);
```

For example, from SerialAnalyzer.cpp:

```
mResults->AddMarker(marker_location, AnalyzerResults::Dot, mSettings->mInputChannel)
```

Currently, the available graphical artifacts are

```
enum MarkerType { Dot, ErrorDot, Square, ErrorSquare, UpArrow, DownArrow, X, ErrorX, Start, Stop,
One, Zero };
```

Like Frames, you must add Markers in order.

Markers are strictly for graphical markup, they can not be used to help generate display text, export files, etc. Only Frames are accessable to do that.

Packets and Trasactions

Packets and Trasactions are only moderatly supported as of now, but they will be becoming more prominate in the software..

Packets are sequential collections of Frames. Grouping Frames into Packets as you create them is easy:

```
U64 CommitPacketAndStartNewPacket();
void CancelPacketAndStartNewPacket();
```

When you add a Frame, it will automatically be added to the current *Packet*. When you've added all the *Frames* you want in a Packet, call *CommitPacketAndStartNewPacket*. In some conditions, especially errors, you will want start a new packet without committing the old one. For this, call *CancelPacketAndStartNewPacket*.

Note that CommitPacketAndStartNewPacket returns an packet id. You can use this id to assign a particular packet to a transaction.

Currently, Packets are only used when exporting data to text/csv. In the future, analyzer tabular views will support nesting Frames into Packets, and identifying Transactions (ids) associated with particular Packets. Generating the textual content to support this is provided in your AnalyzerResults-derived class.