

# Competition of Social Opinions on Two Layer Networks

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**Abstract:** We investigate a model for the competition between two-layer opinion, where the first layer is opinion formation and the second layer is decision making, on multilayer networks. Networks show the two interacting social sectors, the civilians, and representatives. Layer A is civilian opinion layer consists of four states (-2, -1, +1, +2). These states describe the level of influence of opinion dynamics with reinforcement parameter  $\gamma$ . The layer B is the decision making layer consists of only two states (+1, -1). This layer can influence the decision dynamics with the probability in which decision is proportional to the number of interaction with the opposite opinion population raised to the power of  $\beta$ . Starting with a polarized case in which layer A is positive and layer B is negative. In this Paper, we created new models by changing the network structure, and compare these models with the pre-existing model. Then we investigate the condition in which the layer A influence the layer B and the conditions to make consensus in the interconnected network. This study will help to analyze social networks, such as legalization of social issues and prediction of vote results.

**Key Words:** Complex Network, Interconnected Networks, Modeling and Simulation, Python, Social Network Analysis, Language Competition Dynamics, Opinion Dynamics, Consensus

## 1 Introduction

Research on the structure and dynamics of complex network systems is actively underway. This active study of complex systems has contributed to analyze natural or social phenomena, and the theory of complex network has been applied in real world such as climate forecast, social networks, and traffic control systems. [1-5] So far, the researches have been conducted focusing on interactions on a single layer or on the dynamics of each network. However, there are many systems in the world that cannot be explained only on a single layer. They must be described as multiple layer system, that consists of two or more layers and has the interaction between layers. It is called as “Multilayer complex network” [6]. Multilayer networks theories provide a solid and powerful approach to the study of complex phenomena. For example, interdependencies between different networks of a multilayer structure can make cascades of failure events that can dramatically increase the fragility of these systems. That can help to understand spreading of diseases, opinions and ideas when a single layer cannot do explain those phenomena. [7] And, in the real world, the multilayer network theory has already applied to transportation system and social network analysis. [8]

Recently, there has been a lot of interest in modeling social network dynamics, including opinion dynamics, election models and game theory approaches. As the multiplexity is a prominent property of social networks,

it is of fundamental importance to research the social network dynamics with multilayer networks. Opinion dynamics have been developed with the research of voter model and election model. [8] In this paper, opinion dynamics are discussed by analyzing the dynamics of a two-layer competing social network, based on the previous research. [9-12] The model consists of interconnected two layer networks. One layer has the function of social opinion and its own dynamics. The dynamics of the social opinion layer is opinion dynamics that are called as M-model[12], that includes compromise function and persuasion function. The other layer also has the function of decision-making and its own dynamics. The dynamics of the decision making layer is the language competition dynamics that are also called as Abrams-Strogatz model[13-14]. And, as an initial condition, it is assumed that the two layers are in opposite states. As the result of previous research, interconnected competition of the social network have been researched by finding the threshold or critical point for consensus. [9-11] As the result of research, it has been proved that the system can make positive consensus, negative consensus or coexistence parts in interconnected competition of the social network. [9] and it found out that the number of external degree is very important to change the state of layers. [10] We develop the modeling of previous research and research to find out the characteristics of interconnected networks. By switching the network structure of each layer, such as changing the number of nodes or the number of edges, it is investigated and analyzed how the consensus or coexistence states change and what conditions make the social consensus. This can help to explain social networks phenomena, such as conflict between social opinion and the congress. So this research could be used

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as a tool for analyzing legislation problems or predicting decision-making system. The paper is organized as follows. In section 2, the basic model is introduced and the dynamics, that is applied to each layer, are described. In section 3, the simulation results for the base model and revised models are presented. In section 4 the characteristics of each model are described through the comparison and analysis. Finally, in section 5 the simulation results will be summarized and our findings are concluded.

## 2 Modeling

The basic model of this interconnected network consists of two layers that are called layer A and layer B, individually. Each layer consists of random regular network that has  $N$  nodes with  $k$  internal edges on the same layer. Each node of layer A or B connects with a random node on the other layer. That is, each node has only 1 external edge. Dynamics of Layer A follow opinion dynamics. This dynamic is applied to layer A nodes and layer B nodes that are connected with layer A nodes. But, layer B nodes don't change their states, because layer B nodes is applied to decision making dynamics. The state of each node is represented by integer number  $j$  and  $k$ . And the maximum state of nodes is  $M$ . If  $k$  and  $j$  are connected on networks (it includes internal and external edges), the dynamics is like this formula.[10] i) Compromise : if they have opposite orientations, their states become more moderate with probability  $q$  :

$$\begin{aligned} \text{if } j < 0 \text{ and } k > 0 &\Rightarrow (j, k) \rightarrow (j^r, k^l) \text{ with prob. } q \\ \text{if } j > 0 \text{ and } k < 0 &\Rightarrow (j, k) \rightarrow (j^l, k^r) \text{ with prob. } q \end{aligned}$$

If  $j = \pm 1$  and  $k = \mp 1$ , one switches orientation at random:

$$(\pm 1, \mp 1) \rightarrow \begin{cases} (+1, +1) & \text{with prob. } q/2 \\ (-1, -1) & \text{with prob. } q/2 \end{cases}$$

ii) Persuasion : if they have the same orientation, their states become more extreme with probability  $p$  :

$$\begin{aligned} \text{if } j < 0 \text{ and } k < 0 &\Rightarrow (j, k) \rightarrow (j^l, k^l) \text{ with prob. } p \\ \text{if } j > 0 \text{ and } k > 0 &\Rightarrow (j, k) \rightarrow (j^r, k^r) \text{ with prob. } p \end{aligned}$$

Here,  $k^r$  and  $k^l$  denote the right and left neighboring states of  $k$ , defined as

$$k^r = \begin{cases} 1, & \text{for } k = -1 \\ M, & \text{for } k = M \\ k + 1, & \text{otherwise} \end{cases} \quad k^l = \begin{cases} 1, & \text{for } k = -1 \\ M, & \text{for } k = M \\ k + 1, & \text{otherwise} \end{cases} \quad (1)$$

As the initial condition for basic model, the dynamic on layer A has that of M-model with  $M = 2$ . If  $M = 2$ , the node in layer A can have a status of -2, -1, +1, and +2. But, as the initial condition, nodes of layer A has only positive values, a half of nodes are +1 and the others are +2. In case of interaction between layer A node and layer B node, layer A node follows the above formula, but the state of Layer B nodes does not change. In other words, the states of Layer B affect layer A, but

this dynamics does not affect states of layer B nodes. For example, one of layer A node,  $S_i = +2$  is connected with one of layer B node,  $S_j = -1$ . In this case,  $S_i$  is changed into  $S_i = +1$  with prob.  $q$ . But  $S_j$  is not changed. That means layer B node states have influence on layer A nodes. The dynamics of layer B follow language competition dynamics as the decision-making dynamics. Language competition dynamics follow the formula below. The state of node  $i$  in layer B changes with this probability [13, 14]

$$P_B(S_i \rightarrow -S_i) = \left\{ \frac{n^{-S_i}}{i_i + e_i} \right\}^\beta \quad (2)$$

$i_i$  is the number of internal edges and  $e_i$  is the number of external edges.  $n^{-S_i}$  is the number of neighbors of  $i$  with opposite state  $-S_i$ .  $\beta (\geq 0)$  is the volatility exponent that measures how prone a node change state. This formula means that the more the nodes are connected with the opposite state, the easier the nodes can be changed into the opposite state.

The states of layer B nodes can be 1 or -1. But, as an initial condition, the states are only -1. By this formula, the state of layer A has influence on change of layer B node states. In summary, states of layer A nodes are a positive state of 1 or 2 as an initial condition, and the state of layer B node, which is connected with layer A, affects the change of the node on layer A. The states of Layer B nodes are a negative state of -1 as an initial condition, and the state of Layer A nodes, which is connected with layer B, has influence on the change of Layer B node. Under these conditions, we will find out when the consensus happen and what conditions make

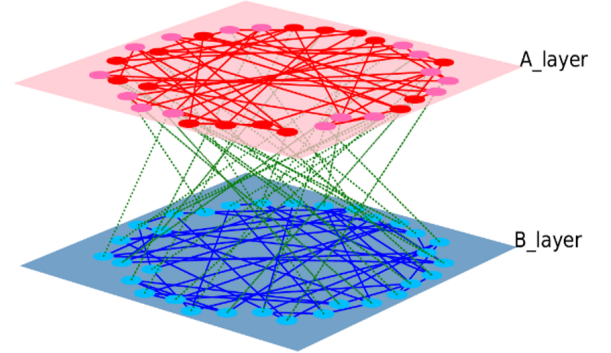


Fig. 1: Competing Interconnected Network

## 3 Simulation Result

We organized interconnection networks in Section 2. Each layer consists of a random regular network that each node has same degree.[15] Each node has five internal edges and one external edge. Layer A dynamics have the probability  $p$  and probability  $q$  denoted by M-model. We observe how the state changes by switching the probability  $p$  and probability  $q$ . To simply represent the probability  $p$  and probability  $q$  as one value, we set the value to  $p+q=1$ , and the  $\gamma = p/q$ .  $\gamma$  represents the strength of opinion.[9] For layer B dynamics, by switching  $\beta$ , we investigate the change of states.  $\gamma$  scale is

from 0 to 2, and  $\beta$  scale is from 0 to 3, basically. But,  $\beta$  scale depends on the number of degrees. So, when the number of degrees is changed, the  $\beta$  scale would be adjusted properly to basic model scale. Among the two dynamics, layer A dynamics are preceded first, and then layer B dynamics are implemented. When each dynamic is performed, one step ends. Basically, 30 steps are taken. And the same procedure is repeated 100 times to calculate the average of each layer states. The 'Average state of layer A and B' is calculated by summing the average of layer A nodes' states and the average of layer B nodes' states. With 'Average state of layer A and B', we can check whether the consensus happens or not in accordance with ' $\gamma$ ' and 'beta' changing. If the positive consensus happens, it would be close to the value of 3, summation of layer A node average state(+2) and layer B node average state(+1), and if the negative consensus happens, it would be close to the value of -3, summation of layer A node(-2) and layer B node(-1). The value between 3 and -3 is not on the consensus yet, so the states of positive and negative are on the coexistence part. First, the basic model is simulated, and then other simulation would be implemented with revised network structure.

### 3.1 Basic Model Result

Basic model simulation result is like Fig2 and Fig3.

In Fig.2(a), as it shows, As  $\beta$  increase, it normally tend to make positive and negative consensus. But, when  $\gamma$  is very low, it can't make positive consensus, when  $\gamma$  is large enough, it can make positive consensus. But, when  $\beta$  is large enough, it is changed into negative consensus. When both of  $\gamma$  and  $\beta$  are large enough, it has coexistence for positive and negative states.

In Fig.2(b), As  $\gamma$  increase, it normally tends to make positive consensus. But, when  $\beta$  is very low, it can't make consensus. And when  $\beta$  is large enough, though  $\gamma$  is large enough, it can't make positive consensus and has a coexistence part.

In Fig.3, it shows the states of two layers according to  $\gamma$  and  $\beta$ . The X-axis is the  $\gamma$  and the Y-axis is the beta, and the Z-axis represents the average sum of the nodes' states in layer A and B.

In Fig.3, The closer the color is blue, the closer it has positive consensus, the closer the color is red, the closer it has negative consensus. A light or white part is the parts that is not a consensus, and has coexistence part with positive and negative states. It has two light or white part, when  $\beta$  is very low or very high. That means it has two transition parts such as coexistence to consensus and consensus to coexistence.

In Fig.4, the fractions of positive states are investigated on each layer. The result of layer A is like Fig.4 (a). Layer A has lots of positive parts. And the part of coexistence is very small. As the  $\beta$  increases, the  $\gamma$  is needed to increase for the positive consensus. As the parameter of layer A dynamics, the  $\gamma$  is operating properly. The result of layer B is like Fig.4 (b). Layer B has various states as  $\gamma$  and  $\beta$  change. But, Almost layer B states depends on power  $\beta$ . When  $\beta$  is very small, layer

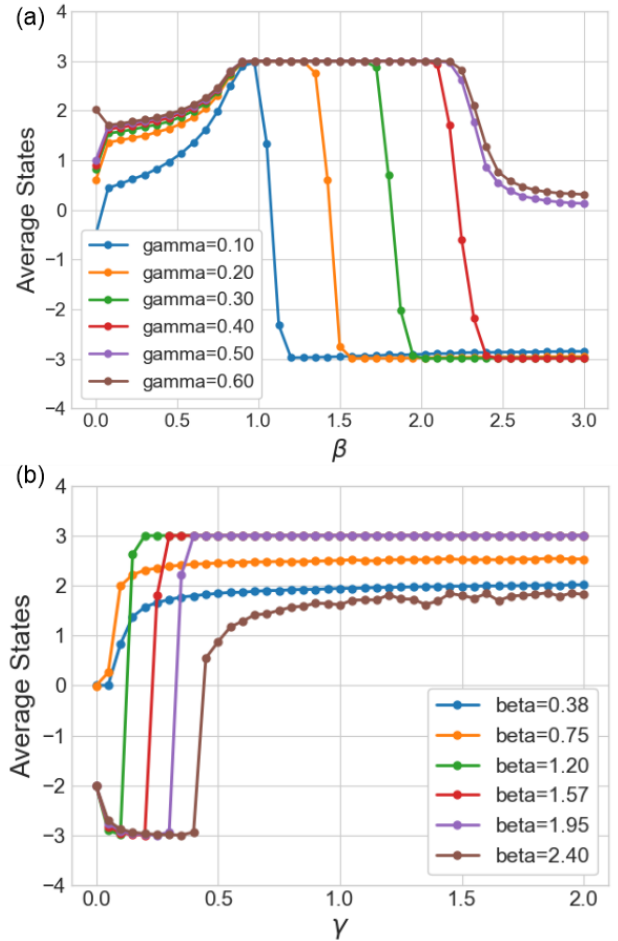


Fig. 2: (a)  $\beta$ -Average state of layer A and B chart according to some  $\gamma$  values. (b)  $\gamma$ -Average state of layer A and B chart according to some  $\beta$  values.

B states are almost in the coexistence. When  $\beta$  is very large, layer B state are almost negative. When  $\beta$  is in the middle ( $0.8 < \beta < 2.25$ ), the states are the consensus parts. The states of layer B is almost like layer A states. As the parameter of layer B dynamics, the  $\beta$  is also operating properly. Fig.4 (c) is the result of the summation of (a) and (b). The chart is almost like Fig.3 result. Through this charts, There is the difference of coexistence parts. The coexistence with small  $\beta$  is due to inner competition of layer B. The coexistence with large  $\beta$  is due to outer competition between layer A and layer B

### 3.2 Leader Model Result

The leader model is the model to reduce the number of nodes in layer B from 2048 to 128 while increase the number of external edges by 16 times as the number of nodes in the node decreases by 1/16. In other words, each layer A node has one external item, but each layer B node has 16 external edges. That is, one node of layer B represents the 16 nodes.  $\gamma$  scale is same with the basic model. But,  $\beta$  scale depends on the number of degrees. So the  $\beta$  scale is adjusted to same property with the basic model. The leader model simulation results are like this Fig.5 Comparing with Basic Model, white or

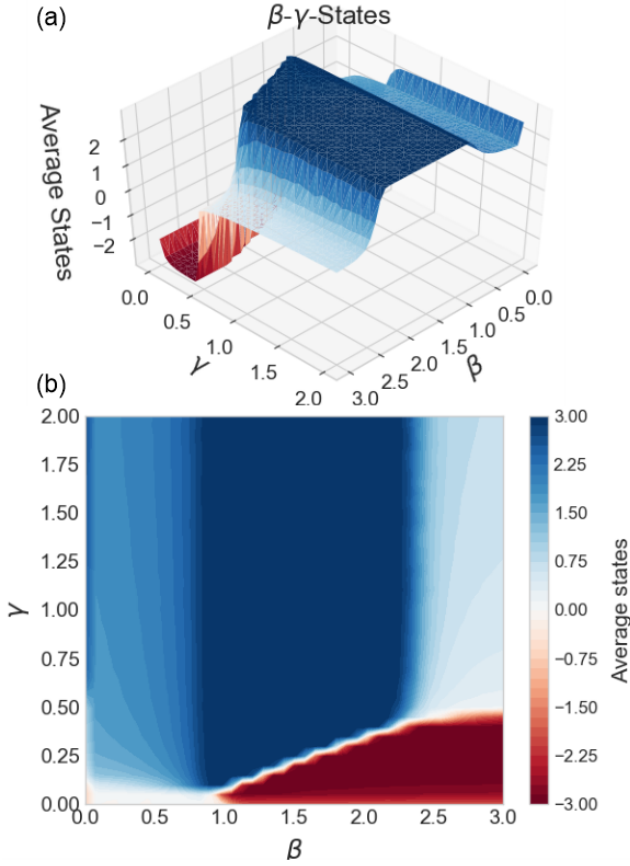


Fig. 3: Basic model 3D result (1). (a)  $\gamma$ - $\beta$ -Average state of layer A and B chart at angle (45, 45). (b)  $\gamma$ - $\beta$ -Average state of layer A and B chart at angle (90, 0)

light parts, that is coexistence parts, are decreased remarkably. And it has only 1 transition part where  $\beta$  is large enough. It shows that leader model has more consensus parts than basic model.

### 3.3 Different Structure Network Model

So far, each layer of the interconnected network consist of random regular network that has the same number of edges for the nodes. Now, the simulation would be implemented with Barabasi-Albert network[16, 17]. For this simulation, each layer has 2048 nodes, 1 external edges for each each node. The internal edges depend on Barabasi-Albert network(BA). So it has total 615 edges for each layer(BA is set up as average 5 internal edges), it has more 295 edges than the random regular network(RR) that has total 320 internal edges(RR is set up as 5 internal edges for each node). The simulation would be carried out, with switching each layer to RR or BA network structure. In Fig. 6 (a) and (b), (b) result has more white part(coexistence) than (a) result. That means increasing internal edges in both layers makes more coexistence part. In Fig. 6 (c), comparing with (a), the red part(negative consensus) is decreased and the blue part(positive consensus) is increased. Since Layer A is BA that has more internal edges, it seems to be more power to keep layer A states. In Fig. 6 (d), comparing with (a), the red part

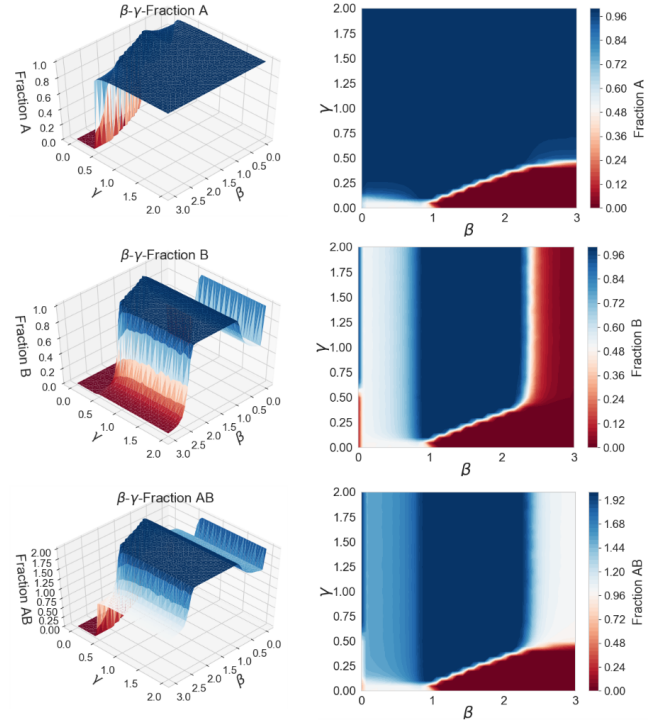


Fig. 4: Basic model 3D result (2) (a)  $\gamma$ - $\beta$ -Fraction A chart. ‘Fraction A’ means the fraction of positive states in the layer A. (b)  $\gamma$ - $\beta$ -Fraction B chart. ‘Fraction B’ means the fraction of positive states in the layer B. (c)  $\gamma$ - $\beta$ -Fraction AB chart. ‘Fraction AB’ means the summation of Fraction A and Fraction B.

and white part are increased. Since Layer B is BA that has more internal edges, it seems to be more power to keep layer B states.

In order to confirm that the number of internal edges affects consensus, The internal edges of layer A and B change to 2 or 5. The simulation is carried out with only RR networks that has total 320 or 128 internal edges on layer. The result is like this Fig 7. As we can see the result, we can find out the number of internal edges affects consensus. In Fig.7 (b) RR(320)-RR(128), it has decreased red part(negative consensus) and increased blue part(positive consensus). That means that layer A has more power than layer B. As the internal edges on layer A increase, the red part get smaller and the blue part get larger. Inversely, in Fig. 7 (c) RR(128)-RR(320), it has increased red part(negative consensus) and decreased blue part(positive consensus). That means that layer B has more power than layer A. Next, in order to compare BA network with RR network that has the similar number of edges, The internal edges of RR network are increased to the similar number of BA network internal edges. The simulation was carried out with RR network that has total 640 internal edges on layer A(layer B has RR network with 320 internal edges). The result is like Fig.8. In Fig. 8 (a), as you can see, BA network simulation result is almost same with RR network. We can analyze the number of edges have influence on the consensus. In other words, The network with much more edges leads to make consensus.



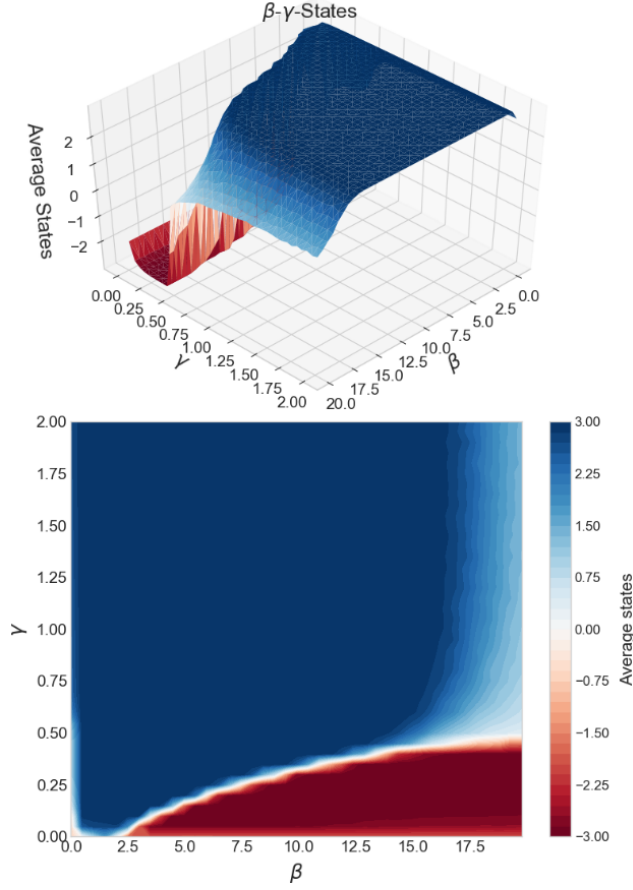


Fig. 5: Leader Model 3D result. (a)  $\gamma$ - $\beta$ -Average state of layer A and B chart at angle(45, 45). (b)  $\gamma$ - $\beta$ -Average state of layer A and B chart at angle(90, 0)

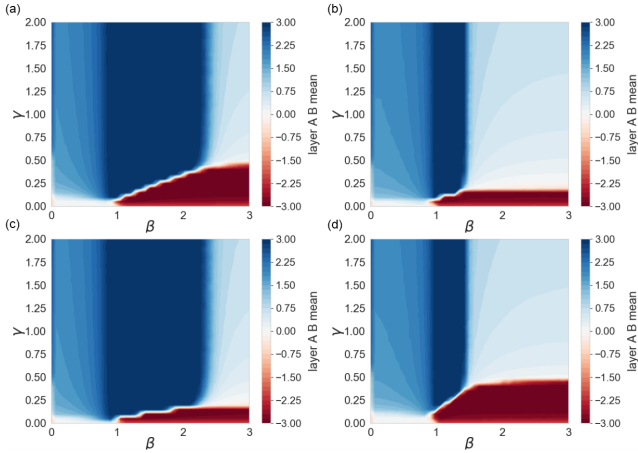


Fig. 6: The simulation results for interconnected network with different structure network (a) layer A(RR)-layer B(RR), (b) layer A(BA)-layer B(BA), (c) layer A(BA)-layer B(RR), (d) layer A(RR)-layer B(BA)

### 3.4 Increasing The Step of Dynamics

The basic model was implemented by 30 steps of interconnected dynamics that include opinion dynamics and decision-making dynamics. In this simulation, the number of step is increased from 30 to 100 steps. Increasing the number of steps in interconnected dynam-

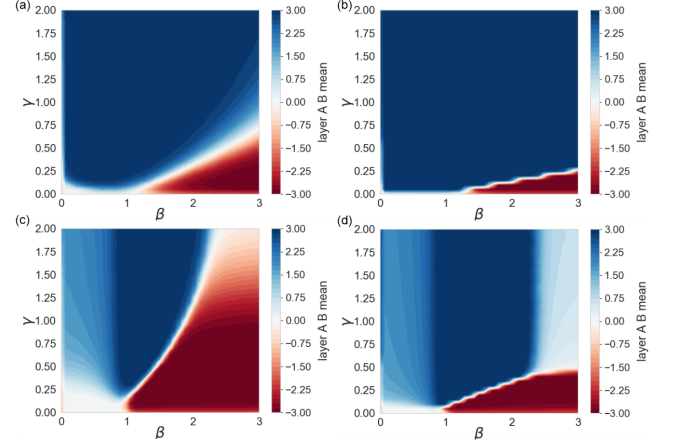


Fig. 7: Consensus Comparison according to changing the number of internal edges on layer A and B (a) RR(128)-RR(128), (b) RR(320)-RR(128), (c) RR(128)-RR(320), (d) RR(320)-RR(320)

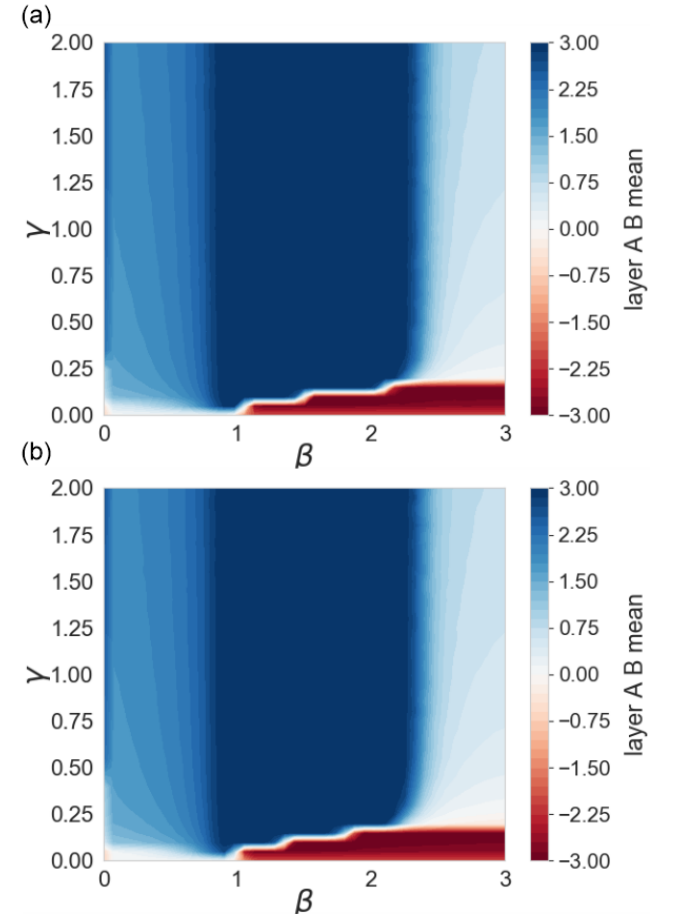


Fig. 8: Comparison between BA network and RR network (a) RR(640)-RR(320), (b) BA(615)-RR(320)

ics means the networks keeps interconnected dynamics for enough time. In the real world, it is the same effect as increasing time. The results of increasing the number of steps to 100 are as follows.

In Fig. 9, Dynamics steps increased Model has more blue part(positive consensus), and white part(coexistence) is decreased. That means consistent

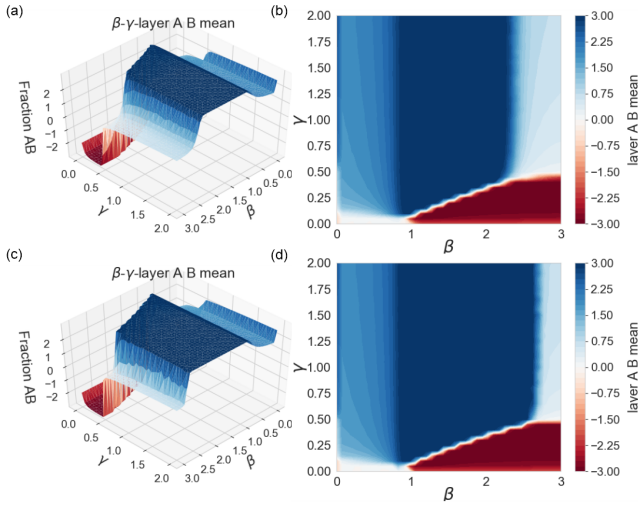


Fig. 9: The comparison between Basic Model(30times dynamics) and Dynamics steps increased Model(100 times)

social opinion can make consensus with its state.

In Fig. 10, the charts show that most of ratios on the layer A are approaching to 0 with steps proceeding, except the case that volatility is very large. The ratios on the layer B are divided by some values. But except some values, they are approaching to 0. That means two layers can make consensus by proceeding the steps with stable  $\gamma$  and  $\beta$ .

#### 4 Comparison and Analysis

In this section, the simulation results are compared and analyzed, and then it would be found out what conditions make the consensus on the interconnected networks. If the leader model compares with the basic model, we can see that the leader model has more consensus part than the basic model (white part is less than basic model). And the basic model has two transition parts, but the leader model has just one transition part. This means that the base model has transition parts when the beta is very small or very large. But in case of the leader model, though beta is very small, the consensus is easy to make. Only if beta is very large, the consensus is hard to happen. The next comparison is models with different structure networks. The total number of internal edges in BA is 615, and the internal edges in RR are total 320. This comparison simulation shows how the number of internal edges affects interconnected dynamics. First, when we check the BA-RR and RR-BA simulation results, we can see that it makes the more consensus with BA network layer states than RR-RR simulation. In other words, the layer with more internal edges seems to have more power to maintain its own state. That is, interconnected networks tend to make consensus with the layer that has more internal edges. RR-RR simulation results have more consensus parts than BA-BA simulation results. we can analyze that BA-BA simulations result in poor consensus due to having a strong power to maintain their both states. And, BA network was compared with RR network that

has the similar number of internal edges. The result is almost same. It can be analyzed that the network with more edges have more power to keep their states and make consensus for its states. The next analysis is a comparison with a model that increases the number of steps in the dynamic. A model that increases the number of steps can be seem to have more consensus with layer A. In other words, it means that social opinion is likely to achieve the consensus if it is given enough time. (Of course, if the volatility is too low or too high, it would not make consensus.) Through these three comparisons and analysis, we can provide three conditions that increase the likelihood of consensus with social opinion. First, as we can see the case of leader model, if reducing the node in the decision-making layer and increasing the external edges, we can increase the probability of consensus. Second, as different network structure comparisons show, for positive consensus, it is needed to have more internal edges than opposite layer. Because increasing the internal edges of social opinion is likely to have more power to keep the states. Third, as shown by the model that increased the number of dynamic steps, if given enough time, there is a high possibility of consensus with social opinion.

#### 5 Conclusion

In this work, we have researched competing interconnected network dynamics. Layer A is a layer of social opinion and has positive states as an initial condition. It is influenced by opinion dynamics. Layer B is a network representing decision making system and has a negative state as an initial condition. It is influenced by the language competition dynamics. When these two layers were connected and interacted, it was researched and analyzed how their states were changed with switching  $\gamma$  and  $\beta$ . In the basic model, the simulation result shows the negative consensus, the positive consensus, and the coexistence sections according to  $\gamma$  and  $\beta$ . Based on these basic models, we presented and simulated leader model, different structure networks model, and model with increased number of dynamic steps. As a result, we found out three conditions that increase the likelihood of consensus with social opinion layer. The first is to reduce nodes in the decision-making layer and increase the external edges like the leader model. The second is to increase the internal edges of social opinion in order to strengthen the power to maintain its state. But too many internal nodes can make internal conflicts. The third is to take enough time and keep social opinion with enough  $\gamma$ . More research will be needed to make generalized model and to be applied to real social networks. we think this research can contribute to providing the characteristics of the system and the framework of social networks analysis such as the legalization or social decision-making system, and we hope it help the research on interconnected networks and multi-layer networks. As the forward work, it would be very interesting to make the generalized model for competition of interconnected network.

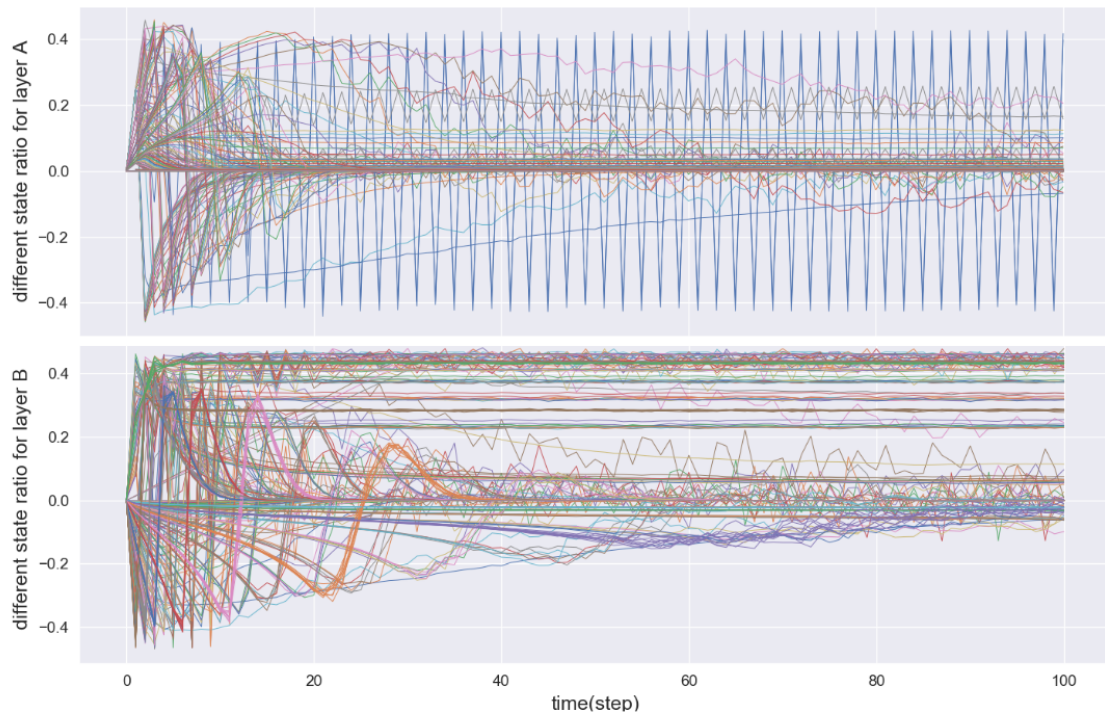


Fig. 10: Time evolution of the fraction of nodes in different states on layer A and layer B, the ratio of different state means the fraction of the number of different state node for each layer. The sign of ratio depends on the major nodes on each layer. For example, if the major nodes on layer A are negative, the sign of that ratio is negative.

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