

# CRes Inversion User Guide

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## I. INTRODUCTION

This user guide describes how to invert harmonic infrasound observations for crater geometry using **CRes** (Crater Resonance), which is a one-dimensional (1D) wave propagation code written in MATLAB that solves linear acoustics within a quasi one-dimensional crater. This user guide is complementary to the **CRes** user guide and focuses on the inversion methodology and implementation. For more details and examples of using **CRes** to invert harmonic infrasound observations for crater geometry see:

- Watson, L. M., Johnson, J. B., Sciotto, M., and Cannata, A. (2020) Changes in crater geometry revealed by inversion of harmonic infrasound observations: 24 December 2018 eruption of Mount Etna, Italy, *Geophysical Research Letters*, in press.
- Watson, L. M., Dunham, E. M., and Johnson, J. B. (2019) Simulation and inversion of harmonic infrasound from open-vent volcanoes using an efficient quasi-1D crater model, *Journal of Volcanology and Geothermal Research*, <https://doi.org/10.1016/j.jvolgeores.2019.05.007>.

## II. DIRECTORY

- **demo** - script files for demonstration
- **doc** - documentation including user guide and license file. The **CRes** user guide is also located in this folder.
- **inversion\_demo** - script files demonstrating how to invert harmonic infrasound observations for crater geometry. Contains synthetic and real data examples.
- **source** - function files used by **CRes** and the inversion scheme
- **GRL2020** - contains script files and data to recreate the figures from Watson et al. (2020).
- **JVGR2019** - contains script files and data to recreate the figures from Watson et al. (2019).

**CRes** and the associated inversion code are freely available online at <https://github.com/leighton-watson/CRes> and is distributed under the MIT license (see `license.txt` for details).

## III. INVERSION SCHEME

**CRes** runs efficiently on a desktop computer and, depending on the number of grid points used to discretize the crater geometry, can simulate the infrasound signal for a specified crater geometry within  $\sim 1$  s. Therefore, because the forward problem runs efficiently, a Markov-Chain Monte-Carlo (MCMC) style inversion scheme is used and can run in several hours, depending on the number of iterations.

The vector of model parameters is defined as  $\vec{x}$  and the inversion is begun from an initial estimate,  $\vec{x}_0$ . The steps for the  $i$ th iteration are shown below:

1. Take a random step in all parameter directions to calculate a vector of proposed parameter values:

$$\vec{x}_i^* = \frac{\vec{x}_{i-1}}{\vec{x}_0} + \vec{h}_{i-1} \Delta x \quad (1)$$

where  $\vec{x}_i^*$  is the vector of proposed parameter values,  $\vec{x}_{i-1}$  is the vector of parameter values at the previous iteration and  $\vec{x}_0$  is the initial estimate.  $\vec{h}_{i-1}$  is the same dimension as  $\vec{x}$  with each entry randomly sampled from the uniform distribution  $[-1,1]$  for each iteration and  $\Delta x$  is the scalar step size. If necessary, repeat the procedure until a value of  $\vec{x}_i^*$  is chosen that satisfies the specified bounds.

2. Simulate infrasound signal for  $\vec{x}_i^*$  using **CRes**
3. Evaluate the misfit function for the proposed parameters,  $M(\vec{x}_i^*)$
4. Accept the proposed parameters,  $\vec{x}_i = \vec{x}_i^*$ , if:
  - (a) The misfit is reduced:  $M(\vec{x}_i^*) < M(\vec{x}_{i-1})$
  - (b)  $\gamma < \alpha$  where  $\gamma$  is a random number sampled from the uniform distribution  $[0,1]$  and  $\alpha$  is a scalar parameter,  $\alpha \in [0,1]$ . This allows the inversion to escape local minima.

Otherwise, rejected the proposed parameters and keep the previous solution,  $\vec{x}_i = \vec{x}_{i-1}$

These steps are repeated until the specified number of iterations is reached.

### i. Misfit Function

In the current version of the inversion code, the misfit function is defined as the difference between the normalized amplitude of the simulated spectra and the data. The misfit function at iteration  $i$  is given by:

$$M(\vec{x}_i) = ||A_{\text{data}} - A(\vec{x}_i)||_2, \quad (2)$$

where  $A_{\text{data}}$  and  $A(\vec{x}_i)$  are the normalized amplitude spectra of the data and simulated spectra at the  $i$ th iteration, respectively. This is the misfit function used by Watson et al. (2020).

Watson et al. (2019) previously defined the misfit function as the difference between the peak frequency and quality factor:

$$M(\vec{x}_i) = \beta_f \frac{|f_0^d - f_0(\vec{x}_i)|}{f_0^d} + \beta_Q \frac{|Q^d - Q(\vec{x}_i)|}{Q^d}, \quad (3)$$

where  $f_0^d$  and  $Q^d$  are the peak frequency and quality factor of the data,  $f_0(\vec{x}_i)$  and  $Q(\vec{x}_i)$  are the peak frequency and quality factor of the simulated infrasound signal at iteration  $i$  for parameters  $\vec{x}_i$ , and  $\beta_f$  and  $\beta_Q$  are weighting parameters. Future updates may add the capability to choose between these two misfit functions.

### ii. Parameterization

The crater geometry is parameterized as a depth,  $L$ , and  $N$  radii values,  $r^k$  where  $k = 1, \dots, N$ . Hence, the parameter vector at the  $i$ th iteration is  $\vec{x}_i = [L_i, r_i^1, r_i^2, \dots, r_i^N]$ . The radii values are equally spaced in depth from the crater outlet to the base. The depth evolves with each iteration

and hence the depths of radii values are also updated with each iteration. The depth of the  $k$ th radii value at the  $i$ th iteration is given by:

$$z_i^k = (k - 1) \frac{L_i}{N - 1}. \quad (4)$$

The crater geometry is linearly interpolated between the  $N$  radii values to create a crater profile that can be used to simulate the infrasound signal. Future work may consider alternative interpolation methods that do not create kinks in the crater geometry.

While the inversion scheme is designed to invert harmonic infrasound observations for the crater geometry, there is also the capability to invert for the width of a specified source (Gaussian or Brune). However, this has not been extensively tested. Furthermore, inverting for the source and geometry simultaneously results in an unstable inversion. Future work may explore source parameterization and inversion.

#### IV. USING CRes INVERSION

The **demo** folder contains several example script files with synthetic and real data:

- `forward_synthetic.m` performs the forward problem and simulates the infrasound signal for a given crater geometry. The infrasound spectra is saved as `forwardSpectra.mat`.
- `inversion_synthetic.m` solves the inversion problem with the synthetic spectra.
- `inversion_data.m` solves the inversion problem with real data. Here, we use data from the December 2018 eruption of Mount Etna (Italy), saved as `Etna2018Phase1.mat` and `Etna2018Phase3.mat` for before and after the onset of the flank eruption, respectively.
- `visualization_synthetic.m` and `visualization_data.m` display the inversion results.

In order to perform the inversion, there are several sets of parameters that need to be specified. Firstly, the parameters that control the forward simulations. These include the frequency range to simulate and the temperature of the crater and atmosphere.

```
% set the parameters for the resonance1d calculations
T = 25; % total time (s)
N = 250; % number of grid points (formulas assume even N)
dt = T/N; % time step (s)
Nyquist = 1/(2*dt); % Nyquist frequency (Hz)
Nf = N/2+1; % number of frequency samples
freq = [0 Nyquist]; % frequency range (Hz)
discrParams = [T N Nf Nyquist dt]; % save parameters into array

craterTemp = 100; % crater temperature
atmoTemp = 0; % atmospheric temperature
temp = [craterTemp, atmoTemp];

order = 4; % order of numerical scheme (4, 6 or 8)
style = 'baffled piston'; % acoustic radiation model ('monopole' or 'baffled piston')
M = problemParametersInv(craterTemp, atmoTemp); % problem parameters required for
resonance1d
```

Secondly, there are several options in the inversion scheme that need to be specified including the number of iterations, parameter step size, and frequency range of the misfit function (equation 2).

```
nIter = 10000; % number of steps
dx = 0.05; % step size % use step size of 0.05 for paper inversions
freqLim = 3; % high cut frequency limit for misfit function (Hz)
```

Thirdly, the inversion needs to be initialized and parameter bounds specified. Here, we only invert for the crater geometry and assume a specified source.

```
geomFlag = 1; % invert for geometry (boolean, 0 = no, 1 = yes)
geomR0 = 100; % radius of initial cylinder
geomDepth = 150; % depth
geomParams = [geomDepth geomR0 geomR0 geomR0 geomR0 geomR0]; % first value is depth,
               other values are radius points that are equally spaced
geomLowerBnds = [50 60 1 1 1 1 1];
geomUpperBnds = [150 120 120 120 120 120 120];
nx = length(geomParams) - 1; % number of geometry parameters
```

There are currently two inversion scheme included in the repository, `mcmc_spec` and `mcmc_spec_noFilt`. Both of these inversion scheme use the MCMC scheme described above and the misfit function shown in equation 2. The difference is that in `mcmc_spec` the simulated infrasound signal is bandpass filtered. This enables the simulated signal to be processed in the same way as the data may be processed. The filter properties are specified by:

```
filterband = [0.25 4.8]; % frequency band to filter
filterorder = 4; % order of butterworth filter
Fs = 10; % sampling frequency
filterProps = [filterband, filterorder, Fs]; % filter properties – same as for data
```

Note that there are numerous variables that must be specified to run the inversion. Details are included in the function files and examples are shown below for `mcmc_spec_noFilt` and `mcmc_spec`, respectively:

```
[x, misfit, simSpec, f, count] = mcmc_spec_noFilt(nIter, dx, ... % perform MCMC inversion
        geomParams, geomFlag, srcParams, srcFlag, srcStyle, ...
        lowerBnds, upperBnds, discrParams, temp, ...
        data_freq, freqLim);
```

```
[x, misfit, simSpec, f, count] = mcmc_spec(nIter, dx, ... % perform MCMC inversion
        geomParams, geomFlag, srcParams, srcFlag, srcStyle, ...
        lowerBnds, upperBnds, discrParams, temp, ...
        filterProps, data_freq, freqLim);
```

The outputs from the inversion are:

- `x` - inversion parameter values at each successful iteration.
- `misfit` - value of misfit at each successful iteration (a successful iteration is defined as where the misfit function is reduced or  $\gamma < \alpha$ ).
- `simSpec` - simulated amplitude spectra.
- `f` - frequency vector.
- `count` - number of successful iterations.

## V. EXAMPLES

### i. Synthetic Inversion

Here, we perform a synthetic inversion. We prescribe the crater geometry with the representative Villarrica (Chile) geometry used by Johnson et al. (2018). This geometry is saved in the **demo** directory as `Johnson2018.mat`. The crater has a depth of 120 m.

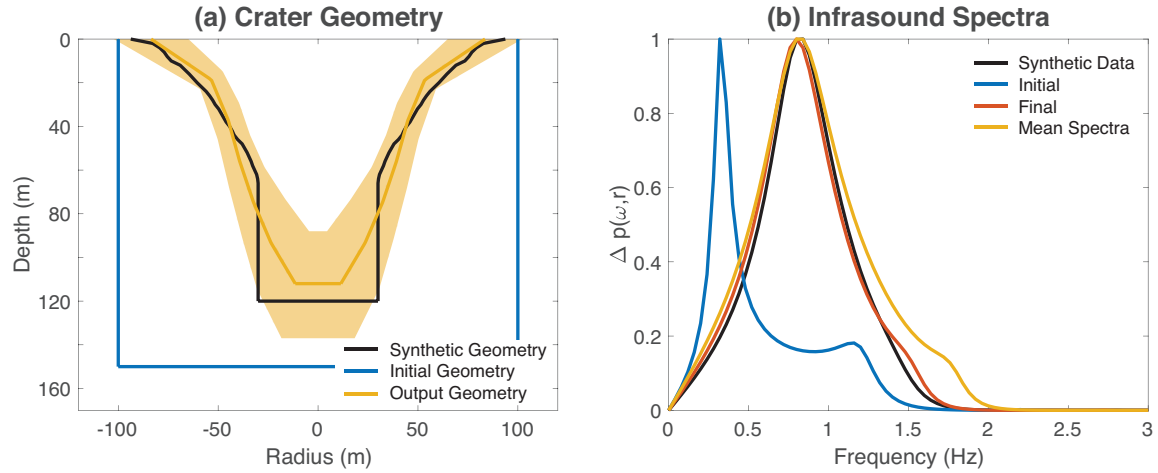
`forward_synthetic.m` performs the forward problem to simulate the infrasound signal for the prescribed crater geometry. The crater temperature is 100°C and the atmospheric temperature is

0°C, which gives speed of sound of 387 m/s in the crater and 331 m/s in the atmosphere. The source is a Gaussian pulse:

$$s(t) = \exp\left(-\frac{1}{2} \frac{t^2}{\sigma^2}\right), \quad (5)$$

with  $\sigma = 0.2$  s controls the width of the pulse.

We initialize the crater geometry as a cylinder with a radius of 100 m and a depth of 150 m and use  $N = 7$  radii values to parameterize the geometry. Figure 1 shows the initial crater geometry and simulated infrasound spectra, which is a poor match to the synthetic data. We perform 10,000 iterations using  $\Delta x = 0.05$  and  $\alpha = 0.1$  with the misfit function is calculated between 0 Hz and 3 Hz. The inverted infrasound signal converges to the synthetic data and the inverted crater geometry well matches the synthetic geometry.



**Figure 1:** Synthetic inversion results showing (a) crater geometry and (b) infrasound spectra. Shaded region in (a) indicates  $\pm 1$  standard deviation in crater geometry parameters.

## ii. Mount Etna Inversion

We now consider harmonic infrasound observations recorded during the December 2018 eruption of Mount Etna (Italy). For more details, see Watson et al. (2020). Here, we consider the harmonic infrasound observations recorded after the flank eruption and use the inversion scheme presented here to invert for the crater geometry.

We initialize the crater geometry as a cylinder with a radius of 100 m and a depth of 200 m and use  $N = 5$  radii values to parameterize the geometry. Based on satellite observations, the crater outlet radius is constrained to be between 80 m and 120 m while the other parameters are unconstrained. We assume a crater temperature of 100°C and an atmospheric temperature is 0°C. The source is described as a Brune spectra:

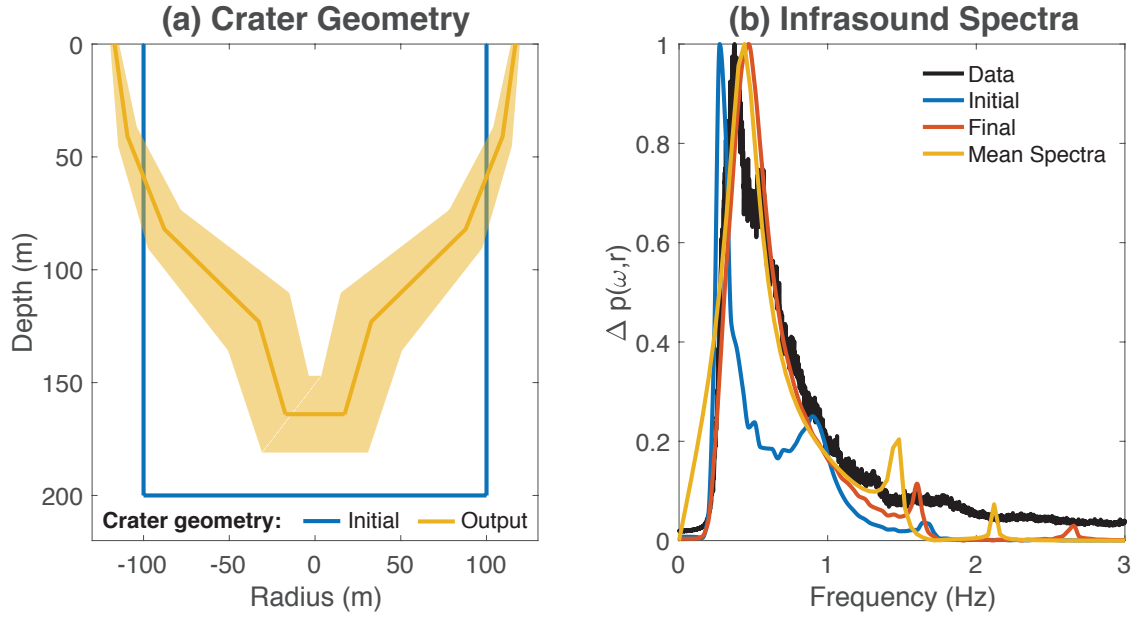
$$s(t) = tH(t) \exp\left(-\frac{t}{\sigma}\right), \quad (6)$$

where  $H$  is the Heaviside function and  $\sigma$  controls the width of the source. We assume  $\sigma = 0.3$  s.

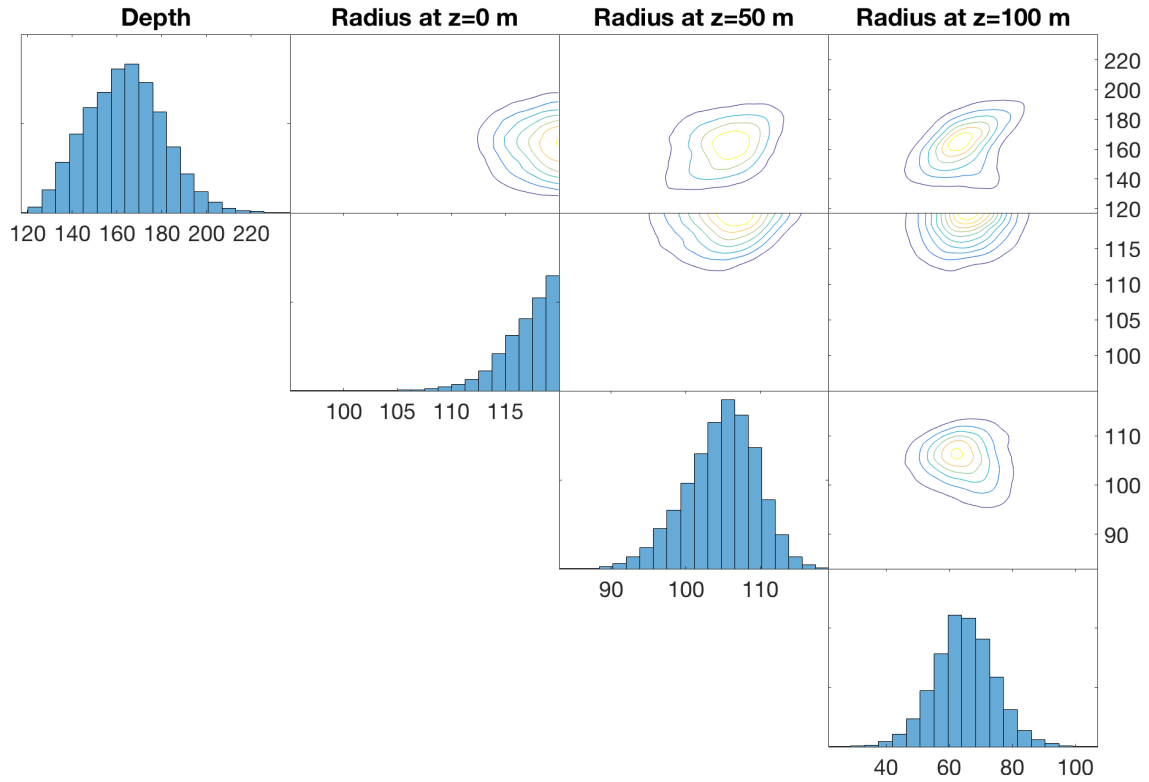
The inversions are run for  $1 \times 10^5$  iterations with  $\Delta x = 0.05$  and  $\alpha = 0.1$  with the misfit function is calculated between 0 Hz and 3 Hz. The simulated infrasound signals are high pass filtered at 0.25 Hz with a 4th order Butterworth filter to match the processing applied to the data.

Inversion results are shown in Figure 2. The output spectra is a much better fit to the infrasound spectra than the initial estimate for the cylindrical crater. The output crater geometry has an outlet radius of 117 m and a depth of 164 m. The crater narrow significantly at depth with a base radius of 18 m.

In addition to plotting the mean crater geometry, we can plot distributions of the various geometry parameters, as shown in Figure 3. This can shed insight on the inversion results, such as showing how well constrained different parameters are or are not. Dependencies between various parameters can be determined by plotting the correlations between parameters.



**Figure 2:** Inversion results for after the onset of the December 24, 2018 flank eruption of Mount Etna showing (a) crater geometry and (b) infrasound spectra. Shaded region in (a) indicates  $\pm 1$  standard deviation in crater geometry parameters



**Figure 3:** Distributions of geometry parameters (depth, radius at  $z=0$ , 50, and 100 m) and correlations between the parameters. Note that the inversion outputs radii values at  $N$  positions equally spaced in depth between outlet and base of crater. Therefore, the output parameters are interpolated between to determine the distributions at specified depths.

## REFERENCES

- Johnson, J. B., Watson, L. M., Palma, J. L., Dunham, E. M., Anderson, J. F., 2018. Forecasting the eruption of an open-vent volcano using resonant infrasound tones. *Geophysical Research Letters*, 1–8.
- Watson, L. M., Dunham, E. M., Johnson, J. B., 2019. Simulation and inversion of harmonic infrasound from open-vent volcanoes using an efficient quasi-1D crater model. *Journal of Volcanology and Geothermal Research* 380, 64–79.
- Watson, L. M., Johnson, J. B., Sciotto, M., Cannata, A., 2020. Changes in crater geometry revealed by inversion of harmonic infrasound observations : 24 December 2018 eruption of Mount Etna , Italy. *Geophysical Research Letters*.