

demo

January 14, 2018

1 A demonstration of some basic computations using infotopo package

- Link: <http://github.com/leihuang/infotopo>
- Reference: <https://github.com/leihuang/infotopo/blob/master/docs/PhDThesisLeiHuang.pdf> (Section 2.7)
- About SloppyCell, around which much of the computation on reaction networks in rxnnet is wrapped: <http://sloppycell.sourceforge.net/user.pdf>

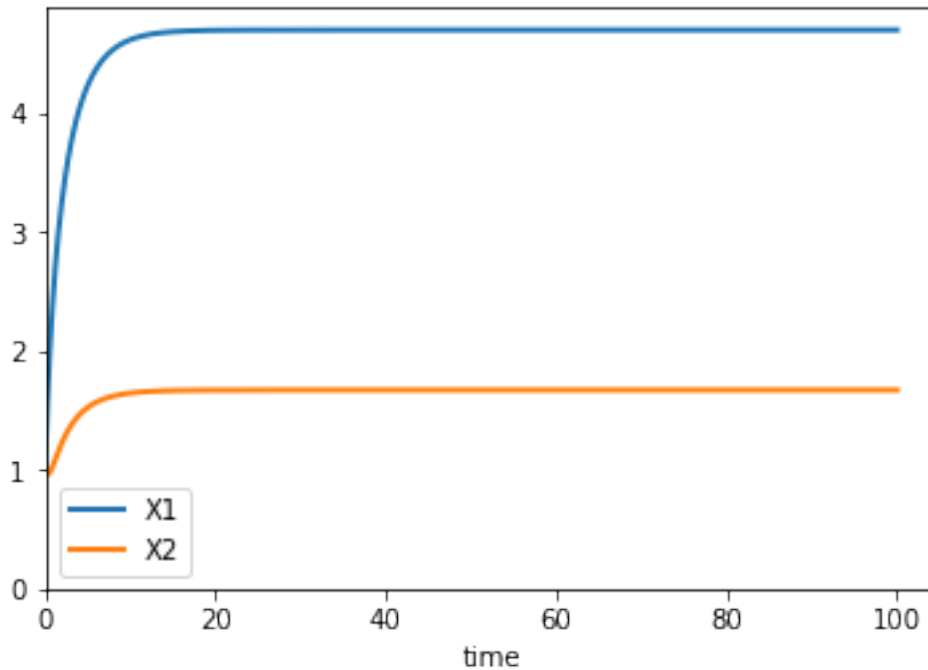
```
In [1]: from __future__ import division, print_function, absolute_import
        from collections import OrderedDict as OD
```

```
        from rxnnet import network, mca, experiments, util
        from infotopo import residual, fitting, sampling
```

```
In [2]: net = network.Network('path3mmh')
        net.add_compartment(id='env')
        net.add_compartment(id='cell')
        net.add_species(id='C1', compartment='env', initial_value=2, is_constant=True)
        net.add_species(id='C2', compartment='env', initial_value=0.5, is_constant=True)
        net.add_species(id='X1', compartment='cell', initial_value=1)
        net.add_species(id='X2', compartment='cell', initial_value=1)
        net.add_reaction(id='R1', eqn='C1<->X1', ratelaw='V1f/K1C1*(C1-X1/KE1)/(1+C1/K1C1+X1/K1X1)',
                        p=OD([('V1f',1),('K1C1',1),('K1X1',1),('KE1',5)]))
        net.add_reaction(id='R2', eqn='X1<->X2', ratelaw='V2f/K2X1*(X1-X2/KE2)/(1+X1/K2X1+X2/K2X2)',
                        p=OD([('V2f',1),('K2X1',1),('K2X2',1),('KE2',4)]))
        net.add_reaction(id='R3', eqn='X2<->C2', ratelaw='V3f/K3X2*(X2-C2/KE3)/(1+X2/K3X2+C2/K3C2)',
                        p=OD([('V3f',1),('K3X2',1),('K3C2',1),('KE3',1)]))
        for KEid in ['KE1', 'KE2', 'KE3']:
            net.set_var_optimizable(KEid, False)
```

```
In [3]: p = net.p.randomize(seed=0, sigma=1)
```

```
In [17]: traj = net.get_traj((0,100), p=p)
        traj.plot()
```



```
In [5]: # get steady-state concentrations
        s = net.get_s(p=p)
        print(s)
```

```
X1    4.704357
X2    1.673599
dtype: float64
```

```
In [6]: # Structural calculation: get stoichiometry matrix and steady-state flux vectors
        print(net.N, '\n\n', net.K)
```

```
      R1  R2  R3
X1    1  -1   0
X2    0   1  -1
```

```
      J1
R1    1
R2    1
R3    1
```

```
In [7]: # MCA calculation: get flux control matrix (rows should sum up to one by the Summation
        nCJ = mca.get_flux_control_matrix(net, p=p, normed=True)
        print(nCJ, '\n')
        print(nCJ.sum(axis=1))
```

	R1	R2	R3
R1	0.276937	0.372677	0.350386
R2	0.276937	0.372677	0.350386
R3	0.276937	0.372677	0.350386

```

R1    1.0
R2    1.0
R3    1.0
dtype: float64

```

At the core of **information geometry** and **information topology** is the abstraction of mathematical models as functions (f) that map from parameters (p) to predictions (y):

$$f : p \mapsto y, \text{ or } y = f(p)$$

With an f specified, one can do a number of standard modeling tasks: * **Parameter estimation**: $p^* = f^{-1}(y)$ with uncertainty estimated as $\delta p = (Df^{-1}) \delta y$ * **Ensemble sampling**: eg, sampling posterior distribution $f(p|y) \propto f(p)f(y|p)$ * **Model comparison** (which includes **model selection** and **model reduction**): given f_1 and f_2 that both predict y , how does one compare them and which one is better?

```

In [8]: # get experiments objects that specify the model predictions (that is, y)
expts_xc = experiments.get_experiments(net.xids, ['C1', 'C2'],
                                         us=util.get_product(*[[1,2,3]]*2))
expts_jc = experiments.get_experiments(net.Jids[0], ['C1', 'C2'],
                                         us=util.get_product(*[[1,2,3]]*2))

```

```

In [18]: expts_xc

```

```

Out[18]:

```

	condition	varids	times
experiment			
1	((C1, =, 1), (C2, =, 1))	[X1, X2]	[inf]
2	((C1, =, 1), (C2, =, 2))	[X1, X2]	[inf]
3	((C1, =, 1), (C2, =, 3))	[X1, X2]	[inf]
4	((C1, =, 2), (C2, =, 1))	[X1, X2]	[inf]
5	((C1, =, 2), (C2, =, 2))	[X1, X2]	[inf]
6	((C1, =, 2), (C2, =, 3))	[X1, X2]	[inf]
7	((C1, =, 3), (C2, =, 1))	[X1, X2]	[inf]
8	((C1, =, 3), (C2, =, 2))	[X1, X2]	[inf]
9	((C1, =, 3), (C2, =, 3))	[X1, X2]	[inf]

```

In [9]: # combine model objects and experiments objects to get predict objects (that is, f)
pred_xc = net.get_predict(expts_xc, tol=1e-13)
pred_jc = net.get_predict(expts_jc, tol=1e-13)
pred = pred_xc + pred_jc

```

Spectrum refers to the list of **singular values** of Df and the number of zeros tells how well-conditioned is f .

Here, the presence of two numerical zeros mean that f has two degrees of **structural non-identifiability** if we use only steady-state concentration data, and that goes away if we *also* use steady-state flux data.

```
In [10]: print(pred_xc.get_spectrum(p))
         print(pred.get_spectrum(p))
```

```
[ 1.20905442e+01  4.93033641e+00  2.52758635e-01  1.39687397e-01
 1.01009238e-01  3.91820667e-02  8.71208005e-03  2.56166801e-16
 1.30507017e-16]
[ 1.22337512e+01  4.93141522e+00  8.37274936e-01  2.49733197e-01
 1.38769116e-01  6.64837163e-02  3.77714875e-02  9.85294255e-03
 3.33095961e-03]
```

```
In [11]: # generating simulation data
         dat = pred.get_dat(p=p)
         print(dat)
```

	Y	sigma
((C1, =, 1), (C2, =, 1)), X1, inf	2.946751	1.0
((C1, =, 1), (C2, =, 1)), X2, inf	1.810122	1.0
((C1, =, 1), (C2, =, 2)), X1, inf	3.415678	1.0
((C1, =, 1), (C2, =, 2)), X2, inf	2.923024	1.0
((C1, =, 1), (C2, =, 3)), X1, inf	3.719251	1.0
((C1, =, 1), (C2, =, 3)), X2, inf	3.971140	1.0
((C1, =, 2), (C2, =, 1)), X1, inf	5.312293	1.0
((C1, =, 2), (C2, =, 1)), X2, inf	2.366553	1.0
((C1, =, 2), (C2, =, 2)), X1, inf	6.115603	1.0
((C1, =, 2), (C2, =, 2)), X2, inf	3.616832	1.0
((C1, =, 2), (C2, =, 3)), X1, inf	6.658750	1.0
((C1, =, 2), (C2, =, 3)), X2, inf	4.772198	1.0
((C1, =, 3), (C2, =, 1)), X1, inf	7.452233	1.0
((C1, =, 3), (C2, =, 1)), X2, inf	2.820369	1.0
((C1, =, 3), (C2, =, 2)), X1, inf	8.545576	1.0
((C1, =, 3), (C2, =, 2)), X2, inf	4.179453	1.0
((C1, =, 3), (C2, =, 3)), X1, inf	9.301372	1.0
((C1, =, 3), (C2, =, 3)), X2, inf	5.422006	1.0
((C1, =, 1), (C2, =, 1)), J_R1, inf	0.578283	1.0
((C1, =, 1), (C2, =, 2)), J_R1, inf	0.419593	1.0
((C1, =, 1), (C2, =, 3)), J_R1, inf	0.326581	1.0
((C1, =, 2), (C2, =, 1)), J_R1, inf	0.845595	1.0
((C1, =, 2), (C2, =, 2)), J_R1, inf	0.655089	1.0
((C1, =, 2), (C2, =, 3)), J_R1, inf	0.539740	1.0
((C1, =, 3), (C2, =, 1)), J_R1, inf	1.016070	1.0
((C1, =, 3), (C2, =, 2)), J_R1, inf	0.811509	1.0
((C1, =, 3), (C2, =, 3)), J_R1, inf	0.685206	1.0

```
In [12]: # make a residual object that contains the predict object and data,
# and do the fitting (using Levenberg-Marquardt algorithm)
res = residual.Residual(pred=pred, dat=dat)
fit = fitting.fit_lm_scipy(res, p0=p.randomize(sigma=0.2))
```

```
In [13]: fit.p
```

```
Out[13]: V1f      5.836039
         K1C1      1.492059
         K1X1      2.661096
         V2f      9.401725
         K2X1      6.472471
         K2X2      0.376334
         V3f      2.585938
         K3X2      0.859541
         K3C2      0.901930
         dtype: float64
```

```
In [14]: # confirm that the best fit parameter recovers the original parameter used for genera
fit.p - p
```

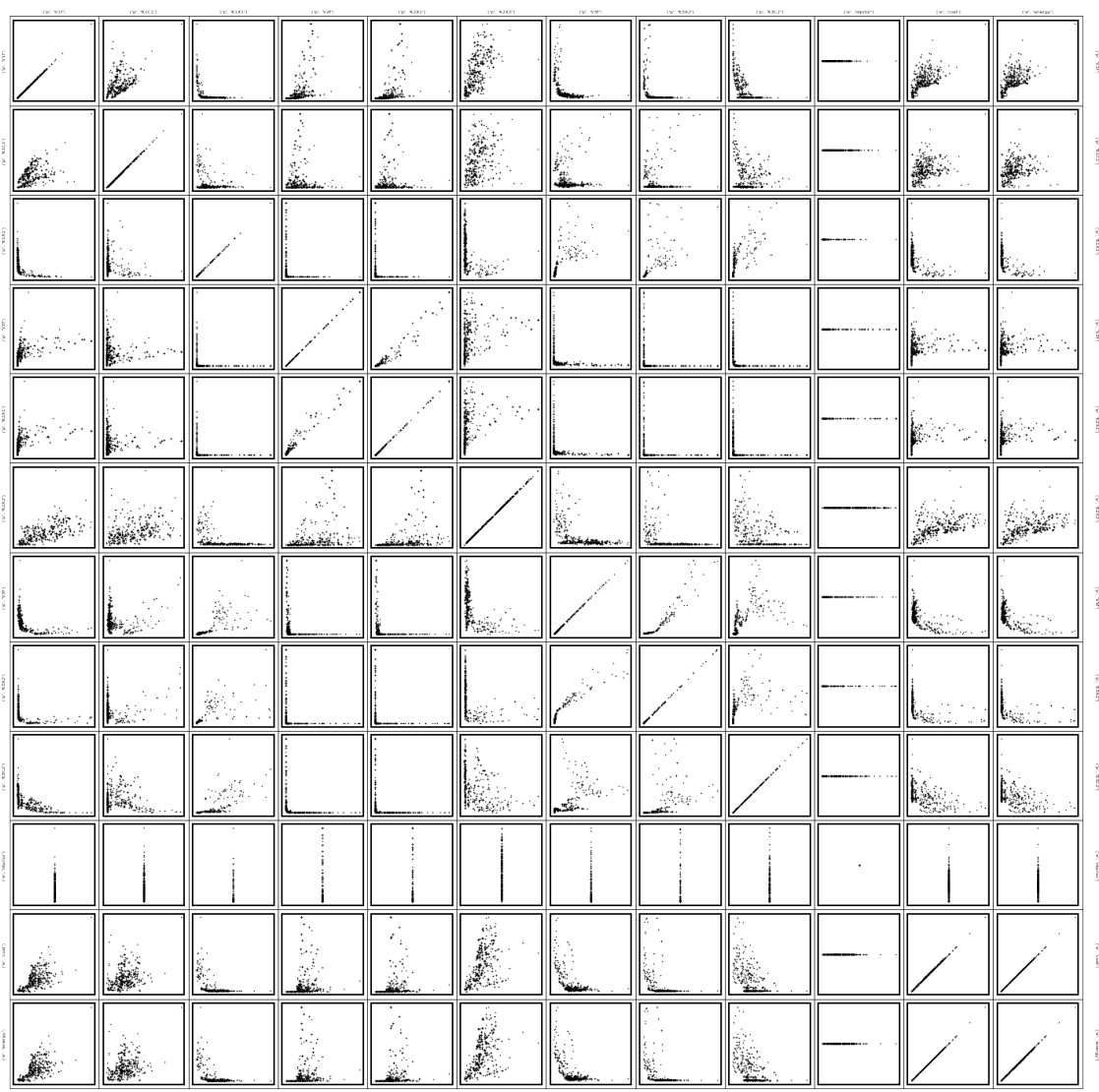
```
Out[14]: V1f      -2.842171e-14
         K1C1     -5.107026e-15
         K1X1      1.376677e-14
         V2f      9.237056e-14
         K2X1      1.012523e-13
         K2X2      2.164935e-15
         V3f      3.552714e-15
         K3X2      1.776357e-15
         K3C2     -1.776357e-15
         dtype: float64
```

```
In [15]: # generating ensembles
```

```
ens = sampling.sampling(res, 1000, stepscale=0.1, interval_print_step=100)
```

```
100
200
300
400
500
600
700
800
900
1000
```

```
In [16]: # scatter-plot the ensembles
ens.scatter()
```



In []: