

Figure 2.18: Relationships between the core classes in the package infotopo. The central class is Predict (ie, a prediction map f), derived from a Model object (specifying a mathematical model \mathscr{M}) and an Experiments object (specifying a behavioral space B and a sampling X). With a Predict object, one can perform a number of standard modeling tasks: generating predictions, fitting it to data (by creating a Residual ob-

integrated to form a Trajectory object and the limiting behaviors can be examined in a Limit object (only partially implemented so far; hence the dashed box) constructed from an integrated geodesic; sampling many limiting behaviors starts to accumulate global and topological information, stored in a HasseDiagram object.

ject and computing a Fit object), and sampling the parameter space using different combinations of priors and posteriors (represented by Ensemble objects). A Predict object is also key to some information geometric and information topological analysis: it can generate a Geodesic object, which can be