GPU computing with Julia

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August 13, 2021







▶ What is a GPU?



- ▶ What is a GPU?
- ► What is Julia?



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- ► What is Julia?
- ► What is CUDA?



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- ► What is Julia?
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- ▶ What is Kernel Abstractions?



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- ► What is Julia?
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- ▶ What is Kernel Abstractions?
- ▶ What is a more complicated example?



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- ► What is Julia?
- ▶ What is CUDA?
- ▶ What is Kernel Abstractions?
- What is a more complicated example?
- ▶ What is the meaning of life?

What is a GPU?



What is a GPU?





This thing

Yeah, but what does it do?



Yeah, but what does it do?





Graphics

Yeah, but what does it do?





Graphics

(In parallel, though)





Dunno, dawg. You are the one that decided to attend this mini-course



If used correctly, GPUs can be much faster for certain tasks



If used correctly, GPUs can be much faster for certain tasks

(But they can also be way slower for other tasks)





- ► The Grid is split into Blocks
- ► Blocks are split into Threads

T_0	T_1	T_2	T_3			
T_4	T_5	T_6	T_7	\mathbf{B}_1	\mathbf{B}_2	\mathbf{B}_3
T_8	T_9	T_{10}	T_{11}	D ₁	D ₂	D ₃
T_{12}	T_{13}	T_{14}	T_{15}			
	E	8_4		\mathbf{B}_{5}	\mathbf{B}_{6}	\mathbf{B}_7
					4	
					0	
	E	3 8		\mathbf{B}_{9}	\mathbf{B}_{10}	\mathbf{B}_{11}
	В	12		\mathbf{B}_{13}	\mathbf{B}_{14}	\mathbf{B}_{15}
	Ъ	12		₽13	₽14	₽15
1						



- ► The Grid is split into Blocks
- ► Blocks are split into Threads
- ► Threads have local memory
- Everything has global memory

T_0	T_1	T_2	T_3			
T_4	T_5	T_6	T_7	\mathbf{B}_1	\mathbf{B}_2	\mathbf{B}_3
T_8	T_9	T_{10}	T_{11}	\mathbf{D}_1	\mathbf{D}_2	\mathbf{D}_3
T_{12}	T_{13}	T_{14}	T_{15}			
	Е	3 ₄		\mathbf{B}_{5}	\mathbf{B}_6	\mathbf{B}_7
	Е	3 ₈		\mathbf{B}_9	\mathbf{B}_{10}	\mathbf{B}_{11}
	В	12	\mathbf{B}_{13}		\mathbf{B}_{14}	\mathbf{B}_{15}



- ► The Grid is split into Blocks
- ► Blocks are split into Threads
- ► Threads have local memory
- Everything has global memory
- Shared mem is faster than global memory, but a pain to use

ſ	T_0	T_1	T_2	T_3				
	T_4	T_5	T_6	T_7	\mathbf{B}_1	\mathbf{B}_2	\mathbf{B}_3	
	T_8	T_9	T_{10}	T_{11}	\mathbf{D}_1	\mathbf{D}_2	\mathbf{D}_3	
	T_{12}	T_{13}	T_{14}	T_{15}				
		E	3_{4}		\mathbf{B}_{5}	\mathbf{B}_{6}	\mathbf{B}_{7}	
			•		_			
					G	<u>'</u>		
						. 0		
		E	3_8		\mathbf{B}_{9}	\mathbf{B}_{10}	\mathbf{B}_{11}	
		В	12		\mathbf{B}_{13}	\mathbf{B}_{14}	\mathbf{B}_{15}	
						$egin{array}{c} {\bf B}_6 \\ {\bf O} \\ {\bf B}_{10} \\ {\bf B}_{14} \end{array}$	\mathbf{B}_{7} \mathbf{B}_{11} \mathbf{B}_{15}	





Ah, like everything

Iterative things are bad because threads are weak

T_4 T_8	\rightarrow	T_2 T_6 T_{10}	T ₃ T ₇ T ₁₁	${f B}_1$	\mathbf{B}_2	${f B}_3$
T ₁₂	В	T ₁₄	T ₁₅	\mathbf{B}_{5}	${f B}_6$	\mathbf{B}_7
	В	8		${f B}_9$	$egin{array}{c} egin{array}{c} \egin{array}{c} \egin{array}{c} \egin{array}{c} \egin{array}{c} \egin{array}{c} \egin{array}$	\mathbf{B}_{11}
	\mathbf{B}_1	12		\mathbf{B}_{13}	\mathbf{B}_{14}	\mathbf{B}_{15}



- Iterative things are bad because threads are weak
- ▶ Really big problems (> 32 GB) are bad because we have limited memory

T_0 T_4	T_1 T_5	T ₂	T_3 T_7			
T_8	T ₉	T_{10}	T ₁₁	\mathbf{B}_1	\mathbf{B}_2	\mathbf{B}_3
T_{12}	T_{13}	T_{14}	T_{15}			
	Е	\mathbf{B}_4		\mathbf{B}_{5}	\mathbf{B}_{6}	${f B}_7$
	Е	B ₈		\mathbf{B}_9	\mathbf{B}_{10}	\mathbf{B}_{11}
	В	12		\mathbf{B}_{13}	\mathbf{B}_{14}	\mathbf{B}_{15}



- Iterative things are bad because threads are weak
- ▶ Really big problems (> 32 GB) are bad because we have limited memory
- Recursive things are bad because threads are weak and we have limited memory

T_0	T_1	T_2	T_3			
T_4	T_5	T_6	T_7	\mathbf{B}_1	\mathbf{B}_2	\mathbf{B}_3
T_8	T_9	T_{10}	T_{11}	\mathbf{D}_1	\mathbf{D}_2	D 3
T_{12}	T_{13}	T_{14}	T_{15}			
	Е	\mathbf{B}_4		\mathbf{B}_{5}	\mathbf{G}_0	
	Е	B ₈		\mathbf{B}_{9}	\mathbf{B}_{10}	\mathbf{B}_{11}
	В	12		\mathbf{B}_{13}	\mathbf{B}_{14}	\mathbf{B}_{15}



- ► Iterative things are bad because threads are weak
- ▶ Really big problems (> 32 GB) are bad because we have limited memory
- Recursive things are bad because threads are weak and we have limited memory
- Good luck getting data off the GPU and onto your SSD with any reasonable speed

T_0	T_1	T_2	T_3			
T_4	T_5	T_6	T_7	\mathbf{B}_1	\mathbf{B}_2	\mathbf{B}_3
T_8	T_9	T_{10}	T_{11}	\mathbf{D}_1	\mathbf{D}_2	D 3
T_{12}	T_{13}	T_{14}	T_{15}			
	_			_	_	_
	E	3 ₄		\mathbf{B}_{5}	\mathbf{B}_{6}	\mathbf{B}_7
				(<u> </u>	0	
	Е	3 ₈		\mathbf{B}_{9}	\mathbf{B}_{10}	\mathbf{B}_{11}
	В	12		\mathbf{B}_{13}	\mathbf{B}_{14}	\mathbf{B}_{15}



- Iterative things are bad because threads are weak
- ► Really big problems (> 32 GB) are bad because we have limited memory
- Recursive things are bad because threads are weak and we have limited memory
- Good luck getting data off the GPU and onto your SSD with any reasonable speed
- Please don't do multi-GPU. Just... Please.

T_0	T_1	T_2	T_3			
T_4	T_5	T_6	T_7	\mathbf{B}_1	\mathbf{B}_2	\mathbf{B}_3
T_8	T_9	T_{10}	T_{11}	D 1	\mathbf{D}_2	\mathbf{D}_3
T_{12}	T_{13}	T_{14}	T_{15}			
	F	8_4		\mathbf{B}_{5}	\mathbf{B}_{6}	\mathbf{B}_{7}
	_	4		2,	20	
				(C	()	
				_	• U	
	Ε	\mathbf{B}_8		\mathbf{B}_{9}	\mathbf{B}_{10}	\mathbf{B}_{11}
				_		
	В	12		\mathbf{B}_{13}	\mathbf{B}_{14}	\mathbf{B}_{15}

So, uh...



But, I mean, they can do matrix operations quickly, so there's that.

but...



Pop-quiz: What's the slowest part of any *n*-dimensional FFT operation?

but...



Pop-quiz: What's the slowest part of any *n*-dimensional FFT operation?

The transpose

What is Julia?



Live demo (hopefully)

What is CUDA



Again, live demo

What is CUDA.jl



We are doing it live!

What is Kernel Abstractions



Why did you even make these slides?