

Chapter 2: Operating-System Structures

Chapter 2: Operating-System Structures

- Operating System Services
- User Operating System Interface
- System Calls
- Types of System Calls
- System Programs
- Operating System Design and Implementation
- Operating System Structure
- Operating System Debugging
- Operating System Generation
- System Boot

Objectives

- To describe the services an operating system provides to users, processes, and other systems
- To discuss the various ways of structuring an operating system



Operating System Services

- Operating systems provide an environment for execution of programs and services to programs and users
- One set of operating-system services provides **functions that are helpful to the user:**
 - **User interface** - Almost all operating systems have a user interface ([UI](#)).
 - ▶ Varies between **Command-Line (CLI)**, **Graphics User Interface (GUI)**, **Batch**
 - **Program execution** - The system must be able to load a program into memory and to run that program, end execution, either normally or abnormally (indicating error)
 - **I/O operations** - A running program may require I/O, which may involve a file or an I/O device

Operating System Services (Cont.)

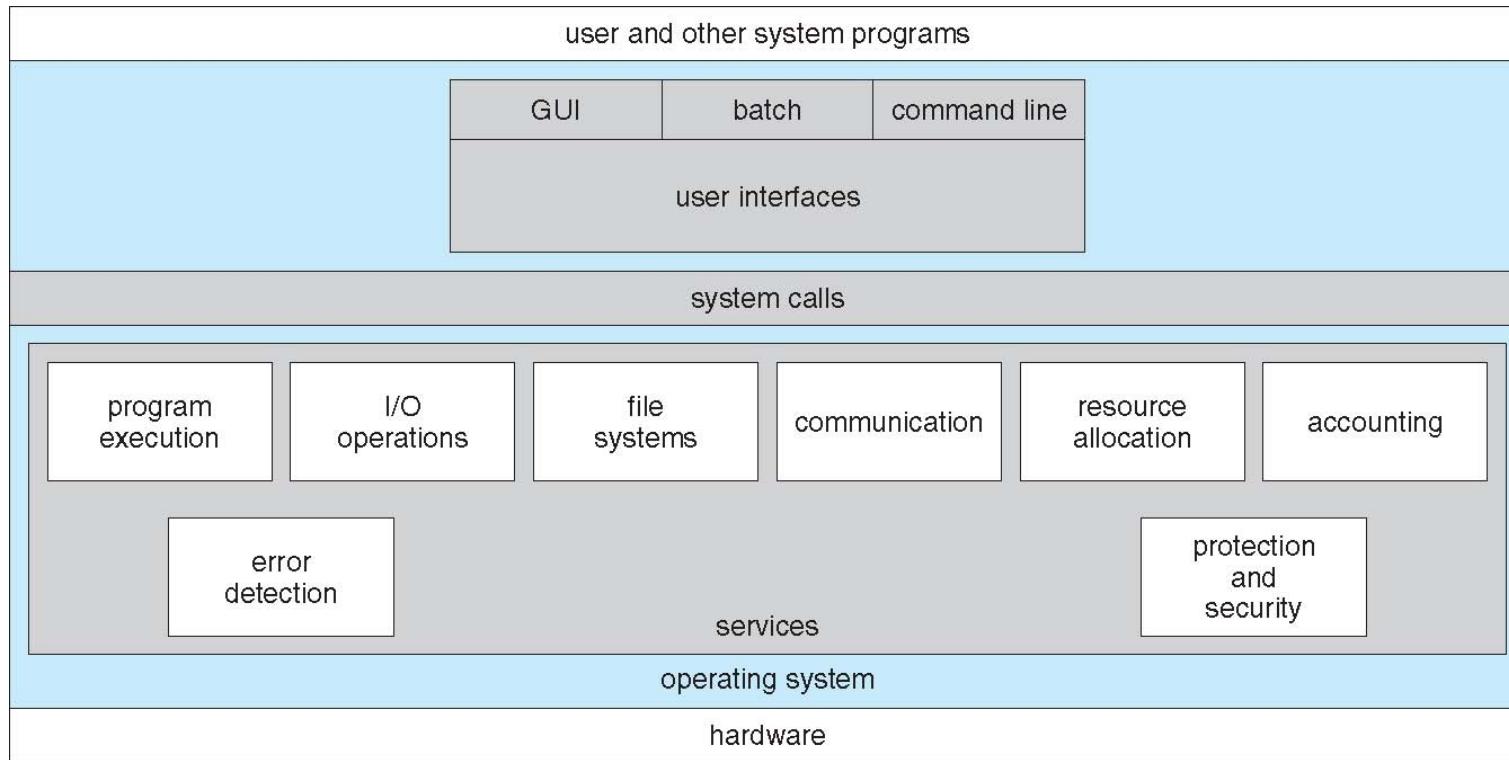
- One set of operating-system services provides **functions that are helpful to the user (계속)**:
 - **File-system manipulation** - The file system is of particular interest. Programs need to **read** and **write** files and directories, **create** and **delete** them, **search** them, **list** file information, permission management.
 - **Communications** – Processes may exchange information, on the same computer or between computers over a network
 - ▶ Communications may be via **shared memory** or through **message passing** (packets moved by the OS)
 - **Error detection** – OS needs to be constantly aware of possible errors
 - ▶ May occur in the CPU and memory hardware, in I/O devices, in user program
 - ▶ For each type of error, OS should take the appropriate action to ensure correct and consistent computing
 - ▶ Debugging facilities can greatly enhance the user's and programmer's abilities to efficiently use the system



Operating System Services (Cont.)

- Another set of OS functions exists for **ensuring the efficient operation of the system itself via resource sharing**
 - **Resource allocation** - When multiple users or multiple jobs running concurrently, resources must be allocated to each of them
 - ▶ Many types of resources - CPU cycles, main memory, file storage, I/O devices.
 - **Accounting** - To keep track of which users use how much and what kinds of computer resources
 - **Protection and security** - The owners of information stored in a multiuser or networked computer system may want to control use of that information, concurrent processes should not interfere with each other
 - ▶ **Protection** involves ensuring that **all access to system resources is controlled**
 - ▶ **Security** of the system from outsiders requires user authentication, extends to defending external I/O devices from invalid access attempts

A View of Operating System Services

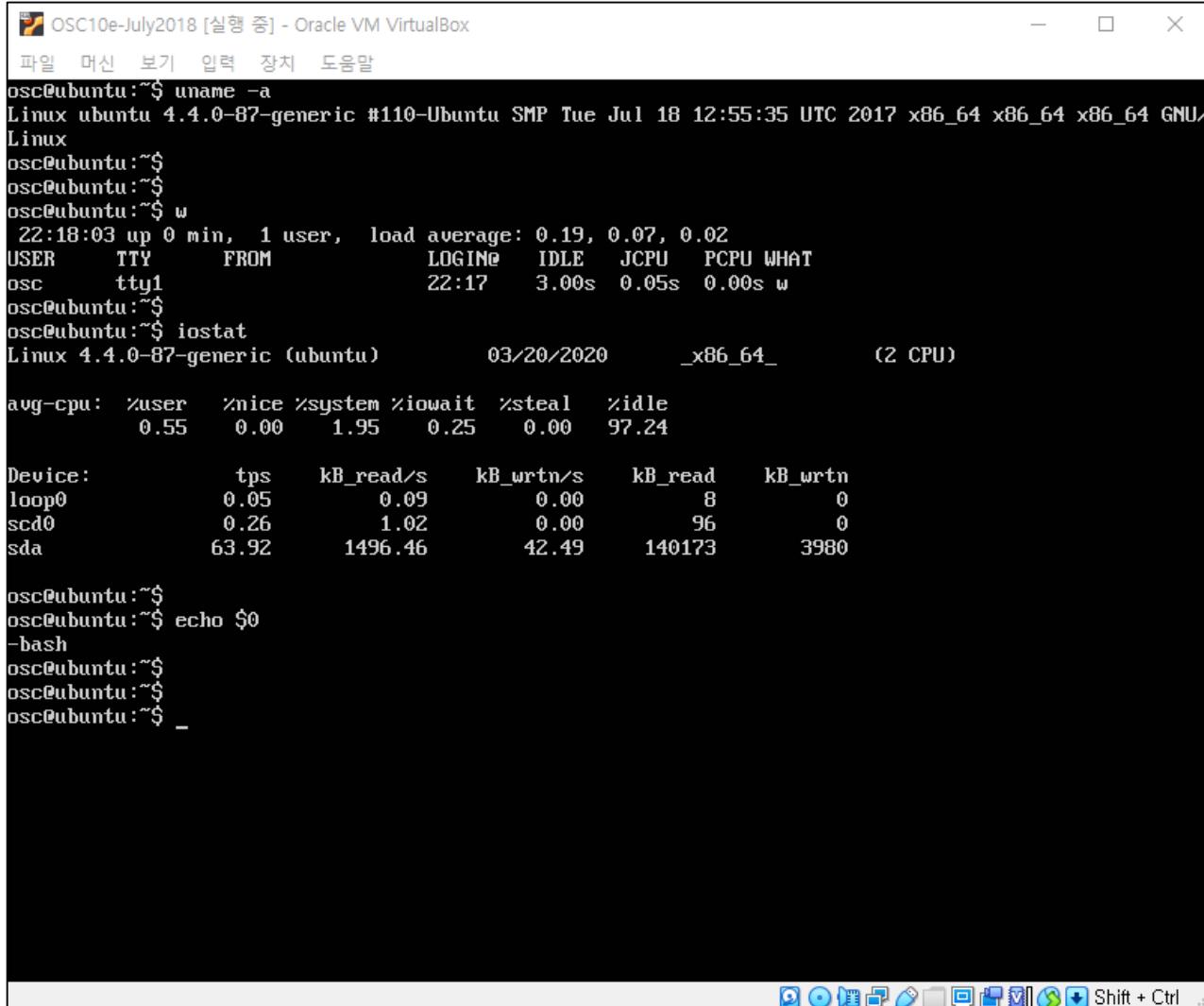


User Operating System Interface - CLI

CLI or **command interpreter** allows direct command entry

- Sometimes implemented in kernel, sometimes by systems program
- Sometimes multiple flavors implemented – **shells**
- Primarily fetches a command from user and executes it
- Sometimes commands built-in, sometimes just names of programs
 - ▶ If the latter, adding new features doesn't require shell modification

Bourne Shell Command Interpreter



The screenshot shows a terminal window titled "OSC10e-July2018 [실행 중] - Oracle VM VirtualBox". The terminal displays a series of commands entered by the user "osc@ubuntu:~\$". The commands include:

- uname -a
- w
- iostat
- echo \$0

The output of the iostat command is as follows:

Device	tps	kB_read/s	kB_wrtn/s	kB_read	kB_wrtn
loop0	0.05	0.09	0.00	8	0
scd0	0.26	1.02	0.00	96	0
sda	63.92	1496.46	42.49	140173	3980

<https://www.osboxes.org/ubuntu/#ubuntu-1804-vbox>

User Operating System Interface - GUI

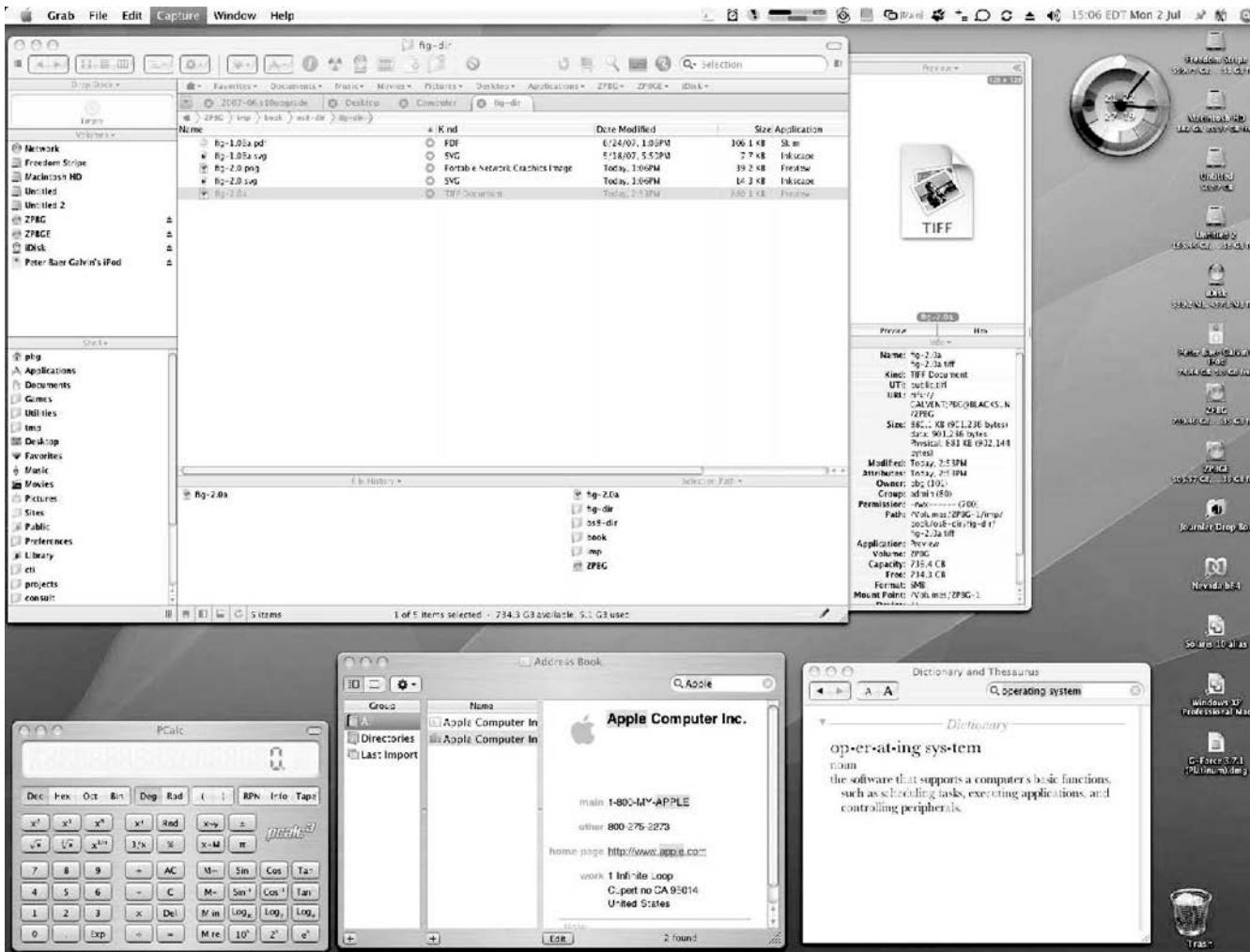
- User-friendly **desktop** metaphor interface
 - Usually mouse, keyboard, and monitor
 - **Icons** represent files, programs, actions, etc
 - Various mouse buttons over objects in the interface cause various actions (provide information, options, execute function, open directory (known as a folder))
 - Invented at Xerox PARC
- Many systems now include both CLI and GUI interfaces
 - Microsoft Windows is **GUI** with **CLI “command” shell**
 - Apple Mac OS X is “Aqua” GUI interface with UNIX kernel underneath and shells available
 - Unix and Linux have CLI with optional GUI interfaces (CDE, KDE, GNOME)

Touchscreen Interfaces

- Touchscreen devices require new interfaces
 - Mouse not possible or not desired
 - Actions and selection based on gestures
 - Virtual keyboard for text entry
 - Voice commands.



The Mac OS X GUI



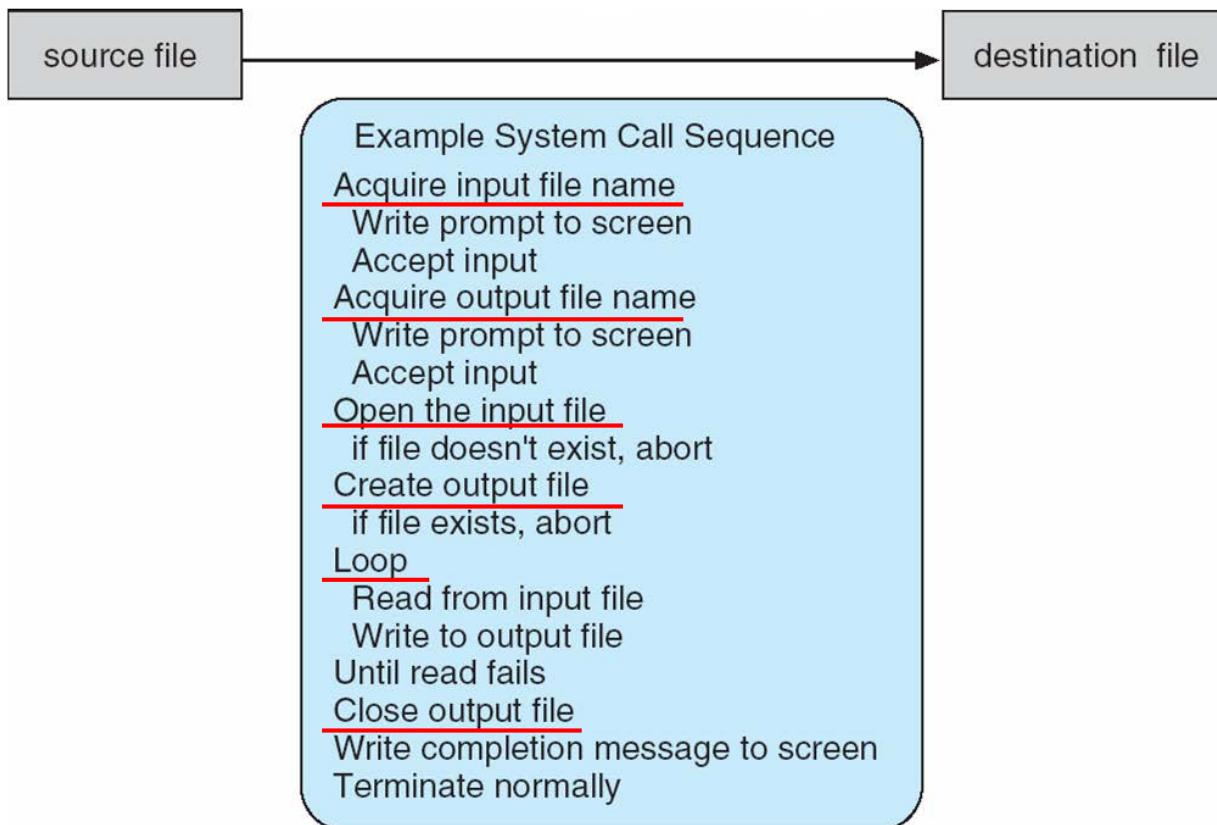
System Calls

- Programming interface to the services provided by the OS
- Typically written in a high-level language (C or C++)
- Mostly accessed by programs via a high-level **Application Programming Interface (API)** rather than direct system call use
- Three most common APIs are **Win32 API** for Windows, **POSIX API** for POSIX-based systems (including virtually all versions of UNIX, Linux, and Mac OS X), and **Java API** for the Java virtual machine (JVM)

Note that the system-call names used throughout this text are generic

Example of System Calls

- System call sequence to copy the contents of one file to another file



Example of Standard API – “read”

EXAMPLE OF STANDARD API

As an example of a standard API, consider the `read()` function that is available in UNIX and Linux systems. The API for this function is obtained from the `man` page by invoking the command

```
man read
```

on the command line. A description of this API appears below:

```
#include <unistd.h>

ssize_t      read(int fd, void *buf, size_t count)
```

return function parameters
value name

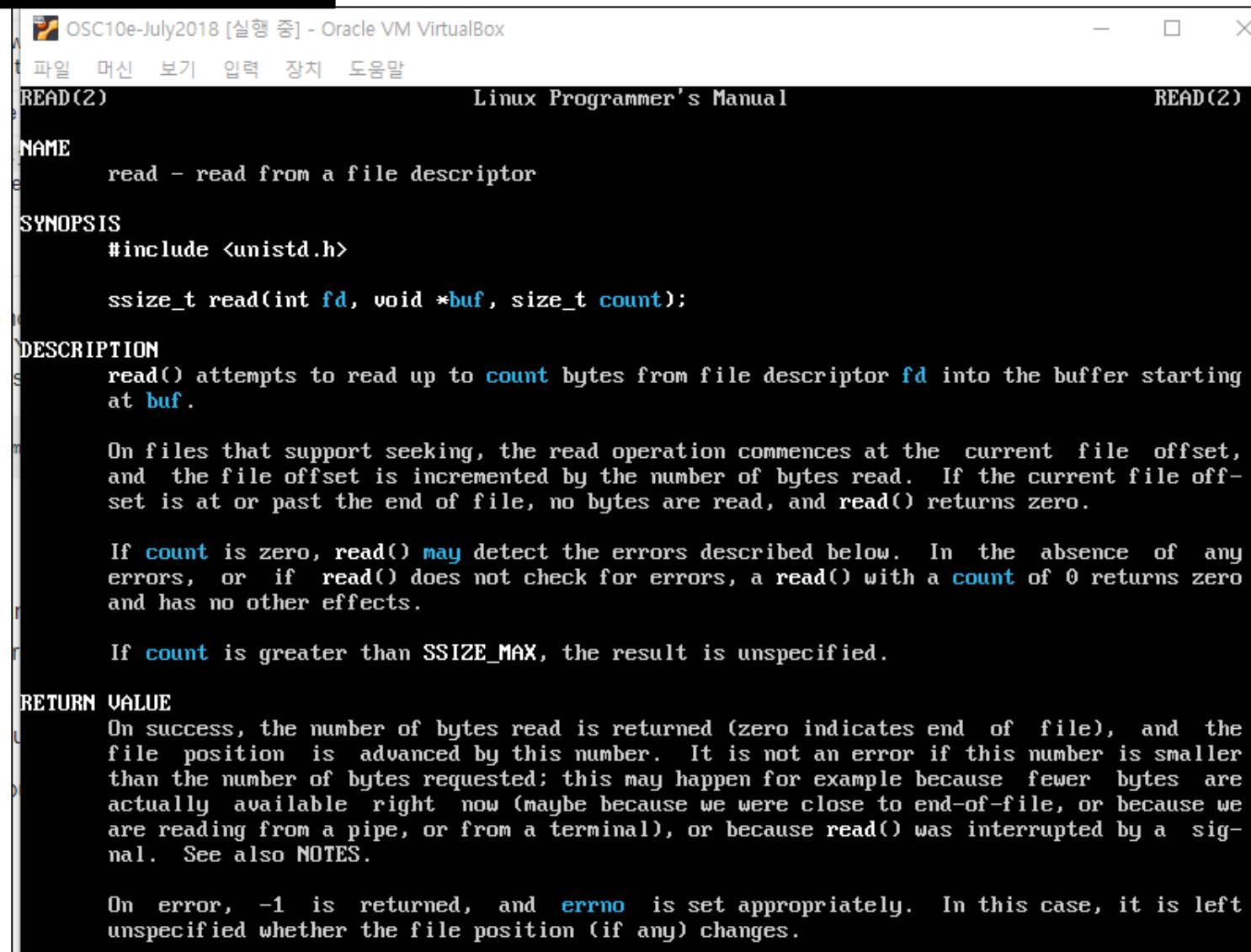
A program that uses the `read()` function must include the `unistd.h` header file, as this file defines the `ssize_t` and `size_t` data types (among other things). The parameters passed to `read()` are as follows:

- `int fd`—the file descriptor to be read
- `void *buf`—a buffer where the data will be read into
- `size_t count`—the maximum number of bytes to be read into the buffer

On a successful read, the number of bytes read is returned. A return value of 0 indicates end of file. If an error occurs, `read()` returns -1.

Example of Standard API – “read”

% man read 결과



The screenshot shows a terminal window titled "OSC10e-July2018 [실행 중] - Oracle VM VirtualBox". The window contains the man page for the read(2) system call. The page is titled "Linux Programmer's Manual" and includes sections for NAME, SYNOPSIS, DESCRIPTION, and RETURN VALUE. The text is in white on a black background.

```
OSC10e-July2018 [실행 중] - Oracle VM VirtualBox
파일 메신 보기 입력 장치 도움말
READ(2)                               Linux Programmer's Manual                               READ(2)

NAME
    read - read from a file descriptor

SYNOPSIS
    #include <unistd.h>

    ssize_t read(int fd, void *buf, size_t count);

DESCRIPTION
    read() attempts to read up to count bytes from file descriptor fd into the buffer starting at buf.

    On files that support seeking, the read operation commences at the current file offset, and the file offset is incremented by the number of bytes read. If the current file offset is at or past the end of file, no bytes are read, and read() returns zero.

    If count is zero, read() may detect the errors described below. In the absence of any errors, or if read() does not check for errors, a read() with a count of 0 returns zero and has no other effects.

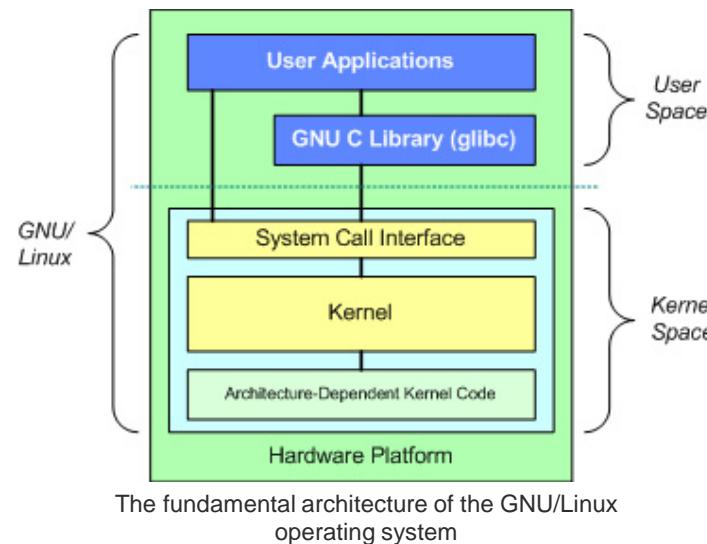
    If count is greater than SSIZE_MAX, the result is unspecified.

RETURN VALUE
    On success, the number of bytes read is returned (zero indicates end of file), and the file position is advanced by this number. It is not an error if this number is smaller than the number of bytes requested; this may happen for example because fewer bytes are actually available right now (maybe because we were close to end-of-file, or because we are reading from a pipe, or from a terminal), or because read() was interrupted by a signal. See also NOTES.

    On error, -1 is returned, and errno is set appropriately. In this case, it is left unspecified whether the file position (if any) changes.
```

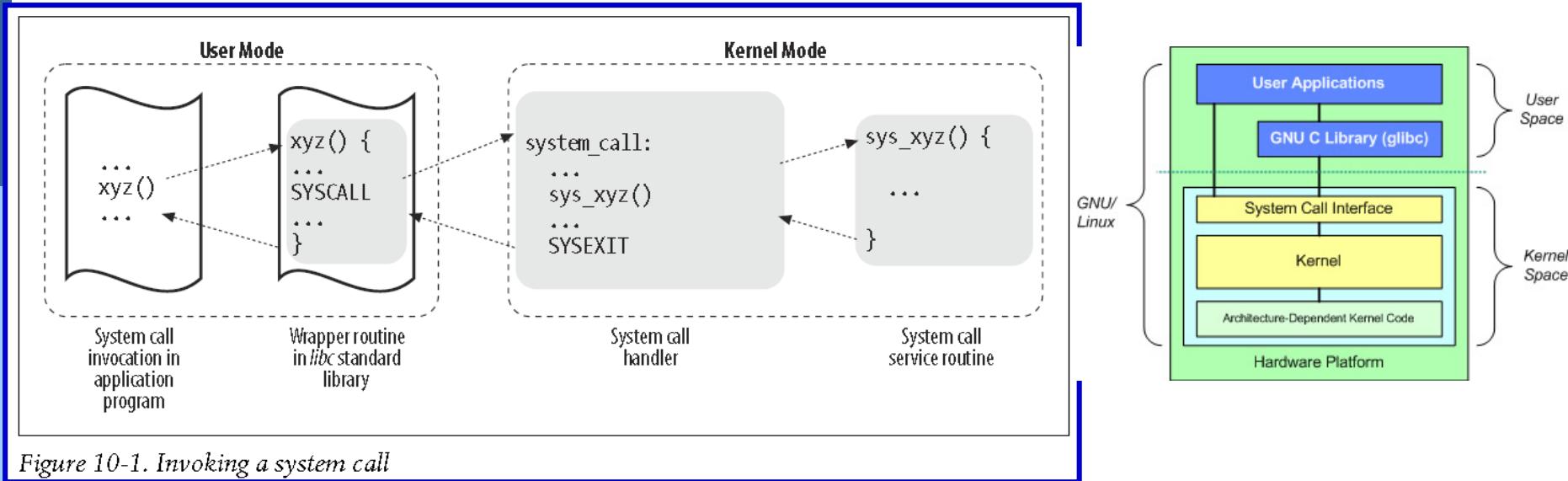
System Call Implementation

- Typically, **a number associated with each system call**
 - **System-call interface** maintains a table indexed according to these numbers
- The system call interface invokes the intended system call in OS kernel and returns status of the system call and any return values
- The caller need know nothing about how the system call is implemented
 - Just needs to obey API and understand what OS will do as a result call
 - Most details of OS interface hidden from programmer by API
 - ▶ Managed by run-time support library (set of functions built into libraries included with compiler)



System Call Implementation

참고 문헌: **Understanding the Linux Kernel** by Daniel Pierre Bovet, Marco Cesati, pp.305~



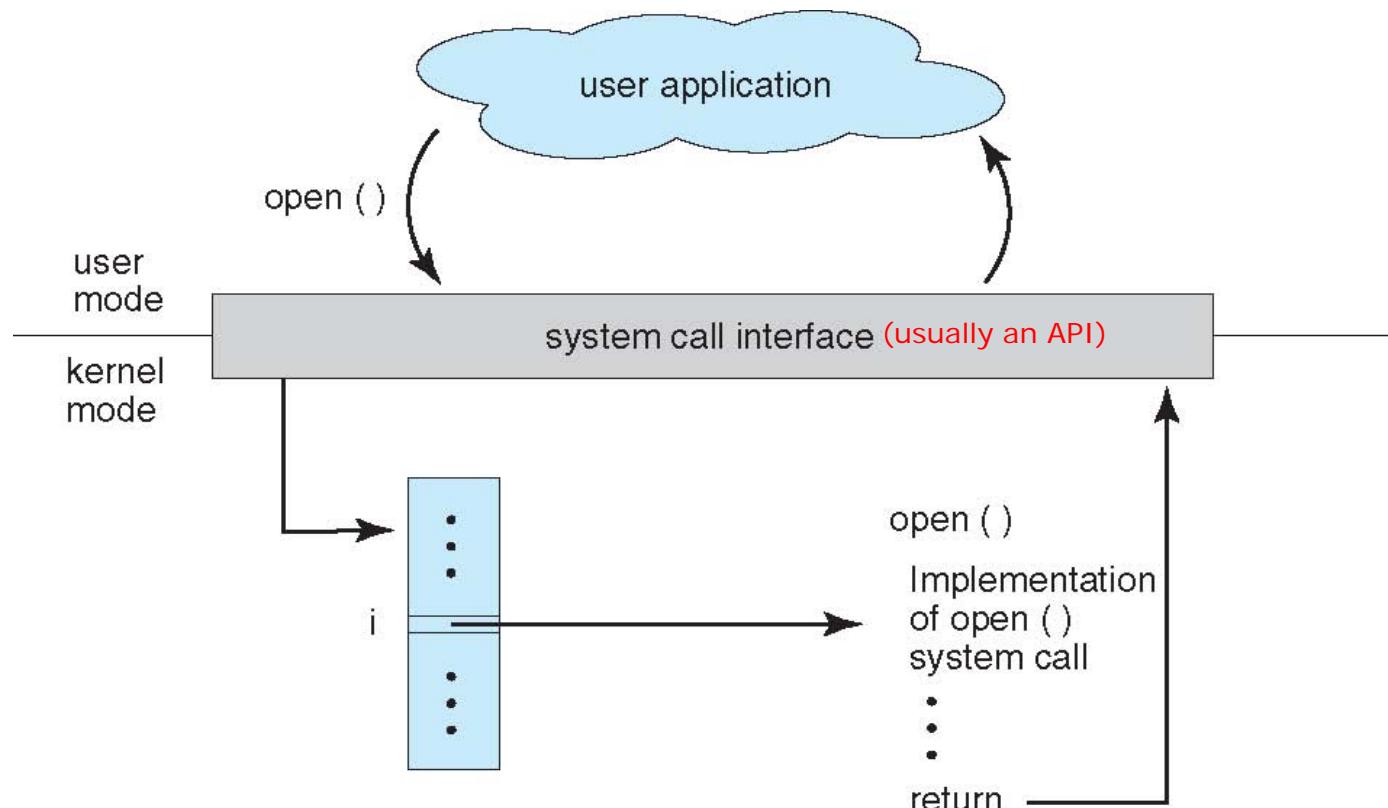
- **API** : a function definition that specifies how to obtain a given service
- **System call**: an explicit request to the kernel make via a software interrupt

API는 libc 표준 C library와 같은 wrapper routine에 구현됨. 그리고 각 system call은 대응되는 wrapper routine을 가짐 (위 그림 참고). 그런데, API와 system call은 1:1 mapping 관계만 존재하는 것은 아님.

예) libc에 있는 malloc(), calloc(), free() API는 brk() system call을 사용함

system_call의 kernel entry point는 0x80 (128)임

API – System Call – OS Relationship



참고 문헌: Understanding the Linux Kernel by Daniel Pierre Bovet, Marco Cesati, pp.305~

System Call Handler and Service Routines

When a User Mode process invokes a system call, the CPU switches to Kernel Mode and starts the execution of a kernel function. In Linux a system call must be invoked by executing the `int $0x80` assembly language instruction, which raises the programmed exception that has vector 128 (see the sections “Interrupt, Trap, and System Gates” and “Hardware Handling of Interrupts and Exceptions,” both in Chapter 4).

Since the kernel implements many different system calls, the process must pass a parameter called the *system call number* to identify the required system call; the `eax` register is used for this purpose. As we shall see in the section “Parameter Passing” later in this chapter, additional parameters are usually passed when invoking a system call.

System Call Implementation

참고 문헌: **Understanding the Linux Kernel** by Daniel Pierre Bovet, Marco Cesati, CH4, pp.153~

Interrupt vectors

As illustrated in Table 4-2, physical IRQs may be assigned any vector in the range 32–238. However, Linux uses vector 128 to implement system calls.

The IBM-compatible PC architecture requires that some devices be statically connected to specific IRQ lines. In particular:

- The interval timer device must be connected to the IRQ0 line (see Chapter 6).
- The slave 8259A PIC must be connected to the IRQ2 line (although more advanced PICs are now being used, Linux still supports 8259A-style PICs).

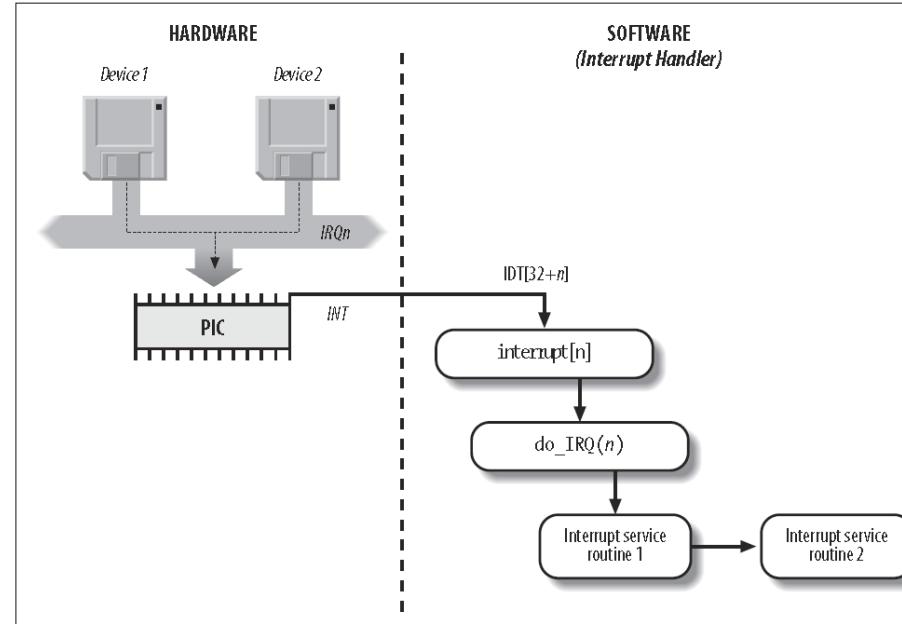


Figure 4-4. I/O interrupt handling

System Call Implementation

- The external mathematical coprocessor must be connected to the IRQ13 line (although recent 80×86 processors no longer use such a device, Linux continues to support the hardy 80386 model).
- In general, an I/O device can be connected to a limited number of IRQ lines. (As a matter of fact, when playing with an old PC where IRQ sharing is not possible, you might not succeed in installing a new card because of IRQ conflicts with other already present hardware devices.)

Table 4-2. Interrupt vectors in Linux

Vector range	Use
0–19 (0x0–0x13)	Nonmaskable interrupts and exceptions
20–31 (0x14–0x1f)	Intel-reserved
<u>32–127 (0x20–0x7f)</u>	<u>External interrupts (IRQs)</u>
<u>128 (0x80)</u>	<u>Programmed exception for system calls (see Chapter 10)</u>
129–238 (0x81–0xee)	External interrupts (IRQs)
239 (0xef)	Local APIC timer interrupt (see Chapter 6)
240 (0xf0)	Local APIC thermal interrupt (introduced in the Pentium 4 models)
241–250 (0xf1–0xfa)	Reserved by Linux for future use
251–253 (0xfb–0xfd)	Interprocessor interrupts (see the section “Interprocessor Interrupt Handling” later in this chapter)
254 (0xfe)	Local APIC error interrupt (generated when the local APIC detects an erroneous condition)
255 (0xff)	Local APIC spurious interrupt (generated if the CPU masks an interrupt while the hardware device raises it)

System Call Implementation

참고 문헌: **Understanding the Linux Kernel** by Daniel Pierre Bovet, Marco Cesati, CH4, pp.153~

Table 4-3. An example of IRQ assignment to I/O devices

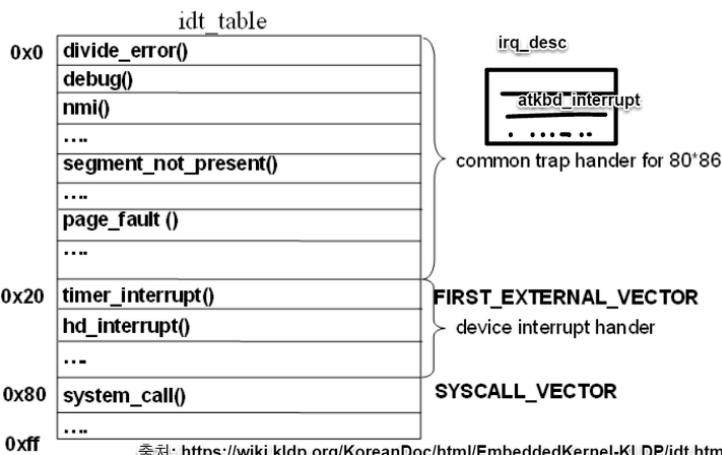
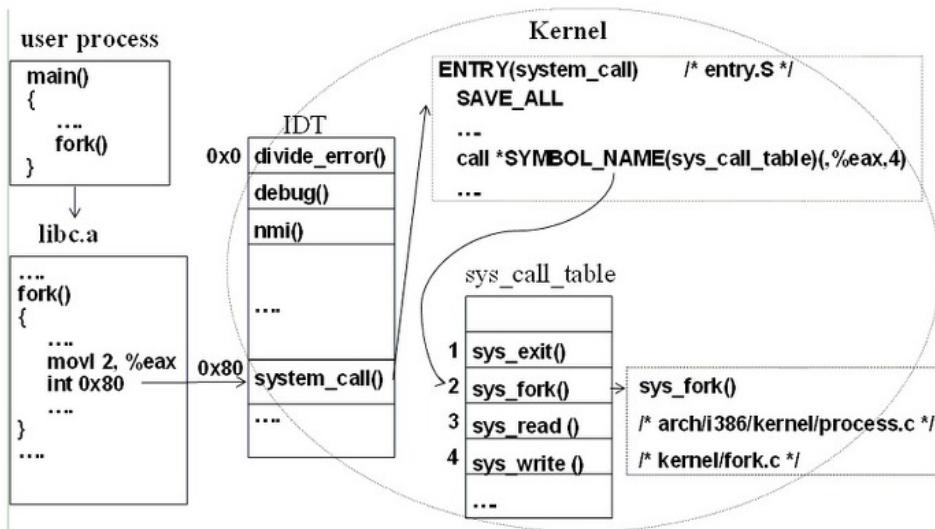
IRQ	INT	Hardware device
0	32	Timer
1	33	Keyboard
2	34	PIC cascading
3	35	Second serial port
4	36	First serial port
6	38	Floppy disk
8	40	System clock
10	42	Network interface
11	43	USB port, sound card
12	44	PS/2 mouse
13	45	Mathematical coprocessor
14	46	EIDE disk controller's first chain
15	47	EIDE disk controller's second chain

System Call Implementation

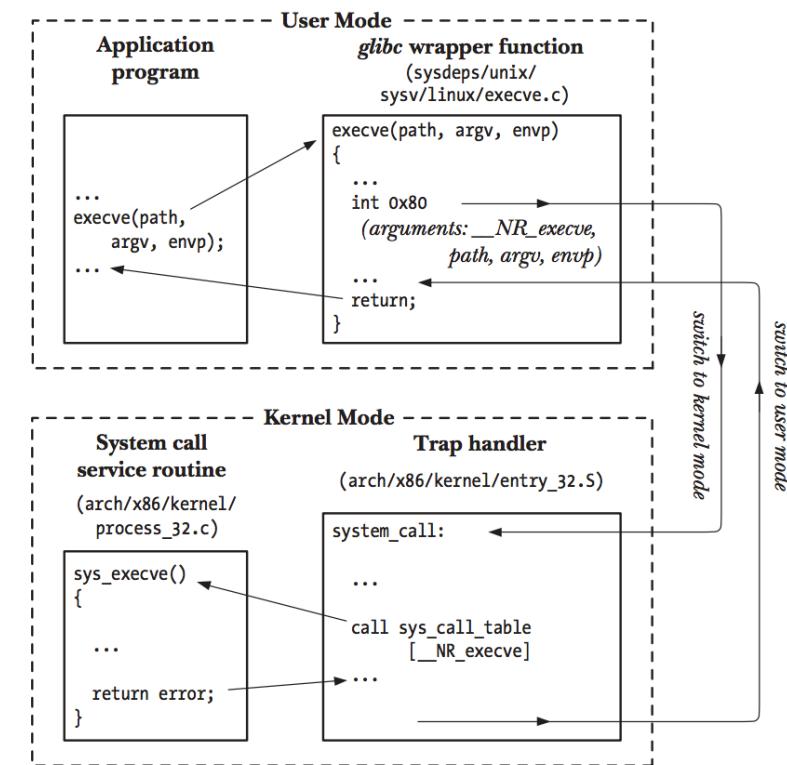
참고 문헌: <https://duksoo.tistory.com/entry/System-call-%EB%93%B1%EB%A1%9D-%EC%88%9C%EC%84%9C>

https://github.com/ex0dus-0x/ex0dus-0x.github.io/blob/master/_posts/2018-06-16-system-call-hijacking.md

<https://www.amazon.com/Linux-Programming-Interface-System-Handbook/dp/1593272200>



출처: <https://wiki.kldp.org/KoreanDoc/html/EmbeddedKernel-KLDP/idt.html>



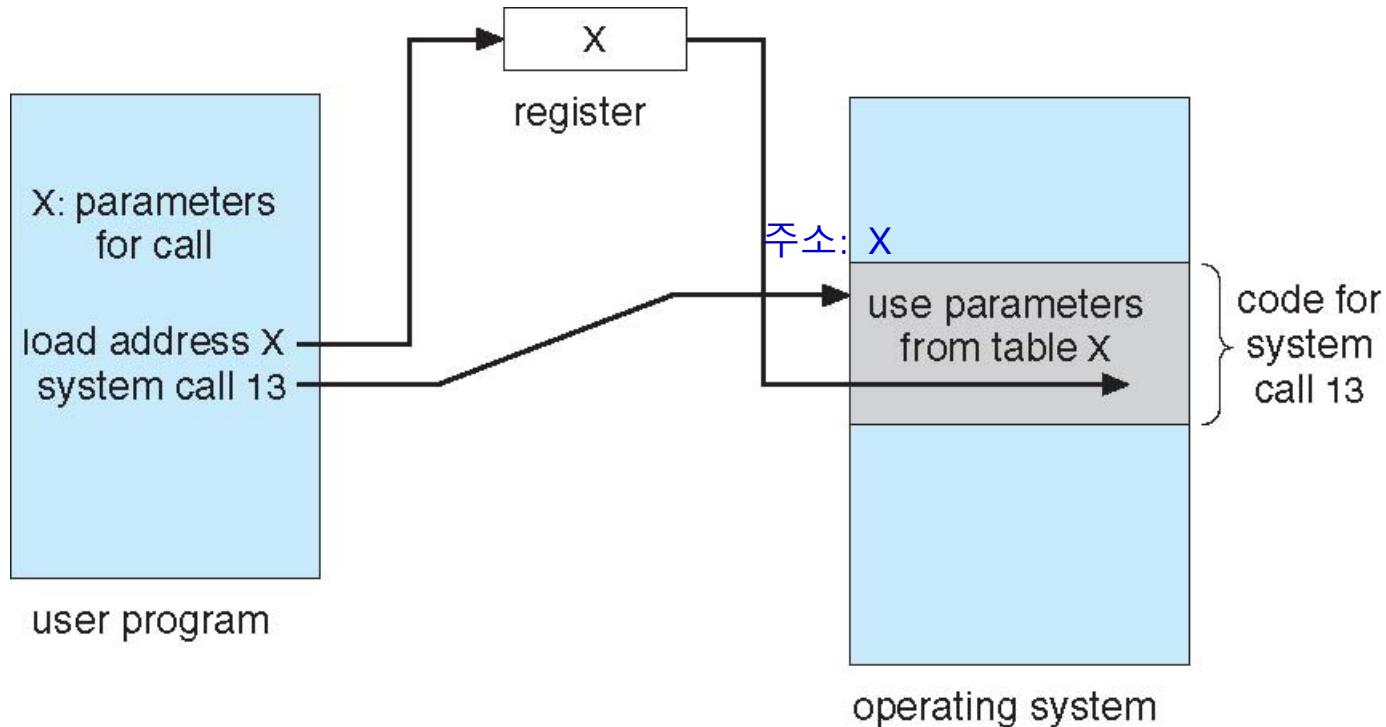
idt_table: Interrupt Descriptor Table



System Call Parameter Passing

- Often, more information is required than simply identity of desired system call
 - Exact type and amount of information vary according to OS and call
- Three general methods used to pass parameters to the OS
 - Simplest: pass the parameters in registers
 - ▶ In some cases, may be more parameters than registers
 - Parameters stored in a block, or table, in memory, and address of block passed as a parameter in a register
 - ▶ This approach taken by Linux and Solaris
 - Parameters placed, or **pushed**, onto the **stack** by the program and **popped** off the stack by the operating system
 - Block and stack methods do not limit the number or length of parameters being passed

Parameter Passing via Table



- 많은 수의 parameter를 전송할 때는 register를 통해서 전달하지 않음
- Memory에 전달할 parameter 저장. 해당 주소를 register에 넣음
- System call 수행

Types of System Calls

➤ Process control

- create process, terminate process
- end, abort
- load, execute
- get process attributes, set process attributes
- wait for time
- wait event, signal event
- allocate and free memory
- Dump memory if error
- **Debugger** for determining **bugs, single step** execution
- **Locks** for managing access to shared data between processes

Types of System Calls

- File management
 - create file, delete file
 - open, close file
 - read, write, reposition
 - get and set file attributes
- Device management
 - request device, release device
 - read, write, reposition
 - get device attributes, set device attributes
 - logically attach or detach devices

Types of System Calls (Cont.)

- Information maintenance
 - get time or date, set time or date
 - get system data, set system data
 - get and set process, file, or device attributes
- Communications
 - create, delete communication connection
 - send, receive messages if **message passing model** to **host name** or **process name**
 - ▶ From **client** to **server**
 - **Shared-memory model** create and gain access to memory regions
 - transfer status information
 - attach and detach remote devices

Types of System Calls (Cont.)

➤ Protection

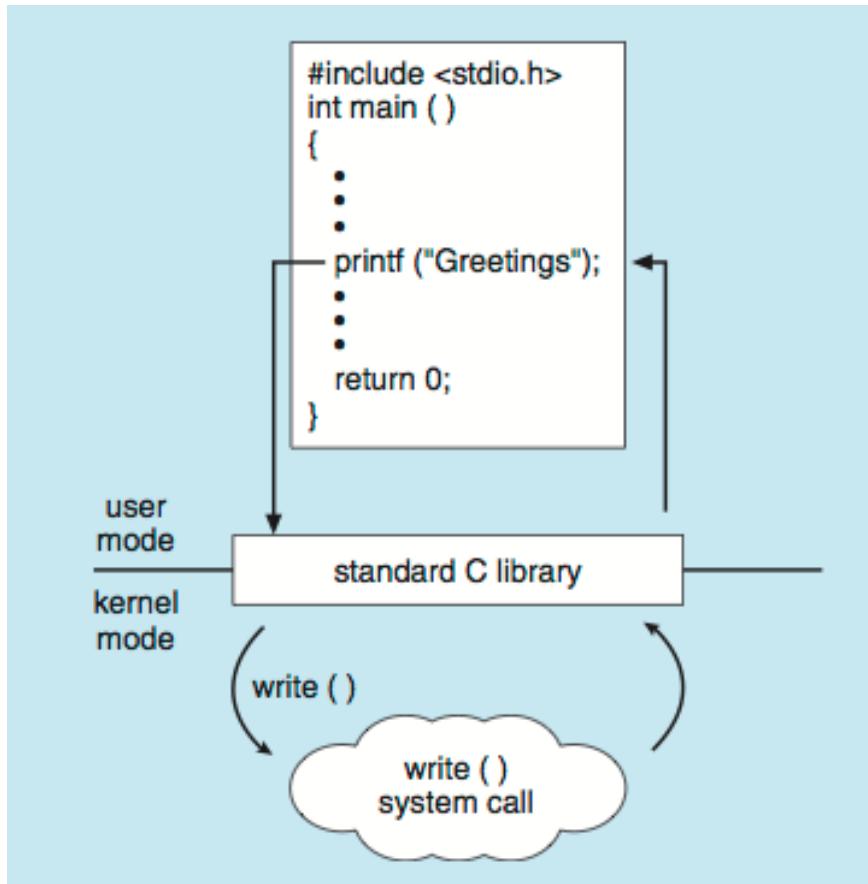
- Control access to resources
- Get and set permissions
- Allow and deny user access

Examples of Windows and Unix System Calls

	Windows	Unix
Process Control	CreateProcess() ExitProcess() WaitForSingleObject()	fork() exit() wait()
File Manipulation	CreateFile() ReadFile() WriteFile() CloseHandle()	open() read() write() close()
Device Manipulation	SetConsoleMode() ReadConsole() WriteConsole()	ioctl() read() write()
Information Maintenance	GetCurrentProcessID() SetTimer() Sleep()	getpid() alarm() sleep()
Communication	CreatePipe() CreateFileMapping() MapViewOfFile()	pipe() shmget() mmap()
Protection	SetFileSecurity() InitializeSecurityDescriptor() SetSecurityDescriptorGroup()	chmod() umask() chown()

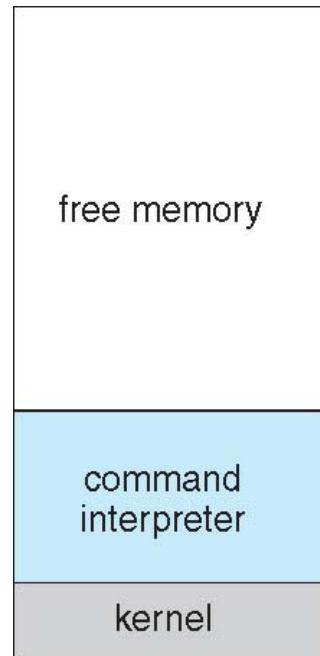
Standard C Library Example

- C program invoking printf() library call, which calls write() system call



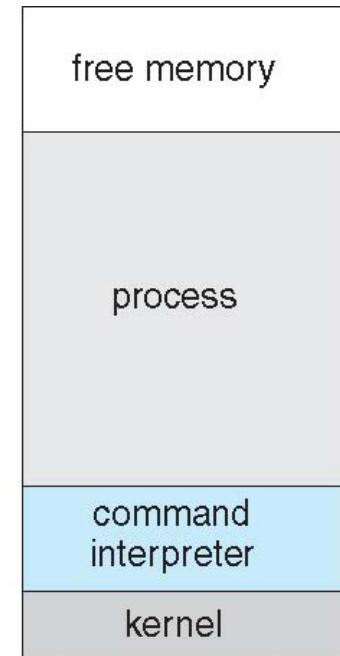
Example: MS-DOS

- Single-tasking
- Shell invoked when system booted
- Simple method to run program
 - No process created
- Single memory space
- Loads program into memory, overwriting all but the kernel
- Program exit -> shell reloaded



(a)

At system startup

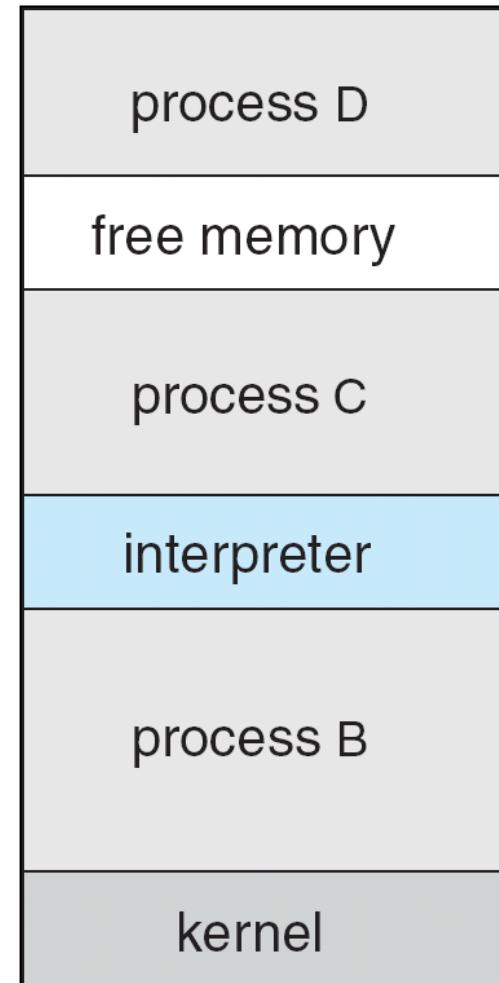


(b)

running a program

Example: FreeBSD

- Unix variant
- Multitasking
- User login -> invoke user's choice of shell
- Shell executes fork() system call to create process
 - Executes exec() to load program into process
 - Shell waits for process to terminate or continues with user commands
- Process exits with:
 - code = 0 – no error
 - code > 0 – error code



System Programs

- System programs provide a convenient environment for program development and execution. They can be divided into:
 - File manipulation
 - Status information sometimes stored in a File modification
 - Programming language support
 - Program loading and execution
 - Communications
 - Background services
 - Application programs
- Most users' view of the operation system is defined by system programs, not the actual system calls

System Programs

- Provide a convenient environment for program development and execution
 - Some of them are simply user interfaces to system calls; others are considerably more complex
- **File management** - Create, delete, copy, rename, print, dump, list, and generally manipulate files and directories
- **Status information**
 - Some ask the system for info - date, time, amount of available memory, disk space, number of users
 - Others provide detailed performance, logging, and debugging information
 - Typically, these programs format and print the output to the terminal or other output devices
 - Some systems implement a **registry** - used to store and retrieve configuration information

System Programs (Cont.)

- **File modification**
 - Text editors to create and modify files
 - Special commands to search contents of files or perform transformations of the text
- **Programming-language support** - Compilers, assemblers, debuggers and interpreters sometimes provided
- **Program loading and execution**- Absolute loaders, relocatable loaders, linkage editors, and overlay-loaders, debugging systems for higher-level and machine language
- **Communications** - Provide the mechanism for creating virtual connections among processes, users, and computer systems
 - Allow users to send messages to one another's screens, browse web pages, send electronic-mail messages, log in remotely, transfer files from one machine to another

System Programs (Cont.)

➤ Background Services

- Launch at boot time
 - ▶ Some for system startup, then terminate
 - ▶ Some from system boot to shutdown
- Provide facilities like disk checking, process scheduling, error logging, printing
- Run in user context not kernel context
- Known as **services, subsystems, daemons**

➤ Application programs

- Don't pertain to system
- Run by users
- Not typically considered part of OS
- Launched by command line, mouse click, finger poke



Operating System Design and Implementation

- Design and Implementation of OS not “solvable”, but some approaches have proven successful
- Internal structure of different Operating Systems can vary widely
- Start the design by defining goals and specifications
- Affected by choice of hardware, type of system
- **User** goals and **System** goals
 - **User goals** – operating system should be convenient to use, easy to learn, reliable, safe, and fast
 - **System goals** – operating system should be easy to design, implement, and maintain, as well as flexible, reliable, error-free, and efficient

Operating System Design and Implementation (Cont.)

- Important principle to separate
 - Policy:** *What* will be done?
 - Mechanism:** *How* to do it?
- Mechanisms determine how to do something, policies decide what will be done
- The separation of policy from mechanism is a very important principle, it allows maximum flexibility if policy decisions are to be changed later (example – timer)
 - A general mechanism insensitive to changes in policy would be more desirable. A change in policy would then require redefinition of only certain parameters of the system
 - 예를 들어, 1초/10초 동안 응답 없는 경우, exception 발생하는 경우: policy(1초? 10초...), mechanism: 이를 어떻게 실현할 것인가.
- Specifying and designing an OS is highly creative task of **software engineering**

Implementation

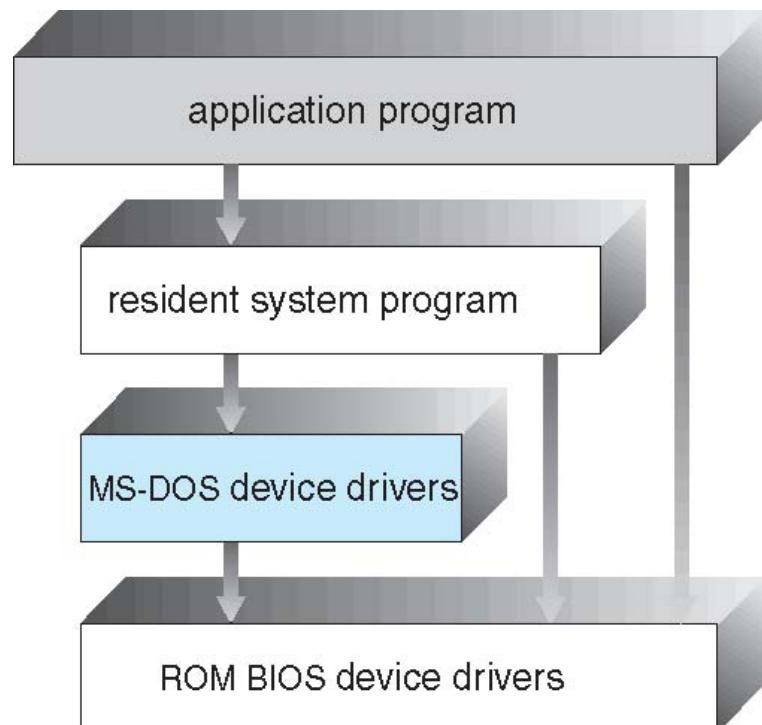
- Much variation
 - Early OSes in assembly language
 - Then system programming languages like Algol, PL/1
 - Now C, C++
- Actually usually a mix of languages
 - Lowest levels in assembly
 - Main body in C
 - Systems programs in C, C++, scripting languages like PERL, Python, shell scripts
- More high-level language easier to port to other hardware
 - But slower
- **Emulation** can allow an OS to run on non-native hardware

Operating System Structure

- General-purpose OS is very large program
- Various ways to structure ones
 - Simple structure – MS-DOS
 - More complex -- UNIX
 - Layered – an abstraction
 - Microkernel -Mach

Simple Structure -- MS-DOS

- MS-DOS – written to provide the most functionality in the least space
 - Not divided into modules
 - Although MS-DOS has some structure, its interfaces and levels of functionality are not well separated



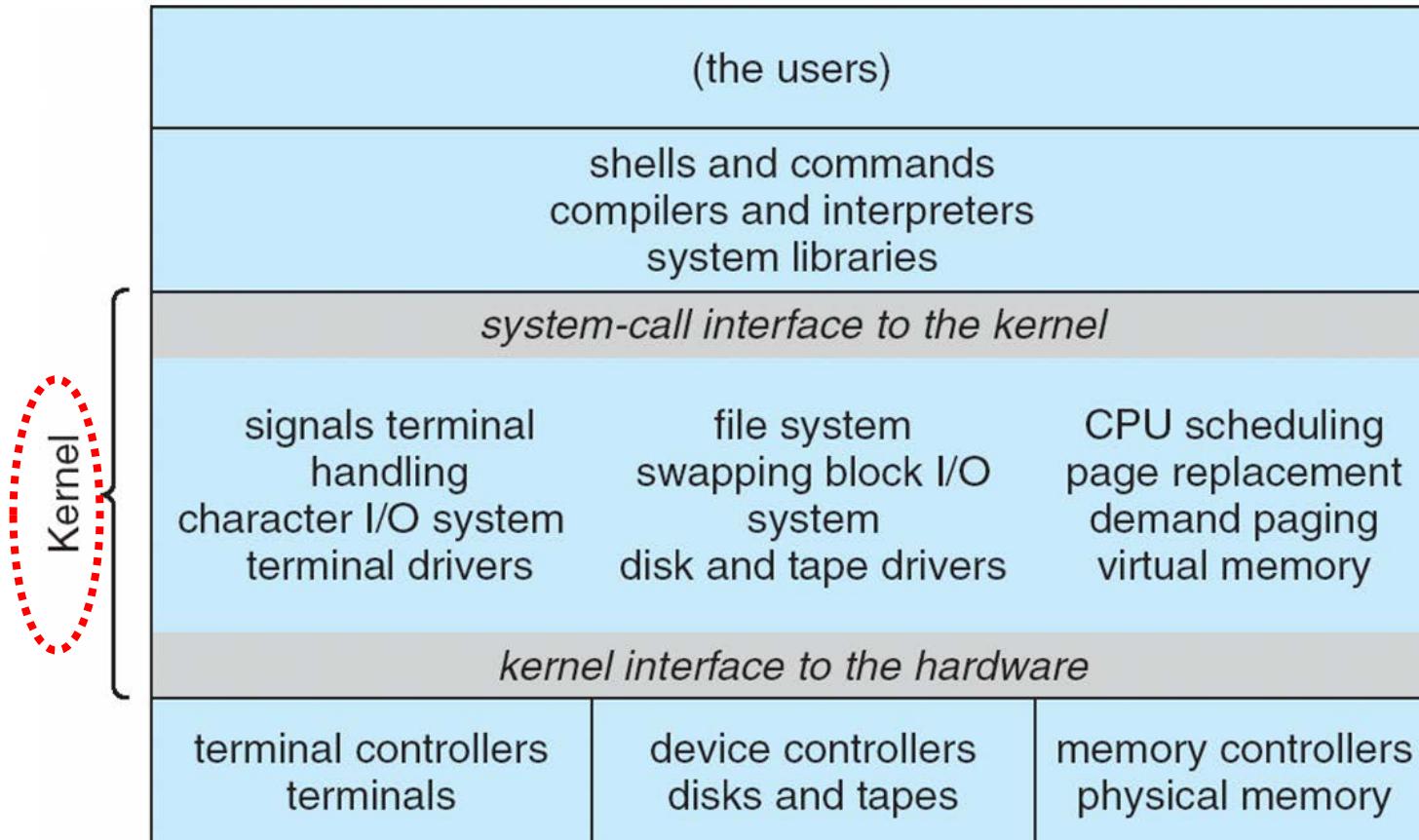
Non Simple Structure -- UNIX

UNIX – limited by hardware functionality, the original UNIX operating system had limited structuring. The UNIX OS consists of two separable parts

- Systems programs
- The kernel
 - ▶ Consists of everything below the system-call interface and above the physical hardware
 - ▶ Provides the file system, CPU scheduling, memory management, and other operating-system functions; a large number of functions for one level

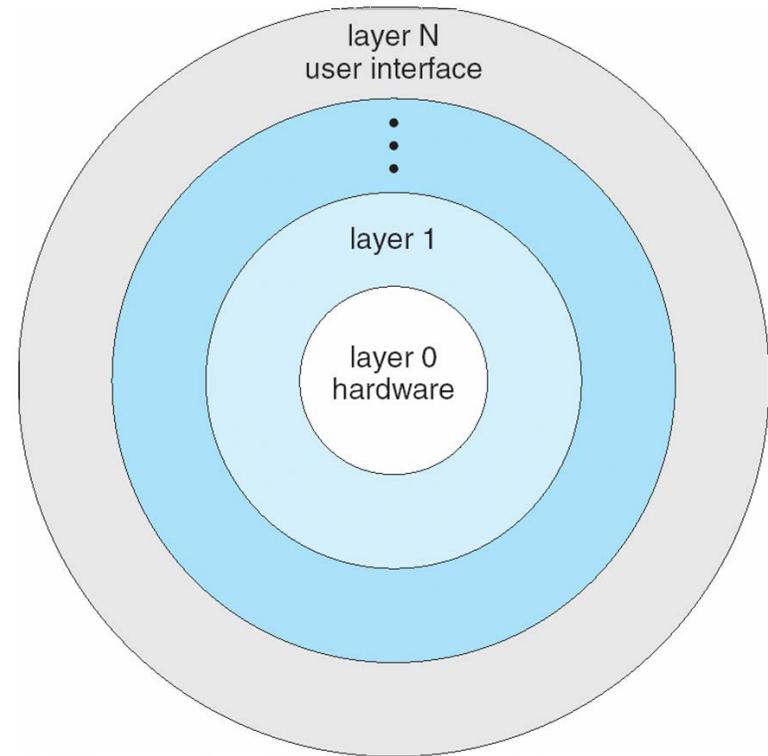
Traditional UNIX System Structure

Beyond simple but not fully layered



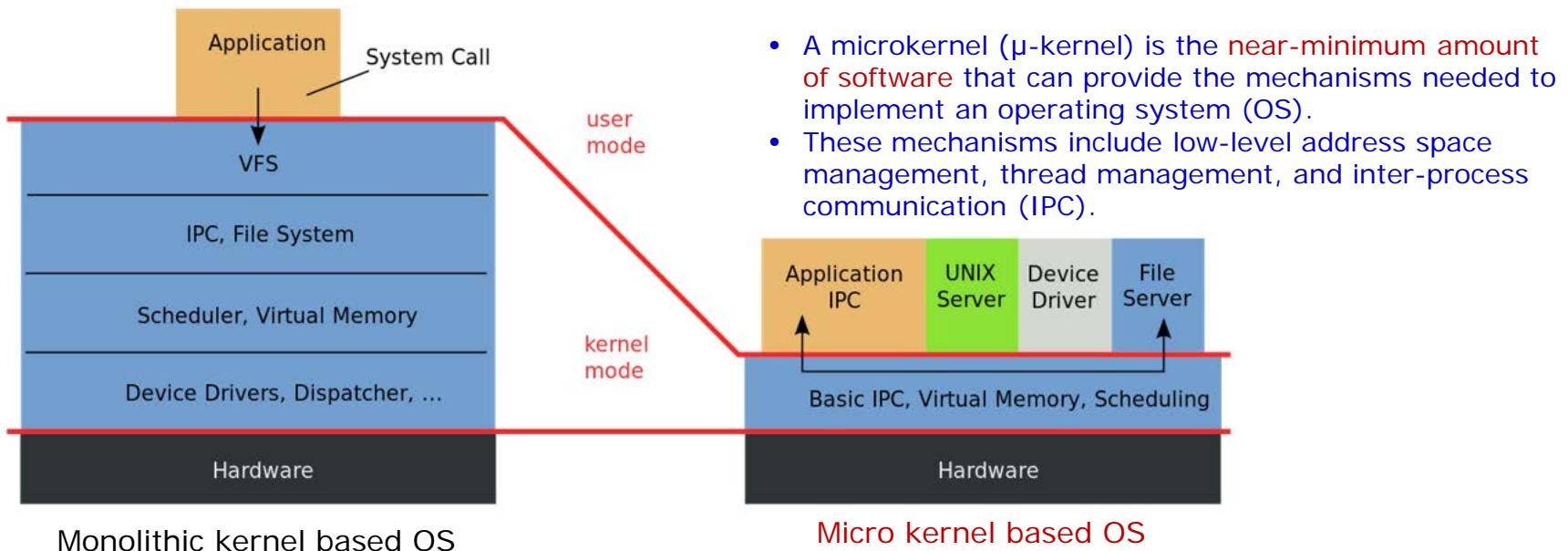
Layered Approach

- The operating system is divided into a number of layers (levels), each built on top of lower layers. The bottom layer (layer 0), is the hardware; the highest (layer N) is the user interface.
- With modularity, layers are selected such that each uses functions (operations) and services of only lower-level layers

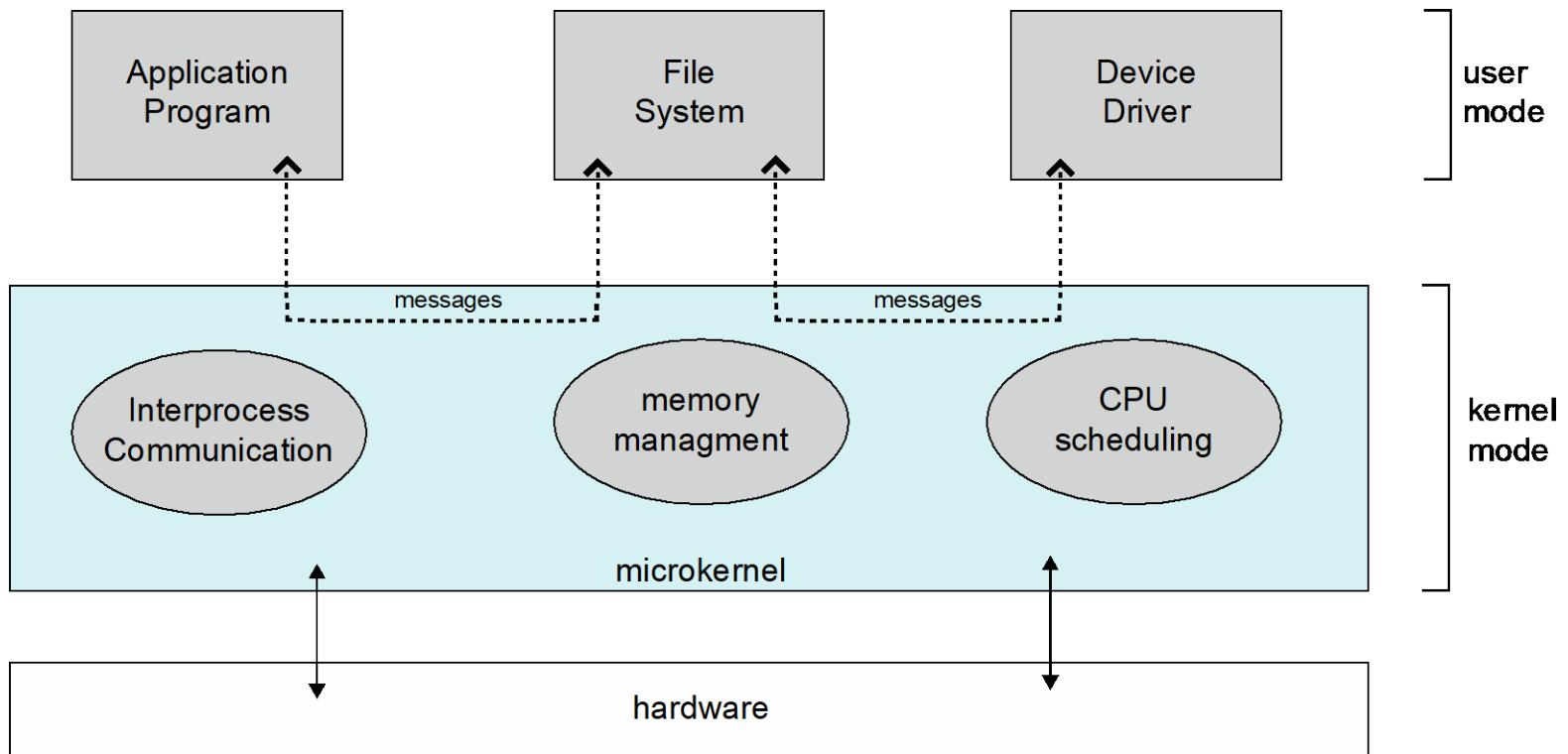


Microkernel System Structure

- Moves as much from the kernel into user space
- **Mach** example of **microkernel**
 - Mac OS X kernel (**Darwin**) partly based on Mach
- Communication takes place between user modules using **message passing**
- Benefits:
 - Easier to extend a microkernel
 - Easier to port the operating system to new architectures
 - More reliable (less code is running in kernel mode)
 - More secure
- Detriments:
 - Performance overhead of user space to kernel space communication



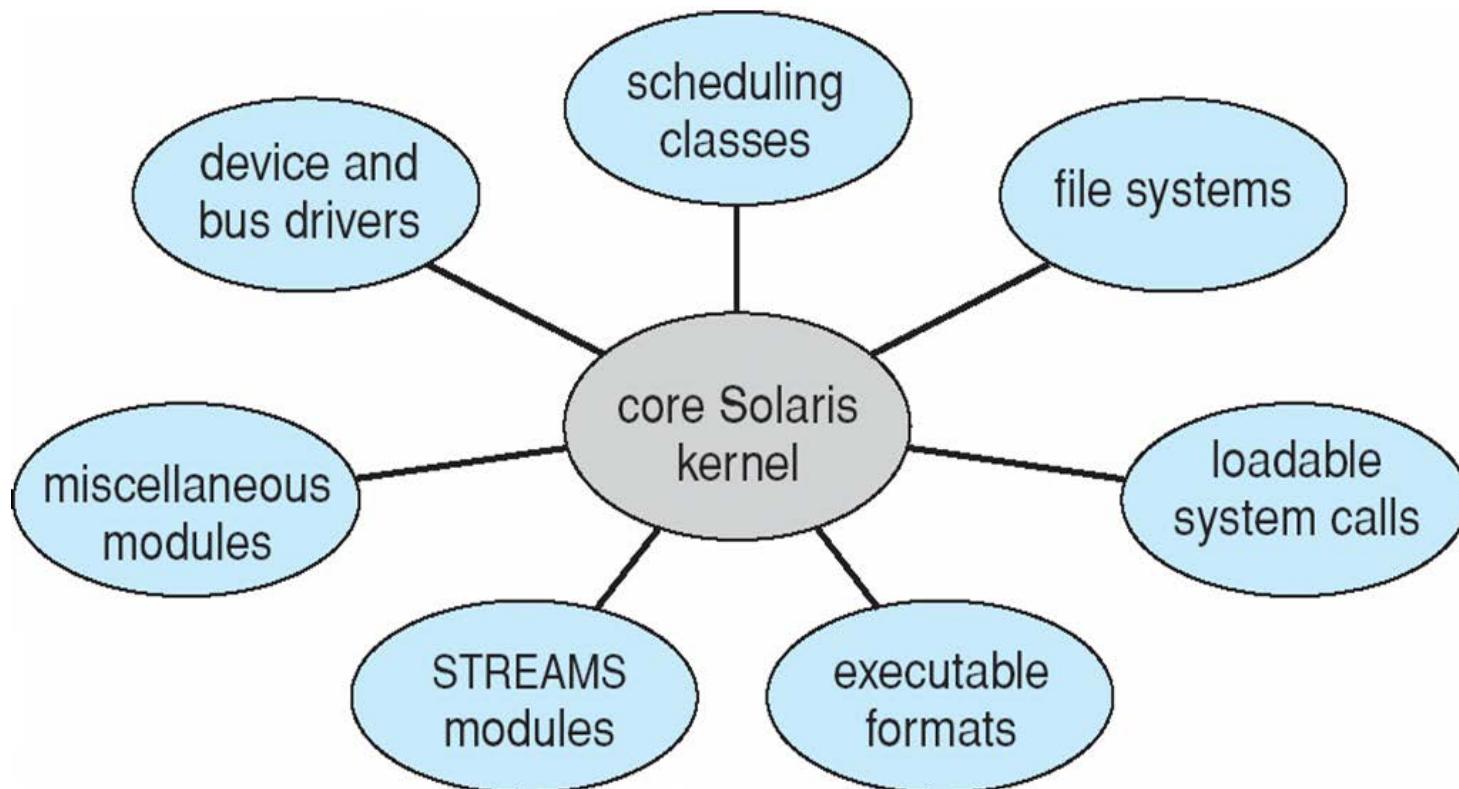
Microkernel System Structure



Modules

- Many modern operating systems implement **loadable kernel modules**
 - Uses object-oriented approach
 - Each core component is separate
 - Each talks to the others over known interfaces
 - Each is loadable as needed within the kernel
- Overall, similar to layers **but with more flexible**
 - Linux, Solaris, etc

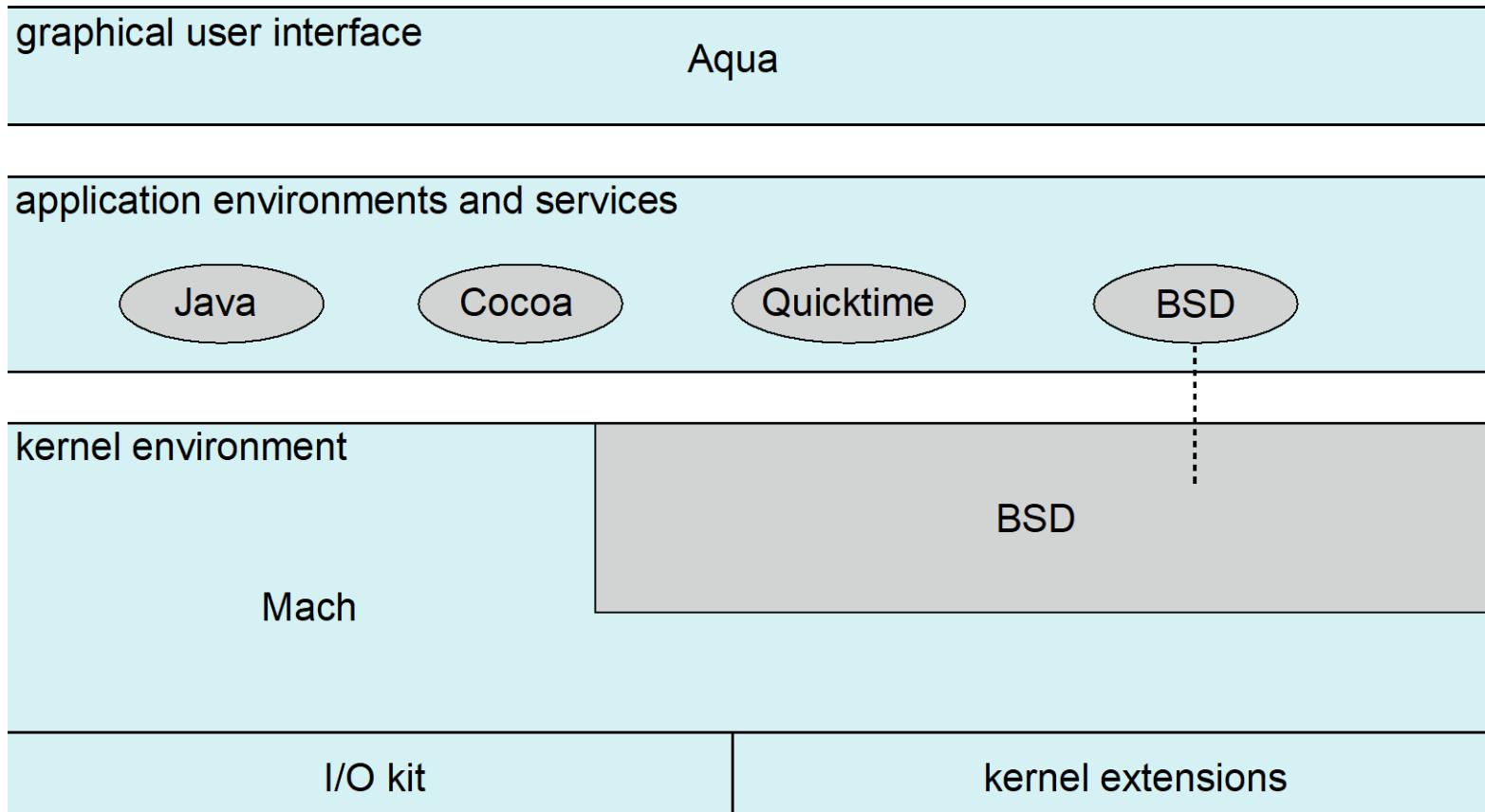
Solaris Modular Approach



Hybrid Systems

- Most modern operating systems are actually **not one pure model**
 - Hybrid combines multiple approaches to address performance, security, usability needs
 - Linux and Solaris kernels in kernel address space, so monolithic, plus modular for dynamic loading of functionality
 - Windows mostly monolithic, plus microkernel for different subsystem **personalities**
- Apple Mac OS X hybrid, **layered**, **Aqua** UI plus **Cocoa** programming environment
 - Below is kernel consisting of **Mach** microkernel and BSD Unix parts, plus I/O kit and dynamically **loadable modules** (called **kernel extensions**)

Mac OS X(“Ten, 10”) Structure



iOS

- Apple mobile OS for *iPhone, iPad*
 - Structured on Mac OS X, added functionality
 - Does not run OS X applications natively
 - ▶ Also runs on different CPU architecture (ARM vs. Intel)
 - **Cocoa Touch** Objective-C API for developing apps
 - **Media services** layer for graphics, audio, video
 - **Core services** provides cloud computing, databases
 - Core operating system, based on Mac OS X kernel

Cocoa Touch

Media Services

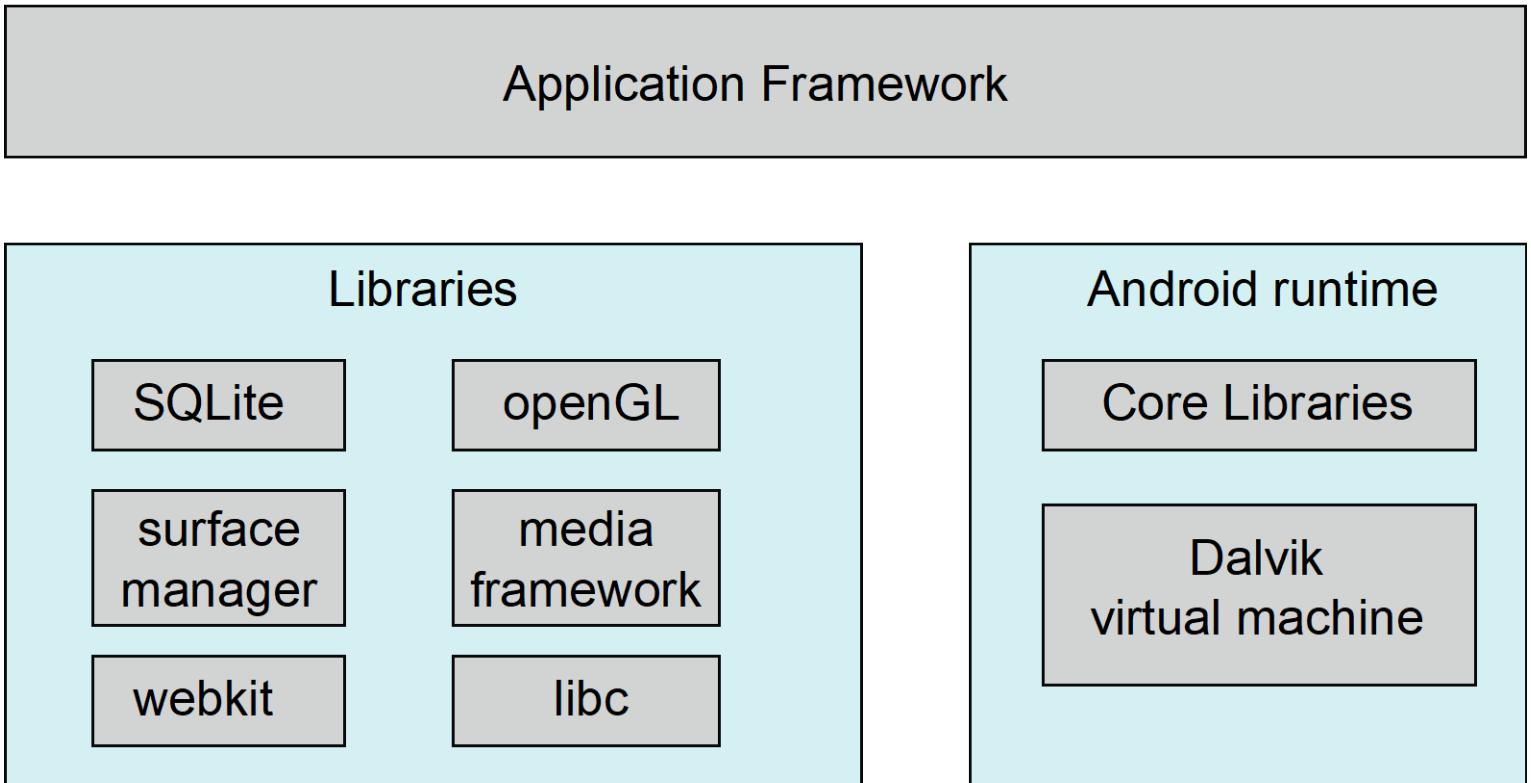
Core Services

Core OS

Android

- Developed by Open Handset Alliance (mostly Google)
 - Open Source
- Similar stack to IOS
- Based on Linux kernel but modified
 - Provides process, memory, device-driver management
 - Adds power management
- Runtime environment includes core set of libraries and **Dalvik virtual machine**
 - Apps developed in Java plus Android API
 - ▶ Java class files compiled to Java bytecode then translated to executable than runs in **Dalvik VM**
- Libraries include frameworks for web browser (webkit), database (SQLite), multimedia, smaller libc

Android Architecture



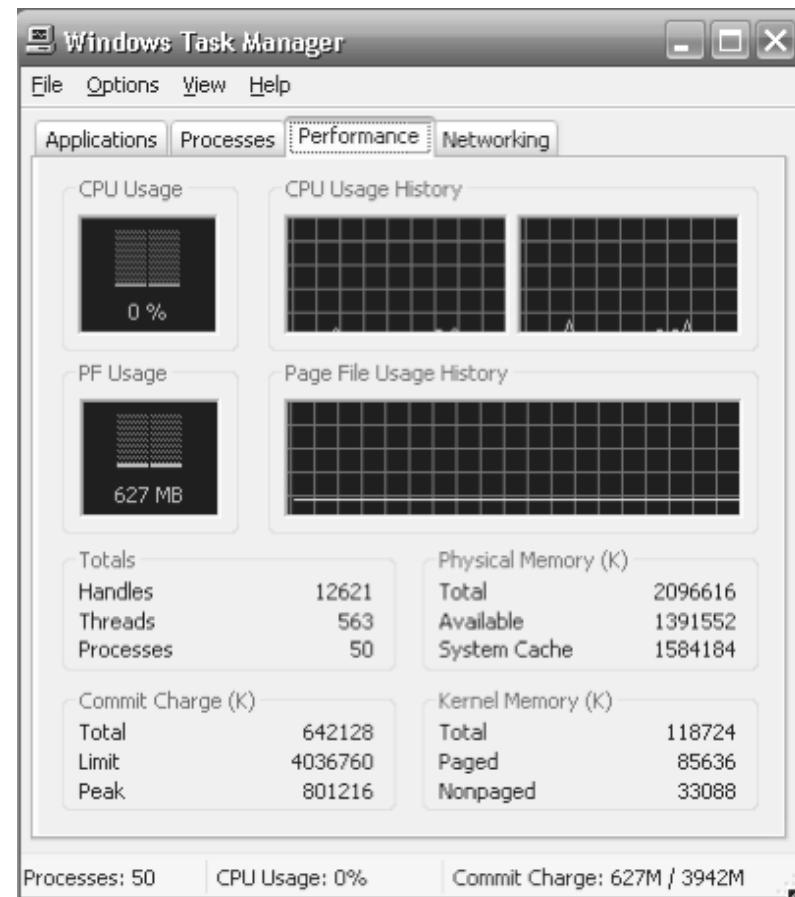
Operating-System Debugging

- **Debugging** is finding and fixing errors, or **bugs**
- OS generate **log files** containing error information
- Failure of an application can generate **core dump** file capturing memory of the process
- Operating system failure can generate **crash dump** file containing kernel memory
- Beyond crashes, performance tuning can optimize system performance
 - Sometimes using **trace listings** of activities, recorded for analysis
 - **Profiling** is periodic sampling of instruction pointer to look for statistical trends

Kernighan's Law: "Debugging is twice as hard as writing the code in the first place. Therefore, if you write the code as cleverly as possible, you are, by definition, not smart enough to debug it."

Performance Tuning

- Improve performance by removing bottlenecks
- OS must provide means of computing and displaying measures of system behavior
- For example, “top” program or Windows Task Manager



DTrace

- Dtrace: observability technology that allows how systems & applications are behaving
- DTrace tool in Solaris, FreeBSD, Mac OS X allows live instrumentation on production systems
- Probes fire when code is executed within a provider, capturing state data and sending it to consumers of those probes
- 실행중인 시스템과 사용자 프로세스, 커널에 probe 추가 가능함
 - 'U': 사용자모드 실행된 것
 - 'K': 커널모드에서 실행된 것
- Example of following XEventsQueued system call move from libc library to kernel and back

```
# ./all.d `pgrep xclock` XEventsQueued
dtrace: script './all.d' matched 52377 probes
CPU FUNCTION
  0 -> XEventsQueued          U
  0  -> _XEventsQueued        U
  0  -> _X11TransBytesReadable U
  0  <- _X11TransBytesReadable U
  0  -> _X11TransSocketBytesReadable U
  0  <- _X11TransSocketBytesreadable U
  0  -> ioctl                U
  0    -> ioctl              K
  0      -> getf              K
  0        -> set_active_fd   K
  0        <- set_active_fd   K
  0      <- getf              K
  0      -> get_udatamodel   K
  0      <- get_udatamodel   K
...
  0      -> releaseef         K
  0        -> clear_active_fd K
  0        <- clear_active_fd K
  0        -> cv_broadcast     K
  0        <- cv_broadcast     K
  0        <- releaseef         K
  0      <- ioctl              K
  0      <- ioctl              U
  0  <- _XEventsQueued        U
  0 <- XEventsQueued          U
```

사용자 모드

커널 모드

사용자 모드

DTrace

Table 1-1 Software Stack Tools

Layer	Layer Examples	Previous Analysis	DTrace Visibility
Dynamic languages	Java, Ruby, PHP, and so on	Debuggers	Yes, with providers
Native code	Compiled C/C++ code	Debuggers, truss	Yes
Libraries	/usr/lib/*, compiled code	apptrace, sotruss, truss	Yes
System calls	man -s 2, read(2), and so on	truss	Yes
Kernel	Proc/threads, FS, VM, and so on	prex; tnf, lockstat, mdb, adb	Yes
Hardware	Disk HBA, NIC, CPU, and so on	cpustat, kstats, and so on	Indirectly, yes

Dtrace (Cont.)

- DTrace code to **record amount of time each process with UserID 101 is in running mode (on CPU) in nanoseconds**

```
sched:::on-cpu
uid == 101
{
    self->ts = timestamp;
}

sched:::off-cpu
self->ts
{
    @time[execname] = sum(timestamp - self->ts);
    self->ts = 0;
}
```

```
# dtrace -s sched.d
dtrace: script 'sched.d' matched 6 probes
^C
      gnome-settings-d          142354
      gnome-vfs-daemon          158243
      dsdm                      189804
      wnck-applet                200030
      gnome-panel                 277864
      clock-applet                374916
      mapping-daemon              385475
      xscreensaver                514177
      metacity                     539281
      Xorg                         2579646
      gnome-terminal                5007269
      mixer_applet2                7388447
      java                         10769137
```

Figure 2.21 Output of the D code.

Operating System Generation

- Operating systems are designed to run on any of a class of machines; the system must be configured for each specific computer site
- **SYSGEN** program obtains information concerning the specific configuration of the hardware system
 - Used to build system-specific compiled kernel or system-tuned
 - Can generate more efficient code than one general kernel

System Boot

- When power initialized on system, execution starts at a fixed memory location
 - Firmware ROM used to hold initial boot code
- Operating system must be made available to hardware so hardware can start it
 - Small piece of code – **bootstrap loader**, stored in **ROM** or **EEPROM** locates the kernel, loads it into memory, and starts it
 - Sometimes two-step process where **boot block** at fixed location loaded by ROM code, which loads bootstrap loader from disk
- Common bootstrap loader, **GRUB**, allows selection of kernel from multiple disks, versions, kernel options
- Kernel loads and system is then **running**

End of Chapter 2