

High dimensional time series analysis



4. Automatic forecasting algorithms

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Outline

- 1 Exponential smoothing
- 2 Lab Session 7
- 3 ARIMA models
- 4 Lab Session 9
- 5 Seasonal ARIMA models
- 6 ARIMA vs ETS
- 7 Lab Session 10

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Historical perspective

- Developed in the 1950s and 1960s as methods (algorithms) to produce point forecasts.
- Combine a "level", "trend" (slope) and "seasonal" component to describe a time series.
- The rate of change of the components are controlled by "smoothing parameters": α , β and γ respectively.
- Need to choose best values for the smoothing parameters (and initial states).
- Equivalent ETS state space models developed in the 1990s and 2000s.

We want a model that captures the level (ℓ_t), trend (b_t) and seasonality (s_t).

How do we combine these elements?

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Multiplicatively?

$$y_t = \ell_{t-1}b_{t-1}s_{t-m}(1+\varepsilon_t)$$

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$$y_t = (\ell_{t-1} + b_{t-1})s_{t-m} + \varepsilon_t$$

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$$y_t = (\ell_{t-1} + b_{t-1})s_{t-m} + \varepsilon_t$$

How do the level, trend and seasonal components evolve over time?

General notation ETS: ExponenTial Smoothing

↑ ↑

Error Trend Season

Error: Additive ("A") or multiplicative ("M")

```
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∠ ↑ △

Error Trend Season
```

Error: Additive ("A") or multiplicative ("M")

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Trend: None ("N"), additive ("A"), multiplicative ("M"), or damped ("Ad" or "Md").

Seasonality: None ("N"), additive ("A") or multiplicative ("M")

ETS(A,N,N): SES with additive errors

Forecast equation
$$\hat{y}_{T+h|T} = \ell_T$$

Measurement equation $y_t = \ell_{t-1} + \varepsilon_t$

State equation $\ell_t = \ell_{t-1} + \alpha \varepsilon_t$

where $\varepsilon_t \sim \text{NID}(0, \sigma^2)$.

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- "innovations" or "single source of error" because equations have the same error process, ε_t .
- Measurement equation: relationship between observations and states.
- Transition/state equation(s): evolution of the state(s) through time.

ETS(M,N,N): SES with multiplicative errors

Forecast equation
$$\hat{y}_{T+h|T} = \ell_T$$

Measurement equation $y_t = \ell_{t-1}(1 + \varepsilon_t)$

State equation $\ell_t = \ell_{t-1}(1 + \alpha \varepsilon_t)$

where $\varepsilon_t \sim \text{NID}(0, \sigma^2)$.

ETS(M,N,N): SES with multiplicative errors

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$$\hat{y}_{T+h|T} = \ell_T$$

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where $\varepsilon_t \sim \text{NID}(0, \sigma^2)$.

Models with additive and multiplicative errors with the same parameters generate the same point forecasts but different prediction intervals.

ETS(A,A,N): Holt's linear trend

Additive errors

Forecast equation
$$\hat{y}_{T+h|T} = \ell_T + hb_T$$

Measurement equation $y_t = \ell_{t-1} + b_{t-1} + \varepsilon_t$

State equations $\ell_t = \ell_{t-1} + b_{t-1} + \alpha \varepsilon_t$
 $b_t = b_{t-1} + \beta \varepsilon_t$

9

ETS(A,A,N): Holt's linear trend

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Multiplicative errors

Forecast equation
$$\hat{y}_{T+h|T} = \ell_T + hb_T$$

Measurement equation $y_t = (\ell_{t-1} + b_{t-1})(1 + \varepsilon_t)$

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 $b_t = b_{t-1} + \beta \varepsilon_t$

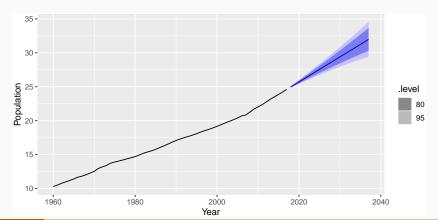
```
aus_economy <- global_economy %>% filter(Code == "AUS") %>%
  mutate(Pop = Population/1e6)
fit <- aus_economy %>% model(AAN = ETS(Pop))
report(fit)
```

```
## Series: Pop
## Model: ETS(A,A,N)
    Smoothing parameters:
##
##
      alpha = 1
##
      beta = 0.327
##
##
    Initial states:
##
    1 b
##
   10.1 0.222
##
##
##
    sigma^2: 0.0041
##
    ATC ATCC BTC
##
```

components(fit) %>%

```
left_join(fitted(fit), by = c("Country", ".model", "Year"))
## # A tsibble: 59 x 8 [1Y]
##
  # Key: Country, .model [1]
     Country .model Year Pop level slope remainder .fitted
##
   <fct> <chr>
                    <dbl> <dbl> <dbl> <dbl> <dbl>
                                                    <dbl>
##
##
   1 Australia AAN 1959
                          NA 10.1 0.222 NA
                                                    NA
   2 Australia AAN 1960 10.3 10.3 0.222 -0.000145
##
                                                    10.3
   3 Australia AAN 1961 10.5 10.5 0.217 -0.0159
##
                                                    10.5
   4 Australia AAN 1962 10.7 10.7 0.231 0.0418
##
                                                    10.7
   5 Australia AAN
                    1963 11.0 11.0 0.223 -0.0229
                                                    11.0
##
##
   6 Australia AAN
                    1964 11.2 11.2 0.221 -0.00641
                                                    11.2
   7 Australia AAN
                    1965 11.4 11.4 0.221 -0.000314
                                                    11.4
##
##
   8 Australia AAN
                    1966 11.7 11.7 0.235 0.0418
                                                    11.6
##
   9 Australia AAN
                    1967 11.8 11.8 0.206 -0.0869
                                                    11.9
## 10 Australia AAN 1968 12.0 12.0 0.208 0.00350
                                                    12.101
## # with 10 mara raws
```

```
fit %>%
  forecast(h = 20) %>%
  autoplot(aus_economy) +
  ylab("Population") + xlab("Year")
```



ETS(A,Ad,N): Damped trend method

Additive errors

Forecast equation
$$\hat{y}_{T+h|T} = \ell_T + (\phi + \cdots + \phi^{h-1})b_T$$

Measurement equation $y_t = (\ell_{t-1} + \phi b_{t-1}) + \varepsilon_t$
State equations $\ell_t = (\ell_{t-1} + \phi b_{t-1}) + \alpha \varepsilon_t$
 $\ell_t = (\ell_{t-1} + \phi b_{t-1}) + \alpha \varepsilon_t$

ETS(A,Ad,N): Damped trend method

Additive errors

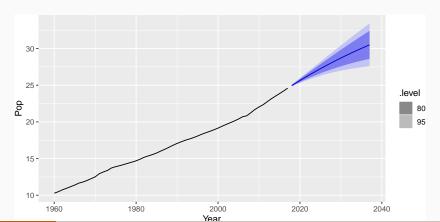
Forecast equation
$$\hat{y}_{T+h|T} = \ell_T + (\phi + \cdots + \phi^{h-1})b_T$$

Measurement equation $y_t = (\ell_{t-1} + \phi b_{t-1}) + \varepsilon_t$

State equations $\ell_t = (\ell_{t-1} + \phi b_{t-1}) + \alpha \varepsilon_t$
 $\ell_t = (\ell_{t-1} + \phi b_{t-1}) + \alpha \varepsilon_t$

- Damping parameter $0 < \phi < 1$.
- If ϕ = 1, identical to Holt's linear trend.
- As $h \to \infty$, $\hat{y}_{T+h|T} \to \ell_T + \phi b_T/(1-\phi)$.
- Short-run forecasts trended, long-run forecasts constant.

```
aus_economy %>%
  model(holt = ETS(Pop ~ trend("Ad"))) %>%
  forecast(h = 20) %>%
  autoplot(aus_economy)
```



Example: National populations

```
fit <- global_economy %>%
 mutate(Pop = Population/1e6) %>%
 model(ets = ETS(Pop))
fit
## # A mable: 263 x 2
## # Key: Country [263]
## Country
                        ets
## <fct>
                       <model>
## 1 Afghanistan
                       <ETS(A,A,N)>
## 2 Albania
                        <ETS(M,A,N)>
## 3 Algeria
                        <ETS(M,A,N)>
## 4 American Samoa
                        <ETS(M,A,N)>
## 5 Andorra
                        <ETS(M,A,N)>
## 6 Angola
                        <ETS(M,A,N)>
## 7 Antigua and Barbuda <ETS(M,A,N)>
## 8 Arab World
                        <ETS(M,A,N)>
## 9 Argentina
                        <ETS(A,A,N)>
## 10 Armenia
                        <ETS(M,A,N)>
## # ... with 253 more rows
```

Example: National populations

9 Albania

ets

##

```
fit %>%
 forecast(h = 5)
## # A fable: 1,315 x 5 [1Y]
  # Key: Country, .model [263]
##
## Country .model Year Pop .distribution
## <fct> <chr> <dbl> <dbl> <dist>
##
   1 Afghanistan ets 2018 36.4 N(36, 0.012)
##
   2 Afghanistan ets
                       2019 37.3
                                 N(37, 0.059)
   3 Afghanistan ets
                       2020 38.2 N(38, 0.164)
##
                       2021 39.0 N(39, 0.351)
##
   4 Afghanistan ets
##
   5 Afghanistan ets
                       2022 39.9
                                 N(40, 0.644)
                       2018 2.87 N(2.9, 0.00012)
##
   6 Albania
               ets
##
   7 Albania
               ets
                       2019 2.87 N(2.9, 0.00060)
##
   8 Albania
               ets
                       2020 2.87 N(2.9, 0.00169)
                       2021 2.86 N(2.9, 0.00362)
```

ETS(A,A,A): Holt-Winters additive method

Forecast equation
$$\hat{y}_{t+h|t} = \ell_t + hb_t + s_{t+h-m(k+1)}$$

Observation equation $y_t = \ell_{t-1} + b_{t-1} + s_{t-m} + \varepsilon_t$
State equations $\ell_t = \ell_{t-1} + b_{t-1} + \alpha \varepsilon_t$
 $b_t = b_{t-1} + \beta \varepsilon_t$
 $s_t = s_{t-m} + \gamma \varepsilon_t$

- k = integer part of (h-1)/m.
- lacksquare $\sum_i s_i \approx 0.$
- Parameters: $0 \le \alpha \le 1$, $0 \le \beta^* \le 1$, $0 \le \gamma \le 1 \alpha$ and m = period of seasonality (e.g. m = 4 for quarterly data).

ETS(M,A,M): Holt-Winters multiplicative method

Forecast equation
$$\hat{y}_{t+h|t} = (\ell_t + hb_t)s_{t+h-m(k+1)}$$

Observation equation $y_t = (\ell_{t-1} + b_{t-1})s_{t-m}(1 + \varepsilon_t)$
State equations $\ell_t = (\ell_{t-1} + b_{t-1})(1 + \alpha \varepsilon_t)$
 $b_t = b_{t-1}(1 + \beta \varepsilon_t)$
 $s_t = s_{t-m}(1 + \gamma \varepsilon_t)$

- k is integer part of (h-1)/m.
- lacksquare $\sum_i s_i \approx m$.
- Parameters: $0 \le \alpha \le 1$, $0 \le \beta^* \le 1$, $0 \le \gamma \le 1 \alpha$ and m = period of seasonality (e.g. m = 4 for quarterly data).

```
holidays <- tourism %>%
  filter(Purpose == "Holiday")
fit <- holidays %>% model(ets = ETS(Trips))
fit
  # A mable: 76 x 4
##
   # Key: Region, State, Purpose [76]
##
      Region
                                 State
                                                     Purpose ets
      <chr>>
                                  <chr>>
                                                     <chr>
                                                             <model>
##
    1 Adelaide
                                 South Australia
                                                     Holiday <ETS(A,N,A)>
##
    2 Adelaide Hills
##
                                 South Australia
                                                     Holiday <ETS(A,A,N)>
##
    3 Alice Springs
                                 Northern Territory
                                                     Holiday <ETS(M,N,A)>
    4 Australia's Coral Coast
##
                                 Western Australia
                                                     Holiday <ETS(M,N,A)>
    5 Australia's Golden Outback Western Australia
##
                                                     Holiday <ETS(M,N,M)>
    6 Australia's North West
##
                                 Western Australia
                                                     Holiday <ETS(A,N,A)>
##
    7 Australia's South West
                                 Western Australia
                                                     Holiday <ETS(M,N,M)>
##
    8 Ballarat
                                 Victoria
                                                     Holiday <ETS(M,N,A)>
##
    9 Barkly
                                 Northern Territory Holiday <ETS(A,N,A)>
                                                     Holiday <ETS(A,N,N)3
## 10 Barossa
                                 South Australia
```

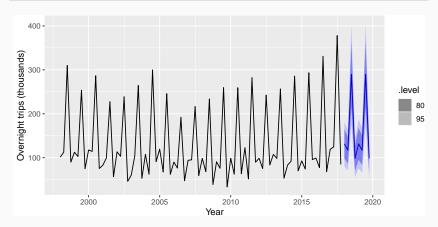
```
fit %>%
  filter(Region=="Snowy Mountains") %>%
  report()
```

```
## Series: Trips
## Model: ETS(M,N,A)
    Smoothing parameters:
##
##
       alpha = 0.157
##
      gamma = 1e-04
##
##
    Initial states:
##
     l s1 s2 s3
                      s4
##
   142 -61 131 -42.2 -27.7
##
##
    sigma^2: 0.0388
##
##
##
   AIC AICC BIC
##
   852
        854
            869
```

```
fit %>% forecast()
```

```
## # A fable: 608 x 7 [10]
## # Key:
             Region, State, Purpose, .model [76]
##
     Region
                 State
                           Purpose .model
                                           Quarter Trips .distribution
##
     <chr>
                 <chr> <chr> <chr> <chr>
                                             <atr> <dbl> <dist>
   1 Adelaide
                 South Aus~ Holiday ets
##
                                           2018 Q1 210. N(210, 457)
   2 Adelaide
##
                 South Aus~ Holiday ets
                                           2018 Q2 173. N(173, 473)
   3 Adelaide
##
                 South Aus~ Holiday ets
                                           2018 Q3 169. N(169, 489)
##
   4 Adelaide
                 South Aus~ Holiday ets
                                           2018 Q4 186. N(186, 505)
##
   5 Adelaide
                 South Aus~ Holiday ets
                                           2019 Q1 210.
                                                        N(210, 521)
##
   6 Adelaide
                 South Aus~ Holiday ets
                                           2019 02 173.
                                                        N(173, 537)
##
   7 Adelaide
                 South Aus~ Holiday ets
                                           2019 03 169.
                                                        N(169, 553)
   8 Adelaide
                 South Aus~ Holiday ets
                                           2019 04 186. N(186, 569)
##
   9 Adelaide H~ South Aus~ Holiday ets
##
                                           2018 Q1 19.4 N(19, 36)
  10 Adelaide H~ South Aus~ Holiday ets
                                           2018 02 19.6 N(20, 36)
## # ... with 598 more rows
```

```
fit %>% forecast() %>%
  filter(Region=="Snowy Mountains") %>%
  autoplot(holidays) +
    xlab("Year") + ylab("Overnight trips (thousands)")
```



Additive Error		Seasonal Component			
Trend		N	Α	М	
	Component	(None)	(Additive)	(Multiplicative)	
N	(None)	A,N,N	A,N,A	A,N,M	
Α	(Additive)	A,A,N	A,A,A	A,A,M	
A_d	(Additive damped)	A,A_d,N	A,A_d,A	A,A_d,M	

Multiplicative Error		Seasonal Component			
	Trend	N	Α	М	
	Component	(None)	(Additive)	(Multiplicative)	
N	(None)	M,N,N	M,N,A	M,N,M	
Α	(Additive)	M,A,N	M,A,A	M,A,M	
A_d	(Additive damped)	M,A _d ,N	M,A_d,A	M,A_d,M	

Estimating ETS models

- Smoothing parameters α , β , γ and ϕ , and the initial states ℓ_0 , b_0 , s_0 , s_{-1} , ..., s_{-m+1} are estimated by maximising the "likelihood" = the probability of the data arising from the specified model.
- For models with additive errors equivalent to minimising SSE.
- For models with multiplicative errors, not equivalent to minimising SSE.

Model selection

Akaike's Information Criterion

$$AIC = -2\log(L) + 2k$$

where *L* is the likelihood and *k* is the number of parameters initial states estimated in the model.

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Corrected AIC

$$AIC_c = AIC + \frac{2(k+1)(k+2)}{T-k}$$

which is the AIC corrected (for small sample bias).

Model selection

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$$AIC = -2\log(L) + 2k$$

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Corrected AIC

$$AIC_c = AIC + \frac{2(k+1)(k+2)}{T-k}$$

which is the AIC corrected (for small sample bias).

Bayesian Information Criterion

$$BIC = AIC + k(\log(T) - 2).$$

AIC and cross-validation

Minimizing the AIC assuming
Gaussian residuals is asymptotically
equivalent to minimizing one-step
time series cross validation MSE.

Automatic forecasting

From Hyndman et al. (IJF, 2002):

- Apply each model that is appropriate to the data.
 Optimize parameters and initial values using MLE (or some other criterion).
- Select best method using AICc:
- Produce forecasts using best method.
- Obtain forecast intervals using underlying state space model.

Method performed very well in M3 competition.

Some unstable models

- Some of the combinations of (Error, Trend, Seasonal) can lead to numerical difficulties; see equations with division by a state.
- These are: ETS(A,N,M), ETS(A,A,M), $ETS(A,A_d,M)$.
- Models with multiplicative errors are useful for strictly positive data, but are not numerically stable with data containing zeros or negative values. In that case only the six fully additive models will be applied.

Exponential smoothing models

Additive Error		Seasonal Component			
Trend		N	Α	М	
	Component	(None)	(Additive)	(Multiplicative)	
N	(None)	A,N,N	A,N,A	<u> </u>	
Α	(Additive)	A,A,N	A,A,A	<u>^,^,\</u>	
A_d	(Additive damped)	A,A _d ,N	A,A_d,A	<u>^,,^</u>	

Multiplicative Error		Seasonal Component		
	Trend	N	Α	М
	Component	(None)	(Additive)	(Multiplicative)
N	(None)	M,N,N	M,N,A	M,N,M
Α	(Additive)	M,A,N	M,A,A	M,A,M
A_d	(Additive damped)	M,A_d,N	M,A_d,A	M,A_d,M

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Lab Session 7

- Find an ETS model for the Gas data from aus_production.
 - Why is multiplicative seasonality necessary here?
 - Experiment with making the trend damped.
- Use ETS() on some of these series: tourism, gafa_stock, pelt.
 - Does it always give good forecasts?
 - Find an example where it does not work well. Can you figure out why?

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AR: autoregressive (lagged observations as inputs)

I: integrated (differencing to make series stationary)

MA: moving average (lagged errors as inputs)

AR: autoregressive (lagged observations as inputs)

I: integrated (differencing to make series stationary)

MA: moving average (lagged errors as inputs)

An ARIMA model is rarely interpretable in terms of visible data structures like trend and seasonality. But it can capture a huge range of time series patterns.

Stationarity

Definition

If $\{y_t\}$ is a stationary time series, then for all s, the distribution of (y_t, \ldots, y_{t+s}) does not depend on t.

Stationarity

Definition

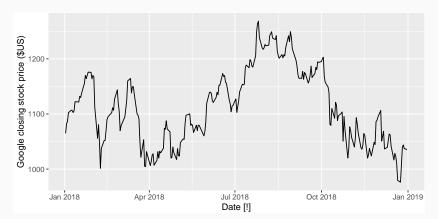
If $\{y_t\}$ is a stationary time series, then for all s, the distribution of (y_t, \ldots, y_{t+s}) does not depend on t.

A stationary series is:

- roughly horizontal
- constant variance
- no patterns predictable in the long-term

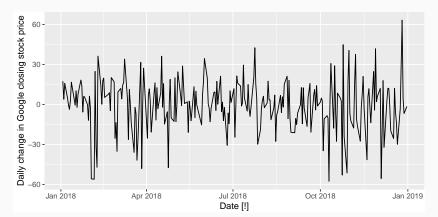
Stationary?

```
gafa_stock %>%
  filter(Symbol == "G00G", year(Date) == 2018) %>%
  autoplot(Close) +
   ylab("Google closing stock price ($US)")
```



Stationary?

```
gafa_stock %>%
  filter(Symbol == "G00G", year(Date) == 2018) %>%
  autoplot(difference(Close)) +
    ylab("Daily change in Google closing stock price")
```



Differencing

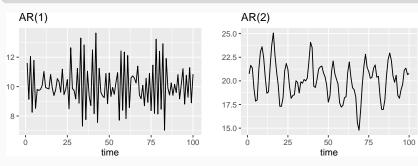
- Differencing helps to **stabilize the mean**.
- The differenced series is the change between each observation in the original series.
- Occasionally the differenced data will not appear stationary and it may be necessary to difference the data a second time.
- In practice, it is almost never necessary to go beyond second-order differences.

Autoregressive models

Autoregressive (AR) models:

$$\mathbf{y_t} = \mathbf{c} + \phi_1 \mathbf{y_{t-1}} + \phi_2 \mathbf{y_{t-2}} + \cdots + \phi_p \mathbf{y_{t-p}} + \varepsilon_t,$$

where ε_t is white noise. This is a multiple regression with **lagged values** of y_t as predictors.

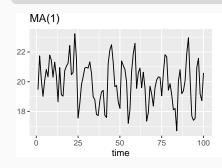


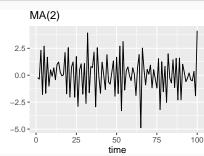
Cyclic behaviour is possible when $p \geq 2$.

Moving Average (MA) models

Moving Average (MA) models:

 $y_t = c + \varepsilon_t + \theta_1 \varepsilon_{t-1} + \theta_2 \varepsilon_{t-2} + \cdots + \theta_q \varepsilon_{t-q},$ where ε_t is white noise. This is a multiple regression with **lagged** *errors* as predictors. Don't confuse this with moving average smoothing!





Autoregressive Moving Average models:

$$y_{t} = c + \phi_{1}y_{t-1} + \dots + \phi_{p}y_{t-p}$$
$$+ \theta_{1}\varepsilon_{t-1} + \dots + \theta_{q}\varepsilon_{t-q} + \varepsilon_{t}.$$

Autoregressive Moving Average models:

$$y_{t} = c + \phi_{1}y_{t-1} + \dots + \phi_{p}y_{t-p}$$
$$+ \theta_{1}\varepsilon_{t-1} + \dots + \theta_{q}\varepsilon_{t-q} + \varepsilon_{t}.$$

Predictors include both lagged values of y_t and lagged errors.

Autoregressive Moving Average models:

$$y_{t} = c + \phi_{1}y_{t-1} + \dots + \phi_{p}y_{t-p}$$
$$+ \theta_{1}\varepsilon_{t-1} + \dots + \theta_{q}\varepsilon_{t-q} + \varepsilon_{t}.$$

Predictors include both lagged values of y_t and lagged errors.

Autoregressive Integrated Moving Average models

- Combine ARMA model with differencing.
- d-differenced series follows an ARMA model.
- Need to choose *p*, *d*, *q* and whether or not to include *c*.

ARIMA(p, d, q) model

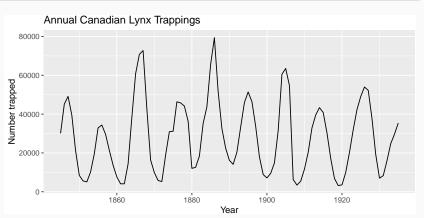
AR: p = order of the autoregressive part

I: d =degree of first differencing involved

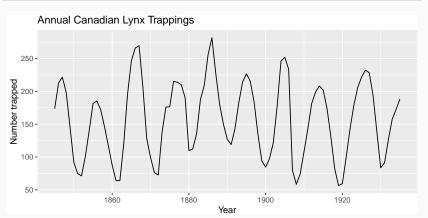
MA: q = order of the moving average part.

- White noise model: ARIMA(0,0,0)
- Random walk: ARIMA(0,1,0) with no constant
- Random walk with drift: ARIMA(0,1,0) with const.
- \blacksquare AR(p): ARIMA(p,0,0)
- \blacksquare MA(q): ARIMA(0,0,q)

```
pelt %>% autoplot(Lynx) +
   xlab("Year") + ylab("Number trapped") +
   ggtitle("Annual Canadian Lynx Trappings")
```

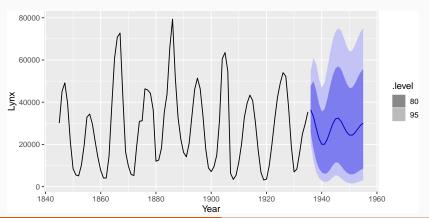


```
pelt %>% autoplot(sqrt(Lynx)) +
    xlab("Year") + ylab("Number trapped") +
    ggtitle("Annual Canadian Lynx Trappings")
```



```
pelt %>%
 model(lynx = ARIMA(sqrt(Lynx))) %>%
 report()
## Series: Lynx
## Model: ARIMA(2,0,1) w/ mean
## Transformation: sqrt(.x)
##
## Coefficients:
##
           arl ar2 mal constant
## 1.5059 -0.8645 -0.331
                                 56.33
## s.e. 0.0583 0.0522 0.108 1.56
##
## sigma^2 estimated as 507.9: log likelihood=-412
## AIC=834 AICc=835 BIC=847
```

```
pelt %>%
  model(lynx = ARIMA(sqrt(Lynx))) %>%
  forecast(h=20) %>%
  autoplot(pelt)
```



Example: National populations

```
fit <- global_economy %>%
 mutate(Pop = Population/1e6) %>%
 model(arima = ARIMA(Pop))
fit
## # A mable: 263 x 2
## # Key: Country [263]
## Country
                        arima
## <fct>
                       <model>
## 1 Afghanistan
                       <ARIMA(4,2,1)>
## 2 Albania
                        <ARIMA(0,2,2)>
## 3 Algeria
                        <ARIMA(2,2,2)>
## 4 American Samoa
                        <ARIMA(2,2,2)>
                        <ARIMA(2,1,2) w/ drift>
## 5 Andorra
## 6 Angola
                        <ARIMA(4,2,1)>
## 7 Antigua and Barbuda <ARIMA(2,1,2) w/ drift>
## 8 Arab World
                        <ARIMA(0,2,1)>
                        <ARIMA(2,2,2)>
## 9 Argentina
## 10 Armenia
                        <ARIMA(3,2,0)>
## # ... with 253 more rows
```

Understanding ARIMA models

- If c = 0 and d = 0, the long-term forecasts will go to zero.
- If c = 0 and d = 1, the long-term forecasts will go to a non-zero constant.
- If c = 0 and d = 2, the long-term forecasts will follow a straight line.
- If $c \neq 0$ and d = 0, the long-term forecasts will go to the mean of the data.
- If $c \neq 0$ and d = 1, the long-term forecasts will follow a straight line.
- If $c \neq 0$ and d = 2, the long-term forecasts will follow a quadratic trend.

Understanding ARIMA models

Forecast variance and d

- The higher the value of *d*, the more rapidly the prediction intervals increase in size.
- For d = 0, the long-term forecast standard deviation will go to the standard deviation of the historical data.

Hyndman and Khandakar (JSS, 2008) algorithm:

- Select no. differences d via KPSS test.
- Select *p*, *q* and inclusion of *c* by minimising AICc.
- Use stepwise search to traverse model space.

Hyndman and Khandakar (JSS, 2008) algorithm:

- Select no. differences d via KPSS test.
- Select p, q and inclusion of c by minimising AICc.
- Use stepwise search to traverse model space.

AICc =
$$-2 \log(L) + 2(p+q+k+1) \left[1 + \frac{(p+q+k+2)}{T-p-q-k-2} \right]$$
. where L is the maximised likelihood fitted to the differenced data, $k = 1$ if $c \neq 0$ and $k = 0$ otherwise.

Hyndman and Khandakar (JSS, 2008) algorithm:

- Select no. differences d via KPSS test.
- Select *p*, *q* and inclusion of *c* by minimising AICc.
- Use stepwise search to traverse model space.

AICc =
$$-2 \log(L) + 2(p+q+k+1) \left[1 + \frac{(p+q+k+2)}{T-p-q-k-2} \right]$$
. where L is the maximised likelihood fitted to the differenced data, $k = 1$ if $c \neq 0$ and $k = 0$ otherwise.

Note: Can't compare AICc for different values of *d*.

Step1: Select current model (with smallest AICc) from:

ARIMA(2, d, 2)

ARIMA(0, d, 0)

ARIMA(1, d, 0)

ARIMA(0, d, 1)

```
Step1: Select current model (with smallest AICc) from:

ARIMA(2, d, 2)

ARIMA(0, d, 0)

ARIMA(1, d, 0)

ARIMA(0, d, 1)
```

- **Step 2:** Consider variations of current model:
 - vary one of p, q, from current model by ± 1 ;
 - **p**, q both vary from current model by ± 1 ;
 - Include/exclude *c* from current model.

Model with lowest AICc becomes current model.

Repeat Step 2 until no lower AICc can be found.

Automatic modelling procedure with ARIMA

- Plot the data. Identify any unusual observations.
- If necessary, transform the data (using a Box-Cox transformation) to stabilize the variance.
- Use ARIMA to automatically select a model.
- Check the residuals from your chosen model by plotting the ACF of the residuals, and doing a portmanteau test of the residuals. If they do not look like white noise, try a modified model.
- Once the residuals look like white noise, calculate forecasts.

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- 7 Lab Session 10

Lab Session 9

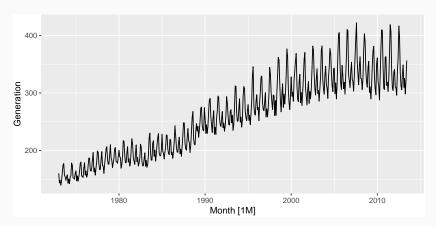
For the United States GDP data (from global_economy):

- if necessary, find a suitable Box-Cox transformation for the data;
- fit a suitable ARIMA model to the transformed data;
- check the residual diagnostics;
- produce forecasts of your fitted model. Do the forecasts look reasonable?

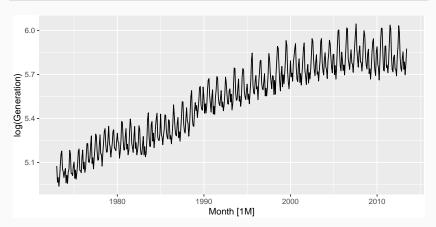
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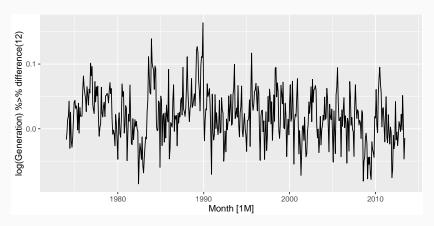
```
usmelec %>% autoplot(
  Generation
)
```



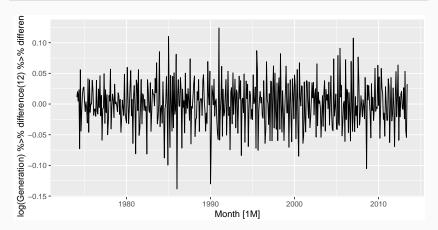
```
usmelec %>% autoplot(
  log(Generation)
)
```

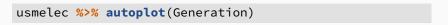


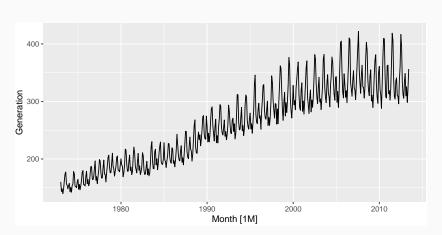
```
usmelec %>% autoplot(
  log(Generation) %>% difference(12)
)
```



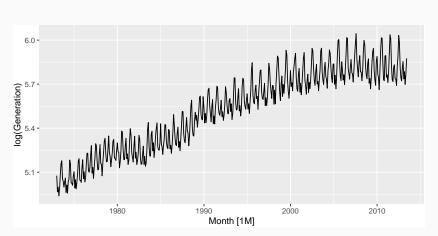
```
usmelec %>% autoplot(
  log(Generation) %>% difference(12) %>% difference()
)
```





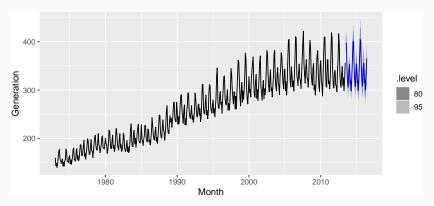




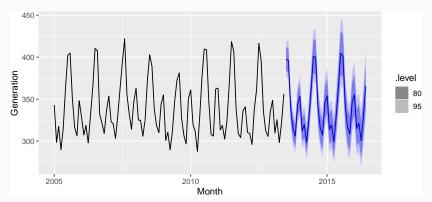


```
usmelec %>%
 model(arima = ARIMA(log(Generation))) %>%
 report()
## Series: Generation
## Model: ARIMA(1,1,1)(2,1,1)[12]
## Transformation: log(.x)
##
## Coefficients:
##
           ar1
                    ma1
                           sar1 sar2 sma1
##
        0.4116 - 0.8483 0.0100 - 0.1017 - 0.8204
## s.e. 0.0617 0.0348 0.0561
                                 0.0529
                                          0.0357
##
## sigma^2 estimated as 0.0006841: log likelihood=1047
## AIC=-2082 AICc=-2082
                           BIC=-2057
```

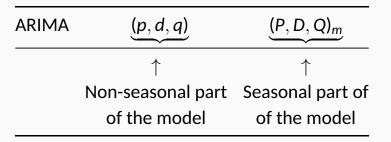
```
usmelec %>%
model(arima = ARIMA(log(Generation))) %>%
forecast(h="3 years") %>%
autoplot(usmelec)
```



```
usmelec %>%
model(arima = ARIMA(log(Generation))) %>%
forecast(h="3 years") %>%
autoplot(filter_index(usmelec, 2005 ~ .))
```



Seasonal ARIMA models



where m = number of observations per year.

- d first differences
- D seasonal differences
- p AR lags
- q MA lags

Common ARIMA models

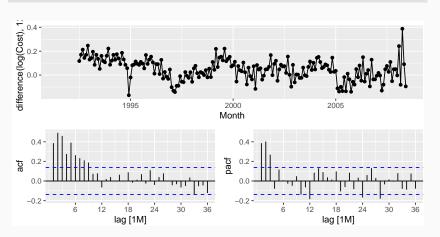
The US Census Bureau uses the following models most often:

ARIMA(0,1,1)(0,1,1) _m	with log transformation
$ARIMA(0,1,2)(0,1,1)_m$	with log transformation
$ARIMA(2,1,0)(0,1,1)_m$	with log transformation
$ARIMA(0,2,2)(0,1,1)_m$	with log transformation
$ARIMA(2,1,2)(0,1,1)_m$	with no transformation

1250000 -1000000 -750000 -

```
h02 %>%
  mutate(log(Cost)) %>%
  gather() %>%
  ggplot(aes(x = Month, y = value)) +
  geom_line() +
  facet_grid(key ~ ., scales = "free_y") +
  xlab("Year") + ylab("") +
  ggtitle("Cortecosteroid drug scripts (H02)")
   Cortecosteroid drug scripts (H02)
```

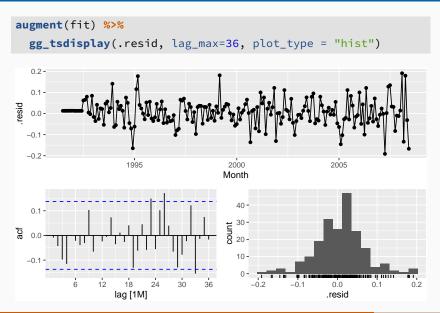
h02 %>% gg_tsdisplay(difference(log(Cost),12),



- Choose D = 1 and d = 0.
- Spikes in PACF at lags 12 and 24 suggest seasonal AR(2) term.
- Spikes in PACF suggests possible non-seasonal AR(3) term.
- Initial candidate model: ARIMA(3,0,0)(2,1,0)₁₂.

.model	AlCc
ARIMA(3,0,1)(0,1,2)[12]	-485
ARIMA(3,0,1)(1,1,1)[12]	-484
ARIMA(3,0,1)(0,1,1)[12]	-484
ARIMA(3,0,1)(2,1,0)[12]	-476
ARIMA(3,0,0)(2,1,0)[12]	-475
ARIMA(3,0,2)(2,1,0)[12]	-475
ARIMA(3,0,1)(1,1,0)[12]	-463

```
fit <- h02 %>%
 model(best = ARIMA(log(Cost) \sim 0 + pdq(3,0,1) + PDQ(0,1,2)))
report(fit)
## Series: Cost
## Model: ARIMA(3,0,1)(0,1,2)[12]
## Transformation: log(.x)
##
## Coefficients:
          arl ar2 ar3 ma1 sma1 sma2
##
## -0.160 0.5481 0.5678 0.383 -0.5222 -0.1769
## s.e. 0.164 0.0878 0.0942 0.190 0.0861 0.0872
##
## sigma^2 estimated as 0.004289: log likelihood=250
## AIC=-486 AICc=-485 BIC=-463
```

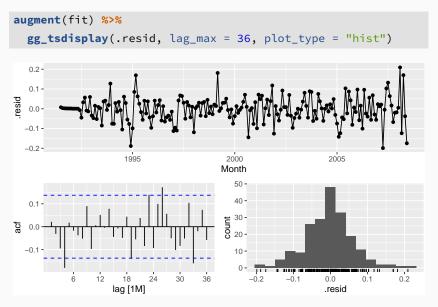


```
augment(fit) %>%
features(.resid, ljung_box, lag = 36, dof = 6)
```

```
## # A tibble: 1 x 3
## .model lb_stat lb_pvalue
## <chr> <dbl> <dbl>
## 1 best 50.5 0.0109
```

```
report(fit)
## Series: Cost
## Model: ARIMA(2,1,0)(0,1,1)[12]
## Transformation: log(.x)
##
## Coefficients:
##
            ar1 ar2 sma1
## -0.8491 -0.4207 -0.6401
## s.e. 0.0712 0.0714 0.0694
##
## sigma^2 estimated as 0.004399: log likelihood=245
## ATC=-483 ATCc=-483 BTC=-470
```

fit <- h02 %>% model(auto = ARIMA(log(Cost)))



```
augment(fit) %>%
features(.resid, ljung_box, lag = 36, dof = 5)
```

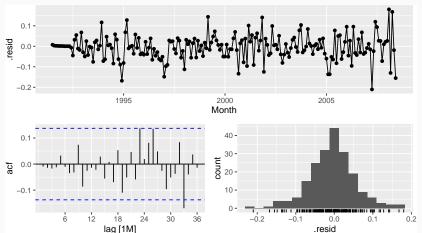
```
## # A tibble: 1 x 3
## .model lb_stat lb_pvalue
## <chr> <dbl> <dbl>
## 1 auto 57.5 0.00260
```

fit <- h02 %>%

```
model(best = ARIMA(log(Cost), stepwise = FALSE,
               approximation = FALSE,
               order constraint = p + q + P + 0 \le 9)
report(fit)
## Series: Cost
## Model: ARIMA(4,1,1)(2,1,2)[12]
## Transformation: log(.x)
##
## Coefficients:
##
               ar2 ar3 ar4 ma1 sar1 sar2
                                                          sma1
           ar1
## -0.0426 0.210 0.202 -0.227 -0.742 0.621 -0.383 -
1.202
## s.e. 0.2167 0.181 0.114 0.081 0.207 0.242 0.118
                                                         0.249
## sma2
## 0.496
## s.e. 0.214
##
## sigma^2 estimated as 0.004061: log likelihood=254
## AIC=-489 AICc=-487
                       BIC=-456
```

```
augment(fit) %>%

gg_tsdisplay(.resid, lag_max = 36, plot_type = "hist")
```



.model lb_stat lb_pvalue
<chr> <dbl> <dbl>
1 best 35.1 0.136

```
augment(fit) %>%
features(.resid, ljung_box, lag = 36, dof = 9)
## # A tibble: 1 x 3
```

Training data: July 1991 to June 2006

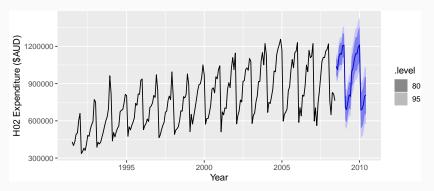
Test data: July 2006-June 2008

```
fit <- h02 %>%
  filter_index(~ "2006 Jun") %>%
  model(
    ARIMA(log(Cost) \sim pdq(3, 0, 0) + PDQ(2, 1, 0)),
    ARIMA(log(Cost) \sim pdq(3, 0, 1) + PDQ(2, 1, 0)),
    ARIMA(log(Cost) \sim pdq(3, 0, 2) + PDQ(2, 1, 0)),
    ARIMA(log(Cost) \sim pdq(3, 0, 1) + PDO(1, 1, 0))
    # ... #
fit %>%
  forecast(h = "2 years") %>%
  accuracy(h02 %>% filter index("2006 Jul" ~ .))
```

```
models <- list(</pre>
  c(3,0,0,2,1,0),
  c(3,0,1,2,1,0),
  c(3,0,2,2,1,0),
  c(3,0,1,1,1,0),
  c(3,0,1,0,1,1),
  c(3,0,1,0,1,2),
  c(3,0,1,1,1,1)
  c(3,0,3,0,1,1),
  c(3,0,2,0,1,1),
  c(2,1,3,0,1,1),
  c(2,1,4,0,1,1),
  c(2,1,5,0,1,1),
  c(4,1,1,2,1,2))
```

- Models with lowest AICc values tend to give slightly better results than the other models.
- AICc comparisons must have the same orders of differencing. But RMSE test set comparisons can involve any models.
- Use the best model available, even if it does not pass all tests.

```
fit <- h02 %>%
  model(ARIMA(Cost ~ 0 + pdq(3,0,1) + PDQ(0,1,2)))
fit %>% forecast %>% autoplot(h02) +
  ylab("H02 Expenditure ($AUD)") + xlab("Year")
```



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ARIMA vs ETS

- Myth that ARIMA models are more general than exponential smoothing.
- Linear exponential smoothing models all special cases of ARIMA models.
- Non-linear exponential smoothing models have no equivalent ARIMA counterparts.
- Many ARIMA models have no exponential smoothing counterparts.
- ETS models all non-stationary. Models with seasonality or non-damped trend (or both) have two unit roots; all other models have one unit root₄

Equivalences

ETS model	ARIMA model	Parameters
ETS(A,N,N)	ARIMA(0,1,1)	$\theta_1 = \alpha - 1$
ETS(A,A,N)	ARIMA(0,2,2)	θ_1 = α + β $-$ 2
		θ_{2} = 1 $-\alpha$
ETS(A,A,N)	ARIMA(1,1,2)	ϕ_1 = ϕ
		θ_1 = α + $\phi\beta$ $-$ 1 $ \phi$
		θ_2 = (1 $-\alpha$) ϕ
ETS(A,N,A)	$ARIMA(0,0,m)(0,1,0)_m$	
ETS(A,A,A)	ARIMA $(0,1,m+1)(0,1,0)_m$	
ETS(A,A,A)	$ARIMA(1,0,m+1)(0,1,0)_m$	

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Lab Session 10

For the fma::condmilk series:

- Do the data need transforming? If so, find a suitable transformation.
- Are the data stationary? If not, find an appropriate differencing which yields stationary data.
- Identify a couple of ARIMA models that might be useful in describing the time series.
- Which of your models is the best according to their AIC values?
- Estimate the parameters of your best model and do diagnostic testing on the residuals. Do the residuals resemble white noise? If not, try to find another ARIMA model which fits better.
- Forecast the next 24 months of data using your preferred model.