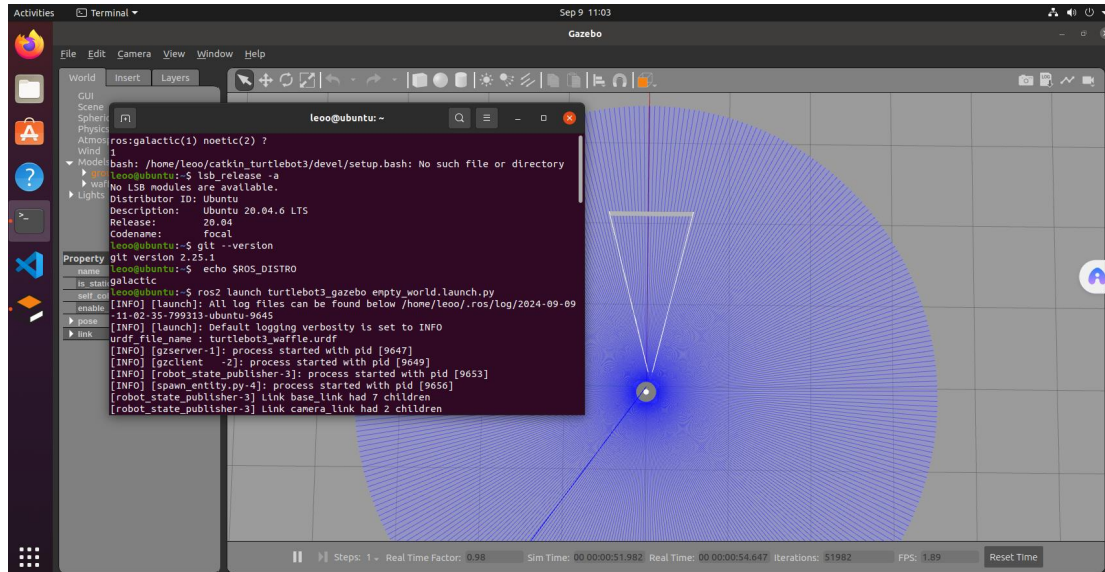


## 1. Screenshots of your software installation:



## 2. A video recording of the Gazebo scene while controlling the Turtlebot3 using teleop, Turtle3teleop: <https://youtu.be/4zq8kyoPLVY>

## 3 and 4. Video recording of the Gazebo scene while controlling the Turtlebot3 using an open loop controller,(Scenario1 : <https://youtu.be/mJQaQI-EySk> Scenario2 : <https://youtu.be/aXCyUxrVKiQ>)

## 5. Github Python script:

[lekangtu123/ENPM662\\_project0: Open loop controller node code \(github.com\)](https://github.com/lekangtu123/ENPM662_project0)