

Appendix B and 5.5 Complex Eigenvalues

HW 26 + HW 27 due together

handwritten only, see course page

(do # 1, 2, 6, 8)

A complex number is written as $z = a + bi$ a, b are real



$$i^2 = -1$$

real part of z $\text{Re}(z)$

$$\text{IR}^2 = \begin{bmatrix} x \\ y \end{bmatrix} \quad x, y \text{ real}$$

IR : set of all real numbers

\mathbb{C} : " .. complex numbers

$$\mathbb{C}^2 = \begin{bmatrix} z_1 \\ z_2 \end{bmatrix} \quad z_1, z_2 \text{ are complex}$$

complex conjugate:

$$z = a + bi$$

$$\overline{3+4i} = 3-4i$$

$$\overline{z} = a - bi$$

$$\overline{3-4i} = 3+4i$$

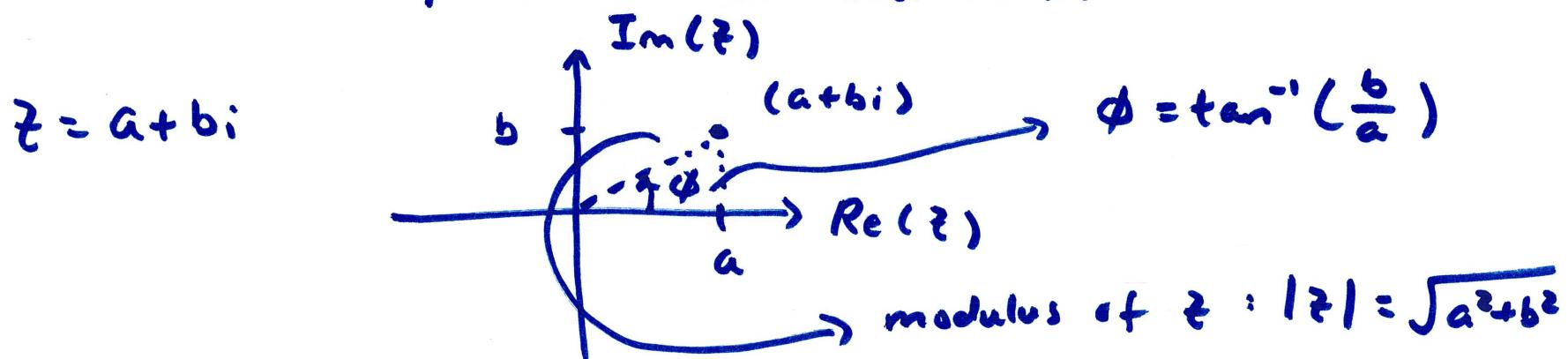
$$(a+bi) + (c+di) = \underline{(a+c)} + \underline{(b+d)i}$$

$$\begin{aligned}(a+bi)(c+di) &= ac + adi + cbi + bd i^2 \\ &= (ac - bd) + (ad + cb)i\end{aligned}$$

division is not like polynomials

$$\begin{aligned}\frac{1+2i}{3+4i} &= \frac{1+2i}{3+4i} \cdot \frac{3-4i}{3-4i} = \frac{(1+2i)(3-4i)}{(3+4i)(3-4i)} \\ &= \frac{3-4i+6i-8i^2}{9-12i+12i-16i^2} = \frac{11+2i}{25} = \frac{11}{25} + \frac{2}{25}i\end{aligned}$$

$a+bi$ can be interpreted like a vector in \mathbb{R}^2



polar form : $z = a + bi = re^{i\phi}$ where r, ϕ defined
as on last page
 $= r(\cos\phi + i\sin\phi)$

de Moivre's Theorem : $z = r(\cos\phi + i\sin\phi)$

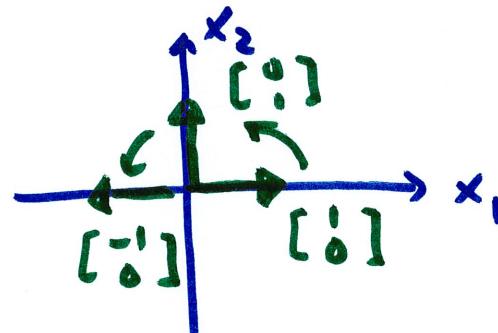
then $z^k = r^k(\cos k\phi + i\sin k\phi)$

5.5 Complex Eigenvalues

$A = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$ what does this do to \vec{x} ?

$$A \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$A \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} -1 \\ 0 \end{bmatrix}$$



this is a quarter circle turn counterclockwise

$$A \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} -y \\ x \end{bmatrix} \quad \text{no vector can preserve heading}$$

$$A\vec{x} = \lambda \vec{x} \quad \lambda = ?$$

find λ 's:

$$|A - \lambda I| = 0 \quad A = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$$

$$\begin{vmatrix} -\lambda & -1 \\ 1 & -\lambda \end{vmatrix} = -\lambda^2 + 1 = 0 \rightarrow \lambda = \pm i$$

find eigenvectors

$$\lambda = i \quad (A - \lambda I) \vec{x} = \vec{0} \quad \begin{bmatrix} -i & -1 & 0 \\ 1 & -i & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & -i & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$x_2 \text{ free} \quad x_1 = ix_2 \quad \text{choose } x_2 = 1$$

$$\vec{v} = \begin{bmatrix} i \\ 1 \end{bmatrix}$$

$$\begin{bmatrix} i & -1 & 0 \\ 1 & i & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & i & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

$$x_2 \text{ free} \quad x_1 = -ix_2 \quad \text{choose } x_2 = 1$$

$$\vec{v} = \begin{bmatrix} -i \\ 1 \end{bmatrix}$$

$$\lambda = -i \quad (A - \lambda I) \vec{x} = \vec{0}$$

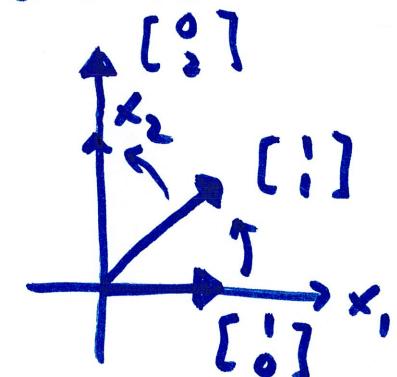
note λ 's and \vec{v} 's are complex conjugate pairs.

Complex λ 's are associated with rotation, but there can be scaling, too.

$$A = \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix}$$

$$A \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$A \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 2 \end{bmatrix}$$



45° ccw turn with a lengthening by a factor of $\sqrt{2}$

eigenvalues tell us this

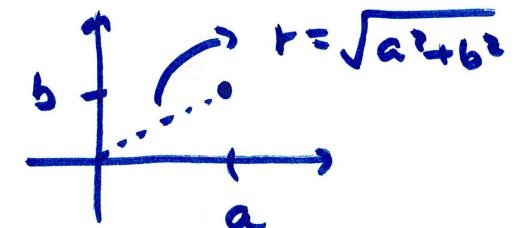
$$\begin{vmatrix} 1-\lambda & -1 \\ 1 & 1-\lambda \end{vmatrix} = 0 \quad (1-\lambda)^2 + 1 = 0 \quad 1-\lambda = i \quad \text{or} \quad 1-\lambda = -i$$
$$\lambda = 1-i \quad \text{or} \quad \lambda = 1+i$$

$\lambda = a+bi$ then the scaling factor is $\sqrt{a^2+b^2}$

$\phi = \tan^{-1}\left(\frac{b}{a}\right)$ is the turning angle

rotation matrix : $\begin{bmatrix} a & -b \\ b & a \end{bmatrix}$ a, b real, not both zero

$$\begin{bmatrix} a & -b \\ b & a \end{bmatrix} = r \begin{bmatrix} a/r & -b/r \\ b/r & a/r \end{bmatrix}$$



$$= \begin{bmatrix} r & 0 \\ 0 & r \end{bmatrix} \begin{bmatrix} \cos \phi & -\sin \phi \\ \sin \phi & \cos \phi \end{bmatrix}$$

↳ scaling factor

$$\phi = \tan^{-1}\left(\frac{b}{a}\right)$$

turning angle

example

$$A = \begin{bmatrix} 1 & -2 \\ 1 & 3 \end{bmatrix} \quad \lambda = 2+i \quad \vec{v} = \begin{bmatrix} -1+i \\ 1 \end{bmatrix}$$

$$\lambda = 2-i \quad \vec{v} = \begin{bmatrix} -1-i \\ 1 \end{bmatrix}$$

$$\lambda = a \pm bi \quad \text{here, } a=2, b=1 \quad r = \sqrt{a^2+b^2} = \sqrt{5}$$

define $C = \begin{bmatrix} a & -b \\ b & a \end{bmatrix} = \begin{bmatrix} 2 & -1 \\ 1 & 2 \end{bmatrix}$ this is hidden inside A

we can decompose A much like how we diagonalize matrices

$$A = P C P^{-1}$$

↳ not diagonal, but a rotation matrix

eigenvectors: $\begin{bmatrix} -1+i \\ 1 \end{bmatrix}, \begin{bmatrix} -1-i \\ 1 \end{bmatrix}$ separate real and img parts

$$\vec{v} = \begin{bmatrix} -1 \\ 1 \end{bmatrix} \pm i \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

↓ ↓
use as columns of P

$$P = \begin{bmatrix} -1 & 1 \\ 1 & 0 \end{bmatrix} \quad P^{-1} = \begin{bmatrix} 0 & 1 \\ 1 & 1 \end{bmatrix} \quad C = \begin{bmatrix} 2 & -1 \\ 1 & 2 \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & -2 \\ 1 & 3 \end{bmatrix} = P C P^{-1} = \begin{bmatrix} -1 & 1 \\ 1 & 0 \end{bmatrix} \underbrace{\begin{bmatrix} 2 & -1 \\ 1 & 2 \end{bmatrix}}_{\text{Scaling + rotation}} \begin{bmatrix} 0 & 1 \\ 1 & 1 \end{bmatrix}$$

$$A\vec{x} = P \underbrace{C P^{-1}}_{\text{change of coordinates/variables}} \vec{x}$$

$\underbrace{\quad}_{\text{scale, rotate}}$

$\underbrace{\quad}_{\text{undo change of variables/coordinates}}$

λ , if complex, must come in pairs.

$$A = \begin{bmatrix} 4 & 0 & 0 \\ 0 & 1 & -1 \\ 0 & 5 & -3 \end{bmatrix}$$

$$\lambda = \overbrace{-1+i, -1-i, 4}^{\text{pairs of complex } \lambda's}$$

$$\vec{v} = \underbrace{\left[\begin{array}{c} 0 \\ 2/\sqrt{5} + 1/\sqrt{5}i \\ 1 \end{array} \right], \left[\begin{array}{c} 0 \\ 2/\sqrt{5} - 1/\sqrt{5}i \\ 1 \end{array} \right], \left[\begin{array}{c} 1 \\ 0 \\ 0 \end{array} \right]}_{\text{pairs}}$$