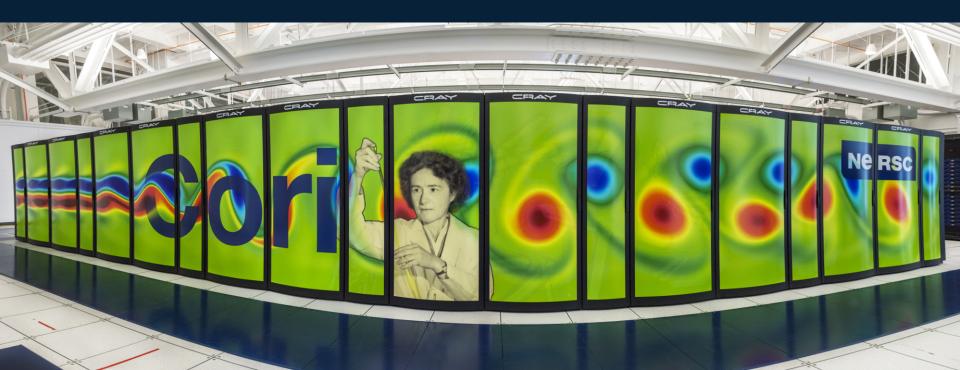
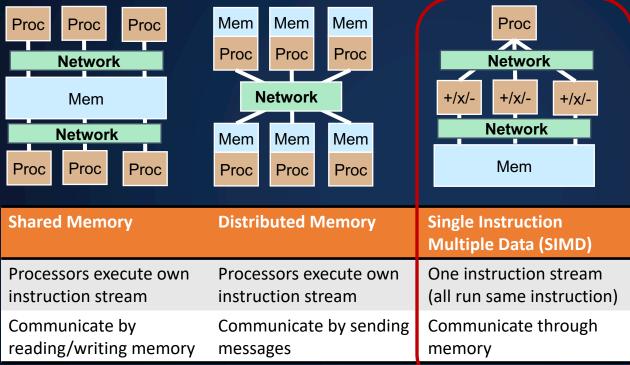
Applications of Parallel ComputersData Parallel Algorithms

https://sites.google.com/lbl.gov/cs267-spr2021



Parallel Machines and Programming



Abstract Machine Models

The Power of Data Parallelism

- Data parallelism: perform the same operation on multiple values (often array elements)
 - Also includes reductions, broadcast, scan...
- Many parallel programming models use some data parallelism
 - SIMD units (and previously SIMD supercomputers)
 - CUDA / GPUs
 - MapReduce
 - MPI collectives

Data Parallel Programming: Unary Operators

Unary operations applied to all elements of an array

```
A = array
B = array
f = square (any unary function, i.e., 1 argument)
B = f(A)

A: 3 1 1 2 3 3 4 2 2 2 1 3 1 1 1 3 3 2 1

f applied to each element

B: 9 1 1 4 9 9 16 4 4 4 1 9 1 1 1 9 9 4 1
```

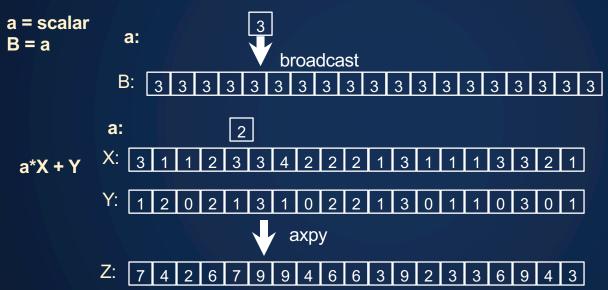
Data Parallel Programming: Binary Operators

Binary operations applied to all pairs of elements

```
A = array
B = array
C = array
- or any other binary operator
C = A - B
                3 1 0 2 3 0 4 2 0 2 1 3 0 1 1 0 3 2 1
                                       - applied to each pair
                0 1 1 4 1 0 2 1 4 3 1 0 1 1 2 3 5 3 2
                | 3 | 0 | 1 | -2 | 2 | 0 | 2 | 2 | -4 | -2 | 0 | 3 | -1 | 0 | -1 | -3 | -2 | -1 | -1 |
```

Data Parallel Programming: Broadcast

Broadcast fill a value into all elements of an array



- Useful for a*X+Y called axpy, saxpy, daxpy
 - For single, double precision, or in general

Array assignment works if the arrays are the same shape

```
A: double [0:4]
B: double [0:4] = [0.0, 1.0, 2.2, 3.3, 4.4]
```

A = B

Array assignment works if the arrays are the same shape

```
A: double [0:4]
B: double [0:4] = [0.0, 1.0, 2.2, 3.3, 4.4]
A = B
```

May have a stride, i.e., not be contiguous in memory

```
A = B [0:4:2] // copy with stride 2 (every other element)
C: double [0:4, 0:4]
A = C [*,3] // copy column of C
```

Array assignment works if the arrays are the same shape

```
A: double [0:4]
B: double [0:4] = [0.0, 1.0, 2.2, 3.3, 4.4]
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```

Gather (indexed) values from one array

```
X: int [0:4] = [3, 0, 4, 2, 1] // a permutation of indices 0 to 4
A = B[X] // A now is [3.3, 0.0, 4.4, 2.2, 1.1]
```

Array assignment works if the arrays are the same shape

```
A: double [0:4]
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A = B[X] // A now is [3.3, 0.0, 4.4, 2.2, 1.1]
```

Scatter (indexed) values from one array

```
A[X] = B // A now is [1.1, 4.4, 3.3, 0.0, 2.2]
```

Array assignment works if the arrays are the same shape

```
A: double [0:4]
B: double [0:4] = [0.0, 1.0, 2.2, 3.3, 4.4]
A = B
```

May have a stride, i.e., not be contiguous in memory

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```

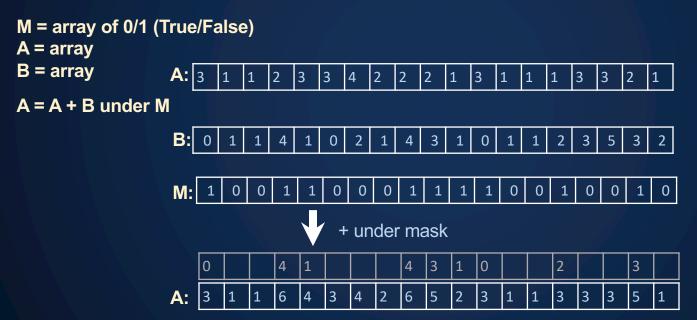
Scatter (indexed) values from one array

2/11/21

```
A[X] = B // A now is [1.1, 4.4, 3.3, 0.0, 2.2]
What if X = [0.0, 0.0, 0.0]? CS267 Lecture
```

Data Parallel Programming: Masks

Can apply operations under a "mask"



Data Parallel Programming: Reduce

Reduce an array to a value with + or any associative op

```
A = array
b = scalar
b = sum(A)

A: 3 1 1 2 3 3 4 2 2 2 1 3 1 1 1 3 3 2 1

sum reduction
b:
```

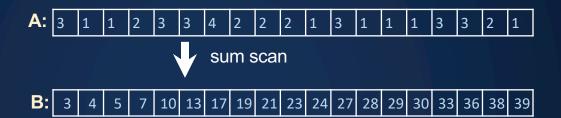
- Associative so we can perform op in different order
- Useful for dot products (ddot, sdot, etc.) $b = X^TY = \Sigma_j X[j] * Y[j]$

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Data Parallel Programming: Scans

- Fill array with partial reductions any associative op
- Sum scan:

A = array B = array B = scan(A,+)



Max scan:



Inclusive and Exclusive Scans

Two variations of a scan, given an input vector [x_0 , x_1 ,..., x_{n-1}]:

inclusive scan includes input x_i when computing output y_i

$$[a_0, (a_0 \otimes a_1), ..., (a_0 \otimes a_1 ... \otimes a_{n-1})]$$

e.g., add scan inclusive([1, 0, 3, 0, 2]) \rightarrow [1, 1, 4, 4, 6]

exclusive scan does not x_i when computing output y_i

```
[I, a_0, (a_0 \odot a_1), ..., (a_0 \odot a_1 ... \odot a_{n-2})] where I is the identity for \bigcirc
```

e.g., add_scan_exclusive([1, 0, 3, 0, 2]) \rightarrow [0, 1, 1, 4, 4]

Inclusive and Exclusive Scans

Two variations of a scan, given an input vector $[x_0, x_1, ..., x_{n-1}]$:

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$$I$$
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e.g., add_scan_exclusive([1, 0, 3, 0, 2])
$$\rightarrow$$
 [0, 1, 1, 4, 4]

Can easily get the inclusive version from the exclusive:

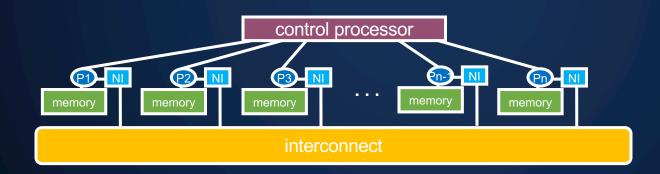
$$scan_inclusive(X) = X \otimes scan_exclusive(X).$$

For the other way you need an inverse for ⊚ (or shift)

Idealized Hardware and Performance Model

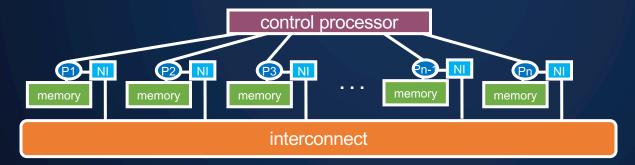
SIMD Systems Implemented Data Parallelism

- SIMD Machine: A large number of (usually) tiny processors.
 - A single "control processor" issues each instruction.
 - Each processor executes the same instruction.
 - Some processors may be turned off on some instructions.



Ideal Cost Model for Data Parallelism

- Machine
 - An unbounded number of processors (p)
 - Control overhead is free
 - Communication is free
- Cost (complexity) on this abstract machine is the algorithm's span or depth, T∞
 - Defines a lower bound on time on real machines



Cost on Ideal Machine (Span)

Span for unary or binary operations (pleasingly parallel)

```
C = A+B

A:

Cost O(1)

since p is unbounded

C:
```

- Even if arrays are not aligned, communication is "free" here
- Reductions and broadcasts



Broadcast and reduction on processor tree

Broadcast of 1 value to p processors with log n span



- Reduction of n values to 1 with log n span
- Takes advantage of associativity in +, *, min, max, etc.

Can reductions go faster? No, log n lower bound on any function of n variables!

n "useful" inputs • • • • • • • •

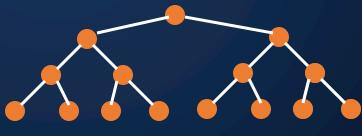
Can reductions go faster? No, log n lower bound on any function of n variables!

- Given a function f (x1,...xn) of n input variables and 1 output variable, how fast can we evaluate it in parallel?
- Assume we only have binary operations, one per time step
- After 1 time step, an output can only depend on two inputs



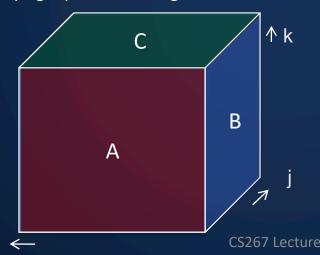
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- Given a function f (x1,...xn) of n input variables and 1 output variable, how fast can we evaluate it in parallel?
- Assume we only have binary operations, one per time step
- After 1 time step, an output can only depend on two inputs
- By induction: after k time units, an output can only depend on 2^k inputs
 - After log₂ n time units, output depends on at most n inputs
- A binary tree performs such a computation.



Multiplying n-by-n matrices in O(log n) time

- Use n³ processors
- Step 1: For all (1 <= i,j,k <= n) P(i,j,k) = A(i,k) * B(k,j)
 - cost = 1 time unit, using n³ processors
- Step 2: For all $(1 \le i,j \le n)$ $C(i,j) = \sum_{k=1}^{n} P(i,j,k)$
 - cost = O(log n) time, using n^2 trees, $n^3 / 2$ processors each



Put a processor at every point in this cube

What about Scan (aka Parallel Prefix)?

Recall: the scan operation takes a binary associative operator ©, and an array of n elements

```
[a_0, a_1, a_2, ... a_{n-1}]
and produces the array
[a_0, (a_0 \circledcirc a_1), ... (a_0 \circledcirc a_1 ... \circledcirc a_{n-1})]
```

Example: add scan of

```
[1, 2, 0, 4, 2, 1, 1, 3] is [1, 3, 3, 7, 9, 10, 11, 14]
```

- Other operators
 - Reals: +, *, min, max (in floating point will assume associative)
 - Booleans: and, or
 - Matrices: mat mul

Can we parallelize a scan?

It looks like this:

```
y(0) = 0;
for i = 1:n
y(i) = y(i-1) + x(i);
```

Takes n-1 operations (adds) to do in serial

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It looks like this:

```
y(0) = 0;
for i = 1:n
y(i) = y(i-1) + x(i);
```

- Takes n-1 operations (adds) to do in serial
- The ith iteration of the loop depends completely on the (i-1)st iteration.

Impossible to parallelize, right?

A clue

```
input = (1, 2, 3, 4, 5, 6, 7, 8)
output = (1, 3, 6, 10, 15, 21, 28, 36)
```

What if we add, say, 5+6+7+8?

Parallel But Terribly Inefficient

```
input = (1, 2, 3, 4, 5, 6, 7, 8)
output = (1, 3, 6, 10, 15, 21, 28, 36)
```

Put 1 processor at element 1, 2 at element 2, 3 at position 3 ...

- O(log n) span ☺
- $O(n^2)$ work \odot

A clue

```
input = (1, 2, 3, 4, 5, 6, 7, 8)
output = (1, 3, 6, 10, 15, 21, 28, 36)
```

Is there any value in adding, say, 5+6+7+8?

If we separately have 1+2+3+4, what can we do?

A clue

Is there any value in adding, say, 5+6+7+8?

If we separately have 1+2+3+4, what can we do?

Suppose we added 1+2, 3+4, etc. pairwise, is this useful?

Algorithm: 1. Pairwise sum 2. Recursive prefix 3. Pairwise sum

1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16
3 7 11 15 19 23 27 31

Algorithm: 1. Pairwise sum 2. Recursive prefix 3. Pairwise sum

1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16
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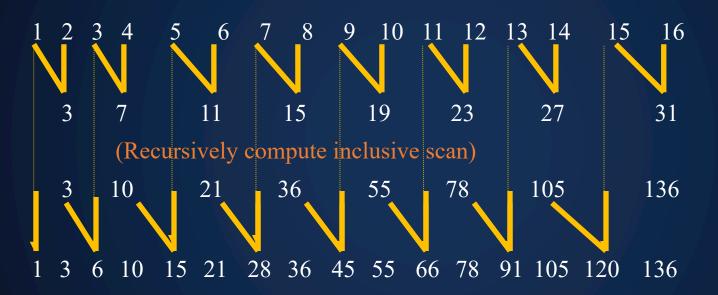
(Recursively compute inclusive scan)

3 10 21 36 55 78 105 136

Algorithm: 1. Pairwise sum 2. Recursive prefix 3. Pairwise sum



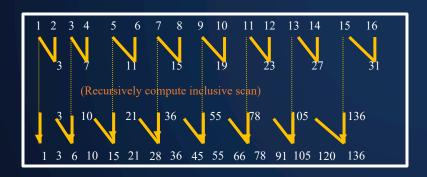
Algorithm: 1. Pairwise sum 2. Recursive prefix 3. Pairwise sum



Parallel prefix cost

Time for this algorithm on one processor (work)

- $T_1(n) = n/2 + n/2 + T_1(n/2) = n + T_1(n/2) = 2n 1$ Time on unbounded number of processors (span)
- $T_{\infty}(n) = 2 \log n$



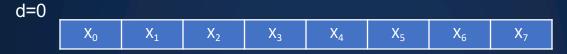
Pairwise sum

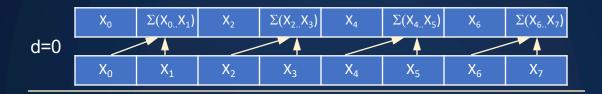
Recursive prefix

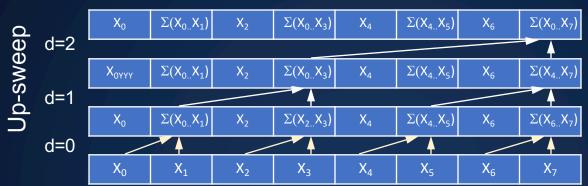
Pairwise sum (update odds)

Parallelism at the cost of more work (2x)!

Up-sweep

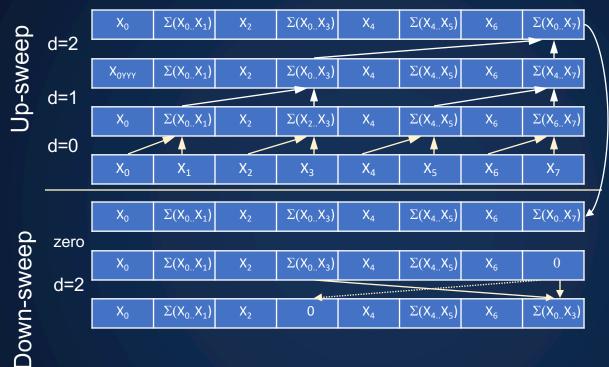


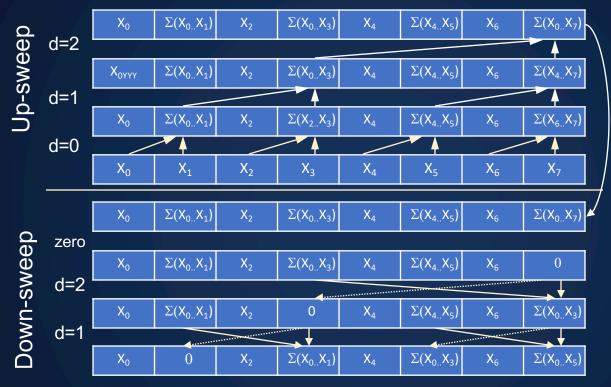


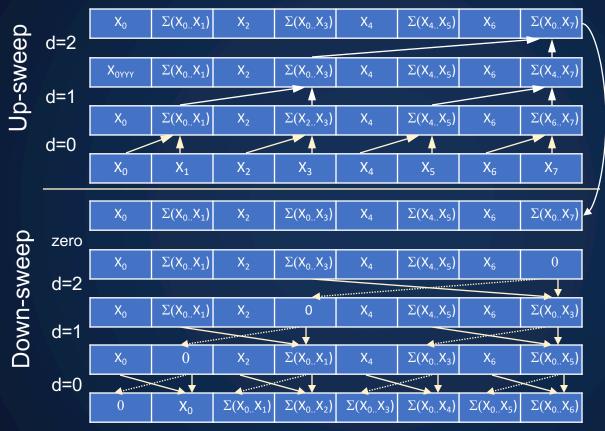


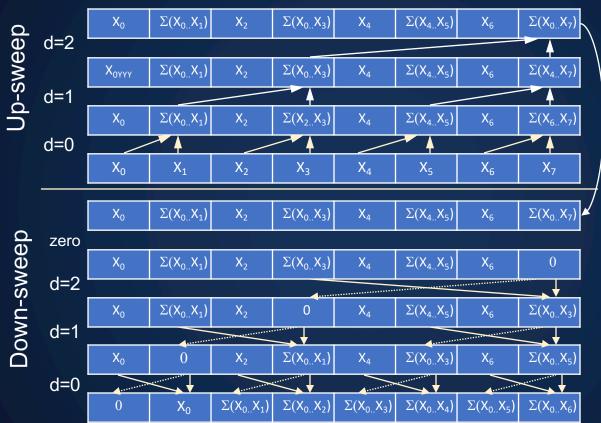












This is both work-efficient (n adds) and space-efficient (update in place)

Algorithm due to Blelloch CS267 Lecture

(Non-trivial) Applications of Data Parallelism

..using scans

Scans are useful for many things (partial list here)

- Reduction and broadcast in O(log n) time
- Parallel prefix (scan) in O(log n) time
- Adding two n-bit integers in O(log n) time
- Multiplying n-by-n matrices in O(log n) time
- Inverting n-by-n triangular matrices in O(log² n) time
- Inverting n-by-n dense matrices in O(log² n) time
- Evaluating arbitrary expressions in O(log n) time
- Evaluating recurrences in O(log n) time
- "2D parallel prefix", for image segmentation (Catanzaro & Keutzer)
- Sparse-Matrix-Vector-Multiply (SpMV) using Segmented Scan
- Parallel page layout in a browser (Leo Meyerovich, Ras Bodik)
- Solving n-by-n tridiagonal matrices in O(log n) time
- Traversing linked lists
- Computing minimal spanning trees
- Computing convex hulls of point sets...

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Application: Stream Compression

Given an array of 0/1 flags

```
flags = 1 0 1 1 0 0 1 1

and an array (stream) of values

values = 3 2 4 1 5 3 3 1

compress into

result = 3 4 1 3 1
```

Application: Stream Compression

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• Step 1: Compute an exclusive add scan of flags:

```
index = 0 1 1 2 3 3 3 4
```

Application: Stream Compression

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flags = 1 0 1 1 0 0 1 1

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values = 3 2 4 1 5 3 3 1

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```

• Step 1: Compute an exclusive add scan of flags:

```
index = 0 1 1 2 3 3 3 4
```

 Step 2: "Scatter" values into result at index, masked by flags result[index] = values at flags



Remove matching elements

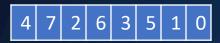
 Given an array of values, and an int x, remove all elements that are not divisible by x:

```
int find (int x, int y) (y \% x == 0) ? 1 : 0;
```

```
values = 3 5 6 12 4 2 3 0
flags = apply(values, find)

1 0 1 1 0 0 1 1
```

Use previous solution to remove those not divisible



Idea: Sort 1 bit at a time:

Os on left, 1s on right

Use a "stable" sort:

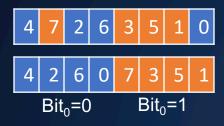
 Keep order as it, unless things need to switch based on the current bit

Start with least-significant bit

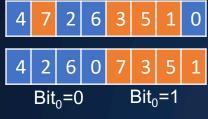
And move up



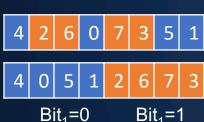
Sort on least significant bit (Bit₀ in [Bit₂, Bit₁, Bit₀]) XX0 < XX1 (evens before odds)

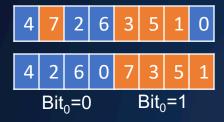


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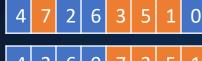


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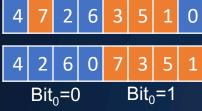




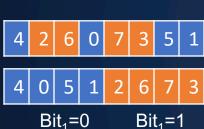
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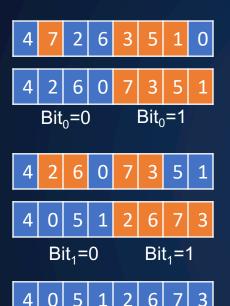


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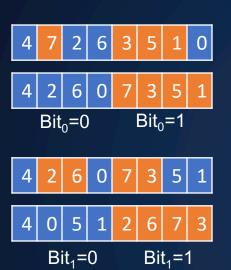


Sort on least significant bit (Bit_0 in $[Bit_2, Bit_1, Bit_0]$) XX0 < XX1 (evens before odds)

Stably sort entire array on next bit X0X < X1X

Stably sort on next bit

0XX < 1XX (<4 before >=4 here)

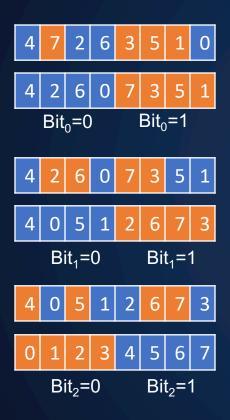


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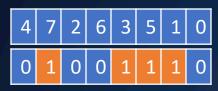
$$0XX < 1XX (<4 before >=4 here)$$

4 7 2 6 3 5 1 0

input

odds = last bit of each element evens = complement of odds (last bit = 0) evpos = exclusive sum scans of evens totalEvens = broadcast last element indx = constant array of 0..n oddpos = totalEvens + indx- epos pos = if evens then evpos else oddpos Scatter input using pos as index

This will just do one step of radix sort (a stable sort on 1 bit)



input

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evens = complement of odds (last bit = 0)

evpos = exclusive sum scans of evens

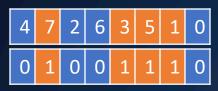
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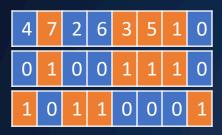
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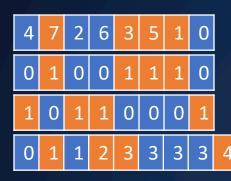
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evens = complement of odds (last bit = 0)

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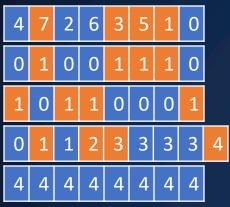
totalEvens = broadcast last element

indx = constant array of 0..n

oddpos = totalEvens + indx- epos

pos = if evens then evpos else oddpos

Scatter input using pos as index



input

odds = last bit of each element

evens = complement of odds (last bit = 0)

evpos = exclusive sum scans of evens

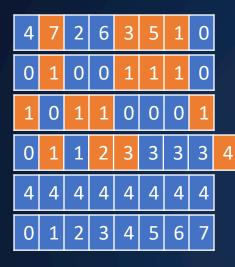
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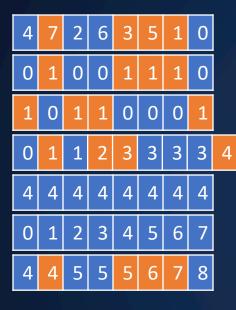
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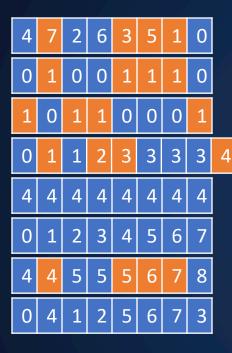
totalEvens = broadcast last element

indx = constant array of 0..n

4+0-0 4+1-1 4+2-1 4+3-2 4+4-3 4+5-3 4+6-3 4+7-3 oddpos = totalEvens + indx— epos

pos = if evens then evpos else oddpos

Scatter input using pos as index



input

odds = last bit of each element

evens = complement of odds (last bit = 0)

evpos = exclusive sum scans of evens

totalEvens = broadcast last element

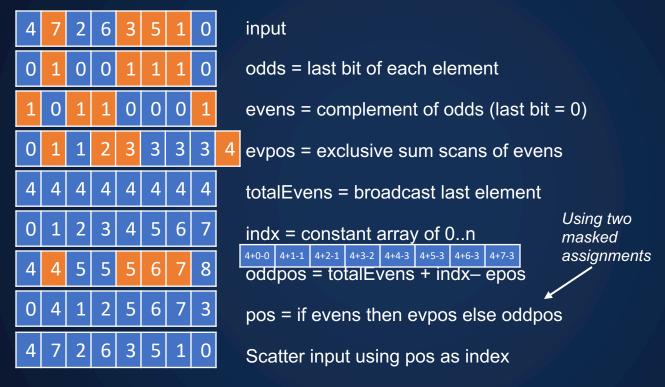
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4+0-0 4+1-1 4+2-1 4+3-2 4+4-3 4+5-3 4+6-3 4+7-3 oddpos = totalEvens + indx— epos

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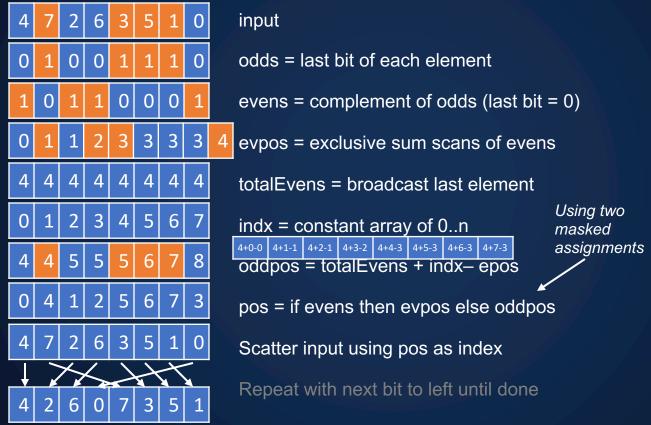
Scatter input using pos as index

Application: Data Parallel Radix Sort



Repeat with next bit to left until done

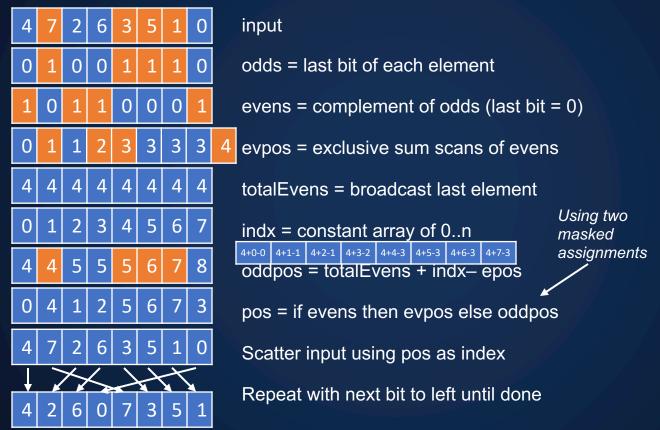
Application: Data Parallel Radix Sort



2/11/21

CS267 Lecture

Application: Data Parallel Radix Sort



2/11/21

Given a linked list of *N* nodes, find the distance (#hops) from each node to the end of the list.

```
val = 1
while next != null
val += next.val
next =
```

```
d(n) =
     0 if n.next is null
     1+d(n.next) otherwise
Approach: put a processor at every node
```

Approach: put a processor at every node

Works if nodes are on arbitrary processors

next.next

Given a linked list of *N* nodes, find the distance (#hops) from each node to the end of the list.

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Works if nodes are on arbitrary processors

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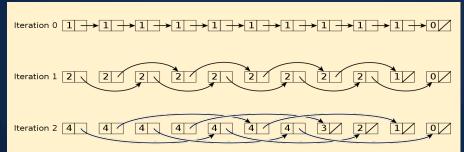
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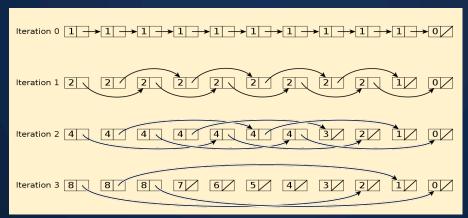
```
d(n)=
0 if
```

0 if n.next is null
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Approach: put a processor at every node

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Works if nodes are on arbitrary processors



Given a linked list of *N* nodes, find the distance (#hops) from each node to the end of the list.

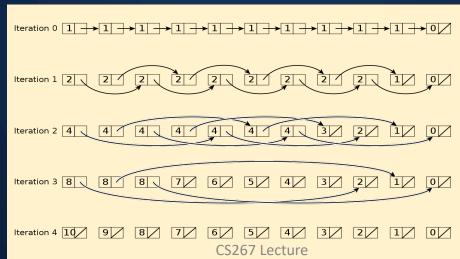
```
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```

0 if n.next is null
1+d(n.next) otherwise

Approach: put a processor at every node

```
val = 1
while next != null
val += next.val
next =
next.next
```

Works if nodes are on arbitrary processors



Application: Fibonacci via Matrix Multiply Prefix

$$F_{n+1} = F_n + F_{n-1}$$

$$\begin{pmatrix} F_{n+1} \\ F_{n} \end{pmatrix} = \begin{pmatrix} 1 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} F_{n} \\ F_{n-1} \end{pmatrix}$$

Can compute all F_n by matmul_prefix on

then select the upper left entry

- Computing sum s of two n-bit binary numbers, think of a and b as array of bits
 - a = a[n-1] a[n-2]...a[0] and b = b[n-1] b[n-2]...b[0]
 - s = a+b = s[n] s[n-1]...s[0] (use carry-bit array c = c[n-1]...c[0] c[-1])

Computing sum s of two n-bit binary numbers, a and b

```
    a = a[n-1] a[n-2]...a[0] and b = b[n-1] b[n-2]...b[0]
    s = a+b = s[n] s[n-1]...s[0] (use carry-bit array c = c[n-1]...c[0] c[-1] )
    Formula c[-1] = 0 ... rightmost carry bit
        for i = 0 to n-1 ... compute right to left
        s[i] = (a[i] xor b[i]) xor c[i-1] ... one or three 1s
        c[i] = ((a[i] xor b[i]) and c[i-1]) or (a[i] and b[i]) ... next carry bit
```

Computing sum s of two n-bit binary numbers, a and b

```
- a = a[n-1] a[n-2]...a[0] and b = b[n-1] b[n-2]...b[0]
 - s = a+b = s[n] s[n-1]...s[0] (use carry-bit array c = c[n-1]...c[0] c[-1] )
Formula c[-1] = 0 ... rightmost carry bit
             for i = 0 to n-1 ... compute right to left
                 s[i] = (a[i] \times or b[i]) \times or c[i-1] ... one or three 1s
                 c[i] = ((a[i] \times or b[i]) \text{ and } c[i-1]) \text{ or } (a[i] \text{ and } b[i]) \dots \text{ next carry bit}
 Example a = 10110 (22)

-a = 22 b = 11101 (29)
Example
                        c = 1 1 1 0 0 0 0
 - b = 29
                          s = 1 \ 1 \ 0 \ 0 \ 1 \ 1
                                                   (51)
```

Challenge: compute all c[i] in O(log n) time via parallel prefix

2/11/21 CS267 Lecture 84

Recall carry bit calculation

```
c[-1] = 0 ... rightmost carry bit
for i = 0 to n-1
c[i] = ( (a[i] xor b[i]) and c[i-1] ) or ( a[i] and b[i] ) ... next carry bit
```

Recall carry bit calculation

```
c[-1] = 0 ... rightmost carry bit
for i = 0 to n-1
c[i] = ((a[i] xor b[i]) and c[i-1]) or (a[i] and b[i]) ... next carry bit
```

Compute all c[i] in O(log n) time via parallel prefix

```
for all (0 \le i \le n-1) p[i] = a[i] xor b[i] ... propagate bit for all (0 \le i \le n-1) g[i] = a[i] and b[i] ... generate bit
```

Both O(1) on n procs

Recall carry bit calculation

```
c[-1] = 0 ... rightmost carry bit
for i = 0 to n-1
c[i] = ((a[i] xor b[i]) and c[i-1]) or (a[i] and b[i]) ... next carry bit
```

```
for all (0 \le i \le n-1) p[i] = a[i] xor b[i] ... propagate bit for all (0 \le i \le n-1) g[i] = a[i] and b[i] ... generate bit

\begin{bmatrix} c[i] \\ 1 \end{bmatrix} = \begin{bmatrix} (p[i] \text{ and } c[i-1]) \text{ or } g[i] \\ 1 \end{bmatrix} = \begin{bmatrix} p[i] \\ 0 \end{bmatrix} \begin{bmatrix} c[i-1] \\ 1 \end{bmatrix} = M[i] * \begin{bmatrix} c[i-1] \\ 1 \end{bmatrix}
```

Recall carry bit calculation

```
c[-1] = 0 ... rightmost carry bit
for i = 0 to n-1
c[i] = ((a[i] \times cr b[i]) \times c[i-1]) \times (a[i] \times cr b[i]) ... next carry bit
```

```
for all (0 <= i <= n-1) p[i] = a[i] xor b[i] ... propagate bit for all (0 <= i <= n-1) g[i] = a[i] and b[i] ... generate bit  \begin{bmatrix} c[i] \end{bmatrix} = \begin{bmatrix} (p[i] \text{ and } c[i-1]) \text{ or } g[i] \end{bmatrix} = \begin{bmatrix} p[i] & g[i] \end{bmatrix} \cdot \begin{bmatrix} c[i-1] & M[i] * [c[i-1]] \\ 1 & 1 & 1 \end{bmatrix} 
= M[i] * M[i-1] * ... M[0] * \begin{bmatrix} 0 \\ 1 \end{bmatrix}
```

Recall carry bit calculation

```
c[-1] = 0 ... rightmost carry bit
for i = 0 to n-1
c[i] = ((a[i] xor b[i]) and c[i-1]) or (a[i] and b[i]) ... next carry bit
```

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for all (0 <= i <= n-1) p[i] = a[i] xor b[i] ... propagate bit for all (0 <= i <= n-1) g[i] = a[i] and b[i] ... generate bit  \begin{bmatrix} c[i] \end{bmatrix} = \begin{bmatrix} (p[i] \text{ and } c[i-1]) \text{ or } g[i] \end{bmatrix} = \begin{bmatrix} p[i] & g[i] \end{bmatrix}^* \begin{bmatrix} c[i-1] \end{bmatrix} = M[i] * \begin{bmatrix} c[i-1] \end{bmatrix} \end{bmatrix} 
= M[i] * M[i-1] * ... M[0] * \begin{bmatrix} 0 \\ 1 \end{bmatrix} 
... evaluate M[i] * M[i-1] * ... * M[0] by parallel prefix ... 2-by-2 Boolean matrix multiplication is associative
```

Recall carry bit calculation

```
c[-1] = 0 ... rightmost carry bit
for i = 0 to n-1
c[i] = ((a[i] xor b[i]) and c[i-1]) or (a[i] and b[i]) ... next carry bit
```

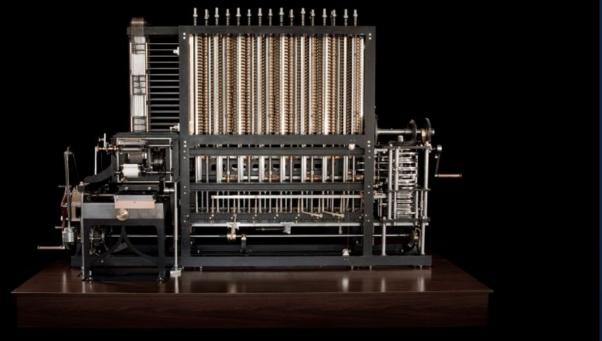
Compute all c[i] in O(log n) time via parallel prefix

```
for all (0 <= i <= n-1) p[i] = a[i] xor b[i] ... propagate bit for all (0 <= i <= n-1) g[i] = a[i] and b[i] ... generate bit  \begin{bmatrix} c[i] \end{bmatrix} = \begin{bmatrix} (p[i] \text{ and } c[i-1]) \text{ or } g[i] \end{bmatrix} = \begin{bmatrix} p[i] & g[i] \end{bmatrix}^{*} \begin{bmatrix} c[i-1] \end{bmatrix} = M[i] * \begin{bmatrix} c[i-1] \end{bmatrix} \\ 1 \end{bmatrix} = M[i] * M[i-1] * ... M[0] * \begin{bmatrix} 0 \\ 1 \end{bmatrix}  ... evaluate M[i] * M[i-1] * ... * M[0] by parallel prefix ... 2-by-2 Boolean matrix multiplication is associative
```

Used in all computers to -- Carry look-ahead addition

This idea is used in all hardware

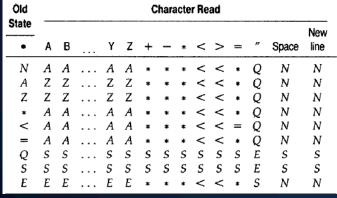
... Even going back to Babbage



Lexical analysis (tokenizing, scanning)

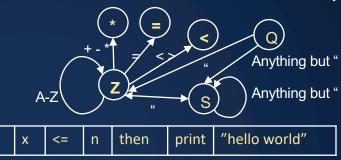
- Given a language of:
 - Identifiers (Z): string of chars
 - Strings (S): in double quotes
 - Ops (*): +,-,*,=,<,>,<=, >=
 - Expression (E), Quotes (Q),...
- Lexical analysis
 - Divide into tokens

Full finite state machine encoded in table



Subset of Finite State Machine for Lexical Analysis

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- Each state in first column; N initial state.
- Each row gives the next state based on the next character at the top.
- Apply string Y"+ to state Z written as
 ZY"+ = ((ZY)")+ = (Z")+ = Q+ = S
- Each column is a state transition for that character

Hillis and Steele, CACM 1986

Lexical analysis (tokenizing, scanning)

Lexical analysis

- Replace every character in the string with the array representation of its state-to-state function (column).
- Perform a parallel-prefix operation with \oplus as the array composition. Each character becomes an array representing the state-to-state function for that prefix.
- Use initial state (N, row 1) to index into these arrays.

	i	f		х		<	=		n
N	Α	Α	N	Α	N	<	*	Ν	Α
A	Z	Z	Ν	Z	Ν	<	*	Ν	Z
Z	Z	Z	Ν	Z	Ν	<	*	Ν	Z
*	Α	Α	Ν	Α	Ν	<	*	Ν	Α
<	Α	Α	Ν	Α	Ν	<	=	Ν	Α
=	Α	Α	Ν	Α	Ν	<	*	Ν	Α
Q	S	S	S	S	S	S	S	S	S
S	S	S	S	S	S	S	S	S	S
E	Е	Е	N	Е	N	<	*	Ν	Ε

<= n	
А	
А	
Α	
Α	
Α	
Α	
S	
S	
Α	

Old		Character Read												
State														New
•	Α	В		Υ	Z	+	_	*	<	>	=		Space	line
N	\boldsymbol{A}	Α		Α	Α	*	*	*	<	<	*	Q	N	N
Α	Z	Z		Z	Z	*	*	*	<	<	*	Q	N	N
Z	Z	Z		Z	Z	*	*	*	<	<	*	Q	N	N
*	Α	Α		Α	Α	*	*	*	<	<	*	Q	N	N
<	Α	Α		Α	Α	*	*	*	<	<	=	Q	N	N
=	Α	Α		Α	Α	*	*	*	<	<	*	Q	N	N
Q	S	S		S	S	S	S	S	S	S	S	Ε	S	S
S	S	S		S	S	S	S	S	S	S	S	E	S	S
Ε	Ε	Ε		Ε	Ε	*	*	*	<	<	*	S	N	N

Hillis and Steele, CACM 1986

Inverting triangular n-by-n matrices

• Fact:
$$\begin{bmatrix} A & 0 \\ C & B \end{bmatrix} = \begin{bmatrix} A^{-1} & 0 \\ -B^{-1}CA^{-1} & B^{-1} \end{bmatrix}$$

in O(log² n) time

Inverting triangular n-by-n matrices

 $\begin{bmatrix} A & 0 \end{bmatrix}$ -1 $\begin{bmatrix} A^{-1} & 0 \end{bmatrix}$ in O(log² n) time

Function Tri_Inv(T) // assume n = dim(T) = 2^m for simplicity

Inverting triangular n-by-n matrices

in O(log² n) time

```
if T is 1-by-1
return 1/T else Write T = \begin{bmatrix} A & 0 \\ C & B \end{bmatrix}
in parallel do {
    invA = Tri Inv(A)
    invB = Tri Inv(B) // implicitly uses a tree
newC = -invB * C * invA // log(n) for matmuls
return
```

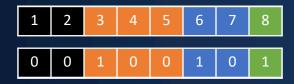
Function Tri Inv(T) // assume $n = dim(T) = 2^m$ for simplicity

```
time(Tri Inv(n)) =
  time(Tri Inv(n/2)) + O(log(n))
      Change variable to m = log n to
      get time(Tri Inv(n)) = O(log^2n)
```

Segmented Scans

Inputs = value array, flag array, associative operator ⊕

Inclusive segmented sum scan



Flags are sometimes done with Boolean and switch points



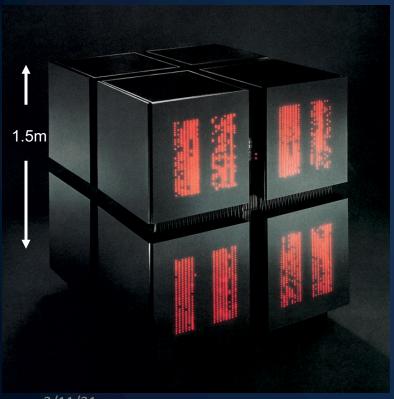
Result



Mapping Data Parallelism to Real Hardware

Connection Machine (CM-1,2)

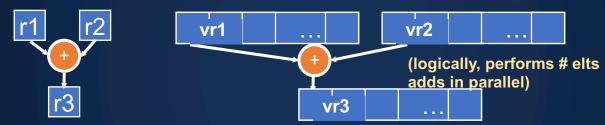
Because communication is more important than processors



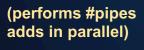
- Designed for AI by Thinking Machines
 Corporation (Hillis and Handler)
- CM-1 and CM-2 SIMD Design
 - 65,536 1-bit processors with 4 KB of memory each
 - 12-D boolean n-cube network (Feynman)
 - CM-2 add 1 floating point processor per 32 1-bit
- Programmed with data parallel languages
 - *Lisp
 - C*
- CM-5 was RISC+Vectors

SIMD/Vector Processorsr Use Data Parallelism

- SIMD instructions operate on a vector of elements
 - These are specified as operations on vector registers



- Vectors "virtualize" the # of lanes (registers wider than #ALUs)
- SIMD on CPUs does not)





SIMD/Vector Processorsr Use Data Parallelism

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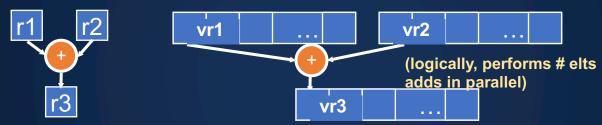
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2/11/21 CS267 Lecture 102

SIMD/Vector Processorsr Use Data Parallelism

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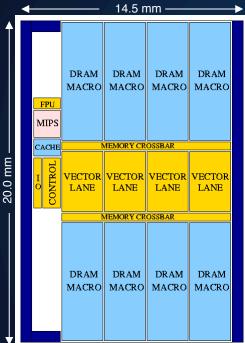


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- SIMD on CPUs does not

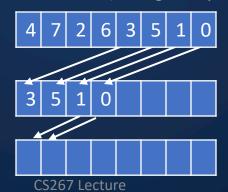


2/11/21 CS267 Lecture 103

VIRAM Processor at Berkeley

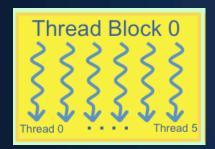


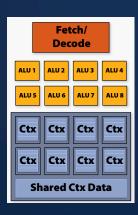
- MIPS Scalar core + 4-lane vector at 200 MHz (in 2002)
- 32-wide vector registers (in 64b)
- Peak vector performance
 - -1.6/3.2/6.4 Gops wo. multiply-add (64b/32b/16b operations)
 - -1.6 Gflops (single-precision)
- Transistor count: ~130M
- Reduction scan (in-register permutation instructions)



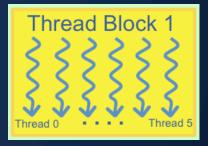
Mapping to GPUs

- For n-way parallelism may use n threads, divided into blocks
- Merge across statements (so A=B; C=A; is a single kernel)
- Mapping threads to ALUs and blocks to SMs is compiler / hardware problem









Bottom Line

- Branches are still expensive on GPUs
- May pad with zeros / nulls etc. to get length
- Often write code with a guard (if i < n), which will turn into mask – fine if n is large
- Non-contiguous memory is supported, but will still have a higher cost
- Enough parallelism to keep ALUs busy and hide latency, memory/scheduling tradeoff

Mapping Data Parallelism to SMPs (and MPPs)

n-way parallelism onto p-way hardware

Binary and unary operations



If arrays are not "aligned" then false sharing / communication require

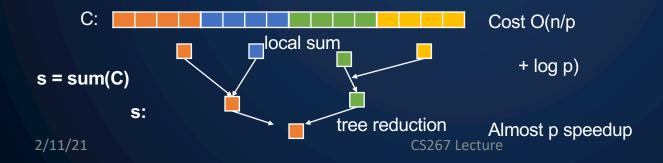
Mapping Data Parallelism to SMPs (and MPPs)

n-way parallelism onto p-way hardware

Binary and unary operations



- If arrays are not "aligned" then false sharing / communication require
- Reductions and broadcasts

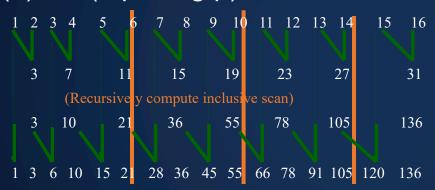


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Parallel prefix cost on p "big" processors

Time for this algorithm in parallel:

• $T_p(n) = O(n/p + \log p)$



Compute local prefix sums in n/p steps

Updates across processors in log p steps

serial time on each processor

communication and computation up and down the processor tree

The myth of log n

The log₂ n span is not the main reason for the usefulness of parallel prefix.

```
    Say n = k*p (k = 1,000,000 elements per proc)

            Cost = (k adds)
            (log<sub>2</sub>P steps)
            (k adds)

    compute and store k parallel scan on values a[0]..a[k-1]
    a[k-1] values
    add 'my' scan result to a[0]..a[k-1]
```

(2,000,000 local adds are serial for each processor, of course)

Key to implementing data parallel algorithms on clusters, SMPs, MPPs, i.e., modern supercomputers

Summary of Data Parallelism

- Sequential semantics (or nearly) is very nice
 - Debugging is much easier without non-determinism
 - Correctness easier to reason about
- Cost model is independent of number of processors
 - How much inherent parallelism
- Need to "throttle" parallelism
 - n >> p can be hard to map, especially with nesting
 - Memory use is a problem
- More reading
 - Classic paper by Hillis and Steele "Data Parallel Algorithms" https://doi.org/10.1145/7902.7903 and on Youtube
 - Blelloch the NESL languages and "NESL Revisited paper, 2006