

Sniper hands-on

Install

- Sniper site: <http://snipersim.org/>
- Sniper support group: <https://groups.google.com/forum/#!forum/snipersim>
- OS: Ubuntu
- Required root permissions
- Git repository was received by mail but still seems to be good.
- Pin need to be downloaded separately – only pin3.7 is working with sniper right now

Install instructions

```
mkdir downloads
cd downloads/
wget https://software.intel.com/sites/landingpage/pintool/downloads/pin-3.7-97619-g0d0c92f4f-gcc-linux.tar.gz &
tar xvzf pin-3.7-97619-g0d0c92f4f-gcc-linux.tar.gz
cd ..
git clone http://snipersim.org/download/bfd8ed6e5a50b1e2/git/sniper.git
mv downloads/pin-3.7-97619-g0d0c92f4f-gcc-linux sniper/pin_kit
sudo apt-get install libc6-dev-i386
g++ --version    to get your_g++_version
sudo apt-get install g++-your_g++_version-multilib    replace with g++ version
sudo apt-get install lib32z1-dev
sudo apt-get install libbz2-dev
sudo apt-get install libboost-dev
sudo apt-get install libsqlite3-dev
make

./run-sniper -c gainestown -c base -- /bin/ls    test run
```

Files

- default performance model is “rob performance model” – model of one core, with OOO.
 - You can find all files under:
common/performance_model/performance_models/rob_performance_model/
- config files: config/
 - basic files: are rob.cfg with gainestown.cfg
- PIN FE – sift/recorder/recorder_base.cc
 - in PIN FE you can extract real data on the instruction pre simulation and save it to be used later on simulation. In example save destination value / number of registers...
- common/performance_model/performance_models/rob_performance_model/rob_timer.cc
 - out of order operations on uops
- common/performance_model/performance_models/micro_op_performance_model.cc
 - micro ops creation and treatment

Files (continue)

- `common/trace_frontend/trace_thread.cc` : void
TraceThread::handleInstructionDetailed(Sift::Instruction &inst, Sift::Instruction &next_inst,
PerformanceModel *prfmdl) Decoding instruction

Debug

- FE (PIN) debug could be using --gdb flag to start gdb shell allowing to debug changes made in FE side of sniper.
- BE – debug simulation by printing out relevant information, simply as “std::cout”

config tweaks

- add config options:

- common/misc/config.cc

- in example:

- adding `m_UOP_debug = Sim()->getCfg()->getBool("uopcache/debug");`

- and then `bool getUOPdebug() const { return m_UOP_debug; }`

- so it could be used in your files to enable/disable DEBUG prints:

- `if (Sim()->getConfig()->getUOPdebug()) std::cout << "DEBUG`

- then in config file it should be added:

- `[uopcache]`

- `debug=true`

- it could be also be added in command line: `-c uopcache/debug=true`

stats

- sim.out file contain simulations details
 - number of instructions
 - cycles
 - cache data
 - IPC and more
- ./tools/dumpstats.py > stats – generating stats collected in simulation:
 - detail stats on caches /performance models/ rob / uops and more.

stats tweaks

- add stats to be collected,
 - include `#include "stats.h"` in your file.
 - create variable to collect your stats
 - register your variable: `registerStatsMetric("uopcache", 0 , "uopcache_hits", &uopcache_hits);`
 - then it will be shown in `dumpstats.py` results.