A REPORT

ON

"Statistical Analysis and Forecasting of Wind Energy (Intra-State)"

By:

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BIRLA INSTITUTE OF TECHNOLOGY AND SCIENCE, PILANI 7th December, 2021

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INTRODUCTION

The use of wind turbines to generate electricity is known as wind energy. Wind energy is a popular, renewable energy source that has a far lower environmental impact than burning fossil fuels. Many individual wind turbines are connected to the electric power transmission network to form wind farms. This scientific process is highly volatile and varying. Because the quantity of energy created is dependent on wind speed, which is dependent on various geographic elements such as location, temperature, humidity, pressure, dew point, and so on, it necessitates a great deal of forecast and analysis of current data.

Parameters:-

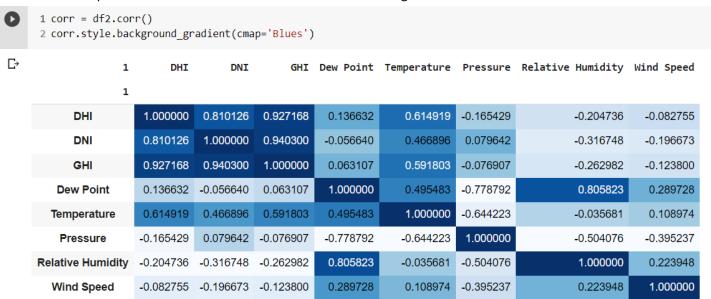
- 1. <u>Direct Normal Irradiance (DNI)</u>: The quantity of solar radiation received per unit area by a surface that is always maintained perpendicular (or normal) to the rays that arrive in a straight line from the direction of the sun at its present location in the sky is known as direct normal irradiation (DNI).
- 2. <u>Diffuse Horizontal Irradiance (DHI)</u>: It is the quantity of energy received per unit area by a surface that has been dispersed by molecules and particles in the atmosphere rather than arriving on a direct path from the sun. Essentially, it is the light emitted by clouds and the blue sky.
- 3. <u>Global Horizontal Irradiance (GHI)</u>: The radiation that reaches the surface of the planet can be depicted in a variety of ways. The entire quantity of shortwave radiation received by a surface horizontal to the ground is referred to as global horizontal irradiance (GHI). This figure, which combines both Direct Normal Irradiance (DNI) and Diffuse Horizontal Irradiance (DHI), is particularly important for solar systems.

Temperature, pressure, dew point and humidity (relative and absolute) affect the wind speed, i.e. a higher pressure gradient leads to higher wind speed and this pressure gradient is related to the temperature and humidity.

METHODOLOGY introduction to Wind speed Analysis of topic/dataset data for features dataset time-series **Obtaining Decompostion** Data Checking of Time-Series visualization of lags Stationarity wind speed PACI ADF-Test Autoregressive Checking for (AR) **Normality** Moving Average Results of Fitting different (MR) Univariate **Best Models** other Models Regions ARMA ARIMA

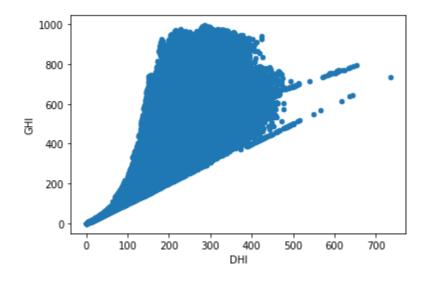
ANALYSIS OF PARAMETERS

Given below is a plot of the correlation values of the variables amongst themselves:

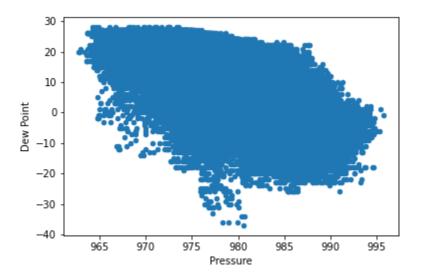


To analyse the correlation between the factors, we tried plotting the graphs.

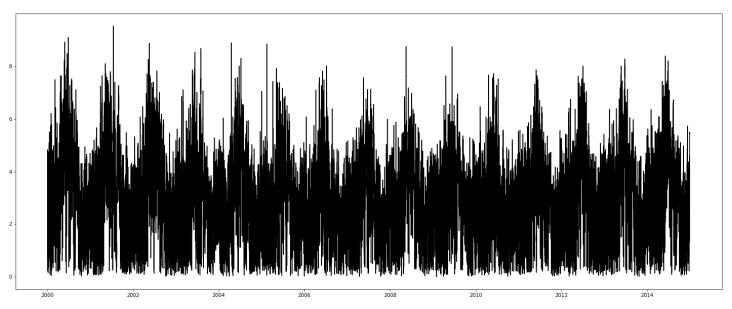
The following Graph shows the case of a strong positive correlation between GHI and DHI (0.927168)



The following graph is a case of strong negative correlation between Dew Point and Pressure (-0.778792)



WIND IS SPEED DATA FOR TIME SERIES



Given is the graph for the timeseries data of the wind speed over the years mentioned.

DISTRIBUTION OF DATA

The distribution of wind speed data was estimated using the maximum likelihood method on several known distributions. The goodness of fit was then determined using the **Kolmogorov-Smirnov** test at 5% significance level.

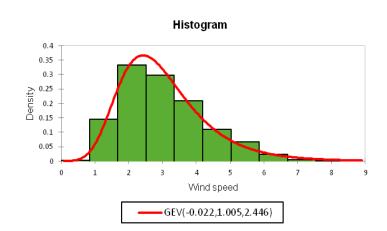
The hypothesis used for the **KS** test was:

H₀: The sample follows the tested distribution

H_a: The sample does not follows the tested distribution

The p-values of some of the prominent distributions are tabulated below along with the histogram of the best fit distribution(**GEV**). From the graph the data is right skewed with skewness of 0.87.

Distribution	p-value	
Normal	0.000	
Gamma	0.023	
<u>GEV</u>	0.038	
Exponential	0.000	
Fisher-Tippett	0.022	

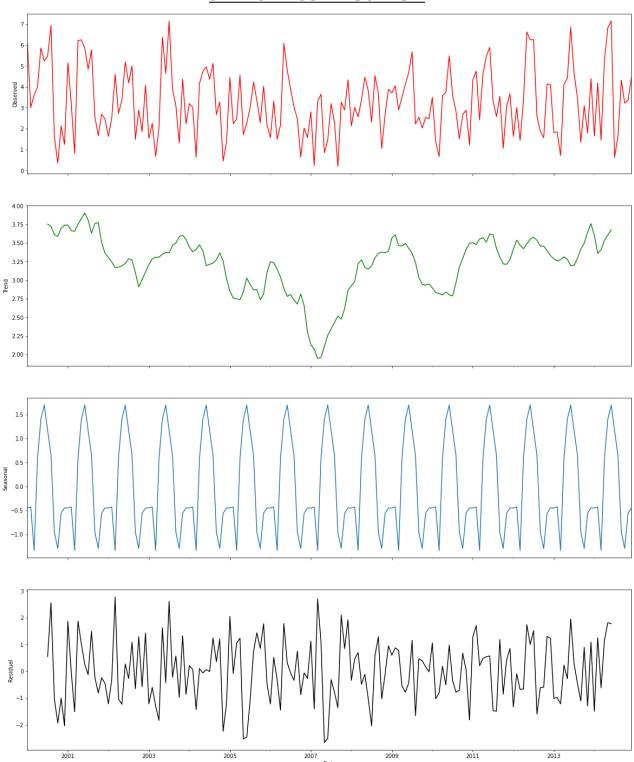


As apparent from the p-values and the frequency plot the distribution is not normal. The closest fit was obtained for the **GEV** (Generalised Extreme values) distribution and even that did not pass the Kolmogorov-Smirnov test. The parameters estimated using **MLE** for the **GEV** distribution and its **KS** test statistics are given below.

D	0.019
P-value (Two-tailed)	0.038
alpha	0.05

Parameter	Value Standard Erro		
k	-0.022	0.012	
beta	1.005	0.013	
μ	2.446	0.012	

SERIES DECOMPOSITION

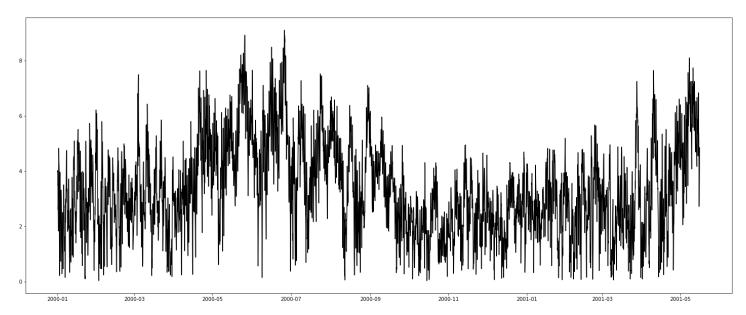


The series has been decomposed into various components such as trend, seasonality and residue, as seen from the figure above there is not much difference between the observed and the residue component. It can be interpreted that there is not much noise in the data. Since seasonal fluctuations don't vary with the level of the series so an additive model was preferred.

DATA STATIONARITY

In stationary time series, the statistical properties like mean, variance and covariance do not depend on time. We require the time series to be stationary for effective and precise predictions using various statistical models.

On visualisation of our data and its decomposition plot, we inferred that there was no major trend and data was distributed around some mean value. Though, there is a clear seasonality on observing the whole data but this is the compressed form for 14 years, If we observe a part of data (say for initial 400 days), we will get the following plot -



Clearly, there is no seasonality factor in the above plot. These observations give us indication for stationarity in our plot but for a conclusive result we need a mathematical tool to confirm stationarity.

AUGMENTED DICKEY-FULLER TEST

This is the mathematical tool or test used for checking stationarity in time series. It determines the presence of unit root in the series. A unit root is a stochastic trend in a time series. If a time series has a unit root then it shows a systematic pattern that is unpredictable. The null and alternative hypotheses for this test are:

Null hypothesis (H_o) : The series has a unit root (or the series is non stationary) **Alternate hypothesis** (H_1) : The series has no unit root (or the series is stationary)

On application of AD Fuller test, we obtain the following results -

```
1 from statsmodels.tsa.stattools import adfuller
2 series = df['Wind Speed']
3 X = series.values
4 result = adfuller(X[:1000])
5 print('ADF Statistic: %f' % result[0])
6 print('p-value:', result[1])
7 print('No of observations used:',result[3])
```

ADF Statistic: -6.440515 p-value: 1.612483425216694e-08 No of observations used: 995 ADF Test Statistic : -6.3795250243283546

p-value : 2.240211241769144e-08

#Lags Used : 31

Number of Observations Used: 5447

strong evidence against the null hypothesis(Ho), reject the null hypothesis. Data has no unit root and is stationary

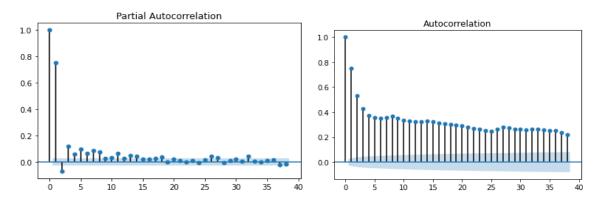
On testing our hypothesis on 1% (or 5%) confidence interval, we observe that our p-value is much lesser than the critical p-value of 0.01. So, the null hypothesis is rejected and we conclude that there is no unit root and our <u>time series is stationary.</u>

LAG PLOTS

Now, before proceeding for implementing various statistical methods on our statistical time series, we must obtain the value of model lags and moving average lags which are necessary for our modelling. To obtain these values, we have two lag plots -

- <u>ACF plot</u>: This autocorrelation function plot is the plot between correlation coefficients (pearson) between time series and lags of itself. It takes both the direct and indirect effects of lags on the correlation coefficient. Using ACF plot, we obtain moving average lags for our time series.
- PACF plot: This plots the partial autocorrelation coefficients which are obtained by considering only the direct impacts of the previous lags. Using PACF plot, we obtain model lags for modelling of our time series.

For our Wind Speed time series data, we obtain the following ACF and PACF plots -



From the PACF plot, we observe that there is only one significant correlation coefficient for the first lag. So, the model lags (p) for time series is 1. From the ACF plot, we observe that after three lags, the slope of the plot almost tapers to 0, so our moving average lags (q) are 3.

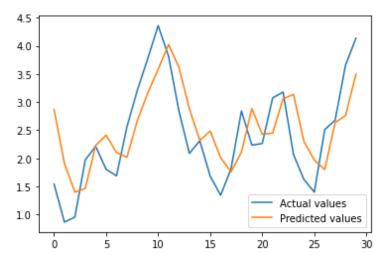
STATISTICAL METHODS AND PREDICTIONS

1. AutoRegression (AR) model:

Autoregression models predict the future values of time series using its own past values. From our PACF plot , we obtained number of lags for our model as 1 , so our model is first order autoregressive model and the corresponding equation will be -

$$Y_t = C_0 + C_1 y_{t-1}$$

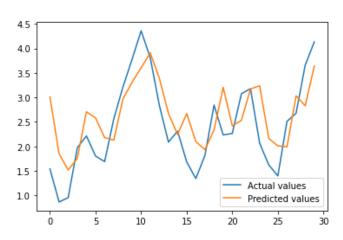
Here, y_{t-1} is the wind speed at first time lag. C_k s are the constant value and Y_t is the predicted value of wind speed at 't' th time step.



After fitting the AR model (p=1) on our data, given is the plotted predictions of wind speed for the last 30 days of the time series.

The MAE score obtained was **0.401**.

2. Moving Average (MA) model:



A moving average is a technique to get an overall idea of the trends in a data set. This model predicts the future values of time series using the past errors. From our ACF plot , we obtained number of moving average lags for our model as 3 , so our model is third order moving average model and the corresponding equation will be -

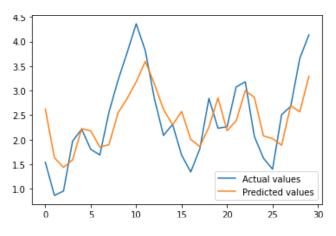
$$Y_t = C_1 + C_2 \varepsilon_{t-1} + C_3 \varepsilon_{t-2} + C_4 \varepsilon_{t-3}$$

Here, ε_k is the error at 'k'th time lag. C_k s are the constant value and Y_t is the predicted value of wind speed at 't' th time step.

After fitting the MA model (q=3) on data, given is the plotted predictions of wind speed for the last 30 days of the time series.

The MAE score obtained was **0.417**.

3. Autoregressive Moving Average (ARMA) model:



An ARMA model, or Autoregressive Moving Average model, is the combination of two polynomials, one for autoregression and the other for moving average. As our model lags and moving average lags are 1 and 3 respectively, we will be fitting ARMA(1,3) model on our data.

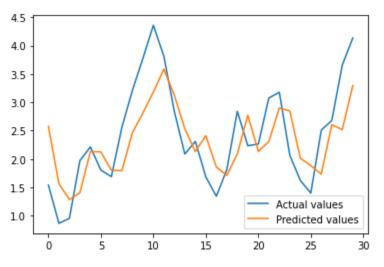
After fitting the ARMA (1,3) model on the data, given is the plotted predictions of wind speed for the last 30 days of the time series.

The MAE score obtained was 0.394.

4. Autoregressive Integrated Moving Average (ARIMA) model:

ARIMA or 'Auto Regressive Integrated Moving Average' model has the "integrated" part added to the ARMA model. The integrated part refers to the differencing (d) which is necessary to make a time series stationary. As wind speed data was already stationary, so differencing will be 0 and hence ARMA and ARIMA models will be the same.

5. Seasonal Autoregressive Integrated Moving Average (SARIMA) model:

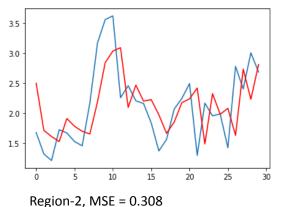


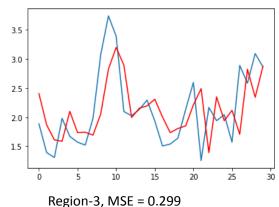
SARIMA model combines the ARIMA model with the ability to perform the same autoregression, differencing, and moving average modelling at seasonal level. We tried a grid search on the parameters of the order and the seasonal order. For us (2, 1, 2) (0, 0, 0) (0) was the best fit for the data. With more computational power we would have tried to do the same procedure with 365 as the seasonal variable but unfortunately it was too computational intensive.

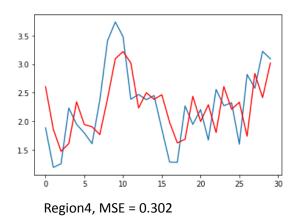
We obtained a MAE score of 0.393

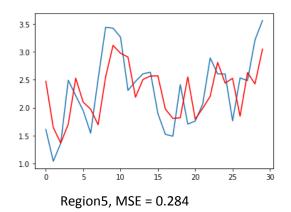
SPATIAL ANALYSIS

The forecasting is done for inter-state regions of Rajasthan, the above given results are obtained for Region-1. To carry out forecasting of other 4 regions, among the above given statistical methods, ARMA seems to work better as it gives 74.3% accuracy and a MSE value of 0.396. Thus we forecasted the wind speed for the other regions on the ARMA(1,3) model with the same parameters. Given below are the graphs of forecasting with the MSE scores. To our surprise, the results obtained with the same model on the other 4 regions are almost similar(or better than) to region-1. This can be because the regions are of the same state and thus will have almost the similar wind speed daily.









Models comparison:

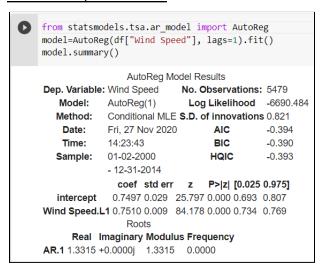
	AR model	MA model	ARMA/ARIMA model	SARIMA Model
MAE Score	0.401	0.417	0.394	0.393

In comparison for all the models, the SARIMA model performed marginally well giving the least MAE score but was at the same time computationally heavy.

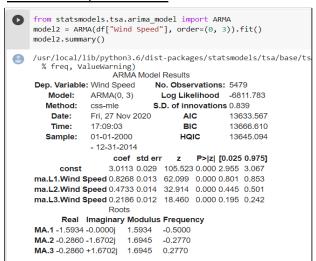
APPENDIX: IMPLEMENTATION AND MODEL SUMMARY

All the implementations are done in python.

AR Model Implementation



MA Model Implementation



ARMA Model Implementation

```
from statsmodels.tsa.arima model import ARMA
model2 = ARMA(df["Wind Speed"], order=(1, 3)).fit()
model2.summary()
/usr/local/lib/python3.6/dist-packages/statsmodels/tsa/
 % freq, ValueWarning)
                  ARMA Model Results
Dep. Variable: Wind Speed
                            No. Observations: 5479
   Model:
            ARMA(1, 3)
                             Log Likelihood -6550.122
  Method:
             css-mle
                           S.D. of innovations 0.800
             Fri, 27 Nov 2020
                                              13112.244
    Date:
                                   AIC
                                              13151.896
    Time:
             18:01:06
                                   BIC
            01-01-2000
                                  HQIC
  Sample:
                                              13126.077
             - 12-31-2014
                  coef std err z P>|z| [0.025 0.975]
      const
                 3.0077 0.105 28.523 0.000 2.801 3.214
ar.L1.Wind Speed 0.9775 0.005 214.920 0.000 0.969 0.986
ma.L1.Wind Speed -0 2284 0 014 -16 030 0 000 -0 256 -0 200
ma.L2.Wind Speed -0.3708 0.015 -24.516 0.000 -0.400 -0.341
ma.L3.Wind Speed -0.1794 0.013 -13.342 0.000 -0.206 -0.153
                 Roots
      Real Imaginary Modulus Frequency
AR.1 1.0231 +0.0000j 1.0231 0.0000
MA.1 1.1355 -0.0000j
                     1.1355
MA.2 -1.6011 -1.5315j
                     2.2156
                              -0.3785
MA.3 -1.6011 +1.5315j
                     2.2156
                             0.3785
```

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