

Notes for Paper 3

Title:Convex relaxation of optimal power flow—Part I:
Formulations and equivalence

Authors:Low S H.

Journal:IEEE Transactions on Control of Network Systems

Tags: Convex relaxation; optimal power flow; power system;
QCQP; SOCP; SDP

0. Summary

1. Power flow models

1.1 Bus injection model

$$s_j = \sum_{k:j \sim k} y_{jk}^H V_j (V_j^H - V_k^H), j \in N^+$$

where superscript H refers the conjugate transpose, s_j is the power flow on node j , $j \sim k$ refers that node j is connected with node k .

Bus 0 is the slack bus, which voltage is fixed and we assume that $V_0 = 1 \angle 0^\circ$; s_j is the net complex power injection at bus $j \in N^+$.

So, the solution for the power flow model $V \in C^{n+1}$, where C is the complex numbers.

Bus type

1. slack bus. V_0 is given, s_0 is variable.
2. generator bus. $Re(s_j) = p_j$ and $|V_j|$ are known, $Im(s_j) = q_j$ and $\angle V_j$ are unknown.
3. load bus. s_j is specified and V_j is variable.

Each bus is characterized by two complex variables V_j and s_j (or four real variables). As described above, two variables will be given at each bus (slack, generator, load), then we can solve

the $n + 1$ complex equations, or $2(n + 1)$ real number equations, to get the remaining $2(n + 1)$ variables.

1.2 Branch Flow Model

$$\begin{aligned} \sum_{k:j \rightarrow k} S_{jk} &= \sum_{i:i \rightarrow j} (S_{ij} - z_{ij} |I_{ij}|^2) + s_j, j \in N^+ \\ I_{ij} &= y_{jk} (V_j - V_k), j \rightarrow k \in \tilde{E} \\ S_{jk} &= V_j I_{jk}^H, j \rightarrow k \in \tilde{E} \end{aligned}$$

The solution $\tilde{x} := (S, I, V) \in C^{2m+n+1}$, where m is the number of directed edges, s_j is the net complex power injection at bus j . The total equation number is $(n + 1) + m + m = 2m + n + 1$, so the equation group is closed.

2. convert OPF into QCQP

Let I_j be the net injection current from bus j to the rest of the network:

$$I_j = \sum_{k:j \sim k} y_{ik} (V_k - V_j)$$

Then we can construct a symmetric matrix to let $I = YV$:

$$Y_{ij} = \begin{cases} \sum_{k:k \sim i} y_{ik}, & \text{if } i = j \\ -y_{ij} & \text{if } i \neq j \text{ and } i \sim j \\ 0, & \text{otherwise.} \end{cases}$$

so BIM is equivalent to:

$$s_j = V_j I_j^H = (e_j^H V)(I^H e_j)$$

where e_j is the $(n + 1)$ dimensional vector with 1 in the j th entry and 0 elsewhere. Because s_j is scalar variable, we have

$$s_j = \text{tr}(s_j) = \text{tr}(e_j^H V V^H Y^H e_j)$$

Because the shape of $e_j^H V V^H$ is the same with that of $(Y^H e_j)^T$, we have

$$s_j = \text{tr}(e_j^H V V^H Y^H e_j) = \text{tr}(Y^H e_j e_j^H V V^H)$$

Then we have (**why?**)

$$s_j = \text{tr}(Y^H e_j e_j^H V V^H) = \text{tr}(Y^H e_j e_j^H) V V^H = V^H Y_j^H V$$

where $Y_j := e_j e_j^H Y$

Then

$$\begin{aligned} \text{Re}(s_j) &= 1/2 V^H (Y_j^H + Y_j) V \\ \text{Im}(s_j) &= 1/(2i) V^H (Y_j^H - Y_j) V \end{aligned}$$

$$\text{Re } s_j = V^H \Phi_j V \quad \text{and} \quad \text{Im } s_j = V^H \Psi_j V.$$

Let their upper and lower bounds be denoted by

$$\begin{aligned} \underline{p}_j &:= \text{Re } \underline{s}_j \quad \text{and} \quad \bar{p}_j := \text{Re } \bar{s}_j \\ \underline{q}_j &:= \text{Re } \underline{s}_j \quad \text{and} \quad \bar{q}_j := \text{Re } \bar{s}_j. \end{aligned}$$

Let $J_j := e_j e_j^H$ denote the Hermitian matrix with a single 1 in the (j, j) th entry and 0 everywhere else, then OPF (7) can be written as a standard form QCQP

$$\min_{V \in \mathbb{C}^{n+1}} V^H C V \quad (10a)$$

$$\text{s.t.} \quad V^H \Phi_j V \leq \bar{p}_j, \quad V^H (-\Phi_j) V \leq -\underline{p}_j \quad (10b)$$

$$V^H \Psi_j V \leq \bar{q}_j, \quad V^H (-\Psi_j) V \leq -\underline{q}_j \quad (10c)$$

$$V^H J_j V \leq \bar{v}_j, \quad V^H (-J_j) V \leq -\underline{v}_j \quad (10d)$$

where $j \in N^+$ in (10).