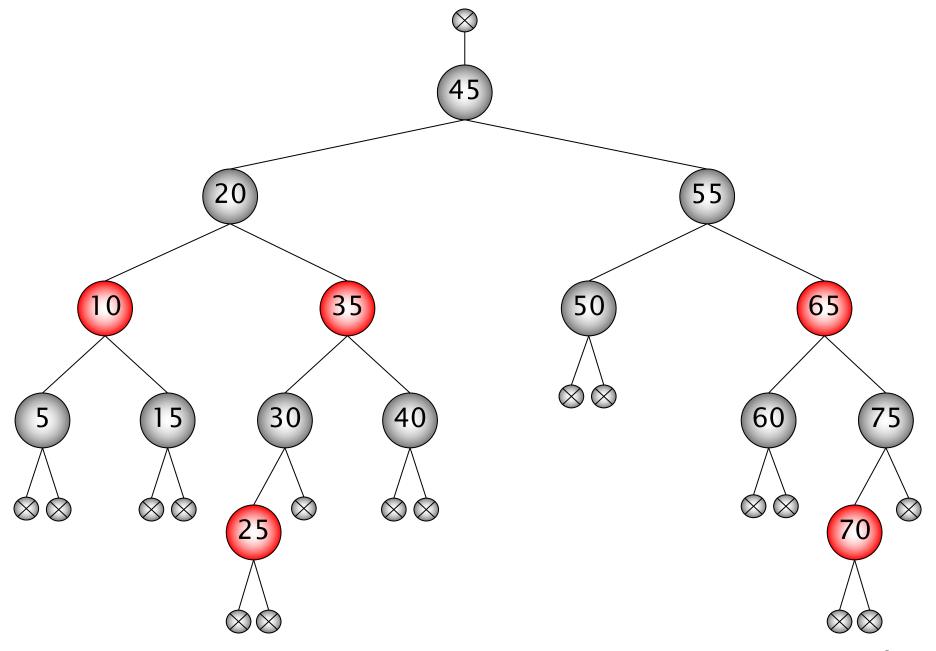
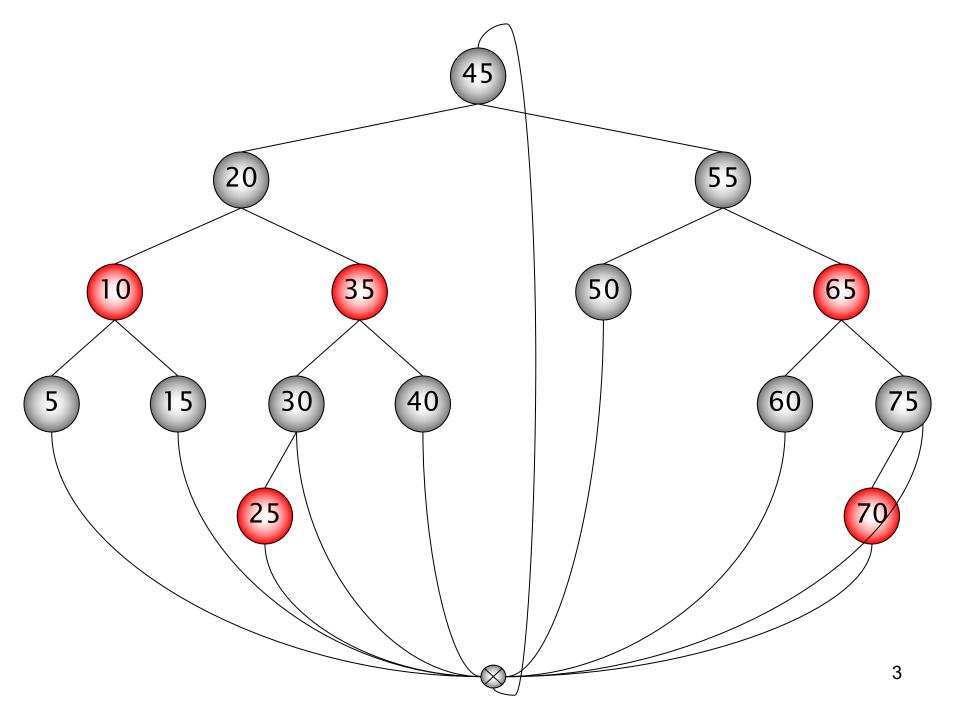
Red-Black Trees

- A red-black tree (RBT) is a type of self-balancing BST
 - Each node in an RBT is labeled as red or black
- Operations on RBTs take $O(\log n)$ time in the worst case since the height of an RBT is at most $2\log_2(n+1)$
 - The height of an AVL tree is at most $1.44 \log_2 n$
- However, a careful nonrecursive implementation can be done relatively effortlessly compared with AVL trees





Definition of Red-Black Trees

An RBT is a BST that satisfies the following *red-black criteria*:

- 1. Every node is either *red* or *black*
- 2. The root of the tree is always **black**
- 3. All leaves are **black**
- 4. If a node is *red*, then its parent is *black*
- 5. Any path from a node to any of its leaves contains the same amount of black nodes, called *black height*

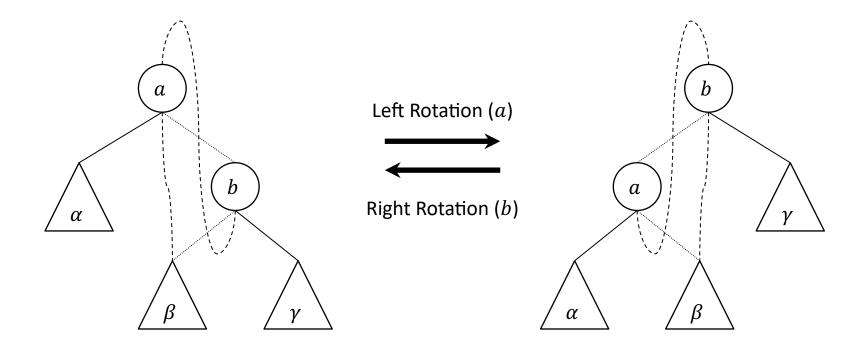
Representation of Red-Black Trees

```
typedef struct Node * Ref;
struct Node {
 int key;
 int color;
 Ref parent, left, right;
ref getNode(int key, int color, Ref nil) {
 p = new Node;
 p->key = key;
 p->color = color;
 p->left = p->right = p->parent = nil;
 return p;
```

The Initial State of a Red-Black Tree

```
Ref nil, root;
nil = new Node;
                                nil
nil->color = BLACK;
nil->key = -1;
nil->left =
nil->right =
nil->parent = nil;
root = nil;
```

Tree Rotation



```
leftRotate(Ref & root, Ref x) {
 y = x->right;
 x->right = y->left;
 if (y->left != nil)
   y->left->parent = x;
 y->parent = x->parent;
 if (x->parent == nil) root = y;
 else
   if (x == x->parent->left)
     x-parent->left = y;
   else
     x->parent->right = y;
 y->left = x;
 x->parent = y;
```

Search Operation

 An RBT is a BST so the search algorithm for an RBT is the same as the search algorithm for a BST

Insertion Operation

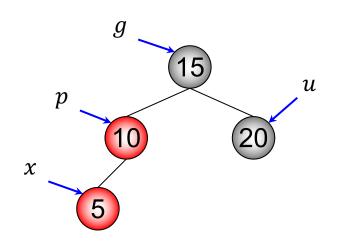
- The new node, as usual, is placed as a leaf in the tree
- The node must be colored red
 - If the parent is black: The red-black criteria are maintained
 - If the parent is red: The operation causes a violation of the criterion "no consecutive red nodes"
 - Rebalancing the tree is needed

Insertion Operation: Pseudo-code

```
void RBT_Insertion(Ref & root, int key) {
   x = getNode(key, RED, nil);
   BST_Insert(root, x);
   Insertion_FixUp(root, x);
}
```

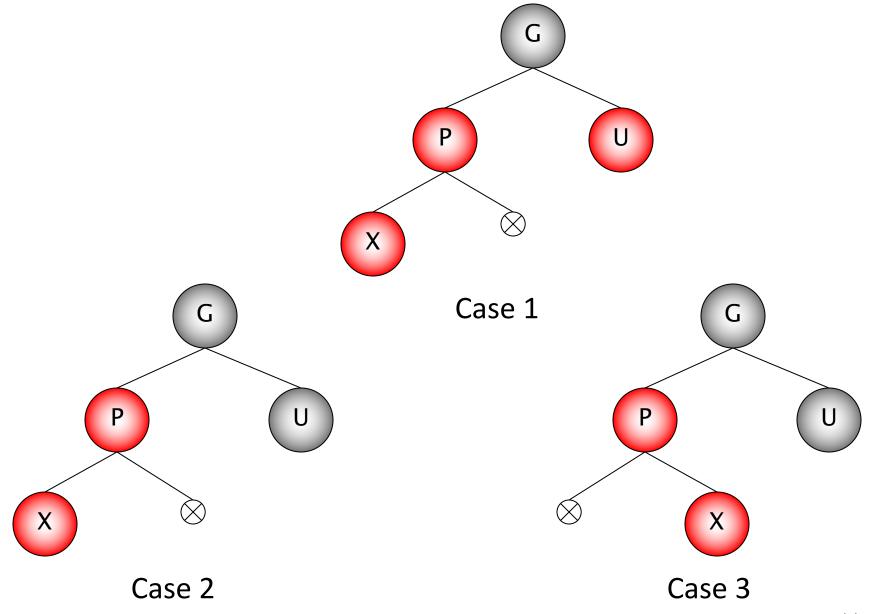
```
BST Insert(Ref & root, ref x) {
 y = nil;
  z = root;
 while (z != nil) {
   y = z;
   if (x->key < z->key)
                               z = z->left;
   else if (x->key > z->key) z = z->right;
   else
                               return;
 x-parent = y;
  if (y == nil) root = x;
 else
   if (x-)key < y-)key y-)left = x;
   else
                          y->right = x;
```

Some Conventions



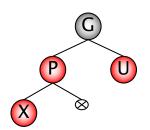
- x: The pointer designated to point to the newly added leaf
- p: The pointer designated to point to the parent of the node pointed to by x
- u: The pointer designated to point to the uncle of the node pointed to by x
- g: The pointer designated to point to the grandparent of the node pointed to by x

Imbalance Cases

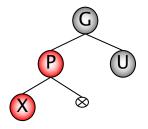


The Strategies for Rebalancing an RBT

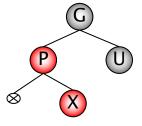
- Case 1
 - \rightarrow Reverse the color of three nodes: u, p, and g

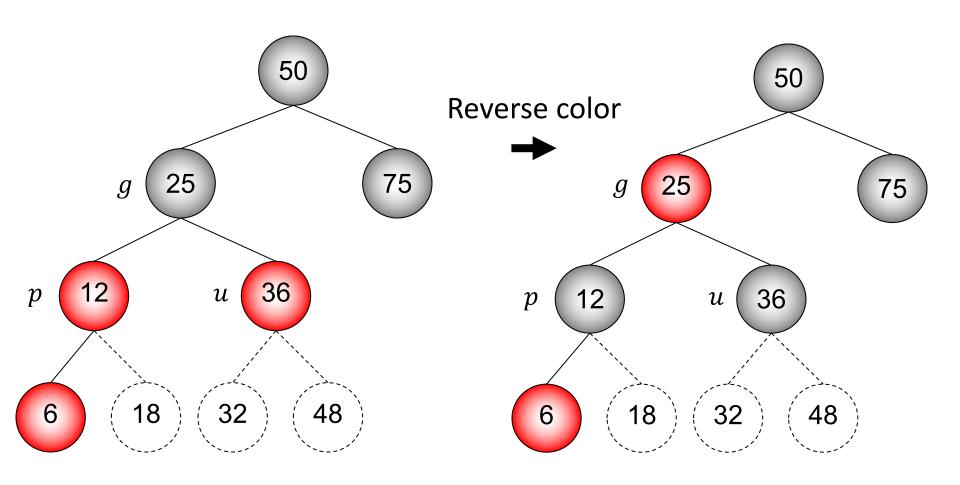


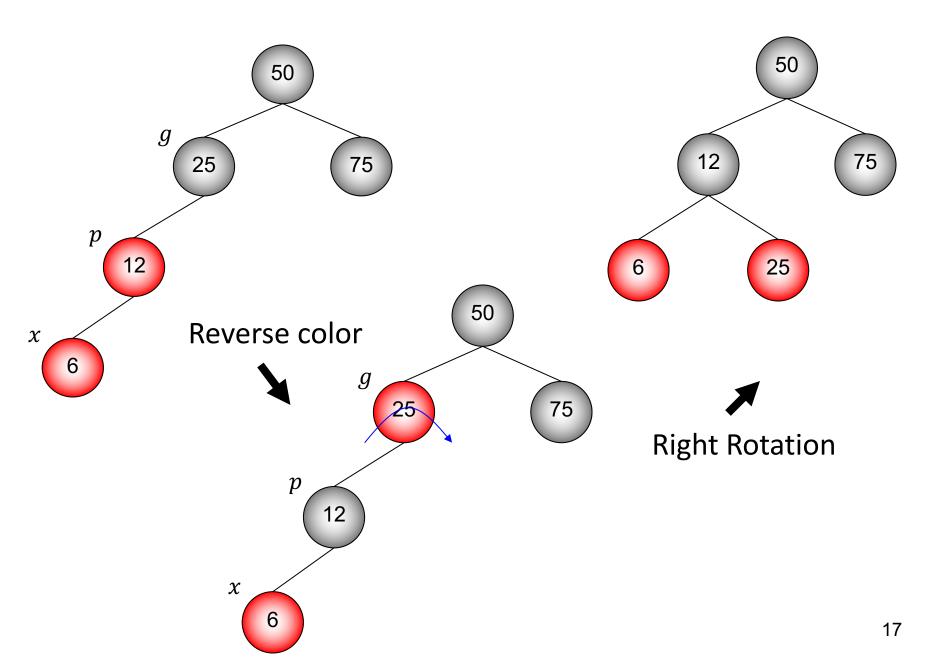
- Case 2
 - \rightarrow Reverse the color of two nodes: p and g
 - \rightarrow Run a rotation at g

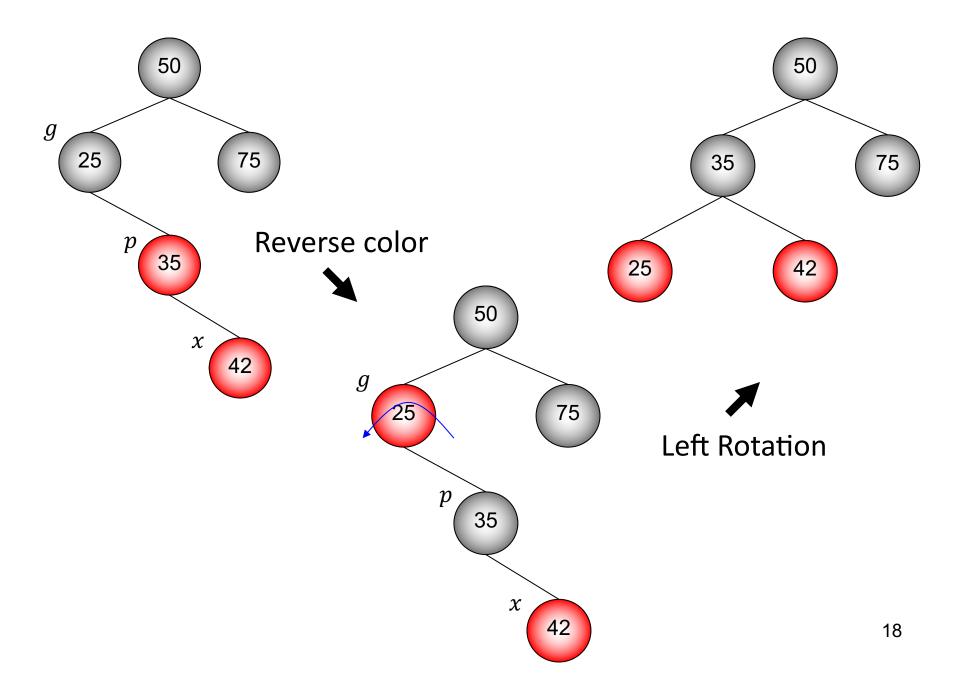


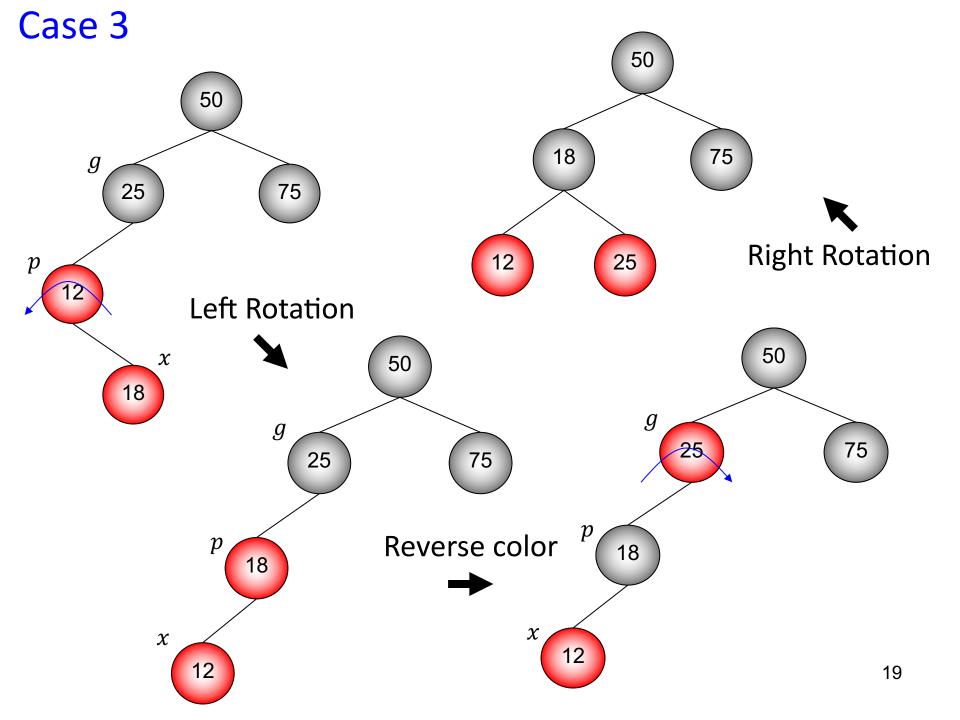
- Case 3
 - \rightarrow Run a rotation at parent p
 - → Go to Case 2

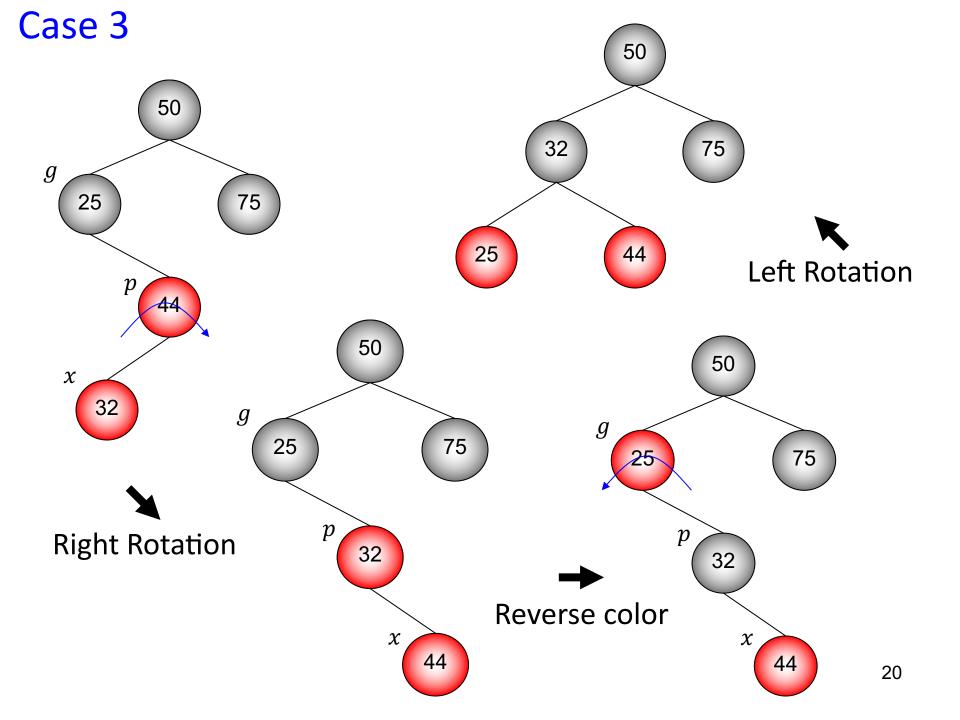












Insertion Operation: Pseudo-code

```
Insertion FixUp(Ref & root, Ref x) {
 while (x-\text{-}parent-\text{-}color == RED)
    if (x->parent == x->parent->parent->left)
      ins leftAdjust(root, x);
    else
      ins rightAdjust(root, x);
  root->color = BLACK;
```

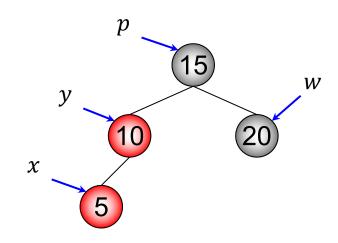
```
ins leftAdjust(Ref & root, Ref & x) {
 u = x->parent->parent->right;
 if (u->color == RED) {
   x->parent->color = u->color = BLACK;
   x->parent->parent->color = RED;
   x = x-parent->parent;
 else {
   if (x == x-)parent->right) {
     x = x->parent; leftRotate(root, x);
   x->parent->color = BLACK;
   x->parent->parent->color = RED;
   rightRotate(root, x->parent->parent);
```

Deletion Operation

- Let r be the node to be deleted. One of the following three cases will arise:
 - 1. *r* is a leaf
 - 2. r has one nonempty subtree
 - 3. r has both nonempty subtrees
- Let's consider the third case:
 - Find the predecessor or successor, say s, of r
 - Copy the data of s into r except the color
 - \square Now, the node to be deleted is s

```
RBT Deletion (Ref & root, int k) {
  z = searchTree(root, k);
  if (z == nil) return;
 y = (z-) = nil) | (z-) = nil) ?
            z : Predecessor(root, z);
  x = (y-) = nil) ? y-) + ight : y-) = ft;
 x->parent = y->parent;
  if (y->parent == nil) root = x;
  else
    if (y == y->parent->left) y->parent->left = x;
   else
                             y->parent->right= x;
  if (y != z) z \rightarrow key = y \rightarrow key;
  // if (y->color == BLACK) Del FixUp(root, x);
  delete y;
```

Some Conventions



- y: The pointer designated to point to the node to be deleted
- x: The pointer designated to point to the child of the node pointed to by y
- p: The pointer designated to point to the parent of the node pointed to by y
- w: The pointer designated to point to the sibling of the node pointed to by y

What'll Happen After Deleting a Node?

- If y was red, the red-black criteria still hold because:
 - No black heights in the tree have changed
 - No red nodes have been made adjacent
- If y was black:
 - The number of black nodes on every path passing through node y is decreased by 1
 - The "no two consecutive red nodes" criterion is also violated if both nodes, p and x, are red
 - Rebalancing the tree is needed

```
RBT Deletion (Ref & root, int k) {
  z = searchTree(root, k);
  if (z == nil) return;
 y = (z-) = nil) | (z-) = nil) ?
            z : Predecessor(root, z);
  x = (y-) = nil) ? y-) + ight : y-) = ft;
 x->parent = y->parent;
  if (y->parent == nil) root = x;
  else
    if (y == y->parent->left) y->parent->left = x;
   else
                             y->parent->right= x;
  if (y != z) z\rightarrow key = y\rightarrow key;
  if (y->color == BLACK) Del FixUp(root, x);
  delete y;
                                               27
```

Black Token

- Black token is an abstract concept
 - It's used to explain the meaning of the rebalancing process
- If y is black then x will receive black token
 - If x is black then x is called doubly-black node
 - If x is red then x is called red-black node
- What is the role of black token?
 - After deleting y, all black heights passing through x are one unit shorter than the others
 - The occurrence of black token logically implies that every black height passing through x is supplemented by one black

Black Token

- The black token tends to be pushed toward the root of the tree
- It could (i) be neutralized on the way to the root or (ii) finally be attached to the root, thus making the root as a doubly-black node
 - In both cases, the rebalancing process stops immediately

The Strategies for Rebalancing an RBT

- There are 4 cases that may happen when a black node is deleted
- We focus our attention on node x, the one with black token

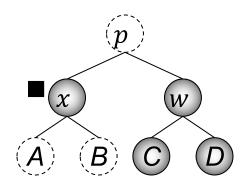
- If x is a red-black node
- → The node will be neutralized by coloring it black

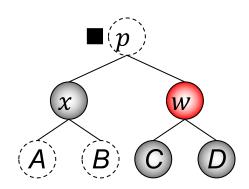
- If x is the root
- → The black token will be eliminated

- Node x is doubly-black
- Its sibling w is black
- Both of w's children are black

Solution:

- \rightarrow Reverse the color of sibling w
- \rightarrow Attach black token to parent p

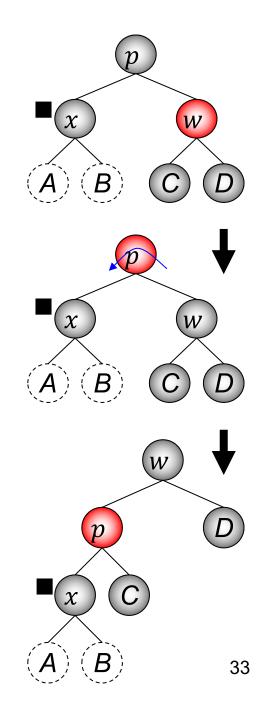




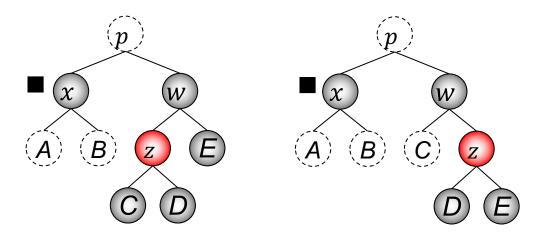
- Node x is doubly-black
- Its sibling w is red

Solution:

- \rightarrow Reverse the color of parent p and sibling w
- \rightarrow Perform a rotation at parent p



- Node x is doubly-black
- Its sibling w is black
- At least one of w's children is red



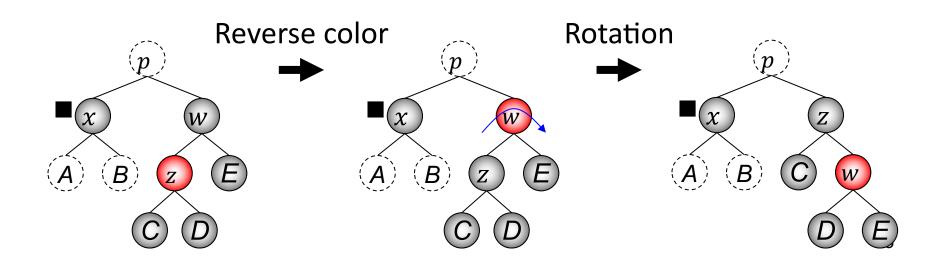
The solution depends on the w's child node which is the external grandchild of grandparent p

Case 4.a

The external grandchild is black

Solution:

- \rightarrow Reverse the color of internal grandchild z and sibling w
- → Perform a rotation at the sibling w
- \rightarrow Go to Case 4.b

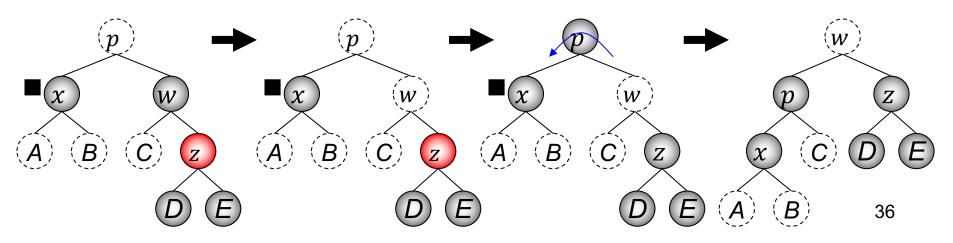


Case 4.b

The external grandchild is red

Solution:

- \rightarrow The sibling w inherits the color of its parent p
- ightharpoonup The color of grandparent p and external grandchild z is set to black
- \rightarrow Perform a rotation at grandparent p



```
Del FixUp(Ref root, Ref x) {
 while (x->color == BLACK && x != root)
   if (x == x->parent->left)
     del leftAdjust(root, x);
   else
     del rightAdjust(root, x);
 x->color = BLACK;
del leftAdjust(Ref & root, Ref & x) {
 w = x->parent->right;
 if (w->color == RED) {
   w->color
                    = BLACK;
   x->parent->color = RED;
   leftRotate(root, x->parent);
   w = x-parent->right;
```

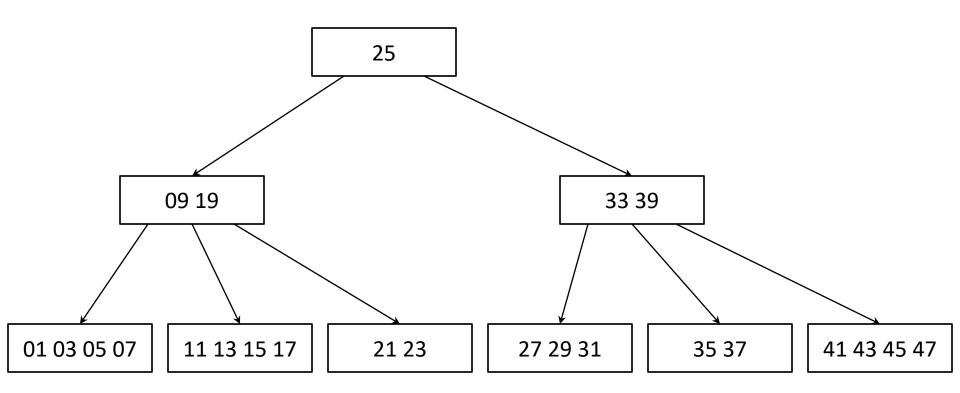
```
if (w->right->color == w->left->color == BLACK) {
 w->color = RED;
 x = x-parent;
else {
 if (w->right->color == BLACK) {
   w->left->color = BLACK;
   w->color = RED;
   rightRotate(root, w);
   w = x->parent->right;
 w->color
             = x->parent->color;
 x->parent->color = w->right->color = BLACK;
 leftRotate(root, x->parent);
 x = root;
                                            38
```

B-Trees

A B-tree of order t is either empty, or has the following properties:

- Every node contains at most 2t keys
- All nodes, except the root, contain at least t keys
- Every node is either a leaf or it has m+1 descendants, where m is its number of keys
- All leaves are on the same level

Example



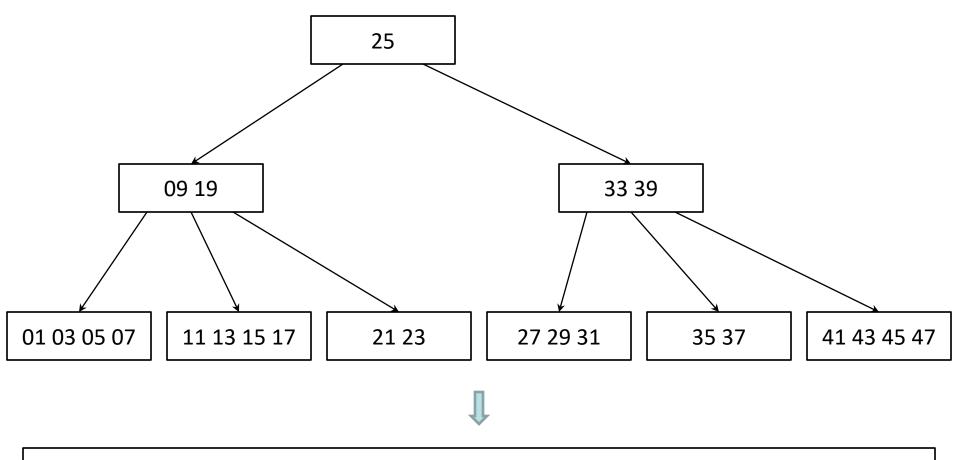
A Node (or Page) in B-Trees

The form of a node is as follows:

where

- $k_1 < k_2 < \dots < k_m$
- p_i is a pointer to a descendant
 - If it's a leaf: $p_i = \text{NULL}, \forall i \in [0, m]$
- All keys in the node to which p_i points are greater than k_i and less than k_{i+1}

Example



(((01 03 05 07) 09 (11 13 15 17) 19 (21 23)) 25 ((27 29 31) 33 (35 37) 39 (41 43 45 47)))

Search Operation

- Let k be the search key. Assume that the node being considered contains m keys: $k_1, k_2, ..., k_m$
- The search must start at the root of tree
 - If m is sufficiently large, one may use binary search; otherwise,
 a sequential search will do
- If the search is unsuccessful:
 - $k < k_1$: Search the node pointed to by p_0
 - $k > k_m$: Search the node pointed to by p_m
 - $k_i < k < k_{i+1}$: Search the node pointed to by p_i
- If the designated pointer is a null pointer: Stop!!!

Insertion Operation

- Assume that the key to be inserted is new
 - The search process terminates at a leaf
- The new key is inserted into the leaf if there is room
- If the leaf is full
 - Insert the new key into the leaf
 - Split the leaf into two nodes
 - Move the median key to the parent node
- The splitting can propogate upward up to the root, causing the tree to increase in height
 - This is the only way that a B-tree may increase its height

Deletion Operation

- Assume that the key to be deleted, say k, is in the tree
 - \square The search process terminates at the node containing k
- There are two different circumstances:
 - It's a leaf: The removal algorithm is plain and simple
 - Otherwise: The key must be replaced by its predecessor or successor, which happen to be on leaves and can easily be deleted
 - In either cases, the key that actually to be deleted is always on a leaf

Deletion Operation

- If the leaf contains more than t keys
 - Delete k and no further action is required
- If the leaf contains only t keys
 - If one of the adjacent siblings has more than t keys: Move one key from that sibling to the parent and one key from the parent to the leaf, and then delete k
 - Otherwise: Combine one of the adjacent siblings with the leaf
 and the median key from the parent, and then delete k
 - This process may propogate all the way up to the root which could result in reducing the height of the B-tree

B-Trees: Summary

- In practice, B-trees are designed to store and manage a large data on secondary storage devices
- A node of a B-tree normally corresponds to a disk page
 - For a typical disk, a page might be 2¹¹ to 2¹⁴ bytes in length
- The time needed to access a disk page is typically $\sim 10^5$ larger than the time needed to compare keys in RAM
 - The number of disk accesses (or the height of B-trees) is the principal indicator of the efficiency of this data structure