

A Family of 4-point Dyadic High Resolution Subdivision Schemes

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Subdivision: why care?

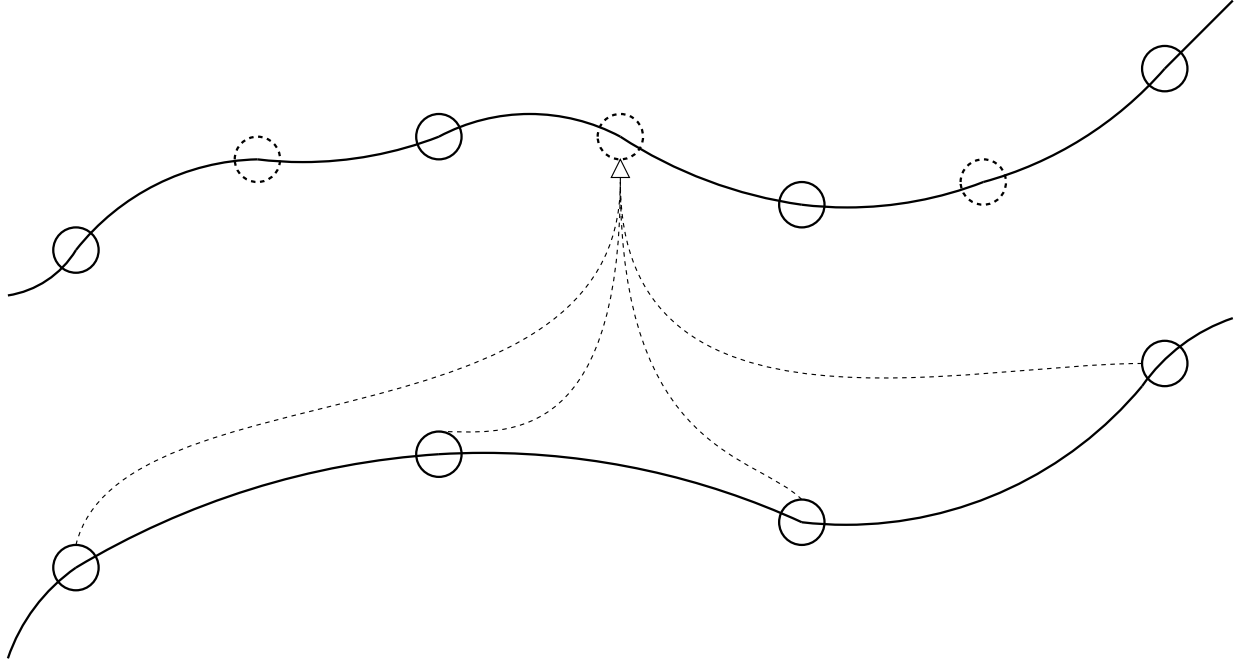
✓ multiscale approach

✓ local interpolation

✓ compactly supported wavelets

How Dubuc did it!

- ✓ 4 points → cubic polynomial
- midpoint value (*dyadic interpolation*)
- ✓ repeat at finer scales

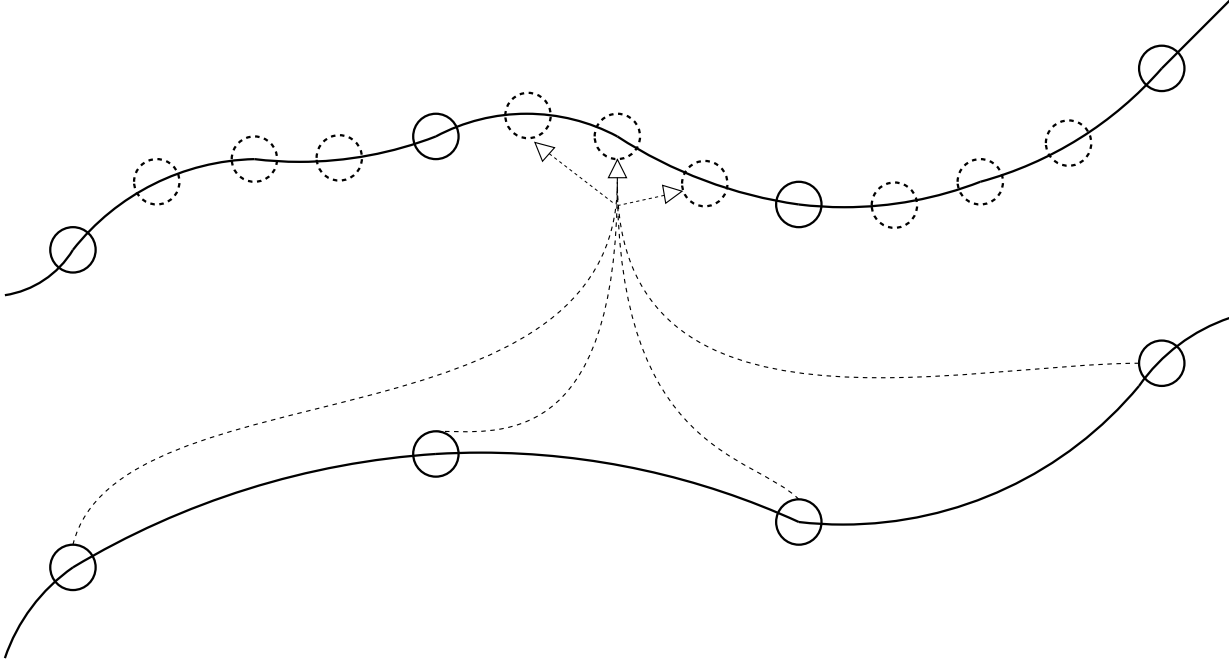


One follow-up...

Same story but...

4 points \rightarrow cubic polynomial

→ midpoint and quartile values (tetradic interpolation)



Question

Given a 4-point subdivision scheme, can we reproduce more than just cubic polynomials?

One more simple trick?

Recall Richardson's extrapolation:

1. an error of order p

$$p_{\Delta x} = a_{true} + \underbrace{k(\Delta x)^p + O(\Delta x^{p+1})}_{\text{some error}}$$

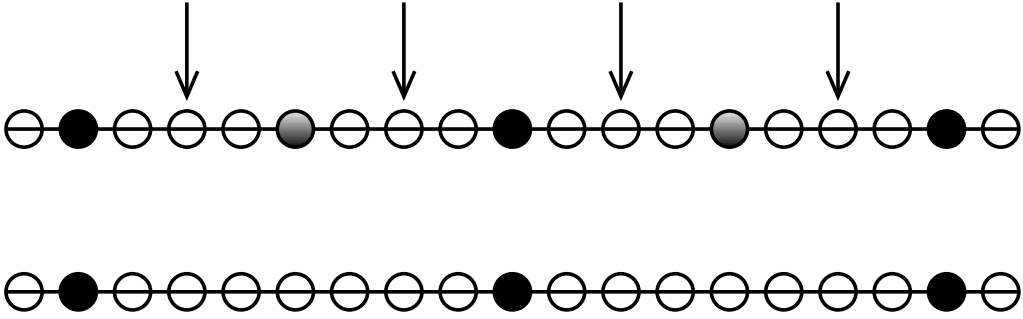
2. $\Delta x \mapsto \Delta x/2$

$$p_{\frac{\Delta x}{2}} = a_{true} + \underbrace{k\left(\frac{\Delta x}{2}\right)^p + O(\Delta x^{p+1})}_{\text{somewhat smaller error}}$$

3. Combine $a_{\Delta x}$ and $a_{\frac{\Delta x}{2}}$,

$$2^d \times a_{\frac{\Delta x}{2}} - a_{\Delta x} = \frac{2^d - 1}{a_{true}} + \underbrace{O(\Delta x^{d+1})}_{\text{we gain an order!}}$$

Guessing early or coarsing it up



✓ Ample storage: why not use it early?

HRS Algorithm

1. recopy stable data: $y_{j+1,4k} = y_{j,2k}$;

2. Tetradic scheme:

✓ cubic p interpolates $y_{j,2k-2}, y_{j,2k}, y_{j,2k+2}, y_{j,2k+4}$

$$\checkmark \quad y_{j+1,4k+1}^{\text{coarse}} = p(x_{j+1,4k+1}), y_{j+1,4k+2}^{\text{fine}}, y_{j+1,4k+3}^{\text{coarse}}, y_{j+1,4k+4}^{\text{fine}} = p(x_{j+1,4k+4})$$

1. Update midpoint:

$$y_{j+1,4k+2} = (1 - \alpha) y_{j+1,4k+2}^{\text{fine}} + \alpha y_{j,2k+1}^{\text{coarse}}.$$

Smoothness

▷ $\alpha = 0 \Rightarrow \text{Dubuc}$

▷ $\text{Dubuc} \Rightarrow C^1$.

▷ For $-25/56 < \alpha < 15/32$, the HRS schemes are C^1 .

Reproduced polynomials

▷ HRS always reproduce cubic polynomials.

▷ Reproduce quartic polynomials when $\alpha = -3/32$.

$y_{j-1,k} = p_4(x_{j-1,k})$ where $p_4(x) = a_4x^4 + a_3x^3 + a_2x^2 + a_1x + a_0$, then

$$y_{j,2k+1}^{\text{coarse}} = p_4(x_{j,2r+1}) - \frac{105a_4}{24j}$$

$$y_{j,2k+1}^{\text{fine}} = p_4(x_{j,2r+1}) - \frac{9a_4}{24j}$$

Initialisation

Need subdivision scheme such that $y_{j-1,k} = p_4(x_{j-1,k}) \implies$

$$\checkmark \quad y_{j,2k+1} = p_4(x_{j,2k+1}) - \frac{105a_4}{16 \times 2^4 j}$$

$$\checkmark \quad y_{j,2k} = p_4(x_{j,2k})$$

(Possible with a 5-point s.s.)

Reproducing quartic polynomials

▷ subdivision \implies 5-point scheme

▷ HRS ($\alpha = -3/32$) \implies 5-point initialization + 4-point for the rest

How does it compare to Vector Subdivision Schemes?

✓ Vector \Rightarrow several fixed value per node

✓ HRS \Rightarrow one value per node but **allowed to changed over time**

Conclusion (a comparative table)

scheme	regularity	reproduced polynomials
Dubuc	C^1	cubic
Deslauriers-Dubuc	C^1	cubic
Dyn-Gregory-Levin	up to C^1	up to cubic
Hassan et al.	C^2	quadratic
presented HRS	up to C^1	cubic to quartic

Key Mathematical Argument

Fourier

$$z^k \mathcal{Z}^k = (z)_D$$

pue

$$\frac{9\mathfrak{I}}{\left(\varepsilon_{-}z+\varepsilon z\right)6}-\frac{9\mathfrak{I}}{\left(\mathfrak{I}_{-}z+z\right)6}+\mathfrak{I}=\left(z\right)\mathfrak{I}$$

then

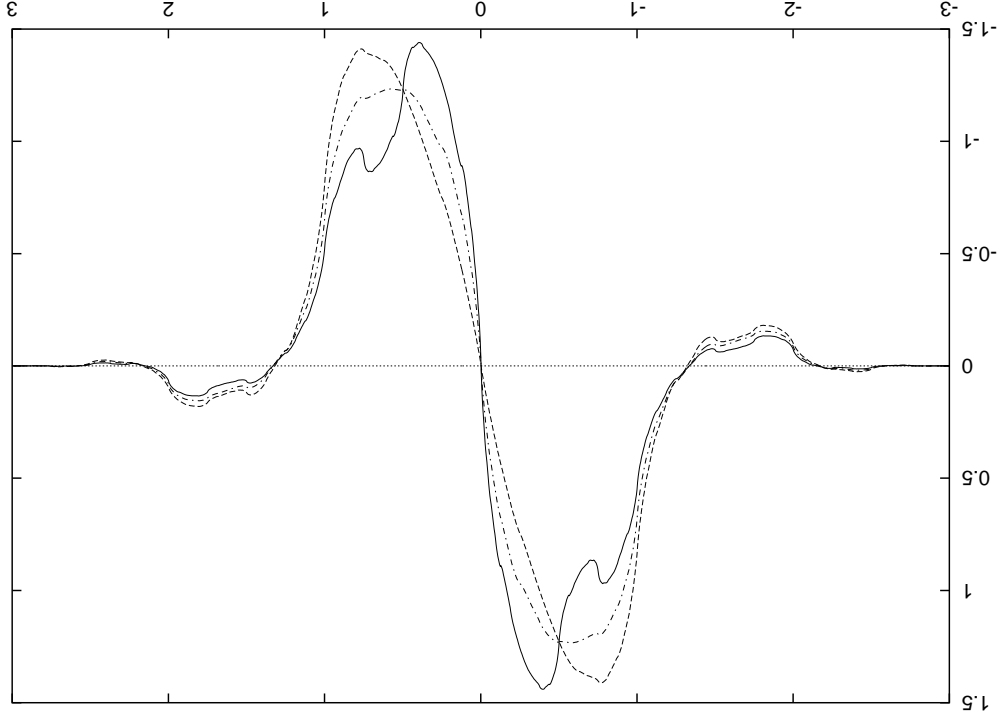
$$\left({}^{\mathcal{Z}} \right)_{\mathcal{I}} \mathcal{D}(\mathcal{Z}) \mathcal{I} = \left(\mathcal{Z} \right)_{\mathcal{I} +} \mathcal{D}$$

HRS requires 2 trig. poly.

$$\left(\tau^z - \right)_f \mathbf{D}(\tau) \tau^z \mathbf{I} + \left(\tau^z \right)_f \mathbf{D}(\tau) \mathbf{I} = \left(\tau \right)_{\mathbf{I}+} \mathbf{D}$$

Bonus material 1 - nice pictures

Derivatives of the fundamental functions for $\alpha = -0.2$ (continuous line), $\alpha = 0$ (dash-dot line), and $\alpha = 0.15$ (dashed line).



Bonus material 2 - intermediate result

▷ (Dyn) Given trigonometric polynomials $\Gamma_1(z)$ and $\Gamma_2(z)$, the HRS scheme defined by

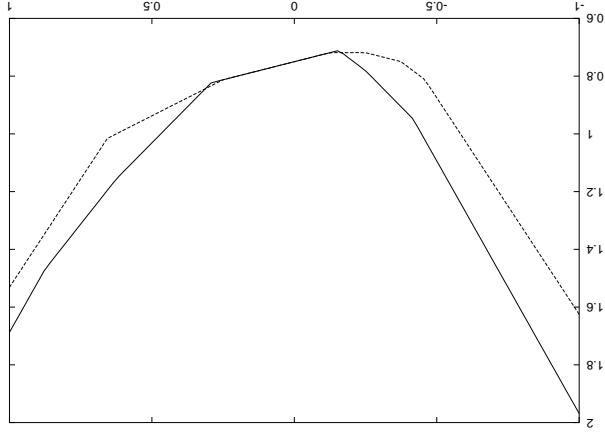
$$P^{j+1}(z) = \Gamma_1(z)P^j(z^2) + \Gamma_2(z)P^j(-z^2)$$

is C^n if the symbol corresponding to finite differences of order $n+1$

$$dH^n_j(z) = \frac{z^{n+1}}{2^{jn}(1-z)^{n+1}} P^j(z)$$

is the symbol of a HRS scheme converging uniformly to zero for all bounded initial data.

Bonus material 3 - more on proof



For a given α , an HRS scheme is differentiable if $\lambda^{HR}(\alpha) = \max \{ \lambda_1(\alpha), \lambda_2(\alpha) \} > 1$.

$$\Gamma > \{(\alpha)^{\top} \gamma, (\alpha)^{\top} \gamma_1\} \max = (\alpha)^{RH} \gamma.$$

Bonus material 4 - proper initialization

1. recopy data at $x_{j+1,2k} = x_{j,k}$: $y_{j+1,2k} = y_{j,k}$;

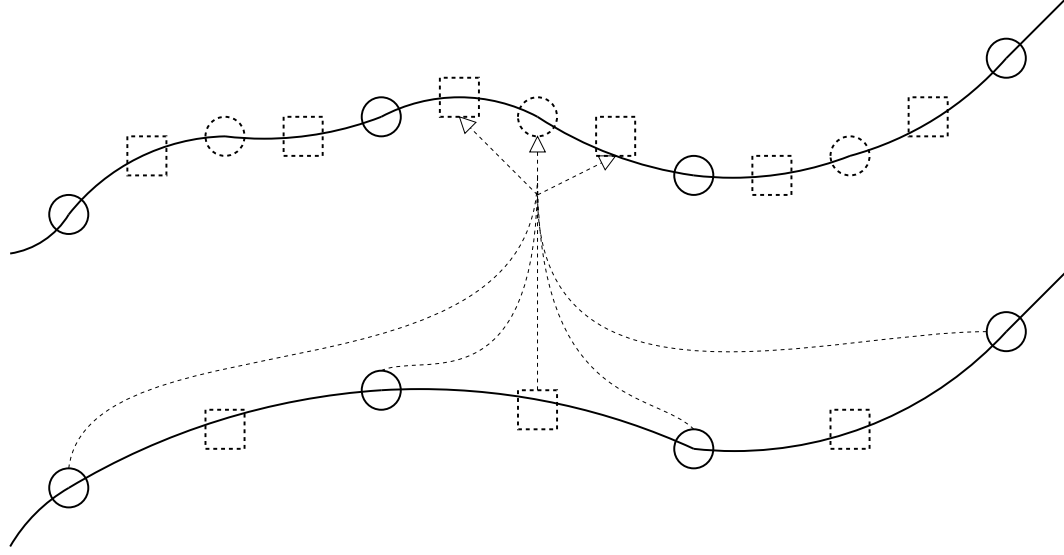
2. extrapolate $y_{j,k+4}$ using $y_{j,k-2}, y_{j,k-1}, y_{j,k}, y_{j,k+1}, y_{j,k+2}$ by the formula

$$y_{j,k} = 5y_{j,k-2} - 24y_{j,k-1} + 45y_{j,k} - 40y_{j,k+1} + 15y_{j,k+1}; \quad (1)$$

3. interpolate midpoint :

$$y_{j+1,2k+1} = \frac{-7y_{j,k-2} + 105y_{j,k} + 35y_{j,k+2} - 5y_{j,k}}{128}.$$

Bonus material 5 - Crunch the tetradic tree into a dyadic one



Some references

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