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model3=Sequential()

model3.add(Conv2D(32, (4,4), activation='relu', padding='same', input_shape=(48,48,1))) #moving ahead with grayscale inputs as RGB didnt show much big of a difference
model3.add(Conv2D(32, (4,4), activation='relu', padding='same'))

model3.add(Conv2D(64, (4,4), padding='same', activation='relu'))
    #removed maxpooling layers
model3.add(Conv2D(64, (4,4), padding='same', activation='relu'))
    #2 layers of conv2D with 64 filters and kernel size increased to (4,4) to capture bigger details

model3.add(Conv2D(64, (4,4), padding='same', activation='relu'))
    #removed maxpooling layers
model3.add(Conv2D(64, (4,4), padding='same', activation='relu'))
    #2 layers of conv2D with 64 filters and kernel size increased to (4,4) to capture bigger details
model3.add(MaxPooling2D(2,2))

model3.add(Conv2D(128, (4,4), padding='same', activation='relu'))
    #2 layers of conv2D with 128 filters
model3.add(Conv2D(128, (4,4), padding='same', activation='relu'))

model3.add(Conv2D(128, (4,4), padding='same', activation='relu'))
    #2 layers of conv2D with 128 filters
model3.add(Conv2D(128, (4,4), padding='same', activation='relu'))
model3.add(MaxPooling2D(2,2))

model3.add(Conv2D(256, (4,4), padding='same', activation='relu'))
    #2 layers of conv2D with 256 filters
model3.add(Conv2D(256, (4,4), padding='same', activation='relu'))

model3.add(Conv2D(256, (4,4), padding='same', activation='relu'))
    #2 layers of conv2D with 256 filters
model3.add(Conv2D(256, (4,4), padding='same', activation='relu'))
model3.add(MaxPooling2D(2,2))

model3.add(Flatten())

model3.add(Dropout(0.2)) #to correct the overfitting that may be caused

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model3.add(BatchNormalization())

model3.add(Dense(32, activation='relu'))
model3.add(Dropout(0.2))                                #to
correct the overfitting that may be caused
model3.add(BatchNormalization())

model3.add(Dense(32, activation='relu'))

model3.add(Dense(4, activation="Softmax"))

model3.summary()
```