

PARALLEL PROGRAMMING...

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Parallel Programming: Overview

SESSION 2/3



Programming Interface for parallel computing

MPI (Message Passing Interface)

OpenMP (Open Multi-Processing)

Programming interface for parallel computing

병렬 컴퓨팅을 위한 프로그래밍 인터페이스

Programming interface...

OpenMP



Remember

CPU CPU Core Core Memory Memory Private Network Arrays Interconnect CPU CPU Core Core Memory Memory

CPU Core CPU Core CPU Core

Memory, Shared Arrays etc.

Typically less memory overhead/duplication.
Communication often implicit, through cache coherency and runtime

MPI (Message Passing Interface) is a multi-process model whose mode of communication between the processes is **explicit.**

==> communication management is the responsibility of the user.

OpenMP (**Open Multi-Processing**) is a multitasking model whose mode of communication between tasks is **implicit**

==> communications is the responsibility of the compiler.



MPI (Message Passing Interface)





MPI (Message Passing Interface)

MPI is a library of subroutines (in Fortran, C, C++)

Allows the coordination of a program running as multiple processes in a distributed-memory environment.

Flexible enough to also be used in a shared-memory environment.

Can be used and compiled on a wide variety of single platforms or (homogeneous or heterogeneous) clusters of computers over a network.

The scalability of MPI is not limited by the number of processors/cores on one computation node, as opposed to shared memory parallel models.

MPI library is standardized, should work (without further changes!) on any machine on which the MPI library is installed.

MPI: Basic Environment



MPI programs start with a function call which initializes the message passing library.

```
MPI_Init(&argc, &argv)
```

Initializes MPI environment

Must be called in every MPI program

Must be first MPI call

Can be used to pass command line arguments to all

```
MPI_Finalize()
```

Terminates MPI environment

Last MPI function call

MPI: Basic Environment



```
MPI_Comm_rank(comm, &rank)
```

Returns the rank of the calling MPI process Within the communicator, comm MPI_COMM_WORLD is set during Init(...) Other communicators can be created if needed

```
MPI_Comm_size(comm, &size)
```

Returns the total number of processes Within the communicator, comm

```
int my_rank, size;
MPI_Init(&argc,&argv);
MPI_Comm_rank(MPI_COMM_WORLD, &my_rank);
MPI_Comm_size(MPI_COMM_WORLD, &size);
```

MPI: Point-to-Point Communication



```
MPI_Send(&buf, count, datatype, dest, tag, comm)
```

Send a message
Returns only after buffer is free for reuse

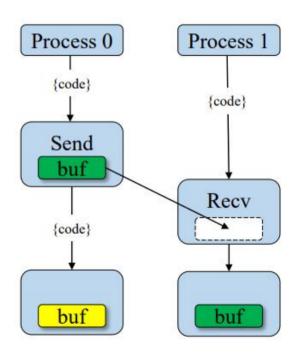
*Blocking**

MPI_Recv(&buf, count, datatype, source, tag, comm, &status)

Received a message Returns only when the data is avaible **Blocking**

MPI_SendRecv(...)

Two way communication **Blocking**



MPI: Point-to-Point Communication



Blocking

- Only returns after completed
 - Received: data has arrived and ready to use
 - Send: safe to reuse sent buffer
- Be aware of deadlocks !!!
- Tip: use when possible



Non-Blocking

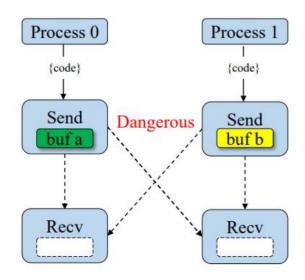
- returns immediately
 - Unsafe to modify buffers until operation is known to be complete
- Allows computation and communication to overlap
- Tip: Use only when needed

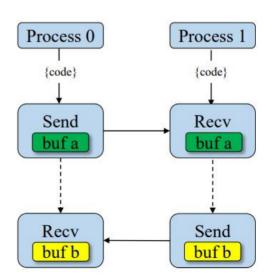
MPI: Deadlock



Blocking calls can results in deadlock

One process is waiting for message that will never arrive Only option is to abort the interrupt/kill the code (CTRL-c) Might not always deadlock - depends on size of system buffer



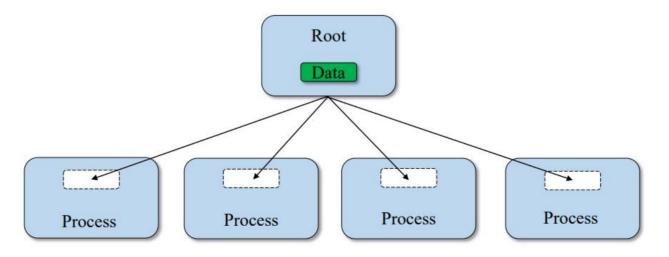


MPI: Coolective Communication (BCast)



```
MPI_Bcast(&buffer, count, datatype, root, comm)
```

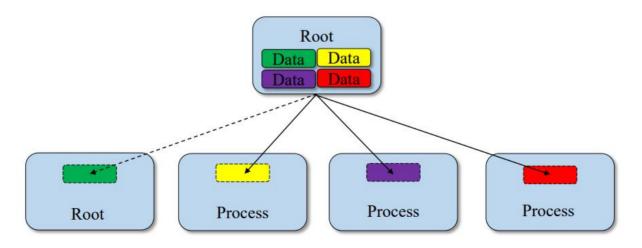
Broadcast a message from the root process to all other processes. Useful when reading in input parameters from file.



MPI: Collective Communication (Scatter)



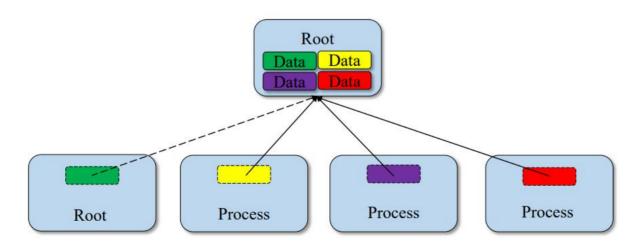
Sends individual messages from the root process to all other processes.



MPI: Collective Communication (Gather)



Opposite of Scatter.

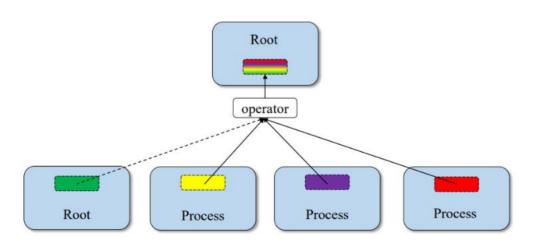


MPI: Collective Communication (Reduce)



Applies reduction operation on data from all processes.

Puts results on root process.



Operator
MPI_SUM
MPI_MAX
MPI_MIN
MPI PROD

MPI: Collective Communication (Allreduce)



Applies reduction operation on data from all processes.

Operator

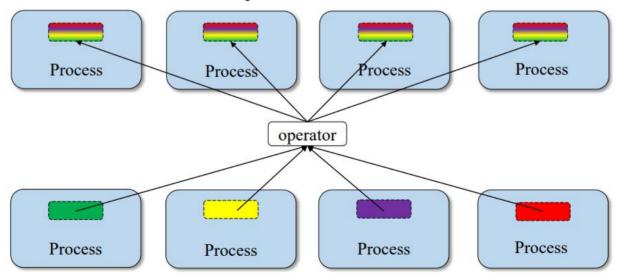
MPI_SUM

MPI_MAX

MPI_MIN

MPI_PROD

Store results on all processes.



MPI: Collective Communication (Barrier)



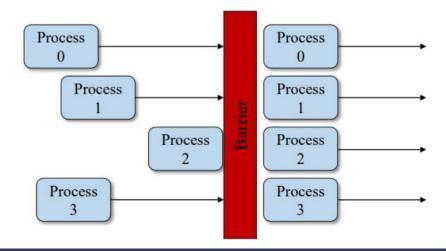
```
MPI_Barrier(comm)
```

Process synchronization (blocking).

All processes forced to wait for each other.

Use only where necessary.

Will reduce parallelism.



MPI: keywords

1 environment

- MPI Init: Initialization of the MPI environment
- MPI Comm rank: Rank of the process
- MPI Comm size: Number of processes
- MPI Finalize: Deactivation of the MPI environment
- MPI Abort: Stopping of an MPI program
- MPI Wtime: Time taking

2 Point-to-point communications

- MPI Send: Send message
- MPI Isend: Non-blocking message sending
- MPI Recv: Message received
- MPI Irecv: Non-blocking message reception
- MPI Sendrecv and MPI Sendrecv replace: Sending and receiving messages
- MPI Wait: Waiting for the end of a non-blocking communication
- MPI Wait all: Wait for the end of all non-blocking communications

3 Collective communications

- MPI Bcast: General broadcast
- MPI Scatter: Selective spread
- MPI Gather and MPI Allgather: Collecting
- MPI Alltoall: Collection and distribution
- MPI Reduce and MPI Allreduce: Reduction
- MPI Barrier: Global synchronization

4 Derived Types

- MPI Contiguous type: Contiguous types
- MPI Type vector and MPI Type create hvector: Types with a constanding
- MPI Type indexed: Variable pitch types
- MPI Type create subarray: Sub-array types
- MPI Type create struct: H and erogenous types
- MPI Type commit: Type commit
- MPI Type get extent: Recover the extent
- MPI Type create resized: Change of scope
- MPI Type size: Size of a type
- MPI Type free: Release of a type



MPI: Keywords

5 Communicator

- MPI Comm split: Partitioning of a communicator
- MPI Dims create: Distribution of processes
- MPI Cart create: Creation of a Cart esian topology
- MPI Cart rank: Rank of a process in the Cart esian topology
- MPI Cart coordinates: Coordinates of a process in the Cart esian topology
- MPI Cart shift: Rank of the neighbors in the Cart esian topology
- MPI Comm free: Release of a communicator

6 MPI-IO

- MPI File open: Opening a file
- MPI File set view: Changing the view
- MPI File close: Closing a file

6.1 Explicit addresses

- MPI File read at: Reading
- MPI File read at all: Collective reading
- MPI File write at: Writing

6.2 Individual pointers

- MPI File read: Reading
- MPI File read all: collective reading
- MPI File write: Writing
- MPI File write all: collective writing
- MPI File seek: Pointer positioning

6.3 Shared pointers

- MPI File read shared: Read
- MPI File read ordered: Collective reading
- MPI File seek shared: Pointer positioning

7.0 Symbolic constants

- MPI COMM WORLD, MPI SUCCESS
- MPI STATUS IGNORE, MPI PROC NULL
- MPI INTEGER, MPI REAL, MPI DOUBLE PRECISION
- MPI ORDER FORTRAN, MPI ORDER C
- MPI MODE CREATE, MPI MODE RONLY, MPI MODE WRONLY



MPI: Program Basics

Include MPI Header File

Start of Program
(Non-interacting Code)

Initialize MPI

Run Parallel Code & Pass Messages

End MPI Environment

(Non-interacting Code)

End of Program

```
#include <mpi.h>
int main (int argc, char *argv[])
MPI_Init(&argc, &argv);
      // Run parallel code
MPI_Finalize(); // End MPI Envir
return 0;
```



MPI: Example



```
#include <mpi.h>
#include <stdio.h>
int main (int argc, char *argv[]) {
 int rank, size;
 MPI Init (&argc, &argv); //initialize MPI library
 MPI Comm size (MPI COMM WORLD, &size); //get number of processes
 MPI Comm rank (MPI COMM WORLD, &rank); //get my process id
 //do something
 printf ("Hello World from rank %d\n", rank);
 if (rank == 0) printf("MPI World size = %d processes\n", size);
 MPI Finalize(); //MPI cleanup
 return 0;
```

4 processes

```
Hello World from rank 3
Hello World from rank 0
MPI World size = 4 processes
Hello World from rank 2
Hello World from rank 1
```

- · Code ran on each process independently
- MPI Processes have private variables
- · Processes can be on completely different machines

MPI: Example Broadcast



```
#include<iostream>
#include<mpi.h>
                                                                 Broadcast a message from the root process to all other processes.
using namespace std;
int main (int argc, char *argv[])
                                                                 Useful when reading in input parameters from file.
     int numprocs, myid, namelen;
     char processor name[MPI MAX PROCESSOR NAME];
     MPI_Init(&argc,&argv);
     MPI Comm size(MPI COMM WORLD,&numprocs);
     MPI Comm rank(MPI COMM WORLD,&myid);
     MPI Get processor name(processor name,&namelen);
     double reel=(double) myid;
     cout<<"Before " <<myid<<" of "<<numprocs<<" on "<<pre>rocessor name<<" integervalue "<<reel<<endl;</pre>
     MPI Bcast(&reel,1, MPI DOUBLE,3,MPI COMM WORLD);
     MPI Barrier (MPI COMM WORLD);
     cout<<"After " << myid<<" of "<< numprocs<<" on "<< processor name<< " integervalue "<< reel<< endl;
     MPI Finalize();
     exit(0);
```

MPI: Example Point-to-Point communication



```
#include<iostream>
#include<mpi.h>
using namespace std;
int main (int argc, char *argv[])
     int numprocs, myid;
     MPI Init(&argc,&argv);
     MPI Comm size(MPI COMM WORLD,&numprocs);
     MPI Comm rank(MPI COMM WORLD,&myid);
     MPI Status status;
     int small=myid;
     cout<<"Before " <<myid<<" of "<<,numprocs<<" small = "<<small,<<endl;
     If (myid==0) { MPI Send(&small,1,MPI INT,3,10,MPI COMM WORLD); }
     If (myid==3) { MPI Recv(&small,1,MPI INT,0,10,MPI COMM WORLD,&status) }
     MPI Barrier (MPI COMM WORLD);
     cout<<"After " <<myid<<" of "<<numprocs<<" small = "<<small<<endl;
     MPI Finalize();
```

MPI: Example Reduction



```
#include<mpi.h>
using namespace std;
double f( double a ) {return (4.0 / (1.0 + a*a));}
int main (int argc, char *argv[])
      int myid, numprocs;
      MPI Init(&argc,&argv);
      MPI Comm size(MPI COMM WORLD,&numprocs);
      MPI Comm rank(MPI COMM WORLD,&myid);
      int n = 10000000000;
      double pi,sum=0.0;
      double startwtime = 0.0;
      if (myid == 0) { startwtime = MPI_Wtime(); }
      MPI Bcast(&n, 1, MPI INT, 0, MPI COMM WORLD);
      for (int i = myid + 1; i \le n; i + numprocs) { sum i = f((i-0.5)/(double) n); }
      sum/= (double) n;
      MPI Reduce(&sum, &pi, 1, MPI DOUBLE, MPI SUM, 0, MPI COMM WORLD);
      if (myid == 0)
        cout<<"pi is approximately equal "<<setprecision(16) << pi << " Error is" << fabs(pi - M PI) << endl;
        cout<<"Wall clock time = "<<MPI Wtime()-startwtime<<endl;</pre>
      MPI Finalize();
      Exit(0);
```

GOAL: The following code computes the π number by using a numerical evaluation of an integral by a rectangle method.

Each virtual core computes a part of the loop and a reduction instruction is performed

COMPILING an MPI Program



- Compiling a program for MPI is almost just like compiling a regular C or C++ program
 - The C compiler is **mpicc** and the C++ compiler is **mpic**++.
 - For example, to compile **MyProg.c** you would use a command like
 - > mpicc O2 -o MyProg MyProg . c









OpenMP is a programming interface for parallel computing on shared memory architecture.



The OpenMP API consists of

- compiler directives (for insertion *into sequential* Fortran/C/C++\$code)
- a few library routines
- some environment variables



Advantages:

- User-friendly
- Incremental parallelization of a serial code
- Possible to have a single source code for both serial and parallelized versions



Disadvantages:

- Relatively limited user control
- Most suitable for parallelizing loops (data parallelism)
- Performance?

OpenMP is a programming interface for parallel computing on shared memory architecture.

• It allows you to manage:



- > the creation of light processes
- the sharing of work between these lightweight processes
- > synchronizations (explicit or implicit) between all light processes
- the status of the variables (private or shared).

- Shared memory model
 - > Threads communicate by accessing shared variables
 - The sharing is defined syntactically
 - Any variable that is seen by two or more threads is shared
 - Any variable that is seen by one thread only is private



- Race conditions possible
 - ➤ Use synchronization to protect from conflicts
 - > Change how data is stored to minimize the synchronization

• Multicore CPUs are everywhere:

- Servers with over 100 cores today and more
- > Even smartphone CPUs have 8 cores

• Multithreading, natural programming model

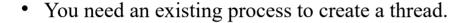
- ➤ All processors share the same memory
- Threads in a process see same address space
- Many shared-memory algorithms developed



Multithreading is hard

- Lots of expertise necessary
- Deadlocks and race conditions
- Non-deterministic behavior makes it hard to debug

OpenMP: Process and thread: whatis the difference?

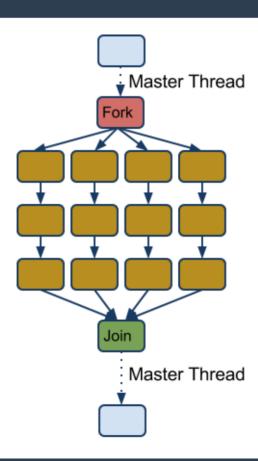




- Each process has at least one thread of execution.
- A process has its own virtual memory space that cannot be accessed by other processes running on the same or on a different processor.
- All threads created by a process share the virtual address space of that process. They read and write to the same address space in memory. They also share the same process and user ids, file descriptors, and signal handlers. However, they have their own program counter value and stack pointer, and can run independently on several processors.

OpenMP: Terminology and behavior

- OpenMP Team = Master + Worker
- **Parallel Region** is a block of code executed by all threads simultaneously (has implicit barrier)
 - The master thread always has thread id 0
 - Parallel regions can be nested
 - If clause can be used to guard the parallel region



OpenMP: General Code Structure





#include <omp.h>

```
main ()
     int var1, var2, var3;
     //serial code
     //start of a parallel region
     #pragma omp parallel private(var1, var2) shared(var3)
     {...}
     //more serial code
     {...}
     //another parallel region
     #pragma omp parallel
     {...}
```



OpenMP: Constructs



Parallel region

Thread creates team, and becomes master (id 0)

All threads run code after

Barrier at end of parallel section



OpenMP: Parallel Clauses



#pragma omp parallel if (scalar_expression)

Only execute in parallel. Otherwise serial.

#pragma omp parallel private (list)

Data local to thread.

Value are not guaranted to be defined on exit (even if defined before)

No storage associated with original object

Use firstprivate and/or lastprivate clause to override



#pragma omp parallel firstprivate (list)

Variables in list are private.

Initialized with the value the variable had before entering the construct.

#pragma omp parallel for lastprivate (list)

Only in for loops

Variables in list are private.

The thread that executes the sequentially last iteration updates the value of the variables in the list.

OpenMP: Parallel Clauses





```
#pragma omp shared (list)
```

Data is accessible by all threads in team. All threads access same address space.

Improperly scoped variables are big source of OMP bugs

- Shared when should be private
- Race condition

```
#pragma omp default (shared | none)
```

Tip: Safest is to use default (none) and declare by hand.

OpenMP Barrier



- When a thread reaches a barrier it only continues after all the threads in the same thread team have reached it
- Each barrier must be encountered by all threads in a team, or none at all
- The sequence of work-sharing regions and barrier regions encountered must be same for all threads in team
- Implicit barrier at the end of: do, parallel, single, workshare

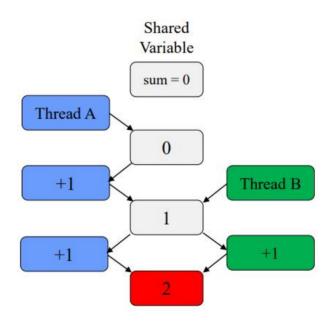
OpenMP: Caution Race Condition



When multiple threads simultaneously read/write Multiple OMP solutions

- Reduction
- Atomic
- Critical

```
#pragma omp parallel for private(i) shared(sum)
for (i=0; i<N; i++) {
   sum += i;
}</pre>
```



Should be 3!

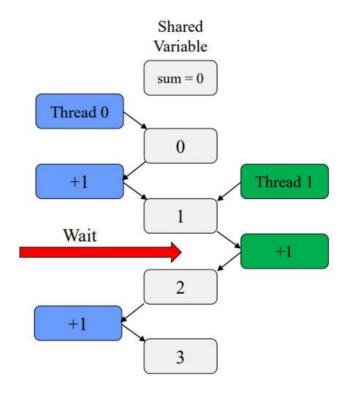
OpenMP: Critical Section



One solution: use critical
Only one tread at a time can execute a
critical section

```
#pragma omp critical
{
    sum += i;
}
```

Downside?
SLOOOWWW
Overhead and serialization



OpenMP: Atomic

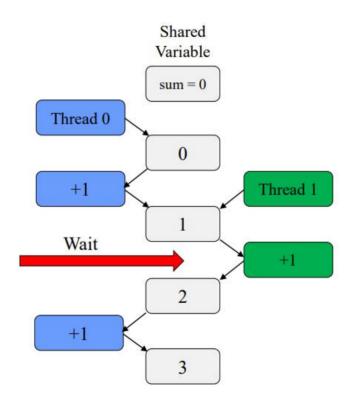


Atomics like "mini" critical Only one line

Certain limitations

#pragma omp atomic
sum += i;

Hardware controlled
Less overhead the critical



OpenMP: Reduction



```
#pragma omp reduction (operator:variable)
```

Avoids race condition

Reduce variable must be shared

Makes variable private, then performs operator at end of loop operator cannot be overloaded (c++)

One of: +,*,-,/ (and &,^,|,&&,||)

OpenMP 3.1: added min and max for c/c++

```
#include <omp.h>
#include <stdio.h>
int main() {
   int i;
   const int N = 1000;
   int sum = 0;

#pragma omp parallel for private(i) reduction(+: sum)
   for (i=0; i<N; i++) {
      sum += i;
   }

   printf("reduction sum=%d (expected %d)\n", sum, ((N-1)*N)/2);</pre>
```

OpenMP: Scheduling omp for



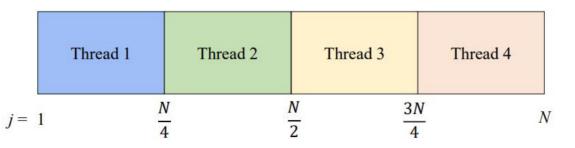
How does a loop get split up?

In MPI, we have to do it manually

If you do not tell what to do, the compiler decides

Usually compiler chooses "static" - chunks of N/p

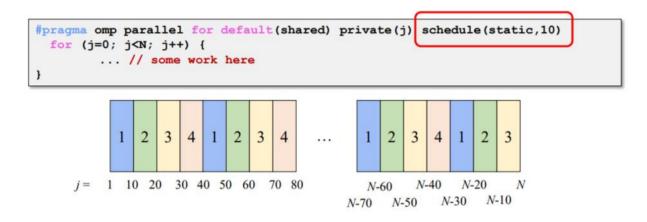




OpenMP: Static Scheduling



You can tell the compiler what size chunks to take.



Keeps assigning chunks until done.

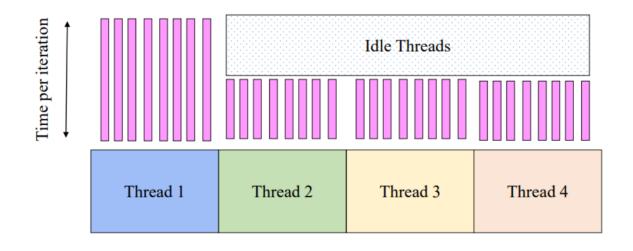
Chunk size that is not a multiple of the loop will results in thread with uneven numbers.

OpenMP: Problem with Static Scheduling



What happens if loop iterations do not take the same amount of time?

Load imbalance



OpenMP: Dynamic Scheduling





Chunks are assigned on the fly, as threads become available When a thread finishes on chunk, it is assigned another

Caveat: higher overhead than static!

OpenMP: For Scheduling Recap





#pragma omp parallel for schedule(type [,size])

Scheduling types

Static

- Chunks of specified size assigned round-robin

Dynamic

- Chunks of specified size are assigned when thread finishes previous chunk

Guided

- Like dynamic, but chunks are exponentially decreasing
- Chunk will not be smaller than specified size

Runtime

- Type and chunk determined at runtime via environment variables

OpenMP: API





- API for library calls that perform useful functions
- Must include "omp:h"
- Will not compile without OpenMP compiler support

```
#include <omp.h> //<-- necessary header file for OpenMP API
#include <stdio.h>
int main(int argc, char *argv[]) {
    printf("OpenMP running with %d threads\n", omp_get_max_threads());

#pragma omp parallel
    {
        //Code here will be executed by all threads
        printf("Hello World from thread %d\n", omp_get_thread_num());
    }
    return 0;
}
```

OpenMP: API



```
void omp set num threads(int num threads)
```

Sets number of treads used in next parallel section Overrides OMP_NUM_THREADS environment variable Positive integer

```
int omp get max threads()
```

Returns max possible (generally set by OMP_NUM_THREADS)

```
int omp_get_num_threads()
```

Returns number of threads currently in team

```
int omp_get_thread_num()
```

Returns thread id of calling thread Between 0 and omp get num threads-1

```
double omp_get_wtime()
```

Returns number of seconds since some point Use inpais time=(t2-t1)

OpenMP: Example Fibonacci



OpenMP: Example Quicksort



```
void quick_sort (int p, int r, float *data)
                                          void par_quick_sort (int n, float *data)
  if (p < r) {
     int q = partition (p, r, data);
                                            #pragma omp parallel
     #pragma omp task
                                              #pragma omp single nowait
     quick_sort (p, q-1, data, low_limit);
                                              quick_sort (0, n, data);
     #pragma omp task
     quick_sort (q+1, r, data, low_limit);}
```

OpenMP: Example Cholesky Factorization

```
#include <stdio.h>
int main(int argc, char* argv[])
{
  printf("Hello world! -main\n");
#pragma omp parallel
  {
    printf(".. worker reporting for duty.\n");
  }
  printf("Over and out! -main\n");
}
```

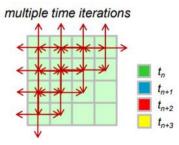
```
> gcc -fopenmp omp_hello.c -o omp
> OMP_NUM_THREADS=3 ./omp
Hello world! -main
.. worker reporting for duty.
.. worker reporting for duty.
.. worker reporting for duty.
Over and out! -main
```

```
void cholesky (int ts, int nt, double* a[nt][nt]) {
  for (int k = 0; k < nt; k++) {
    // Diagonal Block factorization
    #pragma omp task depend(inout: a[k][k])
 Opotrf(a[k][k], ts, ts);
    // Triangular systems
    for (int i = k + 1; i < nt; i++) {
      #pragma omp task depend(in: a[k][k])
                  depend(inout: a[k][i])
    trsm(a[k][k], a[k][i], ts, ts);
    // Update trailing matrix
    for (int i = k + 1; i < nt; i++) {
      for (int j = k + 1; j < i; j++) (
        #pragma omp task depend(inout: a[i][i])
                   depend(in: a[k][i], a[k][j])
      dgemm(a[k][i], a[k][j], a[j][i], ts, ts);
      #pragma omp task depend(inout: a[i][i])
                  depend(in: a[k][i])
     syrk(a[k][i], a[i][i], ts, ts);
                                        OpenMP 4.0
```

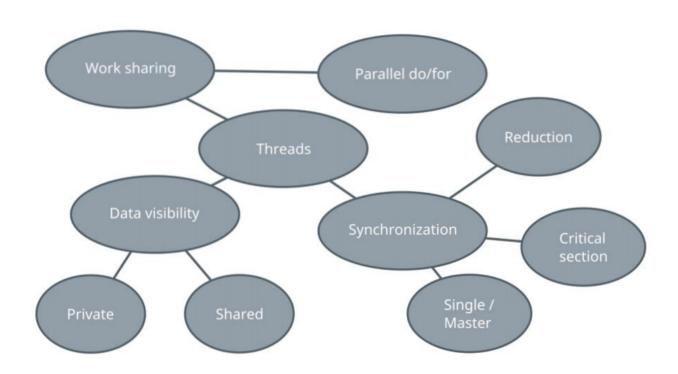
OpenMP: Example Gauss-Seidel

```
void gauss seidel (int tsteps, int size, int TS, int (*p)[size]) {
  int NB = size / TS:
  #pragma omp parallel
  #pragma omp single
  for (int t = 0; t < tsteps; ++t)
    for (int ii=1; ii < size-1; ii+=TS)</pre>
      for (int jj=1; jj < size-1; jj+=TS) {</pre>
        #pragma omp task depend(inout: p[ii:TS][jj:TS])
            depend(in: p[ii-TS:TS][jj:TS], p[ii+TS:TS][jj:TS],
                        p[ii:TS][jj-TS:TS], p[ii:TS][jj:TS])
          for (int i=ii; i<(1+ii) *TS; ++i)
            for (int j=jj; j<(1+jj)*TS; ++j)</pre>
               p[i][j] = 0.25 * (p[i][j-1] * p[i][j+1] *
                                  p[i-1][j] * p[i+1][j]);
```

Gauss-Seidel Method is used to solve the linear system Equations. It is a method of iteration for solving n linear equation Ax=b with the unknown variables.

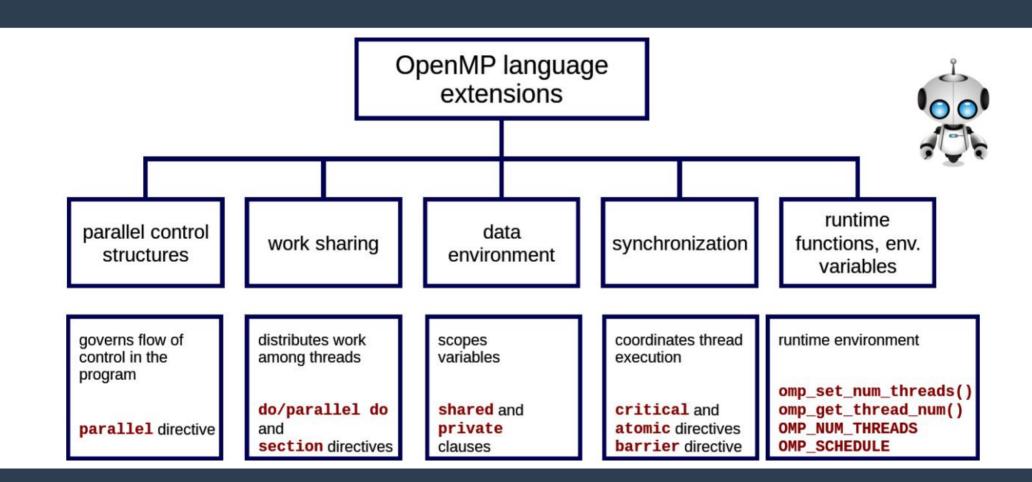


OpenMP: Summary





OpenMP: Summary Overview



OpenMP: Performance Tips



- Avoid serialization!
- Avoid using #pragma omp parallel for before each loop
 - Can have significant overhead
 - Thread creation and scheduling is NOT free!!
 - Try for broader parallelism
 - One #pragma omp parallel, multiple #pragma omp for
 - Always try to parallelize the outer most loop
- Use reduction whenever possible
- Minimize I/O
- Minimize critical
 - Use atomic instead of critical where possible



Hybrid OpenMP-MPI

Hybrid MPI and OpenMP



Hybrid application programs using **MPI + OpenMP** are now common place on large HPC systems.

There are basically two main motivations:

- 1. Reduced memory footprint, both in the application and in the MPI library (eg communication buffers).
- 2. Improved performance, especially at high core counts where pure MPI scalability runs out.

Hybrid MPI and OpenMP

Parallel programming models

Parallel execution is based on threads or processes (or both) which run at the same time on different CPU cores



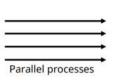
Processes

- Interaction is based on exchanging messages between processes
- MPI (Message passing interface)

Threads

- Interaction is based on shared memory, i.e. each thread can access directly other threads data
- OpenMP

Hybrid MPI and OpenMP

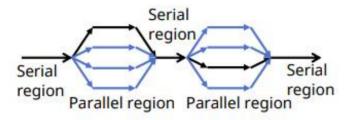


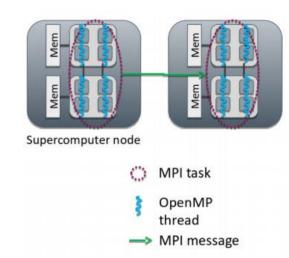
1: MPI: Processes

- Independent execution units
- Have their own memory space
- MPI launches N processes at application startup
- Works over multiple nodes

2: OpenMP: Threads

- Threads share memory space
- Threads are created and destroyed (parallel regions)
- Limited to a single node





- **3: Hybrid programming:** Launch threads (OpenMP) within processes (MPI)
- Shared memory programming inside a node, message passing between nodes
- Optimum MPI task per node ratio depends on the application and should always be experimented.

Hybrid Programming

In hybrid programming each process can have **multiple threads executing simultaneously** All threads within a process share all MPI objects Communicators, requests, etc.

MPI defines 4 levels of thread safety:

- ➤ MPI_THREAD_SINGLE : One thread exists in program
- ➤ MPI_THREAD_FUNNELED : Multithreaded but only the master thread can make MPI calls Master is one that calls MPI_Init_thread()
- > MPI_THREAD_SERIALIZED: Multithreaded, but only one thread can make MPI calls at a time
- ➤ MPI_THREAD_MULTIPLE: Multithreaded and any thread can make MPI calls at any time. Use MPI_Init_thread instead of MPI_Init if more than single thread

Hybrid Programming



Potential advantages of the hybrid approach

- Fewer MPI processes for a given amount of cores
 - Improved load balance
 - All-to-all communication bottlenecks alleviated
- Decreased memory consumption if an implementation uses replicated data
- Additional parallelization levels may be available
- Possibility for dedicating threads for different tasks
 - e.g. dedicated communication thread or parallel I/O
- Dynamic parallelization patterns often easier to implement with OpenMP



Disadvantages of hybridization

- Increased overhead from thread creation/destruction
- More complicated programming
 - Code readability and maintainability issues
- Thread support in MPI and other libraries needs to be considered

Hybrid Programming: Example

```
#include <mpi.h>
#include <omp.h>
int main(int argc, char *argv[]) {
    int my_id, omp_rank;
    int provided, required=MPI_THREAD_FUNNELED;
    MPI_Init_thread(&argc, &argv, required,
                    &provided);
    MPI_Comm_rank(MPI_COMM_WORLD, &my_id);
#pragma omp parallel private(omp_rank)
    omp_rank = omp_get_thread_num();
    printf("I'm thread %d in process %d\n",
           omp_rank, my_id);
    MPI_Finalize();
```

```
$ mpicc -fopenmp hybrid-hello.c -o hybrid-hello
$ srun --ntasks=2 --cpus-per-task=4
    ./hybrid-hello

I'm thread 0 in process 0
I'm thread 0 in process 1
I'm thread 2 in process 1
I'm thread 3 in process 1
I'm thread 1 in process 0
```

Hybrid Programming Example

Numerical integration

$$\int_0^1 \frac{4}{1+x^2} \, dx = \pi$$

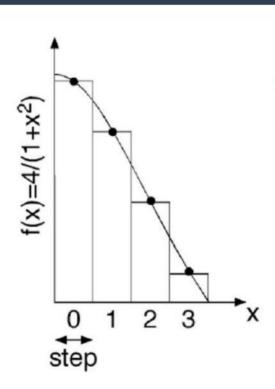
Discretization:

$$\Delta = 1/N: \text{ step} = 1/\text{NBIN}$$

$$x_i = (i+0.5)\Delta \ (i=0,...,N-1)$$

$$\sum_{i=0}^{N-1} \frac{4}{2}\Delta \cong \pi$$

```
#include <stdio.h>
#define NBIN 100000
void main() {
   int i; double step,x,sum=0.0,pi;
   step = 1.0/NBIN;
   for (i=0; i<NBIN; i++) {
      x = (i+0.5)*step;
      sum += 4.0/(1.0+x*x);}
   pi = sum*step;
   printf("PI = %f\n",pi);
}</pre>
```



```
#include <stdio.h>
#include <stdlib.h>
                        /* MPI header file */
#include <mpi.h>
#include <omp.h>
                            /* OpenMP header file */
#define NUM STEPS 100000000
#define MAX THREADS 4
int main(int argc, char *argv[]) {
  int nprocs, myid:
  int tid, nthreads, nbin;
  double start time, end time;
  double pi, Psum=0.0, sum[MAX_THREADS]={0.0};
  double step = 1.0/(double) NUM STEPS;
  /* initialize for MPI */
 MPI Init(&argc, &argv);
                           /* starts MPI */
  /* get number of processes */
  MPI Comm size(MPI COMM WORLD, &nprocs);
  /* get this process's number (ranges from 0 to nprocs - 1) */
  MPI Comm rank(MPI COMM WORLD, &myid);
 nbin= NUM STEPS/nprocs;
```

Hybrid Programming Example

```
#pragma omp parallel private(tid)
     int i:
     double x:
     nthreads=omp get num threads();
     tid=omp get thread num();
     for (i=nbin*myid+tid; i < nbin*(myid+1); i+= nthreads) { /* changed*/
       x = (i+0.5)*step;
       sum[tid] += 4.0/(1.0+x*x);
for(tid=0; tid<nthreads; tid++) /*sum by each mpi process*/
     Psum += sum[tid]*step;
MPI Reduce(&Psum, &pi, 1, MPI DOUBLE, MPI SUM, 0, MPI COMM WORLD):/* added */
  if (myid == 0) {
    printf("parallel program results with %d processes:\n", nprocs);
    printf("pi = %g (%17.15f)\n",pi, pi);
  MPI Finalize():
  return 0;
```

Results

MPI

```
MPI uses 8 processes:
pi = 3.14159 (3.141592653589828)
```

OpenMP

```
OpenMP uses 8 threads:
pi = 3.14159 (3.141592653589882)
```

· Hybrid

```
mpi process 0 uses 4 threads
mpi process 1 uses 4 threads
mpi process 1 sum is 1.287 (1.287002217586605)
mpi process 0 sum is 1.85459 (1.854590436003132)
Total MPI processes are 2
pi = 3.14159 (3.141592653589738)
```



Thank you for your attention!

