System calls for managing POSIX shared memory.

• Step 1: create a shared memory segment. Only one process needs to do create the shared memory segment, but every process that wishes to access it must open it.

```
#include <sys/mman.h>
#include <sys/stat.h>
#include <fcntl.h>
int shm_open (const char * name, int oflag, int mode);
```

Returns a handle (called a file descriptor) to the shared memory segment on success and -1 on error. Must link the program with the real-time library (-lrt) when compiling.

- **name** the name of the shared memory segment. It must be unique to the system, and must start with a '/' character.
- oflag the open flags. Bit-wise or (the '|' operator) one or more of the following: O_RDWR (read/write), O_CREAT (create segment if it doesn't exist), O_TRUNC (delete segment if it does exist). See the man page for shm_open¹ for available flags.
- mode The access permissions for the segment. Use pre-defined constant S_IRWXU (give process User Read, Write and eXecute permission to the segment). See stat.h man page for a full list of available flags.
- Step 2: Set the size of a shared memory segment. Only one process needs to do this, and it is usually done by the process that created the segment.

```
#include <unistd.h>
#include <sys/types.h>
int ftruncate (int fd, unsigned int length);
Returns 0 on success and -1 on error.
fd The file descriptor returned by shm_open().
```

length The desired size of the segment in bytes.

¹Type "man shm_open" at the command line prompt.

• Step 3: Map a shared memory segment into a process's address space. Every process that wishes to use the shared memory segment must do this.

```
#include <sys/mman.h>
void *mmap (void *addr, unsigned int length, int protection,
int flags, int fd, unsigned int offset);
```

Returns address of memory segment in calling process's address space, or (void *) -1 on error.

- addr The address in the process's address space to use for the mapping. Use NULL to let kernel assign address (recommended).
- **length** The size of the shared segment. Use the same size as you used when you created the segment or weird things will happen.
- **protection** What the process is allowed to do to the memory. Bit-wise or of PROT_EXEC, PROT_READ, and PROT_WRITE. Use the same permissions you specified when you created the segment.

flags Use MAP_SHARED.

- fd The file descriptor of the shared memory to map. Use the value returned by shm_open().
- **offset** The distance from the beginning of the shared memory segment to map. Use 0.
- Step 4: Unmap a previously mapped shared memory segment. Every process that has mmap()ed the shared memory segment needs to do this.

```
#include <sys/mman.h>
int munmap (int fd, unsigned int length);
Returns 0 on success, or -1 on error.
```

- fd The file descriptor of the shared memory segment.
- fd The length of the shared memory segment. Use the value you specified when it was mapped with mmap().
- Step 5: Remove reference to a shared memory segment and, if this is the last reference, delete it. Every process that has shm_open()ed the segment needs to do this.

```
#include <sys/mman.h>
int shm_unlink (int fd);
```

Link with -lrt. Returns 0 on success and -1 on error.

fd The file descriptor of a shared memory segment returned by shm_open().

Types and library calls for declaring and using POSIX semaphores. Link with -lpthread. You must #include <semaphore.h> to use semaphores. Semaphore.h defines the semaphore type sem_t.

• int sem_init (sem_t *sem, int pshared, unsigned int value); Initialize a semaphore. Returns 0 on success, -1 on error.

sem A pointer to a semaphore.

pshared Is this semaphore to be shared by different threads (0) or by different processes (1).

value The initial value of the semaphore.

• int sem_post (sem_t *sem);

Atomically increment the semaphore. This is the signal() or P() operation. Returns 0 on success, -1 on error.

sem A pointer to a previously initialized semaphore.

• int sem_wait (sem_t *sem);

Atomically wait for a semaphore to have a positive value and then decrement it. This is the wait() or V() operation. Returns 0 on success, -1 on error.

sem A pointer to a previously initialized semaphore.