

Eigenvalue and Eigenvector

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Abstract

This is the note made by Len Fu during his learning progress in BIT. The main content is from *Linear Algebra Done Right* and *Linear Algebra Allenby*.

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1 Eigenvalue and Eigenvector of the Matrix

1.1 Basis

Definition 1.1. Set A as a $n \times n$ square, if there exists a number λ and n – *nonzero* vector X , satisfying

$$AX = \lambda X \text{ or } (\lambda I - A)X = 0$$

then we say that λ is an eigenvalue of A , and X is an eigenvector of A with eigenvalue λ .

Note.

1. Only squares have eigenvectors and eigenvalues.
2. Eigenvector must be nonvector and eigenvalue can be zero.

Definition 1.2. $(\lambda I - A)$ is the eigenmatrix of A . $|\lambda I - A|$ is the eigenpolynomial of A . $|\lambda I - A| = 0$ is the eigenequation of the matrix A .

Then the eigenvector of A with eigenvalue λ is the combination of the solution vectors of $(\lambda I - A)X = 0$.

Since $(\lambda I - A)X = 0$ and X is nonzero vector, then $\det(\lambda I - A)$ should be zero to ensure X is nonzero vector of the solution.

Consider the solution of $(\lambda I - A)X = 0$. The characteristic polynomial of A is

$$b_n \lambda^n + b_{n-1} \lambda^{n-1} + \cdots + b_1 \lambda + b_0.$$

To solve the polynomial,

$$\begin{vmatrix} \lambda - a_{11} & -a_{12} & \cdots & -a_{1n} \\ -a_{21} & \lambda - a_{22} & \cdots & -a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ -a_{n1} & -a_{n2} & \cdots & \lambda - a_{nn} \end{vmatrix} \\ = b_n \lambda^n + b_{n-1} \lambda^{n-1} + \cdots + b_1 \lambda + b_0$$

Consider the expansion of the determinant, except for

$$(\lambda - a_{11})(\lambda - a_{22}) \cdots (\lambda - a_{nn})$$

other terms' highest order of λ is $n - 2$. Then the coefficients

$$\begin{cases} b_n = 1 \\ b_{n-1} = -(a_{11} + a_{22} + \cdots + a_{nn}) = \text{tr}() \end{cases}$$

And we divide the determinant into two parts and one is

$$\begin{vmatrix} -a_{11} & -a_{12} & \cdots & -a_{1n} \\ -a_{21} & \lambda - a_{22} & \cdots & -a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ -a_{n1} & -a_{n2} & \cdots & \lambda - a_{nn} \end{vmatrix}$$

the other one doesn't contribute to the b_0 , thus

$$b_0 = (-1)^n |A|.$$

From the polynomial theorem,

$$f(\lambda) = (\lambda - \lambda_1)(\lambda - \lambda_2) \cdots (\lambda - \lambda_n) = 0.$$

Then

$$b_0 = (-1)^n \lambda_1 \lambda_2 \cdots \lambda_n \quad b_{n-1} = -(\lambda_1 + \lambda_2 + \cdots + \lambda_n)$$

And there are some properties of the **Eigenvalue and Eigenvector**.

Properties 1.1. 1. $|A| = \lambda_1 \lambda_2 \cdots \lambda_n$.

2. $\text{tr} A = \sum_{i=1}^n \lambda_i$

3. If X_1, X_2, \dots, X_s are eigenvectors of A that belong to eigenvalue λ_0 , then the linear combination of X_1, X_2, \dots, X_s is also an eigenvector of A that belongs to eigenvalue λ_0 . And all eigenvectors plus zero vector forms an **eigenspace** of A with eigenvalue λ_0 , denoted as V_{λ_0} and it's a solution space of $(\lambda_0 I - A)X = 0$.

Properties 1.2. If λ is an eigenvalue of A with eigenvector X , then we have

1. $k\lambda$ is the eigenvalue of kA .
2. λ^m is the eigenvalue of A^m ($m \in \mathbb{N}^*$).
3. $f(\lambda)$ is the eigenvalue of $f(A)$ if f is a polynomial transformation.
4. When A is invertible, λ^{-1} is the eigenvalue of A^{-1}

And X is the eigenvector of matrices above with corresponding eigenvalue.

Properties 1.3. The matrix A and A^T have the same **spectrum**.

1.2 Algebraic Multiplicity and Geometric Multiplicity

Definition 1.3 (Geometric Multiplicity). As for the eigenvalue λ_i of A , its all eigenvectors are the nonzero-solutions of the equation $(\lambda_i I - A)X = 0$. Thus the number of independent eigenvectors of A with eigenvalues λ_i is no more

than $n - \text{rank}(\lambda_i I - A)$. The number is the dimension of the eigenspace V_{λ_i} and the number of the solution vectors of the fundamental system of solutions of A . We call this number as the **geometric multiplicity** of λ_i , equals to

$$q_i = n - \text{rank}(\lambda_i I - A), \quad i = 1, 2, \dots, s.$$

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Definition 1.4 (Algebraic Multiplicity). From the theorem of the polynomial, n-square A on \mathbb{C} can be divided

$$f_A(\lambda) = (\lambda - \lambda_1)^{p_1} (\lambda - \lambda_2)^{p_2} \dots (\lambda - \lambda_s)^{p_s}$$

where $\lambda_1, \lambda_2, \dots, \lambda_s$ are all distinct eigenvalues of A . We call p_i the **algebraic multiplicity** of λ_i .

Theorem 1.1. *The geometric multiplicity of any eigenvalue λ_i of A is not larger than the algebraic multiplicity of λ_i .*

Proof. Set

$$X_{i1}, X_{i2}, \dots, X_{iq}$$

as a basis of the eigenspace V_{λ_i} , we extend it into a basis of \mathbb{C}^n :

$$X_{i1}, X_{i2}, \dots, X_{iq}, Y_1, Y_2, \dots, Y_{n-q_i},$$

then we have

$$\begin{aligned} & A[X_{i1}, X_{i2}, \dots, X_{iq}, Y_1, Y_2, \dots, Y_{n-q_i}] \\ &= [\lambda_i X_{i1}, \lambda_i X_{i2}, \dots, \lambda_i X_{iq}, AY_1, AY_2, \dots, AY_{n-q_i}] \\ &= [X_{i1}, X_{i2}, \dots, X_{iq}, Y_1, Y_2, \dots, Y_{n-q_i}] \begin{bmatrix} \lambda_i I_{q_i} & * \\ 0 & A_1 \end{bmatrix} \end{aligned}$$

where A_1 is $n - q_i$ square. Now set

$$P = [X_{i1}, X_{i2}, \dots, X_{iq}, Y_1, Y_2, \dots, Y_{n-q_i}],$$

obviously P is invertible. Then

□

2 Similarity of the Matrix

2.1 Basis

Definition 2.1. Set $A, B \in C^{n \times n}$. If there exists an n -order invertible matrix P such that

$$P^{-1}AP = B$$

, we say that A and B are similar, denoted as $A \sim B$, and P is called the *similarity transformation* from A to B .

Properties 2.1 (Reflectivity). $A \sim A$.

Properties 2.2 (Symmetry). If $A \sim B$, then $B \sim A$.

Properties 2.3 (Transitivity). If $A \sim B$ and $B \sim C$, then $A \sim C$.

Properties 2.4. 1. $P^{-1}(A_1 + A_2 + \cdots + A_n)P = P^{-1}A_1P + P^{-1}A_2P + \cdots + P^{-1}A_nP = P^{-1}\sum_{i=1}^n A_iP$.

2. $P^{-1}(kA)P = kP^{-1}AP$.

2.2 Conditions of Similar Digonalizablity

Definition 2.2 (Digonalizable). If there exists an invertible matrix P such that

$$P^{-1}AP = D$$

where A is a square and D is a diagonal matrix. Then A is called *diagonalizable*.

Theorem 2.1 (NS Condition). *A n -square A is similar diagonalizable if and only if A has n linear independent eigenvectors.*

Proof.

$$P^{-1}AP = \text{diag}(\lambda_1, \lambda_2, \cdots, \lambda_n)$$

$$AP = P\text{diag}(\lambda_1, \lambda_2, \cdots, \lambda_n)$$

Now set $P = [X_1, X_2, \cdots, X_n]$, and

$$[AX_1, AX_2, \cdots, AX_n] = [\lambda_1 X_1, \lambda_2 X_2, \cdots, \lambda_n X_n]$$

then we have

$$(A - \lambda_i)X_i = 0, \text{ for } i = 1, 2, \cdots, n.$$

Since P is invertible, we can find n linear irrelative vectors X_1, X_2, \cdots, X_n . And X_1, X_2, \cdots, X_n are n linear irrelative eigenvectors of A and $\lambda_1, \lambda_2, \cdots, \lambda_n$ are eigenvalues of A .

Inversely, if A has n linear irrelative eigenvectors X_1, X_2, \dots, X_n with eigenvalues $\lambda_1, \lambda_2, \dots, \lambda_n$, satisfying that

$$AX_i = \lambda_i X_i, \text{ for } i = 1, 2, \dots, n.$$

Set $P = [X_1, X_2, \dots, X_n]$ and obviously P is invertible, and

$$P^{-1}AP = \text{diag} \lambda_1, \lambda_2, \dots, \lambda_n$$

which reveals that A is similar diagonalizable. □

Note.

1. The similar transformation matrix P is not unique.
2. The order of X_1, X_2, \dots, X_n changes as the order of $\lambda_1, \lambda_2, \dots, \lambda_n$ changes.

Theorem 2.2. *The eigenvectors of A with different eigenvalues are linearly independent.*

Proof. Set $\lambda_1, \lambda_2, \dots, \lambda_m$ are non-equal eigenvalues of A , X_1, X_2, \dots, X_m are eigenvectors of A with eigenvalues $\lambda_1, \lambda_2, \dots, \lambda_m$, then

$$AX_i = \lambda_i X_i \text{ for } i = 1, 2, \dots, m.$$

Now I use the mathematical induction to prove the above statement.

Base Case: $m=1$ Since $X_1 \neq 0$, X_1 is linear independent.

Inductive Hypothesis: $m=k-1$ Suppose the statement is true for $m = k - 1$.

Inductive Step: $m=k$ Consider the condition that $m = k$,

$$k_1 X_1 + k_2 X_2 + \dots + k_m X_m = 0$$

Then we left multiply A , we get

$$k_1 AX_1 + k_2 AX_2 + \dots + k_m AX_m = 0.$$

Since $AX_i = \lambda_i X_i$, we get

$$k_1 \lambda_1 X_1 + k_2 \lambda_2 X_2 + \dots + k_m \lambda_m X_m = 0.$$

We multiply λ_m on the first equation and we get

$$k_1 \lambda_m X_1 + k_2 \lambda_2 X_2 + \dots + k_m \lambda_m X_m = 0.$$

Then

$$k_1 (\lambda_1 - \lambda_m) X_1 + k_2 (\lambda_2 - \lambda_m) X_2 + \dots + k_{m-1} (\lambda_{m-1} - \lambda_m) X_{m-1} = 0,$$

and since $\lambda_i \neq \lambda_j$ and X_1, X_2, \dots, X_{m-1} are linearly independent, then

$$k_i = 0 \quad i = 1, 2, \dots, m-1.$$

Correspondingly, $k_m = 0$.

Thus $k_1, k_2, \dots, k_m = 0$, which reveals that X_1, X_2, \dots, X_m are linearly independent. \square

Corollary 2.2.1. *If n -square A has n distinct eigenvalues, then A can be similar diagonalizable.*

Theorem 2.3. *Set $\lambda_1, \lambda_2, \dots, \lambda_n$ are distinct eigenvalues of A , $X_{i1}, X_{i2}, \dots, X_{il_i}$ are linear independent eigenvectors of A belonging to eigenvalue $\lambda_i, i = 1, 2, \dots, m$, then the vector set of $X_{11}, X_{12}, \dots, X_{1l_1}, \dots, X_{m1}, X_{m2}, \dots, X_{ml_l}$ is linear independent.*

Theorem 2.4 (NS Condition). *Set $\lambda_1, \lambda_2, \dots, \lambda_n$ are distinct eigenvalues of A , p_i and q_i are the algebraic multiplicity and geometric multiplicity of λ_i respectively. Then A can be similar diagonalizable if and only if*

$$p_i = q_i \quad i = 1, 2, \dots, s.$$

3 Jordan Canonical Form

4 Exercise

Exercise 4.1. The eigenvalues of A are 1, 2, 3, find the eigenvalues of $A^2 - 2I$.

Solution 4.1.1. We know that $A \sim \text{diag}(1, 2, 3)$ and then $A^2 \sim \text{diag}(1, 4, 9)$. Then $(A^2 - 2I) \sim (\text{diag}(1, 4, 9) - 2I) = \text{diag}(-1, 2, 7)$, then the eigenvalues of $A^2 - 2I$ are $-1, 2, 7$.

Exercise 4.2. Solve the maxima of the

$$f(x_1, x_2) = 2x_1^2 + 2x_1x_2 + 2x_2^2$$

under the constraint $x_1^2 + x_2^2 = 1$ using **Lagrange Multipliers**.

Solution 4.2.1. Using Lagrange Multipliers,

$$L(x_1, x_2) = 2x_1^2 + 2x_1x_2 + 2x_2^2 - \lambda(x_1^2 + x_2^2 - 1)$$

and