imec

IOT PROJECT PRESENTATION

THOMAS JANSSEN

LIAM OORTS

LENNERT VAN HASSELT

JONAS VERCAUTEREN

imec
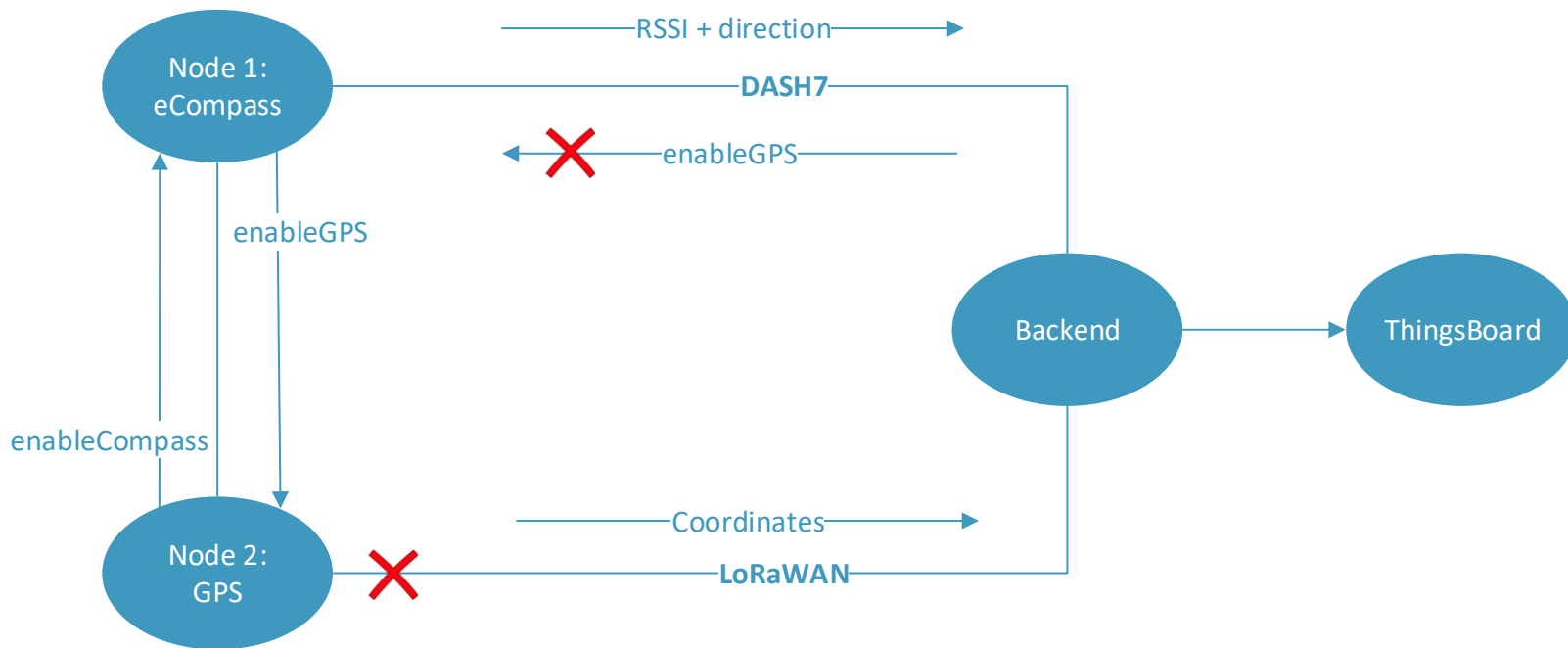
CONTENTS
MONITORING RUNAWAY BEHAVIOR

- Overview
- Planning
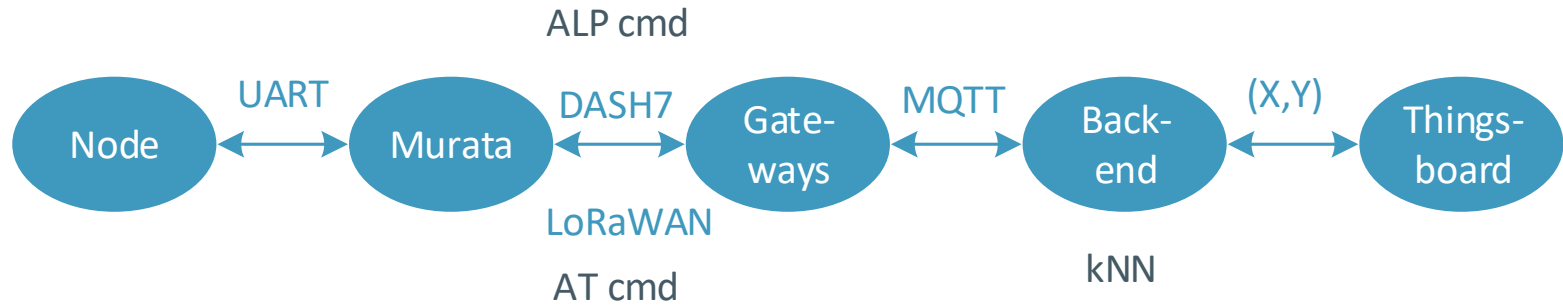- Future work
- Power measurements
- Result: demo

imec

OVERVIEW
DATA FLOW

Node 1: eCompass

RSSI + direction

DASH7

enableGPS

enableGPS

enableCompass

Node 2: GPS

Coordinates

LoRaWAN

Backend

ThingsBoard

imec

OVERVIEW
COMMUNICATION

SCHEDULE

1. ## GPS module (Jonas)

   - Soldering
   - Configuration (GPGGA, each 60s)
   - Converting coordinates
   - Enable if out of safe zone (input eCompass)
   - Disable if in safe zone (re-enable eCompass)
   - Low Power Sleep mode → GPS off
   - TB: longitude, latitude, HDOP
   - STM32 HAL & Mbed

imec

SCHEDULE

2. eCompass (Jonas & Liam)
   - Accelerometer (used as gyroscoop): x/y/z → angles
   - Magnetometer: x/y/z → angles
   - Sensor fusion: accelerometer + magnetometer → Tilt-compensated compass
   - Calibration: hard iron + soft iron (first 30s)
   - Mbed
   - TB: direction
   - Configuration:
     - Magnetometer: single mode, low power mode, interrupt
     - Accelerometer: low power mode, DRDY interrupt
     - Ticker: timer of 1s activating sensors
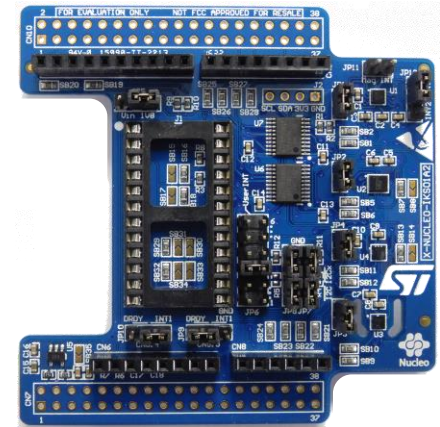
SCHEDULE

3. Fingerprinting (Liam & Thomas)
   - DASH7 fingerprinting database
     - 30 training points
     - 6 measurements per point
     - 4 different gateways

   - Weighted kNN
     - k = 6 optimal
     - Weight function: Distance → RSSI and direction (sensor fusion)

   - TB: X, Y

imec
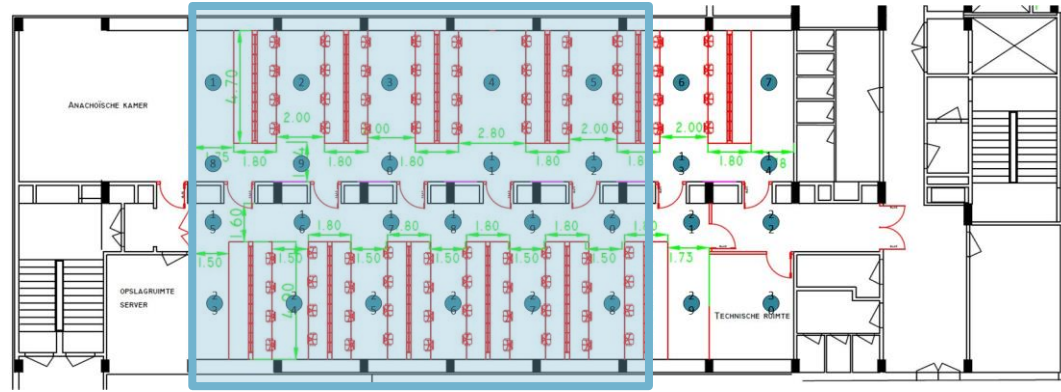
4. LoRaWAN (Lennert)

- I- Cube lrwan extension
  - AT – SLAVE
  - Hardcoded LoRaWan Keys
  - SetDevEUI function

- AT Commands Through UART

- Problem with UART

SCHEDULE

5. DASH7 (Liam & Thomas)
   - Uplink
     - ALP cmd: Return file data action, QoS = 0, multicast, AC = 0x01, file id = 40
     - Data: direction
     - Gateways send RSSI to MQTT broker

   - Downlink
     - Sending ALP command works, receiving the command does not work
     - GPS enable: via button

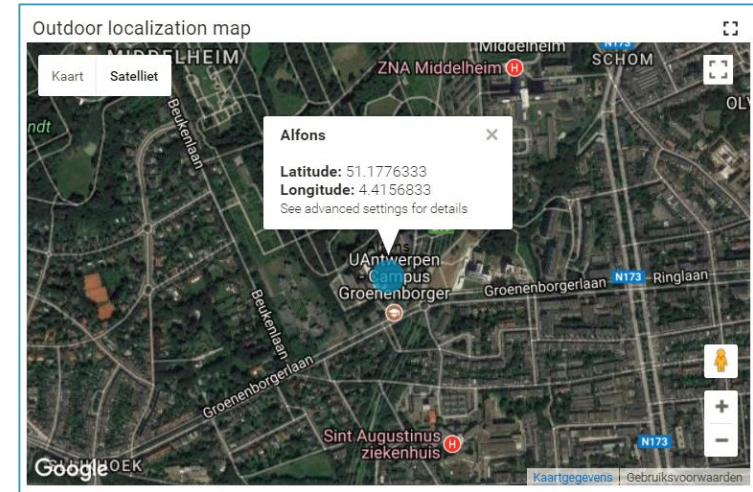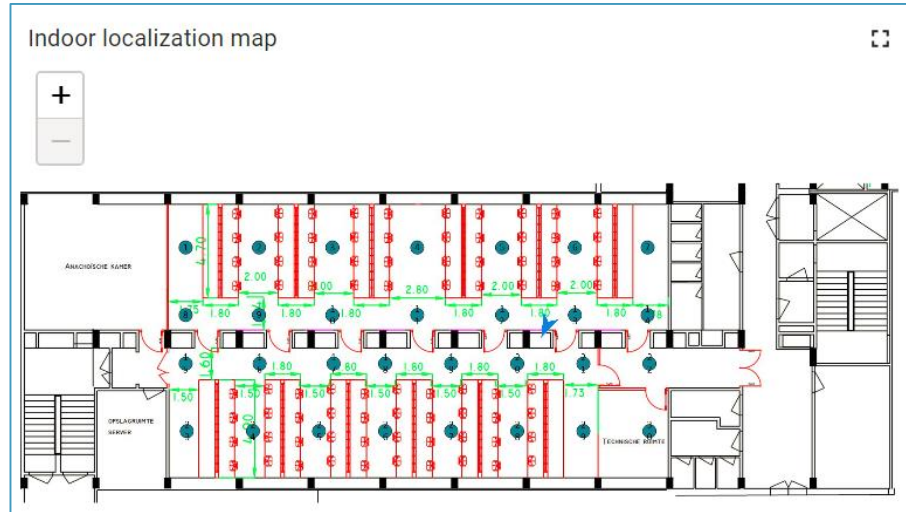   - Disable node if GPS enabled

SCHEDULE

6. Backend & TB (Liam & Thomas)

- Backend
  - Backend.py runs on Ubuntu
  - Fingerprinting-algorithm
  - Processing data of MQTT broker
  - Pub-sub: /tb and /loriot
  - Out of safezone → alarm

- ThingsBoard
  - JSON: X, Y, direction, latitude, longitude, HDOP
  - Widgets: JavaScript

Indoor localization map

Outdoor localization map

Kaart | Satelliet

Alfons ×

Latitude: 51.1776333
Longitude: 4.4156833
See advanced settings for details

imec

FUTURE WORK

- Not realized
  - DASH7 downlink receive
  - LoRaWAN UART send

- Extensions
  - Barometer → sensor fusion + fall detection
  - Alarm button
  - NFC configuratie en proximity
  - Notification system (e.g. Dinner is ready!)
  - PIR sensor motion detection

imec

POWER MEASUREMENTS
LPM01A

- LPM01A-board + STM32 cube monitor power
  - eCompass:
    - Calibration: 32 mA (30s)
    - Sleep between interrupts: 25 mA
    - DASH7 uplink: 29 mA
    - Press button to enable GPS and disable board: 32 mA

  - GPS
    - Nucleo low power sleep with GPS off: 2.4 mA
    - LoRaWAN message: 41 mA peak

STM32 Power Shield
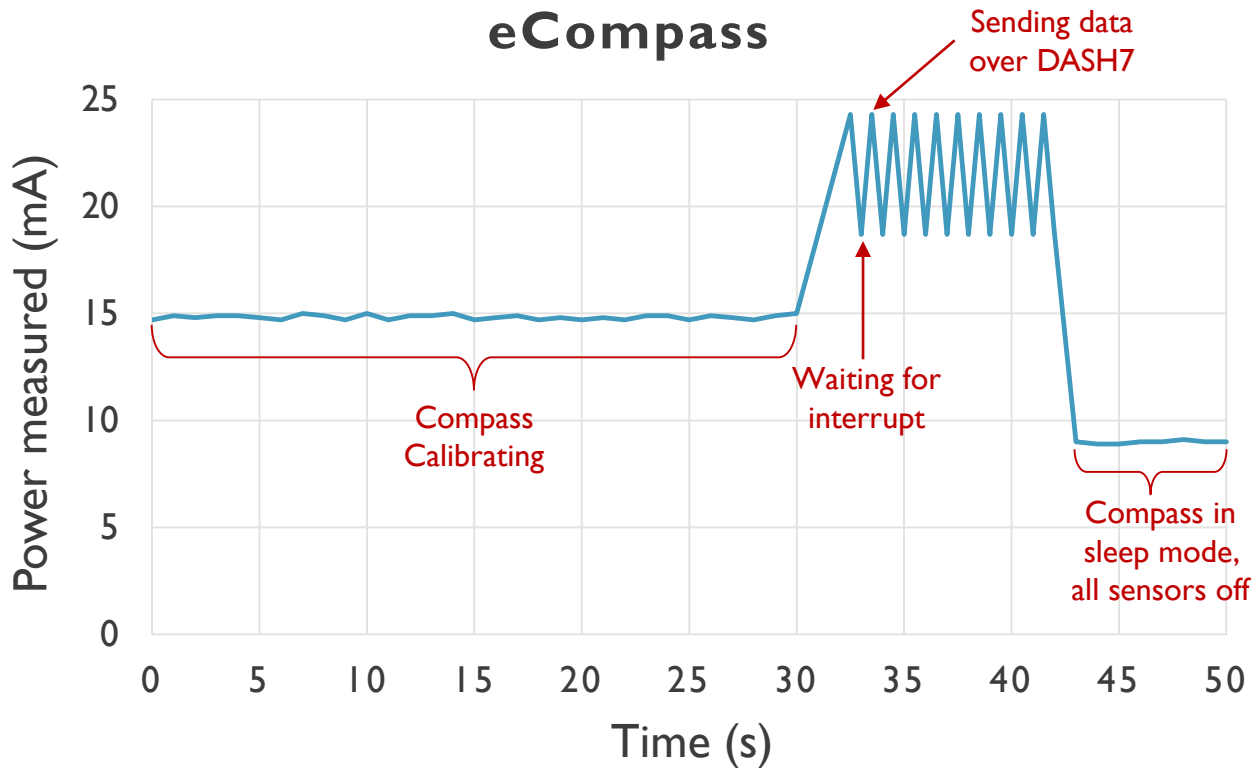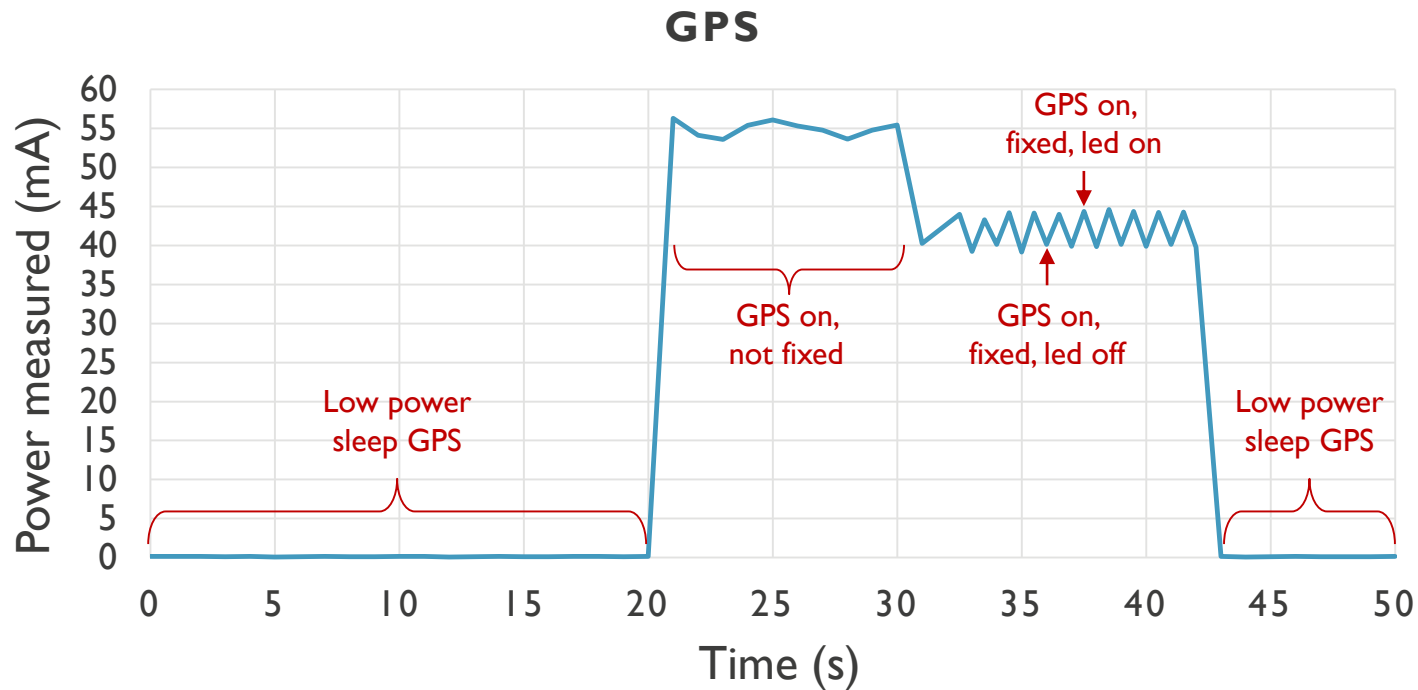Accurate power measurement

STM32 CubeMonitor-Power

imec

POWER MEASUREMENTS
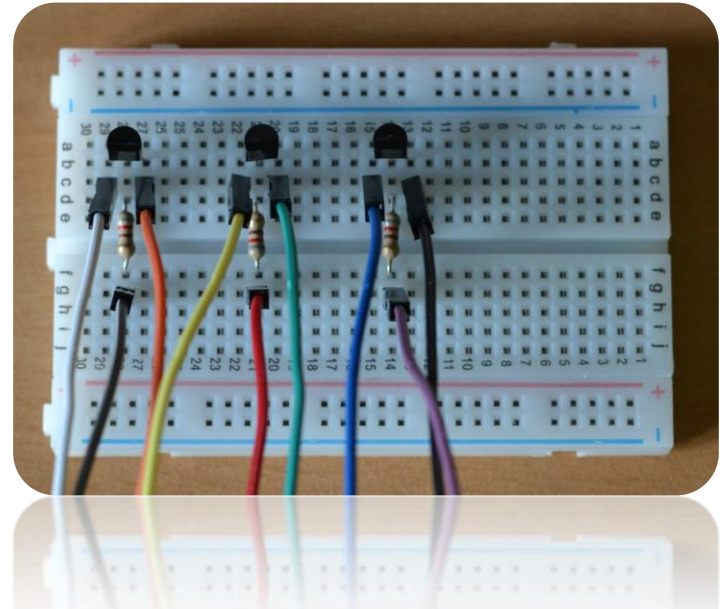## MULTIMETER

eCompass

POWER MEASUREMENTS
MULTIMETER

POWER MEASUREMENTS
LOW POWER ACTIONS

- Solder bridge SB18 of B-L072Z-LRWAN1 opened → LED 7 off
- Transistors used for
  - GPS
  - Discovery board: B-L072Z-LRWAN1 (DASH7)
  - Discovery board: B-L072Z-LRWAN1 (LoRaWAN)

imec

imec

embracing a better life

imec

RESULT: DEMO