

# Logic Programming

Rodica Potolea  
Camelia Lemnaru

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Computer Science

# Agenda

- More built in predicates (and relationship to graphs)
  - findall and more
- Constructs and relationship with graphs
  - For all is true
  - Application – same graph
- Search for a path in graphs
  - Dfs
  - Bfs (and other bfs – next time)

# Built-in predicates

## their utility in graph searching

- `findall` – selects all items (and only those items) with a certain property from a knowledgebase
- Knowing the predicate to use it appropriately
- Knowing HOW is implemented
  - to utilize the strategy in graph problems

# findall

(example from Clocksin and Mellish)

- Suppose we have a knowledge base of some drinks lovers:

```
//likes/2
```

```
//likes(person,drink_person_likes).
```

```
likes(bill,wine).
```

```
likes(dick,beer).
```

```
likes(harry,beer).
```

```
likes(john,beer).
```

```
likes(peter,wine).
```

```
likes(tom,beer).
```

```
?-findall(X,likes(X,beer),L).
```

```
Yes, L=[dick,harry,john,tom].
```

# findall – implementation

```
//findall/3
//findall(collected_var, collector_predicate, collector_var).

findall(X,G,_):-
    asserta(found(end)), // uses an auxiliary knowledge base (akb)
    G, // marker for the bottom of the akb
    // = call(G), G is a predicate; its exe instantiates
    // some argument X.
    asserta(found(X)), // puts G's instantiated argument on top of akb
    fail. // request for backtrack to G.
findall(_,_,L):- // reach here when G fails on backtrack
    collect_found([],L). // starts collecting from the akb, initializing the partial
    // result to empty list.

collect_found(P,L):-
    get_next(X),!, // asks for one element in akb; X hidden; known AFTER call
    collect_found([X|P],L). // adds it in front and go recurse
collect_found(L,L).

get_next(X):-
    retract(found(X)),!, // extracts from top of the akb
    X=/_end. // succeeds if a genuine data; fails when get to end.
```

# findall – implementation

```
//findall/3
//findall(collected_var, collector_predicate, collector_var).

findall(X,G,_):-
    asserta(found(end)),
    G,
    asserta(found(X)),
    fail.
findall(_,_,L):-
    collect_found([],L).

collect_found(P,L):-
    get_next(X),!,
    collect_found([X|P],L).
collect_found(L,L).

get_next(X):-
    retract(found(X)),!,
    X/=end.
```

# findall – execution

```
findall(X,G,_):-
    asserta(found(end)),
    G,
    asserta(found(X)),
    fail.
findall(_,_,L):-
    collect_found([],L).
```

```
collect_found(P,L):-
    get_next(X),!,
```

```
    collect_found([X|P],L) .//created bottom-up↑
```

```
collect_found(L,L).
```

```
get_next(X):-
```

```
    retract(found(X)),!,
```

```
    X/=end.
```

## //initial kb

```
likes(bill,wine).
likes(dick,beer).
likes(harry,beer).
likes(john,beer).
likes(peter,wine).
likes(tom,beer).
```

## //akb

```
found(tom).
found(john).
found(harry).
found(dick).
found(end).
```

collected top-down↓

# findall – related

- **General call:** `?-findall(X,G,L)`  
 where X is a variable  
 G a predicate and X occurs in G  
 L would collect all X's so that G's execution succeeds on X
- Creates the list of X's that satisfy G, in the order of occurrence in the original knowledge base
- Associate predicates:
- `setof(X,G,S)`
- Creates the set of terms (standard order, without duplicates; represented also as list) of X's that satisfy G. If none, fails.
- Differences to `findall`:
  - Order: standard vs as found in the knowledge base
  - Duplicates: no vs found in the knowledge base
  - No term: fails vs empty list
- `bagof(X,G,S)`
  - Same as `setof` BUT list NOT ordered + may have duplicates
  - So same as `findall` but fails if no term matches

`findall(X,G,L):-bagof(X,G,L),!.`

`findall(_,_,[])`



# For all is true technique

- Construct to check if `for_all Predicate1  
is_true Predicate2`
- Aims to identify/verify whether in all cases when P1 is true, P2 is true as well. Thus, checks  $P1 \Rightarrow P2$ .
- Template looks like: `for_all_is_true(X,Y):-`

```

X,
not(Y) , !,
fail.

```

```

for_all_is_true(_, _).

```

```

for_all_is_true(X,Y):-

```

```

X,           //calls X, a predicate, whose execution may instantiate hidden args
not(Y) , !,  //calls Y in the same context. If succeeds, its negation fails,
             //and backtracks to X who is executed again, with a new instance of args
fail.        //the first context of X where Y fails, not(Y) succeeds, and ! is
             //irreversible crossed and the predicate fails overall.

```

```

for_all_is_true(_, _). //if we reached here, in all contexts when X holds true, Y
                        //succeeds as well, therefore,  $X \Rightarrow Y$ 

```

# For all is true in graph context

- Given graphs G1 and G2 with neighbor and edge representations respectively, do they represent the same graph?

**G1**

neighbor(Node, List\_of\_Neighbors)

- G1 and G2 same means  $G1 \Leftrightarrow G2$  which is  $(G1 \Rightarrow G2) + (G2 \Rightarrow G1)$

for\_all edges\_in\_G1

is\_true edge\_in\_G2

**G2**

edge(Node1, Node2)

$(G2 \Rightarrow G1)$

for\_all edges\_in\_G2

is\_true edge\_in\_G1

- Define the edges in the 2 representations:

**An edge in G1:**

```
is_edge_1(X, Y) :- //to find all edges in G1, call is nondeterminist (X,Y, free)
    neighbor(X, L) , //finds first pair first (and next on backtrack), instantiates both X and L.
    member(Y, L) . //nondeterm call on member; instantiate Y, one at a time, eventually all.
```

**An edge in G2:**

```
is_edge_2(X, Y) :-
    edge(X, Y) ;
    edge(Y, X) .
```

# Same graph?

- $(G1 \Rightarrow G2)$   $(G2 \Rightarrow G1)$   
`for_all edges_in_G1` `for_all edges_in_G2`  
`is_true edge_in_G2` `is_true edge_in_G1`
- Denote the `for_all_is_true` as `eq1` and `eq2` depending on the implication  $(G1 \Rightarrow G2)$  respectively  $(G2 \Rightarrow G1)$  we verify

`eq1:-`

```
is_edge_1(X,Y),           //for each edge in the first representation
not(is_edge_2(X,Y)),!,    //there is one edge in the other graph
fail.                     //otherwise we reach here, hence, fail.
```

`eq1. //when we get here,  $G1 \Rightarrow G2$  shown`

`eq2:-`

```
is_edge_2(X,Y),
not(is_edge_1(X,Y)),!,
fail.
```

`eq2.`

`same_graph:-eq1,eq2.`

# Change representation of a graph

- Given graph **G1** a weighted, edge representation and we need to get **G2** with neighbor representation

**G1**

`edge(a, b, 15) .`

`gen_graph2:-`

```
    is_edge(X, _, _),
    not(neighbor(X, L)),
    findall(Z, succ(X, Z), L),
    assertz(neighbor(X, L)),
    fail.
```

`gen_graph2.`

`succ(X, Z):-`

```
    is_edge(X, Y, W),
    Z=p(Y, W) .
```

**G2**

`neighbor(a, [p(b, 15), ...]) .`

- Note:**

`findall(Z, succ(X, Z), L)` same as `findall(p(Y, W), is_edge(X, Y, W), L) .`

- Given **G2**, generate **G1**. Homework.

# Depth first search

- Assume undirected, unweighted graph, edge representation
- 2 stage process: (1) make the trail placing in a queue the vertices in order of visitation (being in the additional knowledge base `vert` (hence a dynamic predicate) is as if we have the vertex colored grey). (2) when done, collect them.

```
df_search(X,_) :-
```

```
    assertz(vert(X)) , //place start/current node in Q
```

```
    is_edge(X,Y) , //take first/next neighbor of current
```

```
    not(vert(Y)) , //if already visited, backtrack to take another; if not, continue from Y
```

```
    df_serach(Y,_) .
```

```
df_search(_,L) :-
```

```
    assertz(vert(end)) ,
```

```
    collect([],L) .//similar to collect in findall, but on vert akb.
```

- It is covering just the connected component of the starting vertex (is similar to `dfs_visit` in Cormen). Need a wrapper to re-run it from all connected components.

# Breadth first search

- Assume undirected, unweighted graph, edge representation
- queue made by the akb named `node` (hence dynamic predicate)

```
bf_search(X,_) :-
```

```
    assertz(node(X)) , //add at the end of the Q the current node
```

```
    node(Y) , //reads from front of Q (first time is first=X=ONLY one in Q) current Y (gets Y instantiated)
```

```
    is_edge(Y,Z) , //take first/next neighbor of current Y (gets Z instantiated); if none, backtrack and take next from Q
```

```
    not(node(Z)) , //if Z already visited, backtrack to take another;
```

```
    assertz(node(Z)) , // if not, put Z in Q and
```

```
    fail. // backtrack anyway to another neighbor of Y
```

```
bf_search(_,L) :-
```

```
    assertz(node(end)) ,
```

```
    collect([],L) . //similar to collect in findall, but on node akb.
```

- There is an issue with this implementation for some languages/versions (due to an optimization). Oral explanation. Fix it! Homework.