Example 6-01 Evaluating components

```
{\theta, \varphi}::Coordinate.
{a,b,c,d,e,f,g,h#}::Indices(values={\theta, \varphi}, position=independent).

/partial{#}::PartialDerivative.

V := { V_{\theta} = \varphi, V_{\varphi} = \sin(\theta) }. # cdb(ex-06.100,V)
dV := \partial_{b}{V_{a}} - \partial_{a}{V_{b}}. # cdb(ex-06.101,dV)

evaluate (dV, V) # cdb(ex-06.102,dV)
```

$$V_a = [V_\theta = \varphi, \ V_\varphi = \sin \theta] \tag{ex-06.100}$$

$$\partial_b V_a - \partial_a V_b = \Box_{ab} \begin{cases} \Box_{\varphi\theta} = \cos\theta - 1\\ \Box_{\theta\varphi} = -\cos\theta + 1 \end{cases}$$
 (ex-06.102)

Example 6-02 Riemann tensor of a 2-sphere

```
{\theta, \varphi}::Coordinate.
     {a,b,c,d,e,f,g,h#}::Indices(values={\theta, \varphi}, position=independent).
     \partial{#}::PartialDerivative.
     Gamma := Gamma^{a}_{b} c   -> 1/2 g^{a}    ( \qquad partial_{b}_{g_{d}} c)
                                                  + \partial_{c}{g_{b d}}
                                                  - \partial_{d}{g_{b c}}).
9
     Rabcd := R^{a}_{b c d} \rightarrow \operatorname{lal}_{c}\operatorname{damma}_{a}_{b d}
10
                                - \partial_{d}{\Gamma^{a}_{b c}}
11
                                + \Gamma^{e}_{b d} \Gamma^{a}_{c e}
12
                                - \Gamma^{e}_{b c} \Gamma^{a}_{d e}.
13
14
     gab := \{ g_{\text{theta}} = r**2, 
15
              g_{\text{varphi}} = r**2 \sin(\theta)**2 . # cdb(ex-06.201,gab)
16
17
     iab := { g^{\star} theta\theta} = 1/r**2,
18
              g^{\text{warphi}} = 1/(r**2 \sin(\theta)**2) }. # cdb(ex-06.202,iab)
19
20
     substitute (Rabcd, Gamma)
                                                                   \# cdb(ex-06.203, Gamma)
21
22
                (Gamma, gab+iab, rhsonly=True)
                                                                   # cdb(ex-06.204, Gamma)
     evaluate
     evaluate
                (Rabcd, gab+iab, rhsonly=True)
                                                                   # cdb(ex-06.205, Rabcd)
     # convert from a rule to a simple expression
26
     Riem := R^{a}_{b} c d.
27
     substitute (Riem, Rabcd)
                                                                   # cdb(ex-06.206, Riem)
28
29
     from cdb.core.component import *
30
31
     RiemCompt = get_component (Riem, $\theta, \varphi, \theta, \varphi$) # cdb(ex-06.207, RiemCompt)
```

$$\left[g_{\theta\theta} = r^2, \ g_{\varphi\varphi} = r^2(\sin\theta)^2\right] \tag{ex-06.201}$$

$$\[g^{\theta\theta} = r^{-2}, \ g^{\varphi\varphi} = \left(r^2 (\sin \theta)^2 \right)^{-1} \]$$
 (ex-06.202)

$$\Gamma^{a}{}_{bc} \to \Box_{cb}{}^{a} \begin{cases} \Box_{\varphi\theta}{}^{\varphi} = (\tan\theta)^{-1} \\ \Box_{\theta\varphi}{}^{\varphi} = (\tan\theta)^{-1} \\ \Box_{\varphi\varphi}{}^{\theta} = -\frac{1}{2}\sin(2\theta) \end{cases}$$
 (ex-06.204)

$$R^{a}_{bcd} \to \Box_{db}^{a}{}_{c} \begin{cases} \Box_{\varphi\varphi}^{\theta}{}_{\theta} = (\sin\theta)^{2} \\ \Box_{\varphi\theta}^{\varphi}{}_{\theta} = -1 \\ \Box_{\theta\varphi}^{\theta}{}_{\varphi} = -(\sin\theta)^{2} \\ \Box_{\theta\theta}^{\varphi}{}_{\varphi} = 1 \end{cases}$$
 (ex-06.205)

$$\Box_{db}{}^{a}{}_{c} \begin{cases} \Box_{\varphi\varphi}{}^{\theta}{}_{\theta} = (\sin\theta)^{2} \\ \Box_{\varphi\theta}{}^{\varphi}{}_{\theta} = -1 \\ \Box_{\theta\varphi}{}^{\theta}{}_{\varphi} = -(\sin\theta)^{2} \\ \Box_{\theta\theta}{}^{\varphi}{}_{\varphi} = 1 \end{cases}$$
 (ex-06.206)

$$R^{\theta}_{\varphi\theta\varphi} = -(\sin\theta)^2 \tag{ex-06.207}$$

Example 6-03 Using complete to compute the inverse metric

This version uses complete to compute the inverse metric.

```
{\theta, \varphi}::Coordinate.
     {a,b,c,d,e,f,g,h#}::Indices(values={\theta, \varphi}, position=independent).
     \partial{#}::PartialDerivative.
     g^{a b}::InverseMetric. # essential when using complete (gab, $g^{a b}$)
     Gamma := Gamma^{a}_{b c} \rightarrow 1/2 g^{a d} ( partial_{b}_{g_{d c}})
                                                   + \partial_{c}{g_{b d}}
                                                   - \partial_{d}{g_{b c}}).
10
11
     Rabcd := R^{a}_{b c d} \rightarrow \operatorname{partial}_{c}{\operatorname{Gamma}_{a}_{b d}}
12
                                 - \partial_{d}{\Gamma^{a}_{b c}}
13
                                 + \Gamma^{e}_{b d} \Gamma^{a}_{c e}
14
                                 - \Gamma^{e}_{b c} \Gamma^{a}_{d e}.
15
16
     gab := \{ g_{\text{theta}} = r**2, 
17
               g_{\text{varphi}} = r**2 \cdot (\theta)**2 .
                                                                     # cdb(ex-06.301,gab)
18
19
     complete (gab, $g^{a b}$)
                                                                     # cdb(ex-06.302,gab)
20
21
     substitute (Rabcd, Gamma)
22
23
                 (Gamma, gab, rhsonly=True)
                                                                     # cdb(ex-06.303, Gamma)
     evaluate
24
                 (Rabcd, gab, rhsonly=True)
                                                                     # cdb(ex-06.304, Rabcd)
     evaluate
```

$$\left[g_{\theta\theta} = r^2, \ g_{\varphi\varphi} = r^2 (\sin \theta)^2\right] \tag{ex-06.301}$$

$$\left[g_{\theta\theta} = r^2, \ g_{\varphi\varphi} = r^2 (\sin \theta)^2, \ g^{\theta\theta} = r^{-2}, \ g^{\varphi\varphi} = \left(r^2 (\sin \theta)^2 \right)^{-1} \right] \tag{ex-06.302}$$

$$\Gamma^{a}{}_{bc} \to \Box_{cb}{}^{a} \begin{cases} \Box_{\varphi\theta}{}^{\varphi} = (\tan\theta)^{-1} \\ \Box_{\theta\varphi}{}^{\varphi} = (\tan\theta)^{-1} \\ \Box_{\varphi\varphi}{}^{\theta} = -\frac{1}{2}\sin(2\theta) \end{cases}$$
 (ex-06.303)

$$R^{a}_{bcd} \to \Box_{db}^{a}{}_{c} \begin{cases} \Box_{\varphi\varphi}^{\theta}{}_{\theta} = (\sin\theta)^{2} \\ \Box_{\varphi\theta}^{\varphi}{}_{\theta} = -1 \\ \Box_{\theta\varphi}^{\theta}{}_{\varphi} = -(\sin\theta)^{2} \\ \Box_{\theta\theta}^{\varphi}{}_{\varphi} = 1 \end{cases}$$
 (ex-06.304)

Example 6-04 Components by scalar projection

This example shows how one component of the Riemann tensor can be computed using a scalar projection.

```
{\theta, \varphi}::Coordinate.
     {a,b,c,d,e,f,g,h#}::Indices(values={\theta, \varphi}, position=independent).
     theta{#}::LaTeXForm{"\theta"}.
     varphi{#}::LaTeXForm{"\varphi"}.
     # usual definitions for the connection and Riemann tensor
     Gamma := Gamma^{a}_{b c} \rightarrow 1/2 g^{a d} ( partial_{b}_{g_{d c}})
                                                  + \partial_{c}{g_{b d}}
10
                                                  - \partial_{d}{g_{b c}}).
11
12
     Rabcd := R^{a}_{b c d} \rightarrow \operatorname{partial}_{c}{\operatorname{Gamma}_{a}_{b d}}
13
                                - \partial_{d}{\Gamma^{a}_{b c}}
14
                                + \Gamma^{e}_{b d} \Gamma^{a}_{c e}
15
                                - \Gamma^{e}_{b c} \Gamma^{a}_{d e}.
16
17
     substitute (Rabcd, Gamma)
18
19
     gab := { g_{\text{theta}} = r**2,
20
              g_{\text{varphi}} = r**2 \sin(\theta)**2 . # cdb(ex-06.400,gab)
21
22
     iab := { g^{\star} theta\theta} = 1/r**2,
23
              g^{\tilde{x}} = 1/(r**2 \sin(\theta)**2) }.
24
25
     # complete (gab, $g^{a b}$)
     # evaluate (Rabcd, gab+iab, rhsonly=True)
27
28
     # define the basis for vectors and dual vectors
29
30
     basis := {theta^{\theta} = 1, varphi^{\varphi} = 1}.
31
     dual := {theta_{\theta} = 1, varphi_{\varphi} = 1}.
32
     # obtain components by contracting with basis
34
```

```
35
     compt := R^{a}_{b c d} theta_{a} varphi^{b} theta^{c} varphi^{d}. # cdb(ex-06.401, compt)
    substitute (compt,Rabcd)
37
38
     evaluate (compt,gab+iab+basis+dual)
                                                                         # cdb(ex-06.402,compt)
39
40
     compt_sympy = compt._sympy_()
41
     # cdbBeg(print.ex-06.04)
43
     print ('type compt = ' + str(type(compt)))
                                                         # shows that compt is a Cadabra object
44
     print ('type gphiphi = ' + str(type(compt_sympy))) # shows that gphiphi is a Python object
45
    print ('
                 compt = ' + str(compt))
                                                         # will contain LaTeX markup
     print ('
                 gphiphi = ' + str(compt_sympy))
                                                         # will be pure Python/SymPy
47
     # cdbEnd(print.ex-06.04)
49
     checkpoint.append (compt)
50
```

$$R^{\theta}_{\varphi\theta\varphi} = R^{a}_{bcd}\theta_{a}\varphi^{b}\theta^{c}\varphi^{d}$$

$$= (\sin\theta)^{2}$$
(ex-06.401)
$$= (\cos\theta)^{2}$$

Where is example-06-04.cdbcopy?

Example 6-05 Components by selection

This example shows how one component of the metric tensor can be computed by indexing the result of a call to evaluate.

```
{\theta, \varphi}::Coordinate.
     {a,b,c,d,e,f,g,h#}::Indices(values={\theta, \varphi}, position=independent).
     theta{#}::LaTeXForm{"\theta"}.
     varphi{#}::LaTeXForm{"\varphi"}.
     gab := { g_{\text{theta}} = r**2,
              g_{\text{varphi}} = r**2 \sin(\theta)**2 . # cdb(ex-06.500,gab)
     metric := g_{a} b}.
10
11
     evaluate (metric,gab)
12
13
     indcs = metric[2][1][0]
                                                               # cdb(ex-06.501,indcs)
     compt = metric[2][1][1]
                                                               # cdb(ex-06.502,compt)
15
16
     # cdbBeg(print.ex-06.05)
17
     print ('metric = ' + str(metric.input_form())+'\n') # reveals Cadabra's internal structure for storing metric
18
19
     print ('metric[0] = ' + str(metric[0]))
     print ('metric[1] = ' + str(metric[1]))
     print ('metric[2] = ' + str(metric[2])+'\n')
22
23
     print ('metric[2][1] = '+ str(metric[2][1]))
24
     print ('metric[2][1][0] = '+ str(metric[2][1][0]))
     print ('metric[2][1][1] = '+ str(metric[2][1][1]))
     # cdbEnd(print.ex-06.05)
27
28
     checkpoint.append (indcs)
29
     checkpoint.append (compt)
```

$$g_{\varphi\varphi} = g_{[\varphi, \varphi]} \qquad (ex-06.501)$$

$$= r^2 (\sin \theta)^2 \qquad (ex-06.502)$$

Where is example-06-05.cdbcopy?