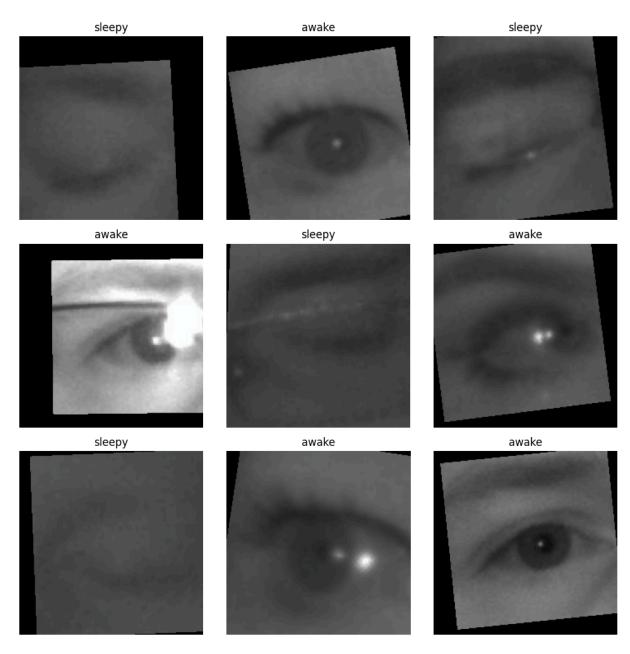
```
In [1]: # import kagglehub
        # # DownLoad Latest version
        # path = kagqlehub.dataset download("akashshingha850/mrl-eye-dataset")
        # print("Path to dataset files:", path)
In [2]: import os
        from torchvision import datasets, transforms, models
        import torch.nn as nn
        import torch.optim as optim
        from torch.optim import lr_scheduler
        import torch
        import matplotlib.pyplot as plt
        import numpy as np
        from tqdm.notebook import tqdm, trange
In [3]: os.environ['KMP_DUPLICATE_LIB_OK']='TRUE'
        # Data Preparation
        data_dir = r'C:\Users\leoki\.cache\kagglehub\datasets\akashshingha850\mrl-eye-datas
        # Define transformations for the dataset
        data_transform = {
                 'train' : transforms.Compose([
                    transforms.Grayscale(num output channels=3),
                    transforms.Resize(256),
                    transforms.CenterCrop(224),
                    transforms.RandomAffine(degrees=15, translate=(0.1, 0.1), scale=(0.8, 1
                    transforms.ToTensor(),
                    transforms.Normalize([0.485, 0.456, 0.406], [0.229, 0.224, 0.225])
                 'val' : transforms.Compose([
                    transforms.Grayscale(num_output_channels=3),
                    transforms.Resize(256),
                    transforms.CenterCrop(224),
                    transforms.ToTensor(),
                    transforms Normalize([0.485, 0.456, 0.406], [0.229, 0.224, 0.225])
                    ]),
                 'test': transforms.Compose([
                    transforms.Grayscale(num_output_channels=3),
                    transforms. Resize(256),
                    transforms.CenterCrop(224),
                    transforms.ToTensor(),
                    transforms Normalize([0.485, 0.456, 0.406], [0.229, 0.224, 0.225])
                    ])
            }
        phases = ['train', 'val', 'test']
        # Create dataset using ImageFolder
        image_datasets = {x: datasets.ImageFolder(os.path.join(data_dir, x), data_transform
                          for x in phases}
```

```
# Create Dataloaders to feed data to the model
        dataloaders = {x: torch.utils.data.DataLoader(image datasets[x], batch size=64, shu
        class_names = image_datasets['train'].classes
        # Check GPU availability
        device = torch.device("cuda" if torch.cuda.is_available() else "cpu")
        print("Using device:", device)
        print("Class names:", class_names)
       Using device: cuda
       Class names: ['awake', 'sleepy']
In [4]: # Get a batch of training data
        # Since the dataloader is shuffled, this will be a random batch
        inputs, classes = next(iter(dataloaders['train']))
        # Create a 3x3 grid of subplots
        fig, axes = plt.subplots(3, 3, figsize=(10, 10))
        # Mean and std for un-normalization, same as before
        mean = np.array([0.485, 0.456, 0.406])
        std = np.array([0.229, 0.224, 0.225])
        # Plot the first 9 images from the batch
        for i in range(9):
            # Select the subplot
            ax = axes.flat[i]
            # Get the i-th image tensor
            img = inputs[i]
            # --- Un-normalize and format the image for display ---
            img = img.numpy().transpose((1, 2, 0)) # Transpose dimensions
                                       # Un-normalize
            img = std * img + mean
                                                 # Clip values to [0, 1] range
            img = np.clip(img, 0, 1)
            # Display the image
            ax.imshow(img)
            # Set the title to the correct class name
            ax.set_title(class_names[classes[i]])
            # Turn off the axes (ticks and labels)
            ax.axis('off')
        # Adjust layout to prevent titles from overlapping and show the plot
        plt.tight_layout()
        plt.show()
```



In [5]: # Model Definition
 from torchvision.models import ResNet18_Weights
 model = models.resnet18(weights=ResNet18_Weights.IMAGENET1K_V1)

Freeze all Layers; will only train the final Layer
Want to preserve the general features already Learned by the pretrained model & o
 for param in model.parameters():
 param.requires_grad = False

num_ftrs = model.fc.in_features

Replace the final Layer with a new one that has 2 outputs (awake/sleepy)
New params have requires_grad=True by default
model.fc = nn.Linear(num_ftrs, len(class_names))

model = model.to(device)

```
In [6]: optimizer = optim.Adam(model.fc.parameters(), lr=0.001)
        criterion = nn.CrossEntropyLoss()
        epochs = 13 # Increased epochs for more thorough training
        epoch_pbar = trange(epochs, desc="Overall Progress")
        for epoch in epoch pbar:
            epoch_metrics = {}
            for phase in ['train', 'val']:
                if phase == 'train':
                    model.train()
                else:
                    model.eval()
                running loss = 0.0
                running_corrects = 0
                phase_pbar = tqdm(dataloaders[phase], desc=f"Epoch {epoch+1} - {phase}", le
                for inputs, labels in phase pbar:
                    inputs = inputs.to(device)
                    labels = labels.to(device)
                    optimizer.zero_grad()
                    with torch.set_grad_enabled(phase == 'train'):
                        outputs = model(inputs)
                        _, preds = torch.max(outputs, 1)
                        loss = criterion(outputs, labels.long())
                        if phase == 'train':
                            loss.backward()
                            optimizer.step()
                    running_loss += loss.item() * inputs.size(0)
                    running_corrects += torch.sum(preds == labels.data)
                epoch_loss = running_loss / len(image_datasets[phase])
                epoch_acc = running_corrects.double() / len(image_datasets[phase])
                epoch_metrics[f'{phase}_loss'] = f"{epoch_loss:.4f}"
                epoch_metrics[f'{phase}_acc'] = f"{epoch_acc:.4f}"
            epoch_pbar.set_postfix(epoch_metrics)
        model_path = 'eyenet_model.pth'
        torch.save(model.state_dict(), model_path) # Save the final model state
       Overall Progress:
                           0%|
                                        | 0/13 [00:00<?, ?it/s]
       Epoch 1 - train:
                          0%|
                                       | 0/796 [00:00<?, ?it/s]
                                     | 0/266 [00:00<?, ?it/s]
       Epoch 1 - val:
                        0%|
       Epoch 2 - train:
                          0%
                                      0/796 [00:00<?, ?it/s]
       Epoch 2 - val:
                        0%
                                     | 0/266 [00:00<?, ?it/s]
       Epoch 3 - train:
                                      | 0/796 [00:00<?, ?it/s]
                          0% l
       Epoch 3 - val:
                        0%|
                                     | 0/266 [00:00<?, ?it/s]
                                      | 0/796 [00:00<?, ?it/s]
       Epoch 4 - train:
                          0%|
                                     | 0/266 [00:00<?, ?it/s]
       Epoch 4 - val:
                        0%|
                                      | 0/796 [00:00<?, ?it/s]
       Epoch 5 - train:
                          0%
       Epoch 5 - val:
                        0%
                                     | 0/266 [00:00<?, ?it/s]
```

```
Epoch 6 - train:
                         0%
                                      | 0/796 [00:00<?, ?it/s]
       Epoch 6 - val:
                                    | 0/266 [00:00<?, ?it/s]
       Epoch 7 - train:
                                     0/796 [00:00<?, ?it/s]
                         0%|
       Epoch 7 - val:
                       0%|
                                    | 0/266 [00:00<?, ?it/s]
       Epoch 8 - train:
                                     | 0/796 [00:00<?, ?it/s]
                         0%
       Epoch 8 - val:
                       0%
                                    | 0/266 [00:00<?, ?it/s]
       Epoch 9 - train:
                         0%|
                                     0/796 [00:00<?, ?it/s]
                                     | 0/266 [00:00<?, ?it/s]
       Epoch 9 - val:
                       0%|
                                      | 0/796 [00:00<?, ?it/s]
       Epoch 10 - train:
                          0%|
                                     | 0/266 [00:00<?, ?it/s]
       Epoch 10 - val:
                        0%
                                      | 0/796 [00:00<?, ?it/s]
       Epoch 11 - train:
                          0%
                                      | 0/266 [00:00<?, ?it/s]
       Epoch 11 - val:
                        0%|
       Epoch 12 - train:
                                      | 0/796 [00:00<?, ?it/s]
                          0%|
       Epoch 12 - val:
                        0%|
                                     | 0/266 [00:00<?, ?it/s]
                                      | 0/796 [00:00<?, ?it/s]
       Epoch 13 - train:
                          0%|
       Epoch 13 - val:
                                      | 0/266 [00:00<?, ?it/s]
                        0%
In [7]: # Test Model
        model.load_state_dict(torch.load(model_path))
        model.eval()
        running_corrects = 0
        with torch.no_grad():
            for inputs, labels in dataloaders['test']:
                inputs = inputs.to(device)
                labels = labels.to(device)
                outputs = model(inputs)
                _, preds = torch.max(outputs, 1)
                running_corrects += torch.sum(preds == labels.data)
        test_acc = running_corrects.double() / len(image_datasets['test'])
        print(f"Test Accuracy: {test_acc:.4f}")
       Test Accuracy: 0.9544
```

In []: