

Towards machine-checked proofs

MPRI 2.4

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1 Why mechanize definitions and proofs?

2 Coq in a nutshell

3 Representing abstract syntax with binders

On paper: the nominal representation

In a machine: de Bruijn's representation

Why formalize programming languages?

Why
mechanize?

Coq in a
nutshell

Syntax with
binders

Nominal
de Bruijn

To obtain **precise definitions** of programming languages, including:

- dynamic semantics;
- type systems, sometimes known as “static semantics”.

To obtain **rigorous proofs of soundness** for tools such as

- interpreters,
- compilers,
- type systems (“**well-typed programs do not go wrong**”),
- type-checkers and type inference engines,
- static analyzers (e.g. abstract interpreters),
- program logics (e.g. Hoare logic, separation logic),
- deductive program provers (e.g. verification condition generators).

Challenge 1: Scale

Hand-written proofs have difficulty **scaling up**:

- From minimal calculi (λ , π) and toy languages (IMP, MiniML) to large **real-world languages** such as Java, C, JavaScript, ...
- From textbook compilers to multi-pass **optimizing compilers** producing code for real processors.
- From textbook abstract interpreters to **scalable and precise static analyzers** such as Astrée.

Challenge 2: Trust

Hand-written proofs are seldom **trustworthy**.

- Authors struggle with huge LaTeX documents.
- Reviewers give up on checking huge but boring proofs.

*Proofs written by computer scientists are boring:
they read as if the author is programming the reader.*

John C. Mitchell

- Proof cases are omitted because they are “obvious” or “analogous to the previous case”.
- It is difficult to maintain hand-written proofs as the definitions evolve.

Opportunity: machine-assisted proof

Mechanized theorem proving has made great progress.

Landmark examples in mathematics:

- the 4-color th.: Haken & Appel (1976), Gonthier & Werner (2005);
- the Feit-Thompson theorem: Gonthier *et al.* (2013);
- Kepler's conjecture: Hales *et al.* (2015).

Programming language theory is a **good match** for proof assistants:

- discrete objects (trees); no reals, no analysis, no topology...
- large definitions; proofs with many similar cases;
- syntactic techniques (induction); few deep mathematical concepts.

The POPLmark challenge

In 2005, Aydemir *et al.* challenged the POPL community:

How close are we to a world where every paper on programming languages is accompanied by an electronic appendix with machine-checked proofs?

13 years later, about 20% of the papers at recent POPL conferences come with such an electronic appendix.

Proof assistants

An interactive proof assistant offers:

- A formal **specification language**,
in which definitions are written and theorems are stated.
- A set of **commands** for building proofs,
either automatically or interactively.
- Often, an independent, automated **proof checker**,
so the above commands do not have to be trusted.

*A Mathematical Assistant satisfying the possibility of
independent checking by a small program is said to satisfy
the de Bruijn criterion.*

*Barendregt and Wiedijk,
The Challenge of Computer Mathematics, 2005.*

Popular proof assistants include Coq, Agda, HOL4, Isabelle/HOL...

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Computations and functions

Coq offers a **pure functional programming language** in the style of ML, with recursive functions and pattern-matching.

```
Fixpoint factorial (n: nat) :=  
  match n with  
  | 0    => 1  
  | S p => n * factorial p  
end.
```

```
Fixpoint concat (A: Type) (xs ys: list A) :=  
  match xs with  
  | nil => ys  
  | x :: xs => x :: concat xs ys  
end.
```

The language is **total**: all functions terminate. This is enforced by requiring every recursive call to be decreasing w.r.t. the subterm ordering.

Mathematical logic

Propositions can be expressed in this language. They have type **Prop**.

Definition divides $(a\ b: N) := \text{exists } n: N, b = n * a.$

Theorem factorial_divisors:

forall n i, $1 \leq i \leq n \rightarrow \text{divides } i (\text{factorial } n).$

Definition prime $(p: N) :=$

$p > 1 \wedge (\text{forall } d, \text{divides } d\ p \rightarrow d = 1 \vee d = p).$

Theorem Euclid:

forall n, **exists** p, $p \geq n \wedge \text{prime } p.$

The standard logical connectives and quantifiers are available.

Inductive types

An **inductive type** is a data type.

It is equipped with a finite number of **constructors**.

Its inhabitants are generated by repeated application of the constructors.

```
Inductive nat: Type :=  
| 0: nat  
| S: nat -> nat.  
  
Inductive list: Type -> Type :=  
| nil: forall A, list A  
| cons: forall A, A -> list A -> list A.
```

E.g., the inhabitants of **nat** are 0, S 0, S (S 0), etc.

This is well suited to describe the **syntax** of a programming language.

Inductive predicates

An **inductive predicate** is equipped with a finite number of constructors, and is generated by repeated application of the constructors.

```
Inductive even: nat -> Prop :=  
| even_zero:  
  even 0  
| even_plus_2:  
  forall n, even n -> even (S (S n)).
```

On paper, this is typically written in the form of inference rules:

$$\frac{}{0 \text{ is even}} \qquad \frac{n \text{ is even}}{S (S n) \text{ is even}}$$

The inhabitants of the type `even n` can be thought of as **derivation trees** whose conclusion is `even n`.

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Binding and α -equivalence

Most programming languages provide constructs that **bind** variables, e.g.:

- function abstractions (in terms): $\lambda x.t$
- local definitions (in terms): $\text{let } x = t \text{ in } t$
- quantifiers (in types): $\forall \alpha. \alpha \rightarrow \alpha$

α -equivalence is a relation that allows renamings of bound variables, e.g.:

$$\lambda x. x + 1 \equiv_{\alpha} \lambda y. y + 1 \qquad \forall \alpha. \alpha \text{ list} \equiv_{\alpha} \forall \beta. \beta \text{ list}$$

α -equivalence can be defined as follows (Pitts, 2006):

$$\lambda x. t \equiv_{\alpha} \lambda y. \binom{x}{y} t \quad \text{if } y \notin \text{fv}(\lambda x. t) \\ \text{where } \binom{x}{y} \text{ swaps all occurrences of } x \text{ and } y$$

Implicit α -equivalence

On paper, it is customary to confuse α -equivalence \equiv_α with equality $=$.

This plays a role, for instance, in the definition of System F .

This is the traditional rule for type-checking a function application:

$$\frac{\Gamma \vdash e_1 : \tau \rightarrow \tau' \quad \Gamma \vdash e_2 : \tau}{\Gamma \vdash e_1 e_2 : \tau'}$$

The rule should be written as follows, if α -equivalence was explicit:

$$\frac{\Gamma \vdash e_1 : \tau \rightarrow \tau' \quad \Gamma \vdash e_2 : \tau_2 \quad \tau \equiv_\alpha \tau_2}{\Gamma \vdash e_1 e_2 : \tau'}$$

In simply-typed λ -calculus, this issue does not arise, as there are no quantifiers in types: α -equivalence and equality of types coincide.

Explicit α -equivalence

In principle, one should distinguish between:

- **trees** versus **equivalence classes** of trees;
- **equality** = versus **α -equivalence** \equiv_{α} .

This sounds easy enough, but leads to subtleties when defining mathematical **functions** that consume or produce trees... such as:

- **program transformations**, which produce and consume **syntax** trees;
- **proofs**, which produce and consume **derivation** trees.

Functions on equivalence classes

To define a **function** f from \mathbb{T}/\equiv_α to \mathbb{T}/\equiv_α ,
it suffices to first define a **relation** F between \mathbb{T} and \mathbb{T} ,
and to require two conditions:

Functions on equivalence classes

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it suffices to first define a **relation** F between \mathbb{T} and \mathbb{T} ,
and to require two conditions:

- every tree is α -equivalent to some tree in the domain of F :

$$\forall t \in \mathbb{T} \quad \exists t', u' \in \mathbb{T} \quad t \equiv_\alpha t' \wedge t' F u'$$

- note: the domain of F need not be \mathbb{T}
- “without loss of generality, **let us assume** that x does not occur in ...”

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- F is **compatible** with α -equivalence:

$$\forall t, t', u, u' \in \mathbb{T} \quad t F u \wedge t' F u' \wedge t \equiv_\alpha t' \Rightarrow u \equiv_\alpha u'$$

- note: F need not be deterministic (single-valued)
- nondeterminism is fine as long as all choices yield α -eq. results
- “**let us pick** a name x outside of ...”

Free variables

The classic definition of the set of the **free variables** of a λ -term:

$$\begin{aligned}fv(x) &= \{x\} \\fv(\lambda x.t) &= fv(t) \setminus \{x\} && \text{-- no requirement on } x \\fv(t_1 \ t_2) &= fv(t_1) \cup fv(t_2)\end{aligned}$$

A total function from \mathbb{T} to sets of names.

Condition 1 is vacuously satisfied (the relation is defined everywhere).

Condition 2 requires checking the following equality:

$$fv(\lambda x.t) = fv(\lambda y.(\overset{x}{\underset{y}{t}}) \quad \text{where } y \notin fv(\lambda x.t)$$

This follows from the fact that fv is **equivariant**, i.e., commutes with swaps:

$$fv(\pi t) = \pi fv(t)$$

and from the fact that neither x nor y appear in the set $fv(\lambda x.t)$.

Thus, fv gives rise to a total function from \mathbb{T}/\equiv_α to sets of names.

Capture-avoiding substitution

The classic definition of capture-avoiding substitution:

$$\begin{aligned}x[u/x] &= u \\y[u/x] &= y && \text{if } y \neq x \\(\lambda z. t)[u/x] &= \lambda z. t[u/x] && \text{if } z \notin \text{fv}(u) \cup \{x\} \\(t_1 \ t_2)[u/x] &= t_1[u/x] \ t_2[u/x]\end{aligned} \quad \text{— avoid capture!}$$

A partial function from \mathbb{T} to \mathbb{T} .

Condition 1 holds, as only a **finite** number of choices for z are forbidden.

Condition 2 requires checking:

$$\lambda z. t[u/x] \equiv_{\alpha} \lambda z'. t'[u/x] \quad \text{where } z, z' \notin \text{fv}(u) \cup \{x\} \text{ and } \lambda z. t \equiv_{\alpha} \lambda z'. t'$$

which follows, again, from the fact that substitution is equivariant.

Thus, this gives rise to a total function from $\mathbb{T}/\equiv_{\alpha}$ to $\mathbb{T}/\equiv_{\alpha}$.

Naïve substitution

Naïve substitution does not have the side condition $z \notin fv(u) \cup \{x\}$.

It is a total function from \mathbb{T} to \mathbb{T} ,
but **fails** condition 2,

hence does **not** give rise to a function from \mathbb{T}/\equiv_α to \mathbb{T}/\equiv_α .

$$(\lambda y. x + y)[2 \times y/x] = \lambda y. 2 \times y + y \quad - \text{naïve}$$

$$(\lambda y. x + y)[2 \times y/x] =$$

$$(\lambda \mathbf{z}. x + \mathbf{z})[2 \times y/x] = \lambda \mathbf{z}. 2 \times y + \mathbf{z} \quad - \text{capture-avoiding}$$

Representations of syntax

How should syntax with binding be represented in a proof assistant?

Several representations come to mind:

- equivalence classes of trees – the **nominal** approach (Pitts, 2006);
- **de Bruijn** notation – used in this course (de Bruijn, 1972);
- (parametric) **higher-order abstract syntax** (Chlipala, 2008);
- the **locally nameless** representation (Charguéraud, 2009);
- and many more.

One should choose a representation for which the proof assistant has **good support**.

What about the nominal approach?

The nominal approach is prevalent in informal (paper) proofs.

It is **implemented** in Nominal Isabelle (**Urban, 2008**).

- **Urban and Narboux (2008)** present typical proofs about operational semantics.

It is **not** well supported in Coq, perhaps for engineering reasons.

- **Cohen (2013)** shows how to use quotients in Coq (when they exist) and how to construct them (up to certain axioms or hypotheses).

What about other approaches?

The **POPLmark challenge** proposes a benchmark problem:
a proof of type soundness for $F_{<}$.

15 solutions have been proposed, using 8 different representations
in 7 different proof assistants.

No consensus, yet!

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de Bruijn indices



A simple idea: **don't use names**.

Instead, use **pointers** from variables back to their binding site.

A second idea: use **relative** pointers, encoded as natural integers.

- 0 denotes the nearest enclosing λ ,
i.e., the **most recently bound** variable;
- 1 denotes the next enclosing λ , and so on.

$\lambda x.x$ is $\lambda 0$.

$\lambda f.\lambda x.f\ x$ is $\lambda\lambda(1\ 0)$.

Why is this a good idea?

de Bruijn syntax has several strengths:

- it is easily defined;
- it is **inductive** – terms are trees, no quotient is required;
- it is **canonical** – α -equivalence is just equality.

Its drawbacks are well-known, too:

- terms are more difficult to read – a **printer** may be needed;
- definitions and theorems can seem difficult to write and read – mostly a matter of **habit**?

λ -terms in de Bruijn's notation

The syntax of λ -calculus is simple:

$$t ::= x \mid \lambda t \mid t t \quad \text{where } x \in \mathbb{N}$$

In Coq:

```
Inductive term :=  
| Var: nat -> term  
| Lam: term -> term  
| App: term -> term -> term.
```

Suggested exercises

Exercise: In OCaml, implement **conversions** between the nominal representation and de Bruijn's representation, both ways.

Exercise: In OCaml, implement an exhaustive **enumeration** of the λ -terms of size s and with at most n free variables. (Let variables have size 0; let λ -abstractions and applications contribute 1.)

Exercise: Use this exhaustive enumeration to **test** that the above conversions are inverses of each other.

Substitution



— Substitution is the *éminence grise* of the λ -calculus.

Abadi, Cardelli, Curien, Lévy, **Explicit substitutions**, 1990.

Substitutions

Let a substitution σ be a **total** function of variables \mathbb{N} to terms \mathbb{T} .

It can also be thought of as an infinite sequence $\sigma(0) \cdot \sigma(1) \cdot \dots$

Let id be the **identity** substitution: $id(x) = x$.

- $0 \cdot 1 \cdot 2 \cdot \dots$

Let $+i$ be the **lift** substitution: $(+i)(x) = x + i$.

- $i \cdot (i + 1) \cdot (i + 2) \cdot \dots$

Let $t \cdot \sigma$ be the **cons** substitution that maps 0 to t and $x + 1$ to $\sigma(x)$.

- $t \cdot \sigma(0) \cdot \sigma(1) \cdot \dots$

id can in fact be viewed as sugar for $0 \cdot (+1)$.

Substitution application and composition

Can we define $t[\sigma]$, the **application** of the substitution σ to the term t ?

It should satisfy the following laws:

$$\begin{aligned}x[\sigma] &= \sigma(x) \\ (\lambda t)[\sigma] &= ? \\ (t_1 \ t_2)[\sigma] &= t_1[\sigma] \ t_2[\sigma]\end{aligned}$$

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and the **composition** of two substitutions $\sigma_1 ; \sigma_2$ should satisfy:

$$(\sigma_1 ; \sigma_2)(x) = (\sigma_1(x))[\sigma_2]$$

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These equations are mutually recursive, so **do not form a valid definition**.

This can be worked around by first inductively defining $t[+1]$ (“**lift**”).

— in fact, one must define $t[\uparrow^i(+1)]$.

Then, we define $\sigma ; +1$, whence $\uparrow\sigma$, whence $t[\sigma]$ (“**subst**”).

de Bruijn algebra

The following equations are **sound**, that is, valid:

$$\begin{array}{ll} (\lambda t)[\sigma] = \lambda(t[0 \cdot (\sigma; +1)]) & id; \sigma = \sigma \\ (t_1 \ t_2)[\sigma] = t_1[\sigma] \ t_2[\sigma] & \sigma; id = \sigma \\ 0[t \cdot \sigma] = t & (\sigma_1; \sigma_2); \sigma_3 = \sigma_1; (\sigma_2; \sigma_3) \\ (+1); (t \cdot \sigma) = \sigma & (t \cdot \sigma_1); \sigma_2 = t[\sigma_2] \cdot (\sigma_1; \sigma_2) \end{array}$$

Furthermore, they are **complete** (Schäfer *et al.*, 2015).

That is, if an equation based on the following grammar is **valid**, then it **logically follows** from the above equations.

$$\begin{array}{ll} t & ::= 0 \mid \lambda t \mid t \ t \mid t[\sigma] \mid T \\ \sigma & ::= +1 \mid t \cdot \sigma \mid \sigma; \sigma \mid \Sigma \end{array}$$

Schäfer *et al.* also prove that validity is **decidable**.

de Bruijn algebra

Decidability means that the machine can answer questions for us.

Does $t[id] = t$ hold? **Yes.**

Does $t[\sigma_1][\sigma_2] = t[\sigma_1 ; \sigma_2]$ hold? **Yes.**

Does $t[+1][u \cdot id] = t$ hold? **Yes.**

And so on, and so forth.

For proofs of the first two equations above, see Schäfer *et al.*, Fact 6.

Yet, we do not really care about these proofs – a machine can find them.

Coq tactics for de Bruijn algebra

The Coq library **Autosubst** offers two tactics:

- `autosubst` **proves an equation** between terms or substitutions;
- `asimpl` **simplifies a goal** in which a term or substitution appears.

λ -terms with AutoSubst

The syntax of λ -calculus can be declared as follows:

```
Inductive term :=  
| Var:          var -> term  
| Lam: {bind term} -> term  
| App: term -> term -> term.
```

AutoSubst defines `var` as a synonym for `nat`
and `{bind term}` as a synonym for `term`.

AutoSubst defines substitution application, composition, etc., for us.

AutoSubst key notations

$t \cdot \sigma$	<code>t .: sigma</code>	substitution “cons”
$+i$	<code>ren (+i)</code>	the substitution $+i$
id	<code>ids</code>	the identity substitution
$t[\sigma]$	<code>t.[sigma]</code>	substitution application
$\sigma_1 ; \sigma_2$	<code>sigma1 >> sigma2</code>	substitution composition
$\uparrow\sigma$	<code>up sigma</code>	taking a substitution under a binder
$\uparrow^n \sigma$	<code>upn n sigma</code>	taking a substitution under n binders
$t.[u \cdot id]$	<code>t.[u/]</code>	substituting u for 0 in t

“lift” as end-of-scope

Suppose we are writing a program in de Bruijn’s notation.

Suppose we are in a context where n variables exist
and we wish to refer to a subterm t that has $n - 1$ free variables.
That is, t does **not** know about one of our variables, say i , where $0 \leq i < n$.

We cannot just refer to t , as some indices would be off by one.

Instead, we must use $t[\uparrow^i (+1)]$.

Ugly, low-level index arithmetic? No: read it as an **end-of-scope** mark.

Adopt a nicer notation for it, say “eos i in t ”.

There is no syntax for it in the λ -calculus; it is a **meta-level** notation.

A related, **object-level** end-of-scope construct, “abdmal”,
has been studied by **Hendriks and van Oostrom (2003)**.

Calculi of explicit substitutions

Similarly, we have viewed substitution application as a **meta-level** operation. There is no syntax for it in the λ -calculus.

In the $\lambda\sigma$ -calculus, however, there is **syntax for substitutions** and **substitution application**, and a set of **small-step reduction rules** that explain how substitutions interact with λ -abstractions and applications.

Abadi, Cardelli, Curien, Lévy, **Explicit substitutions**, 1990.

Curien, Hardin, Lévy, **Confluence properties
of weak and strong calculi of explicit substitutions**, 1992.