

# Type inference

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MPRI

# Intro



# What nobody wants

```
let rec length (type a) (li : a list) : int =  
  match li with  
  | [] -> 0  
  | (x : a) :: (xs : a list) ->  
    1 + length (type a) xs
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```

**Guessing** the types.

Sounds boring, but very useful!

Meta-theory: mathematics of usability.

# Generalities

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# Type inference, formally

From a program  $t$  in some typing context  $\Gamma$ ,  
can we **guess** a type  $A$  and a derivation of  $\Gamma \vdash t : A$  ?



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What does it mean that a type system is *decidable* ?

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Context (in)consistency

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$\Gamma \vdash t : ?$

Typability ; Type inference

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Typing inference

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Decidability



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$\Gamma \vdash ? : A$	Inhabitation
$\Gamma \vdash ? : 0$	Context (in)consistency
$\Gamma \vdash t : ?$	Typability ; Type inference
$? \vdash t : A$	Context inference
$? \vdash t : ?$	Typing inference
$\Gamma \vdash t : A$	Decidability

*Remark:* the game also has a relational version:

$$\begin{array}{lll} \Gamma \vdash_1 t : A & \implies & \Gamma \vdash_2 t : A \\ \Gamma \vdash_1 ? : A & \implies & \Gamma \vdash_2 ? : A \\ \Gamma \vdash_1 t : ? & \implies & \Gamma \vdash_2 t : ? \end{array}$$

# Implicit vs. Explicit syntax

**Implicitly** typed syntax (Curry-style):

$$t ::= x, y, z \mid \lambda x. t \mid t u$$

$$\frac{\Gamma, x:A \vdash t : B}{\Gamma \vdash \lambda x. t : A \rightarrow B}$$

$$\emptyset \vdash \lambda x. x : ?$$

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Explicit syntax: one-to-one correspondence with derivations.

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Explicit syntax: one-to-one correspondence with derivations.

(*Syntax-directed*: at most one typing rule per term.)

Inference: from implicit to explicit.

# Implicit vs. Explicit: System F

Implicit:

$$t ::= x, y, z \mid \lambda x. t \mid t u$$

$$\frac{\Gamma, \alpha \vdash t : A}{\Gamma \vdash t : \forall \alpha. A}$$

$$\frac{\Gamma \vdash t : \forall \alpha. A \quad \Gamma \vdash B}{\Gamma \vdash t : A[\alpha := B]}$$



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Implicit polymorphism is not syntax-directed.

Inhabitation and type inference are undecidable.

Type inference is undecidable for full System F.

Two avenues of progress:

- require some type annotations from the user (more explicit syntax)
- move to a less powerful type system

Tweak the language to make inference possible.

In this course, two common approaches:

1. Bidirectional type inference (for STLC)
2. Hindley-Damas-Milner type inference (for ML)

Two basic proof steps to pass this course: **induction** and **inversion**.

Inversion on inference rules: eliminate rules that do not match the goal.

Example:

$$\begin{array}{c}
 \frac{}{\Gamma, x:A \vdash x : A} \quad \frac{\Gamma, x:A \vdash t : B}{\Gamma \vdash \lambda x. t : A \rightarrow B} \quad \frac{\Gamma \vdash t : A \rightarrow B \quad \Gamma \vdash u : A}{\Gamma \vdash t u : B} \quad v ::= x \mid \lambda x. t
 \end{array}$$

Prove that  $\emptyset \vdash v : A \rightarrow B$  implies  $x:A \vdash t : B$  for some  $x, t$  such that  $v = \lambda x. t$ .

# **Bidirectional type inference for STLC**

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$$\frac{\Gamma, x:A \vdash t : B}{\Gamma \vdash \lambda x. t : A \rightarrow B}$$

Idea: we cannot easily *infer*  $\Gamma \vdash \lambda x. t : ?$  but we can easily *check*  $\Gamma \vdash \lambda x. t : A \rightarrow B$ .

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Idea: we cannot easily *infer*  $\Gamma \vdash \lambda x. t : ?$  but we can easily *check*  $\Gamma \vdash \lambda x. t : A \rightarrow B$ .

Separate  $\Gamma \vdash t : A$  into two judgments:

Check:  $\Gamma \vdash t \Leftarrow A$

Infer:  $\Gamma \vdash t \Rightarrow A$

# Re-inventing bidirectional inference

$$\frac{}{\Gamma, x:A \vdash x : A} \qquad \frac{\Gamma, x:A \vdash t : B}{\Gamma \vdash \lambda x. t : A \rightarrow B} \qquad \frac{\Gamma \vdash t : A \rightarrow B \quad \Gamma \vdash u : A}{\Gamma \vdash t u : B}$$

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Soundness:  $\Gamma \vdash t \Leftarrow A \quad \vee \quad \Gamma \vdash t \Rightarrow A \quad \implies \quad \Gamma \vdash t : A \quad ?$

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Problem:

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Completeness:  $\Gamma \vdash t : A \quad \implies \quad \Gamma \vdash t \Leftarrow A \quad ?$

Problem:  $(\lambda x. t) u$

Solution:



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Completeness:  $\Gamma \vdash t : A \quad \implies \quad \Gamma \vdash t \Leftarrow A \quad ?$

Problem:  $(\lambda x. t) u$

Solution:  $t ::= \dots \mid (t : A)$

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$$\frac{\Gamma \vdash t \Rightarrow A \rightarrow B \quad \Gamma \vdash u \Leftarrow A}{\Gamma \vdash t u \Rightarrow B}$$

Soundness:  $\Gamma \vdash t \Leftarrow A \quad \vee \quad \Gamma \vdash t \Rightarrow A \quad \Longrightarrow \quad \Gamma \vdash t : A \quad ?$

Completeness:  $\Gamma \vdash t : A \quad \Longrightarrow \quad \Gamma \vdash t \Leftarrow A \quad ?$

Problem:  $(\lambda x. t) u$

Solution:  $t ::= \dots \mid (t : A)$

$$\frac{\Gamma \vdash t \Leftarrow A}{\Gamma \vdash (t : A) \Rightarrow A}$$

Completeness:  $\Gamma \vdash t : A \quad \Longrightarrow \quad \exists t', \quad [t'] = t \quad \wedge \quad \Gamma \vdash t' \Leftarrow A$

# Bidirectional type inference

Bidirectional typing works *really well* for  $\beta\eta$ -normal forms.

$$n ::= x \mid n \ t \mid (t : A)$$

$$t ::= \lambda x. t \mid n$$

For actual programs, it requires adding some annotations.

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Problems:

1. Simple program transformations break typability.

$$t \ u \quad \Longrightarrow \quad \text{let app} = \lambda x. \lambda y. x \ y \text{ in app } t \ u$$

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For System F and beyond: see [Dunfield and Krishnaswami 2021].

# Hindley-Damas-Milner

## type inference for ML

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## Idea (1)

$$A ::= X, Y, Z \mid A \rightarrow B$$

$$\frac{\Gamma, x:A \vdash t : B}{\Gamma \vdash \lambda x. t : A \rightarrow B}$$

Idea: if we read this rule in mode

$\Gamma \vdash t : ?$

then  $A$  is *unknown*



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Unknown type variables

$$A ::= \dots \mid a_?, b_?, c_?$$

$$\frac{\Gamma, x:a_? \vdash_{\text{inf}} t : B}{\Gamma \vdash_{\text{inf}} \lambda x. t : a_? \rightarrow B}$$

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Unknown type variables  $A ::= \dots \mid a_?, b_?, c_?$

$$\frac{\Gamma, x:a_? \vdash_{\text{inf}} t : B}{\Gamma \vdash_{\text{inf}} \lambda x. t : a_? \rightarrow B}$$

To express the application rule in this style, we use unification constraints  $A \stackrel{?}{=} B$ :

$$\frac{\Gamma \vdash_{\text{inf}} t : A \quad \Gamma \vdash_{\text{inf}} u : B \quad A \stackrel{?}{=} (B \rightarrow c_?)}{\Gamma \vdash_{\text{inf}} t u : c_?}$$

## Idea (2)

$$\frac{}{\Gamma, x:A \vdash_{\text{inf}} x : A} \quad \frac{\Gamma, x:a_{?} \vdash_{\text{inf}} t : B}{\Gamma \vdash_{\text{inf}} \lambda x. t : a_{?} \rightarrow B} \quad \frac{\Gamma \vdash_{\text{inf}} t : A \quad \Gamma \vdash_{\text{inf}} u : B \quad A \stackrel{?}{=} (B \rightarrow c_{?})}{\Gamma \vdash_{\text{inf}} t u : c_{?}}$$

Typing  $\Gamma \vdash_{\text{inf}} t : ?$  gives:

- a type  $A$
- mentioning some unknowns  $\overline{a_{?}}$
- and a collection of unification constraints  $A \stackrel{?}{=} B$

*A system of equations.*

If a *solution*  $\gamma$  exists, mapping unknowns to known types, we have  $\gamma(\Gamma) \vdash t : \gamma(A)$ .

Example:  $\emptyset \vdash \lambda x. \lambda y. x y : ?$

## Idea (2)

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that is,  $(b_{\text{?}} \rightarrow c_{\text{?}}) \rightarrow (b_{\text{?}} \rightarrow c_{\text{?}})$

# Meta-theory

Define a language of *constraints*:  $C ::= \text{True} \mid \text{False} \mid C_1 \wedge C_2 \mid \exists a_?. C \mid A \stackrel{?}{=} B$

And a *constraint generation* function  $_{\Gamma} \llbracket t \rrbracket_A$  such that

$$\gamma \vdash _{\Gamma} \llbracket t \rrbracket_A \implies \gamma(\Gamma) \vdash t : \gamma(A)$$

$$\Gamma \vdash t : A \implies \exists \gamma. \gamma \vdash _{\Gamma} \llbracket t \rrbracket_A$$

$$\gamma \vdash \text{True}$$

$$\frac{\gamma \vdash C_1 \quad \gamma \vdash C_2}{\gamma \vdash C_1 \wedge C_2}$$

$$\frac{\gamma[a_? := A] \vdash C}{\gamma \vdash \exists a_?. C}$$

$$\frac{\gamma(A) = \gamma(B)}{\gamma \vdash A \stackrel{?}{=} B}$$

Questions:

- is this enough?

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$$\begin{array}{c} \gamma \vdash \text{True} \\ \gamma \vdash C_1 \quad \gamma \vdash C_2 \\ \hline \gamma \vdash C_1 \wedge C_2 \end{array} \qquad \frac{\gamma[a_? := A] \vdash C}{\gamma \vdash \exists a_?. C} \qquad \frac{\gamma(A) = \gamma(B)}{\gamma \vdash A \stackrel{?}{=} B}$$

Questions:

- is this enough? (several solutions?)

Cool “applicative” approach: [Pottier 2014]

# “let”-polymorphism

Idea:

$$\begin{aligned}\emptyset \vdash \lambda x. \lambda y. x y : ? &\implies a_? \rightarrow b_? \rightarrow c_? \text{ with } a_? = b_? \rightarrow c_? \\ &\implies (b_? \rightarrow c_?) \rightarrow b_? \rightarrow c_? \\ &\implies \forall \beta \gamma. (\beta \rightarrow \gamma) \rightarrow \beta \rightarrow \gamma\end{aligned}$$

Realisation:

$$\frac{\Gamma \vdash_{\text{inf}} t : A[\overline{a_?}] \quad \overline{a_?} \notin \Gamma \quad \Gamma, x:\forall \overline{\alpha}. A[\overline{a_?} := \overline{\alpha}] \vdash u : B}{\Gamma \vdash_{\text{inf}} \text{let } x = t \text{ in } u : B}$$

```
let f x =  
  let y z = (x, z) in  
  ...
```



Unification constraints: **union-find** data structure.

(Live-coding exercise!)

Efficient generalization: variable **ranks** (or **levels**).

# Whacky project ideas from the audience

- NbE for a dependently typed language
- Effect handlers
- Linear types / session types
- lambda-lambda-bar-mu-mutilda (recursion and corecursion?)
- modal type systems / type-systems for stream programming

# References

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François Pottier. 2014. Hindley-Milner elaboration in applicative style. *ICFP*. <http://cambium.inria.fr/~fpottier/publis/fpottier-elaboration.pdf>.

Jana Dunfield and Neel Krishnaswami. 2021. Bidirectional Typing. *ACM Computing Surveys* 54, 5, 1–38. <https://arxiv.org/abs/1908.05839>.