

## MPRI 2.4

# From operational semantics to (verified) interpreter

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## 1 Efficient execution mechanisms

A naïve interpreter

Natural semantics

Environments and closures

An efficient interpreter

## 2 Scaling up the language

## 1 Efficient execution mechanisms

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## 2 Scaling up the language

# A naïve interpreter

An **interpreter** executes a program (represented by its AST).

Let us write one, in OCaml, by paraphrasing the small-step semantics.

# Abstract syntax

This is the abstract syntax of the  $\lambda$ -calculus:

```
type var = int (* a de Bruijn index *)
type term =
| Var of var
| Lam of (* bind: *) term
| App of term * term
```

For example, the term  $\lambda x.x$  is represented as follows:

```
let id =
  Lam (Var 0)
```

## Renaming

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Scaling up

lift\_  $i$   $k$  represents the renaming  $\uparrow^i (+k)$ .

```
let rec lift_ i k (t : term) : term =
  match t with
  | Var x ->
    if x < i then t else Var (x + k)
  | Lam t ->
    Lam (lift_ (i + 1) k t)
  | App (t1, t2) ->
    App (lift_ i k t1, lift_ i k t2)

let lift k t =
  lift_ 0 k t
```

Thus, lift  $k$  represents  $+k$ . (This renaming adds  $k$  to every variable.)

It is used when one moves the term  $t$  down into  $k$  binders. (Next slide.)

## Substitution

`subst_ i sigma` represents the substitution  $\uparrow^i \sigma$ .

```
let rec subst_ i (sigma : var -> term) (t : term) : term =
  match t with
  | Var x ->
    if x < i then t else lift i (sigma (x - i))
  | Lam t ->
    Lam (subst_ (i + 1) sigma t)
  | App (t1, t2) ->
    App (subst_ i sigma t1, subst_ i sigma t2)

let subst sigma t =
  subst_ 0 sigma t
```

Thus, `subst sigma` represents  $\sigma$ .

## Substitution

A substitution is encoded as a total function of variables to terms.

```
let singleton (u : term) : var -> term =
  function 0 -> u | x -> Var (x - 1)
```

`singleton u` represents the substitution  $u \cdot id$ .

# Recognizing values

It is easy to test whether a term is a value:

```
let is_value = function
| Var _      ->
| Lam _      ->
    true
| App _      ->
    false
```

## Performing one step of reduction

A direct transcription of Plotkin's definition of call-by-value reduction:

```
let rec step (t : term) : term option =
  match t with
  | Lam _ | Var _ -> None
  (* Plotkin's BetaV *)
  | App (Lam t, v) when is_value v ->
    Some (subst (singleton v) t)
  (* Plotkin's AppL *)
  | App (t, u) when not (is_value t) ->
    in_context (fun t' -> App (t', u)) (step t)
  (* Plotkin's AppVR *)
  | App (v, u) when is_value v ->
    in_context (fun u' -> App (v, u')) (step u)
  (* All cases covered already, but OCaml cannot see it. *)
  | App (_, _) ->
    assert false
```

We have guarded `AppL` so that `AppL` and `AppVR` are mutually exclusive.

## Performing one step of reduction

`in_context` is just the `map` combinator of the type `_ option`.

```
let in_context f ox =
  match ox with
  | None -> None
  | Some x -> Some (f x)
```

## Performing many steps of reduction

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Scaling up

To evaluate a term, one performs as many reduction steps as possible:

```
let rec eval (t : term) : term =
  match step t with
  | None ->
    t
  | Some t' ->
    eval t'
```

The function call `eval t` either diverges or returns an irreducible term, which must be either a value or stuck.

## Sources of inefficiency

Unfortunately, this is a terribly inefficient way of interpreting programs.

At each reduction step, one must:

- Find the next redex, that is, decompose the term  $t$  as  $E[\lambda(x.u) v]$ .  
Time:  $O(\text{depth}(E))$ , that is,  $O(\text{height}(t))$ .
- Perform the substitution  $u[v/x]$ .  
Time:  $O(\text{size}(u) \times \text{size}(v))$ .
- Construct the term  $E[u[v/x]]$ .  
Time:  $O(\text{depth}(E))$ , that is,  $O(\text{height}(t))$ .

Thus, one reduction step requires much more than constant time!

There seem to be two main sources of inefficiency:

- We keep forgetting the current evaluation context,  
only to discover it again at the next reduction step.
- We perform costly substitutions.

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## Towards an alternative to small steps

A reduction sequence from an application  $t_1 t_2$  to a final value  $v$  always has the form:

$$t_1 t_2 \xrightarrow[\text{cbv}]{\star} (\lambda x. u_1) t_2 \xrightarrow[\text{cbv}]{\star} (\lambda x. u_1) v_2 \xrightarrow[\text{cbv}]{\star} u_1[v_2/x] \xrightarrow[\text{cbv}]{\star} v$$

where  $t_1 \xrightarrow[\text{cbv}]{\star} \lambda x. u_1$  and  $t_2 \xrightarrow[\text{cbv}]{\star} v_2$ . That is,

Evaluate operator; evaluate operand; call; continue execution.

Idea: define a “big-step” relation  $t \downarrow_{\text{cbv}} v$ ,  
which relates a term directly with the **final outcome**  $v$  of its evaluation,  
and whose definition reflects the above structure.

# Natural semantics, a.k.a. big-step semantics

The relation  $t \downarrow_{\text{cbv}} v$  means that evaluating  $t$  terminates and produces  $v$ .

Here is its definition, for call-by-value:

$$\frac{\text{BIGCBVVALUE} \quad \text{BIGCBVAPP}}{v \downarrow_{\text{cbv}} v \quad t_1 \downarrow_{\text{cbv}} \lambda x. u_1 \quad t_2 \downarrow_{\text{cbv}} v_2 \quad u_1[v_2/x] \downarrow_{\text{cbv}} v}{t_1 \ t_2 \downarrow_{\text{cbv}} v}$$

Exercise: define  $\downarrow_{\text{cbn}}$ .

## Example

Let us write  $\downarrow$  for  $\downarrow_{\text{cbv}}$ , and “ $v \downarrow \cdot$ ” for “ $v \downarrow v$ ”.

$$\begin{array}{c}
 \lambda x.x \downarrow \cdot \\
 1 \downarrow \cdot \\
 1 \downarrow \cdot \\
 \hline
 \lambda x.\lambda y.y \ x \downarrow \cdot \quad \overline{(\lambda x.x) \ 1 \downarrow 1} \quad \lambda y.y \ 1 \downarrow \cdot \\
 \hline
 (\lambda x.\lambda y.y \ x) \ ((\lambda x.x) \ 1) \downarrow \lambda y.y \ 1 \quad \lambda x.x \downarrow \cdot \quad \overline{(\lambda x.x) \ 1 \downarrow 1} \\
 \hline
 (\lambda x.\lambda y.y \ x) \ ((\lambda x.x) \ 1) \ (\lambda x.x) \downarrow 1
 \end{array}$$

Whereas a proof of  $t \xrightarrow{\text{cbv}} t'$  has linear structure,  
 a proof of  $t \downarrow_{\text{cbv}} v$  has tree structure.

## Some history



Martin-Löf uses big-step semantics, in English:

To execute  $c(a)$ , first execute  $c$ . If you get  $(\lambda x) b$  as result, then continue by executing  $b(a/x)$ .  
Thus  $c(a)$  has value  $d$  if  $c$  has value  $(\lambda x) b$  and  $b(a/x)$  has value  $d$ .

He proposes type theory (1975) as a very high-level programming language in which both **programs** and **specifications** can be written.

Which is what we are doing today, in **this** lecture!

Per Martin-Löf,  
**Constructive Mathematics and Computer Programming**, 1984.

# Some history

Kahn promotes big-step operational semantics:

$\rho \vdash \text{number } N \Rightarrow N$	(1)
$\rho \vdash \text{true} \Rightarrow \text{true}$	(2)
$\rho \vdash \text{false} \Rightarrow \text{false}$	(3)
$\rho \vdash \lambda P.E \Rightarrow [\lambda P.E, \rho]$	(4)
$\frac{\rho \vdash \text{value} \ i \infty \text{ ident} \mapsto \alpha}{\rho \vdash \text{ident} \ i \infty \mapsto \alpha}$	(5)
$\frac{\rho \vdash E_1 \Rightarrow \text{true} \quad \rho \vdash E_2 \Rightarrow \alpha}{\rho \vdash \text{if } E_1 \text{ then } E_2 \text{ else } E_3 \Rightarrow \alpha}$	(6)
$\frac{\rho \vdash E_1 \Rightarrow \text{false} \quad \rho \vdash E_2 \Rightarrow \alpha}{\rho \vdash \text{if } E_1 \text{ then } E_2 \text{ else } E_3 \Rightarrow \alpha}$	(7)
$\frac{\rho \vdash E_1 \Rightarrow \alpha \quad \rho \vdash E_2 \Rightarrow \beta}{\rho \vdash (E_1, E_2) \Rightarrow (\alpha, \beta)}$	(8)
$\frac{\rho \vdash E_1 \Rightarrow [\lambda P.E, \rho_1] \quad \rho \vdash E_2 \Rightarrow \alpha \quad \rho_1 \cdot P \mapsto \alpha \vdash E_1 \Rightarrow \beta}{\rho \vdash E_1 E_2 \Rightarrow \beta}$	(9)
$\frac{\rho \vdash E_1 \Rightarrow \alpha \quad \rho \cdot P \mapsto \alpha \vdash E_1 \Rightarrow \beta}{\rho \vdash \text{let } P = E_1 \text{ in } E_2 \Rightarrow \beta}$	(10)
$\frac{\rho \cdot P \mapsto \alpha \vdash E_1 \Rightarrow \alpha \quad \rho \cdot P \mapsto \alpha \vdash E_1 \Rightarrow \beta}{\rho \vdash \text{letrec } P = E_1 \text{ in } E_2 \Rightarrow \beta}$	(11)



Figure 2. The dynamic semantics of mini-ML

He gives a big-step operational semantics of MiniML, a static type system, and a compilation scheme towards the CAM.

Gilles Kahn, **Natural semantics**, 1987.

## A big-step interpreter

The call `eval t` attempts to compute a value  $v$  such that  $t \downarrow_{\text{cbv}} v$  holds.

```
exception RuntimeError
let rec eval (t : term) : term =
  match t with
  | Lam _ | Var _ -> t
  | App (t1, t2) ->
    let v1 = eval t1 in
    let v2 = eval t2 in
    match v1 with
    | Lam u1 -> eval (subst (singleton v2) u1)
    | _       -> raise RuntimeError
```

If `eval` terminates normally, then it **obviously** returns a value;  
but it can also fail to terminate or terminate with a runtime error. (Why?)

This interpreter does not forget and rediscover the evaluation context.  
The context is now **implicit** in the interpreter's **stack**!

We **could** prove this interpreter correct, but will first optimize it further.

# Equivalence between small-step and big-step semantics

## Lemma (From big-step to small-step)

If  $t \downarrow_{\text{cbv}} v$ , then  $t \xrightarrow{\star}_{\text{cbv}} v$ .

### Proof.

By induction on the derivation of  $t \downarrow_{\text{cbv}} v$ .

Case **BigCBVValue**. We have  $t = v$ . The result is immediate.

Case **BigCBVApp**.  $t$  is  $t_1 t_2$ , and we have three subderivations:

$$t_1 \downarrow_{\text{cbv}} \lambda x. u_1$$

$$t_2 \downarrow_{\text{cbv}} v_2$$

$$u_1[v_2/x] \downarrow_{\text{cbv}} v$$

Applying the ind. hyp. to them yields three reduction sequences:

$$t_1 \xrightarrow{\star}_{\text{cbv}} \lambda x. u_1$$

$$t_2 \xrightarrow{\star}_{\text{cbv}} v_2$$

$$u_1[v_2/x] \xrightarrow{\star}_{\text{cbv}} v$$

By reducing under an evaluation context and by chaining, we obtain:

$$t_1 t_2 \xrightarrow{\star}_{\text{cbv}} (\lambda x. u_1) t_2 \xrightarrow{\star}_{\text{cbv}} (\lambda x. u_1) v_2 \xrightarrow{\text{cbv}} u_1[v_2/x] \xrightarrow{\star}_{\text{cbv}} v$$

See [LambdaCalculusBigStep/bigcbv\\_star\\_cbv](#).



# Equivalence between small-step and big-step semantics

**Lemma (From small-step to big-step, preliminary)**

*If  $t_1 \rightarrow_{cbv} t_2$  and  $t_2 \downarrow_{cbv} v$ , then  $t_1 \downarrow_{cbv} v$ .*

**Proof (Sketch).**

By induction on the first hypothesis and case analysis on the second hypothesis. See [LambdaCalculusBigStep/cbv\\_bigcbv\\_bigcbv](#). □

**Lemma (From small-step to big-step)**

*If  $t \rightarrow_{cbv}^* v$ , then  $t \downarrow_{cbv} v$ .*

**Proof.**

By induction on the first hypothesis, using  $v \downarrow_{cbv} v$  in the base case and the above lemma in the inductive case.

See [LambdaCalculusBigStep/star\\_cbv\\_bigcbv](#). □

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## An alternative to naïve substitution

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Scaling up

A basic need is to record that  $x$  is bound to  $v$  while evaluating a term  $t$ .

So far, we have used an eager substitution,  $t[v/x]$ , but:

- This is inefficient.
- This does not respect the separation between immutable **code** and mutable **data** imposed by current hardware and operating systems.

Idea: instead of applying the substitution  $[v/x]$  to the code, record the binding  $x \mapsto v$  in a data structure, known as an **environment**.

An environment is a **finite map** of variables to (closed) values.

## A first attempt

Let us **try** and define a new big-step evaluation judgement,  $e \vdash t \downarrow_{\text{cbv}} v$ .

(previous definition)

 $\text{BIGCBVVALUE}$ 

$$\frac{}{v \downarrow_{\text{cbv}} v}$$

 $\text{BIGCBVAPP}$ 

$$\frac{\begin{array}{c} t_1 \downarrow_{\text{cbv}} \lambda x. u_1 \\ t_2 \downarrow_{\text{cbv}} v_2 \\ u_1[v_2/x] \downarrow_{\text{cbv}} v \end{array}}{t_1 t_2 \downarrow_{\text{cbv}} v}$$

(attempt at a new definition)

 $\text{EBIGCBVVAR}$ 

$$\frac{e(x) = v}{e \vdash x \downarrow_{\text{cbv}} v}$$

 $\text{EBIGCBVLAM}$ 

$$\frac{}{e \vdash \lambda x. t \downarrow_{\text{cbv}} \lambda x. t}$$

 $\text{EBIGCBVAPP}$ 

$$\frac{\begin{array}{c} e \vdash t_1 \downarrow_{\text{cbv}} \lambda x. u_1 \\ e \vdash t_2 \downarrow_{\text{cbv}} v_2 \\ e[x \mapsto v_2] \vdash u_1 \downarrow_{\text{cbv}} v \end{array}}{e \vdash t_1 t_2 \downarrow_{\text{cbv}} v}$$

What is wrong with this definition?

# Lexical scoping versus dynamic scoping

What value should the following OCaml code produce?

```
let x = 42 in
let f = fun () -> x in
let x = "oops" in
f()
```

# Lexical scoping versus dynamic scoping

What value should the following OCaml code produce?

```
let x = 42 in
let f = fun () -> x in
let x = "oops" in
f()
```

Well,

- The answer is 42. This is lexical scoping. This is  $\lambda$ -calculus.
- The answer is not "oops". That would be dynamic scoping.

# Lexical scoping versus dynamic scoping

What value should the following OCaml code produce?

```
let x = 42 in
let f = fun () -> x in
let x = "oops" in
f()
```

Well,

- The answer is 42. This is lexical scoping. This is  $\lambda$ -calculus.
- The answer is not "oops". That would be dynamic scoping.

Thus, the free variables of a  $\lambda$ -abstraction must be evaluated:

- in the environment that exists at the function's creation site,
- not in the environment that exists at the function's call site.

## A failed attempt

Thus, our first attempt is wrong:

- It implements **dynamic scoping** instead of lexical scoping.
- If  $e \vdash t \downarrow_{\text{cbv}} v$  and  $\text{fv}(t) \subseteq \text{dom}(e)$  then we would expect that  $v$  is closed and  $t[e] \downarrow_{\text{cbv}} v$  holds — but that is **not** the case.
- The candidate rule **EBigCbvLAM** obviously **violates** this property.  
It fails to **record the environment** that exists at function creation time.

How can we **fix** the problem?

## Closures



The result of evaluating a  $\lambda$ -abstraction  $\lambda x.t$ , where  $fv(\lambda x.t)$  may be nonempty, should **not** be  $\lambda x.t$ .

It should be a **closure**  $\langle \lambda x.t \mid e \rangle$ ,

- that is, a **pair** of a  $\lambda$ -abstraction and an environment,
- in other words, a pair of a **code** pointer and a pointer to a heap-allocated **data structure**.

Landin, *The Mechanical Evaluation of Expressions*, 1964.

## Closures and environments

The abstract syntax of closures is:

$$c ::= \langle \lambda x.t \mid e \rangle$$

We expect the evaluation of a term to produce a closure:

$$e \vdash t \downarrow_{\text{cbv}} c$$

Because evaluating  $x$  produces  $e(x)$ ,  
an environment must be a finite map of variables to closures:

$$e ::= [] \mid e[x \mapsto c]$$

Thus, the syntaxes of closures and environments are **mutually inductive**.

# A big-step semantics with environments

Evaluating a  $\lambda$ -abstraction produces a newly allocated closure.

$$\text{EBigCbvVar} \quad \frac{e(x) = c}{e \vdash x \downarrow_{\text{cbv}} c}$$

$$\text{EBigCbvLam} \quad \frac{fv(\lambda x.t) \subseteq \text{dom}(e)}{e \vdash \lambda x.t \downarrow_{\text{cbv}} \langle \lambda x.t \mid e \rangle}$$

$$\text{EBigCbvApp} \quad \frac{\begin{array}{c} e \vdash t_1 \downarrow_{\text{cbv}} \langle \lambda x.u_1 \mid e' \rangle \\ e \vdash t_2 \downarrow_{\text{cbv}} c_2 \\ e'[x \mapsto c_2] \vdash u_1 \downarrow_{\text{cbv}} c \end{array}}{e \vdash t_1 t_2 \downarrow_{\text{cbv}} c}$$

Invoking a closure causes the closure's code to be evaluated **in the closure's environment**, extended with a binding of formal to actual.

## Equivalence between big-step semantics without and with environments

How can we relate the judgements  $t \downarrow_{\text{cbv}} v$  and  $e \vdash t \downarrow_{\text{cbv}} c$ ?

What lemma should we state?

## Equivalence between big-step semantics without and with environments

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Assuming  $t$  is closed, we would like to prove that

$$t \downarrow_{\text{cbv}} v$$

holds if and only if

## Equivalence between big-step semantics without and with environments

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What lemma should we state?

Assuming  $t$  is closed, we would like to prove that

$$t \downarrow_{\text{cbv}} v$$

holds if and only if

$$\boxed{\quad} \vdash t \downarrow_{\text{cbv}} c$$

holds for **some** closure  $c$  such that  $c$  represents  $v$  in a certain sense.

## Decoding closures

$c$  represents  $v$  can be defined as  $\lceil c \rceil = v$ , where  $\lceil c \rceil$  is defined by:

$$\lceil (\lambda x.t \mid e) \rceil = (\lambda x.t)[\lceil e \rceil]$$

and where the substitution  $\lceil e \rceil$  maps every variable  $x$  in  $\text{dom}(e)$  to  $\lceil e(x) \rceil$ .

( $\lceil c \rceil$  and  $\lceil e \rceil$  are mutually inductively defined.)

# Equivalence between big-step semantics without and with environments

One implication is easily established:

**Lemma (Soundness of the environment semantics)**

$e \vdash t \downarrow_{cbv} c$  implies  $t[\lceil e \rceil] \downarrow_{cbv} \lceil c \rceil$ .

**Proof (Sketch).**

By induction on the hypothesis.

See [LambdaCalculusBigStep/ebigcbv\\_bigcbv](#). □

In particular,  $\emptyset \vdash t \downarrow_{cbv} c$  implies  $t \downarrow_{cbv} \lceil c \rceil$ .

# Equivalence between big-step semantics without and with environments

The reverse implication requires a more complex statement:

## Lemma (Completeness of the environment semantics)

If  $t[\lceil e \rceil] \downarrow_{\text{cbv}} v$ , where  $\text{fv}(t) \subseteq \text{dom}(e)$  and  $e$  is well-formed, then there exists  $c$  such that  $e \vdash t \downarrow_{\text{cbv}} c$  and  $\lceil c \rceil = v$ .

## Proof (Sketch).

By induction on the first hypothesis and by case analysis on  $t$ .

See [LambdaCalculusBigStep/bigcbv\\_ebigcbv](#). □

In particular, if  $t$  is closed, then  $t \downarrow_{\text{cbv}} v$  implies  $[] \vdash t \downarrow_{\text{cbv}} c$ ,  
for some closure  $c$  such that  $\lceil c \rceil = v$ .

# Equivalence between big-step semantics without and with environments

The notion of **well-formedness** on the previous slide is inductively defined:

$$\frac{\begin{array}{c} \text{fv}(\lambda x.t) \subseteq \text{dom}(e) \\ e \text{ is well-formed} \end{array}}{\langle \lambda x.t \mid e \rangle \text{ is well-formed}} \qquad \frac{\forall x, x \in \text{dom}(e) \Rightarrow e(x) \text{ is well-formed}}{e \text{ is well-formed}}$$

**Lemma (Well-formedness is an invariant)**

If  $e \vdash t \downarrow_{\text{cbv}} c$  holds and  $e$  is well-formed, then  $c$  is well-formed.

**Proof.**

See [LambdaCalculusBigStep/ebigcbv\\_wf\\_cvalue](#).

□

This property is exploited in the proof of the previous lemma.

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## From big-step semantics to interpreter, again

The big-step semantics  $e \vdash t \downarrow_{\text{cbv}} c$  is a 3-place relation.

We now wish to define a (partial) function of two arguments  $e$  and  $t$ .

We **could** do this in OCaml, as we did earlier today.

Let us do it in Coq and prove this interpreter correct and complete!

See [LambdaCalculusInterpreter](#).

## Syntax

The syntax of terms (in de Bruijn's representation) is as before.

The syntax of closures and environments is as shown earlier:

```
Inductive cvalue :=
| Clo: {bind term} -> list cvalue -> cvalue.
```

```
Definition cenv :=
list cvalue.
```

## A first attempt

```
Fail Fixpoint interpret (e : cenv) (t : term) : cvalue :=
  match t with
  | Var x =>
    nth x e dummy_cvalue
    (* dummy is used when x is out of range *)
  | Lam t =>
    Clo t e
  | App t1 t2 =>
    let cv1 := interpret e t1 in
    let cv2 := interpret e t2 in
    match cv1 with Clo u1 e' =>
      interpret (cv2 :: e') u1
    end
  end.
```

Why is this definition **rejected** by Coq?

## A standard trick: fuel

We parameterize the interpreter with a maximum recursive call depth  $n$ .

```
Fixpoint interpret (n : nat) e t : option cvalue :=
  match n with
  | 0      => None (* not enough fuel *)
  | S n   =>
    match t with
    | Var x      => Some (nth x e dummy_cvalue)
    | Lam t      => Some (Clo t e)
    | App t1 t2 =>
        interpret n e t1 >>= fun cv1 =>
        interpret n e t2 >>= fun cv2 =>
        match cv1 with Clo u1 e' =>
          interpret n (cv2 :: e') u1
        end
    end
  end end.
```

The interpreter can now fail, therefore has return type `option cvalue`.

# Equivalence between the big-step semantics and the interpreter

If the interpreter produces a result, then it is a correct result.

## Lemma (Soundness of the interpreter)

*If  $\text{interpret } n \ e \ t = \text{Some } c$  and  $\text{fv}(t) \subseteq \text{dom}(e)$  and  $e$  is well-formed then  $e \vdash t \downarrow_{\text{cbv}} c$  holds.*

## Proof (Sketch).

By induction on  $n$ , by case analysis on  $t$ , and by inspection of the first hypothesis. See [LambdaCalculusInterpreter/interpret\\_ebigcbv](#). □

An interpreter that always returns *None* would satisfy this lemma, hence the need for a completeness statement...

# Equivalence between the big-step semantics and the interpreter

If the evaluation of  $t$  is supposed to produce  $c$ , then, given sufficient fuel, the interpreter returns  $c$ .

## Lemma (Completeness of the interpreter)

*If  $e \vdash t \downarrow_{cbv} c$ , then there exists  $n$  such that  $\text{interpret } n e t = \text{Some } c$ .*

## Proof (Sketch).

By induction on the hypothesis, exploiting the fact that *interpret* is monotonic in  $n$ , that is,  $n_1 \leq n_2$  implies  $\text{interpret } n_1 e t \leq \text{interpret } n_2 e t$ , where the “definedness” partial order  $\leq$  is generated by  $\text{None} \leq \text{Some } c$ . See [LambdaCalculusInterpreter/ebigcbv\\_interpret](#). □

## Summary

If  $t$  is closed and  $v$  is a value, then the following are equivalent:

$$t \xrightarrow{\star}_{\text{cbv}} v$$

small-step substitution semantics

$$t \downarrow_{\text{cbv}} v$$

big-step substitution semantics

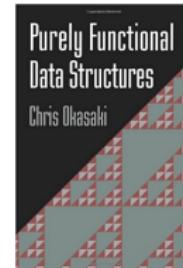
$$\exists c \left\{ \begin{array}{l} \boxed{\quad} \vdash t \downarrow_{\text{cbv}} c \\ \boxed{c} = v \end{array} \right.$$

big-step environment semantics

$$\exists c \exists n \left\{ \begin{array}{l} \text{interpret } n \boxed{\quad} t = \text{Some } c \\ \boxed{c} = v \end{array} \right.$$

interpreter

## Complexity and cost model



For simplicity, we have represented environments as [lists](#).

Thus, extension has complexity  $O(1)$ , but lookup has complexity  $O(n)$ , where  $n$  is the number of variables in scope.

For greater efficiency, one should use a data structure that allows both operations in time  $O(\log n)$ , such as Okasaki's [random access lists](#).

When “extracting” the interpreter from Coq to OCaml, one should also instruct Coq to represent natural numbers as OCaml machine integers.

Okasaki, [Purely functional data structures](#), 1996 (§6.4.1).

# Complexity and cost model

Efficient  
execution  
mechanisms

A naive  
interpreter

Natural  
semantics  
Environments  
and closures

An efficient  
interpreter

Scaling up

With these changes, the interpreter is reasonably efficient.

For time, it offers a relatively clear cost model:

- Evaluating a variable costs  $O(\log n)$ .
- Evaluating a  $\lambda$ -abstraction costs  $O(1)$ .
- Evaluating an application costs  $O(\log n)$ .

$n$  is the maximum number of variables in scope and could be considered  $O(1)$ , as it depends only on the program's text, not on the input data.

Caveat: the cost of garbage collection is not accounted for in this model.

## Digression: the cost of garbage collection

Let  $H$  be the total heap size.

Let  $R$  be the total size of the *live* objects. Thus,  $R \leq H$ .

Assuming a copying collector, one collection costs  $O(R)$ .

Collection takes place when the heap is full, so frees up  $H - R$  words.

Thus, the *amortized* cost of collection, per freed-up word, is

$$\frac{O(R)}{H - R}$$

Under the hypothesis  $\frac{R}{H} \leq \frac{1}{2}$ , this cost is  $O(1)$ . That is,

*Provided the heap is not allowed to become more than half full,  
freeing up an object takes constant (amortized) time.*

## Full closures versus minimal closures

In reality, this interpreter has one subtle but serious inefficiency.

When a closure  $\langle \lambda x.t \mid e \rangle$  is allocated,  
**the entire environment**  $e$  is stored in it,  
even though  $fv(\lambda x.t)$  may be a **strict subset** of the domain of  $e$ .

We store data that the closure will never need. This is a **space leak**!

To fix this, one should store **a trimmed-down environment** in the closure.

**Exercise:** state and prove that, if  $x$  does not occur free in  $t$ , then the evaluation of  $t$  in an environment  $e$  does not depend on the value  $e(x)$ .

**Exercise:** define an optimized interpreter where, at a closure allocation, every unneeded value in  $e$  is replaced with a dummy value. Prove it equivalent to the simpler interpreter.

## 1 Efficient execution mechanisms

A naïve interpreter

Natural semantics

Environments and closures

An efficient interpreter

## 2 Scaling up the language

## Syntactic sugar

Some constructs may be viewed as syntactic sugar, that is, compiled away by macro-expansion.

E.g., “let  $x = t_1$  in  $t_2$ ” can be viewed as sugar for “ $(\lambda x. t_2) t_1$ ”.

This yields the desired semantics. The following are lemmas:

 $\text{LETV}$ 

$$\frac{}{\text{let } x = v \text{ in } t \longrightarrow_{\text{cbv}} t[v/x]}$$

 $\text{LETL}$ 

$$\frac{t \longrightarrow_{\text{cbv}} t'}{\text{let } x = t \text{ in } u \longrightarrow_{\text{cbv}} \text{let } x = t' \text{ in } u}$$

One may prefer to view “let  $x = t_1$  in  $t_2$ ” as a primitive construct if there is:

- a special typing rule for it, e.g., in ML;
- a special compilation rule for it, e.g., in the CPS transform.
- a restriction of applications to the form “ $v v$ ”, so “let” is the only sequencing construct.

# Products

It is easy to add **pairs** and **projections** to the (call-by-value)  $\lambda$ -calculus.

$$\begin{array}{ll} t ::= \dots | (t, t) | \pi_i t & \text{where } i \in \{0, 1\} \\ v ::= \dots | (v, v) \\ E ::= \dots | (E, t) | (v, E) | \pi_i E \end{array}$$

One new reduction rule is needed:

$$\frac{\text{PROJ}}{\pi_i (v_0, v_1) \xrightarrow{\text{cbv}} v_i}$$

**Exercise:** Extend the call-by-name  $\lambda$ -calculus with pairs and projections.

**Exercise:** Propose a definition of pairs and projections as sugar in the call-by-value  $\lambda$ -calculus. Check that this yields the desired semantics.

One similarly adds **injections** and **case analysis** to CBV  $\lambda$ -calculus.

$$\begin{aligned} t &::= \dots | \text{inj}_i t | \text{case } t \text{ of } x.t \parallel x.t && \text{where } i \in \{0, 1\} \\ v &::= \dots | \text{inj}_i v \\ E &::= \dots | \text{inj}_i E | \text{case } E \text{ of } x.t \parallel x.t \end{aligned}$$

One new reduction rule is needed:

CASE

$$\overline{\text{case } \text{inj}_i v \text{ of } x_0.t_0 \parallel x_1.t_1 \longrightarrow_{\text{cbv}} t_i[v/x_i]}$$

Exercise: Extend the call-by-name  $\lambda$ -calculus with sums.

## Recursive functions

The construct  $\lambda x.t$  is replaced with  $\mu f.\lambda x.t$ .

$$\begin{array}{lcl} t & ::= & \dots | \mu f.\lambda x.t \\ v & ::= & \dots | \mu f.\lambda x.t \end{array}$$

$\lambda x.t$  is sugar for  $\mu_.\lambda x.t$ .

“let rec  $f x = t$  in  $u$ ” is sugar for “let  $f = \mu f.\lambda x.t$  in  $u$ ”.

The  $\beta$ -reduction rule is amended as follows:

$$\frac{\beta_v}{(\mu f.\lambda x.t) v \longrightarrow_{\text{cbv}} t[v/x][\mu f.\lambda x.t/f]}$$

## A few things to remember

An efficient interpreter uses environments and closures, not substitutions.

- It can (easily) be proved correct and complete!

There are several styles of (operational) semantics.

- They can (easily) be proved equivalent!

For denotational semantics, see:

Benton, Birkedal, Kennedy, Varming, Formalizing domains,  
ultrametric spaces and semantics of programming languages, 2010.

Dockins, Formalized, Effective Domain Theory in Coq, 2014.

## A few things to remember

Machine-checked proofs are hard when your definitions are too complex, your statements are wrong, and you are missing key lemmas and tactics.

By which I mean, of course,

## A few things to remember

Machine-checked proofs are hard when your definitions are too complex, your statements are wrong, and you are missing key lemmas and tactics.

By which I mean, of course, that machine-checking helps (forces) you to

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- get definitions right,
- write precise statements,
- develop high-level lemmas and tactics.

"But as for you, be strong and do not give up,  
for your work will be rewarded."

