

HELP sw-to-cmd : switch to cmd mode by RC sw-to-js : switch to js mode by RC rc-api-on : RC in API mode rc-api-off : RC not in API mode js-act : User acts the joystick : odometry valid odom-v odom-x : odometry invalid : odometry loop-closure odom-o : command valid cmd-vcmd-x: command invalid

: command renewed

rc-api && raw-mode rc-api-off

Joystick control without odom

