## Method of Moments for Mixture of Gaussians

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# 1 Mixture of Spherical Gaussians with the same variance parameter $\sigma^2$

For clarity of presenting the idea of method of moments, we consider the mixture of spherical Gaussians with the same covariance. Under this setting, a random variable  $X \in \mathbb{R}^d$  is generated as follows:

$$p(Z = i) = w_i$$

$$X|Z = i \sim \mathcal{N}(\mu_i, \sigma^2 I_d)$$
(1)

for i = 1, ..., k, where k is a known number and  $k \le d$ ,  $I_d$  is the  $d \times d$  identity matrix, and  $\sigma^2$  is the variance parameter common to all k components. We further assume the following non-degeneracy condition:

**Non-degeneracy Condition**:  $\mu_i, i = 1, ..., k$  are linearly independent, and  $w_i > 0$  for all i = 1, ..., k.

We target to recover the parameters  $\{w_i, \mu_i\}_{i=1}^k$  and  $\sigma^2$  from a sample of data points  $\{x_n\}_{n=1}^N$  generated according to (1).

## 2 Raw Moments

## 2.1 Tensor product

In order to work with moments (especially moments of order higher than 2), we need to the notion of tensor product, denoted by  $\otimes$ . Let  $X_1, X_2, X_3 \in \mathbb{R}^d$ , we define  $X_1 \otimes X_2 \otimes X_3$  such that

$$(X_1 \otimes X_2 \otimes X_3)_{ilm} = (X_1)_j (X_2)_l (X_3)_m \tag{2}$$

for j, l, m = 1, ..., d. In a similar style, we define  $X_1 \otimes X_2 = X_1 X_2^T$ .

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#### 2.2 Moments of Mixture of Gaussians

Given (1), when Z = i we can write and

$$X = \mu_i + Y$$

$$Y \sim \mathcal{N}(0, \sigma^2 I_d)$$
(3)

We can compute the following raw moments up to order 3

$$\mathbb{E}[X] = \sum_{i=1}^{k} w_i \mu_i \tag{4}$$

We will denote  $M_1 = \mathbb{E}[X]$  in the following.

$$\mathbb{E}[X \otimes X] = \sum_{i=1}^{k} w_i \mathbb{E}[X \otimes X | Z = i]$$
 (5)

$$= \sum_{i=1}^{k} w_i \mathbb{E}[(\mu_i + Y) \otimes (\mu_i + Y)]$$
 (6)

$$=\sum_{i=1}^{k} w_i \mu_i \otimes \mu_i + \sigma^2 I_d \tag{7}$$

Note we have used the fact that  $\mathbb{E}[Y] = 0$ , and  $\mathbb{E}[Y \otimes Y] = \sigma^2 I_d$ . Plus the fact that  $\mathbb{E}[Y \otimes Y \otimes Y] = 0$ , we compute the 3rd order moment

$$\mathbb{E}[X \otimes X \otimes X] = \sum_{i=1}^{k} w_i \mathbb{E}[X \otimes X \otimes X | Z = i]$$
(8)

$$= \sum_{i=1}^{k} w_i \mathbb{E}[(\mu_i + Y) \otimes (\mu_i + Y) \otimes (\mu_i + Y)]$$
(9)

$$= \sum_{i=1}^{k} w_i \mu_i \otimes \mu_i \otimes \mu_i + \tag{10}$$

$$\sum_{i=1}^{k} w_i \left( \mathbb{E}[\mu_i \otimes Y \otimes Y] + \mathbb{E}[Y \otimes \mu_i \otimes Y] + \mathbb{E}[Y \otimes Y \otimes \mu_i] \right)$$

Now let's take a closer look at the term

$$\sum_{i=1}^{k} w_i \mathbb{E}[Y \otimes \mu_i \otimes Y] = \mathbb{E}[Y \otimes (\sum_{i=1}^{k} w_i \mu_i) \otimes Y]$$
$$= \mathbb{E}[Y \otimes M_1 \otimes Y]$$

In order to further simplify it, we look at a particular cell

$$\mathbb{E}[(Y \otimes M_1 \otimes Y)_{jlm}] = (M_1)_l \mathbb{E}[Y_j Y_m]$$
$$= (M_1)_l \sigma^2 \delta_{jm}$$

where  $\delta_{jm}$  is the Kronecker delta. Thus, in tensor form we have

$$\mathbb{E}[Y \otimes M_1 \otimes Y] = \sigma^2 \sum_{j=1}^d e_j \otimes M_1 \otimes e_j \tag{11}$$

where  $\{e_1, \ldots, e_d\}$  is the canonical basis of d dimension. Similarly we have

$$\mathbb{E}[M_1 \otimes Y \otimes Y] = \sigma^2 \sum_{i=1}^d M_1 \otimes e_i \otimes e_i$$
 (12)

$$\mathbb{E}[Y \otimes Y \otimes M_1] = \sigma^2 \sum_{i=1}^d e_i \otimes e_j \otimes M_1 \tag{13}$$

Thus, in summary we have

$$\mathbb{E}[X \otimes X \otimes X] = \sum_{i=1}^{k} w_i \mu_i \otimes \mu_i \otimes \mu_i +$$

$$\sigma^2 \sum_{j=1}^{d} (M_1 \otimes e_j \otimes e_j + e_j \otimes M_1 \otimes e_j + e_j \otimes e_j \otimes M_1)$$
(14)

## 3 Parameter identification from the moments

From the data sample  $\{x_n\}_{n=1}^N$ , we can compute the empirical moments  $\widetilde{\mathbb{E}}[X]$ ,  $\widetilde{\mathbb{E}}[X \otimes X]$ , and  $\widetilde{\mathbb{E}}[X \otimes X \otimes X]$  as estimates of the theoretical moments. For this reason, we say  $\mathbb{E}[X]$ ,  $\mathbb{E}[X \otimes X]$ , and  $\mathbb{E}[X \otimes X \otimes X]$  are observable. We want to come up with a recipe to identify the parameters  $\{w_i, \mu_i\}_{i=1}^k$  and  $\sigma^2$  from these observable moments.

## 3.1 Identify $\sigma^2$

Let's compute the covariance matrix of X

$$cov(X) = \mathbb{E}[(X - M_1) \otimes (X - M_1)] \tag{15}$$

$$= \sum_{i=1}^{k} w_i \mathbb{E}[(X - M_1) \otimes (X - M_1) | Z = i]$$
 (16)

$$= \sum_{i=1}^{k} w_i \mathbb{E}[(\mu_i - M_1 + Y) \otimes (\mu_i - M_1 + Y)]$$
 (17)

$$= \sum_{i=1}^{k} w_i (\mu_i - M_1) \otimes (\mu_i - M_1) + \sigma^2 I_d$$
 (18)

Note that because  $\sum_{i=1}^k w_i(\mu_i - M_1) = 0$ , the k vectors  $(\mu_i - M_1)$  for  $i = 1, \ldots, k$  are linearly dependent. Thus, from (18) we know  $\sigma^2 = \lambda_{\min}(cov(X))$ , i.e.,  $\sigma^2$  is

the smallest eigenvalue of cov(X). Note because  $cov(X) = \mathbb{E}[X \otimes X] - M_1 \otimes M_1$ , cov(X) is also observable.

# 3.2 Identify $\{w_i, \mu_i\}_{i=1}^k$

We define the following two purified moments

$$M_2 = \mathbb{E}[X \otimes X] - \sigma^2 I_d \tag{19}$$

$$=\sum_{i=1}^{k} w_i \mu_i \otimes \mu_i \tag{20}$$

$$M_3 = \mathbb{E}[X \otimes X \otimes X] - \sigma^2 \sum_{j=1}^d (M_1 \otimes e_j \otimes e_j + e_j \otimes M_1 \otimes e_j + e_j \otimes e_j \otimes M_1)$$
(21)

$$=\sum_{i=1}^{k} w_i \mu_i \otimes \mu_i \otimes \mu_i \tag{22}$$

Once we have identified  $\sigma^2$ ,  $M_2$  is observable thanks to equation (19), and  $M_3$  is observable thanks to equation (21). In the **Non-degeneracy Condition**, we only assume  $\mu_i$ , i = 1, ..., k to be linearly independent, which is not strong enough for us to extract  $\mu_i$  directly through the tensor decomposition in equation (22). We want to cook up another tensor that admits an *orthogonal tensor decomposition*, on which we can apply the *tensor power method*. From (20), we see that  $M_2$  is a symmetric positive semidefinite matrix with rank k. Thus, it admits a thin eigendecomposition

$$M_2 = U\Lambda U^T \tag{23}$$

where  $U = (u_1, \ldots, u_k) \in R^{d \times k}$ , and  $\Lambda = diag(\lambda_1, \ldots, \lambda_k)$  is a diagonal matrix with  $\lambda_i > 0$  for  $i = 1, \ldots, k$ . Now let's define whitening matrix

$$B = U\Lambda^{-1/2} \tag{24}$$

and the following whitened vectors

$$\widehat{\mu}_i = \sqrt{w_i} B^T \mu_i \tag{25}$$

Also note that because  $\mu_i \in span(U)$ , and  $w_i > 0$ , we recover  $\mu_i$  by

$$\mu_i = \frac{1}{\sqrt{w_i}} (B^T)^{\dagger} \widehat{\mu_i} \tag{26}$$

where  $B^T$ )<sup>†</sup> is the Moore-Penrose pseudoinverse on the right of  $B^T$  such that  $B^T(B^T)^{\dagger} = I_k$ . From the definition of (24), we have

$$I_k = B^T M_2 B = M_2(B, B) (27)$$

$$=\sum_{i=1}^{k} w_i(B^T \mu_i) \otimes (B^T \mu_i) \tag{28}$$

$$= \sum_{i=1}^{k} (\sqrt{w_i} B^T \mu_i) \otimes (\sqrt{w_i} B^T \mu_i)$$
 (29)

$$=\sum_{i=1}^{k}\widehat{\mu_i}\otimes\widehat{\mu_i}\tag{30}$$

Thus, the vectors  $\widehat{\mu}_i$ ,  $i=1,\ldots,k$  are orthogonal. Now we apply the whitening to  $M_3$  as follows:

$$M_3(B, B, B) = \sum_{i=1}^k w_i(B^T \mu_i) \otimes (B^T \mu_i)$$
 (31)

$$=\sum_{i=1}^{k} \frac{1}{\sqrt{w_i}} \widehat{\mu_i} \otimes \widehat{\mu_i} \otimes \widehat{\mu_i}$$
 (32)

Thus, the whitened tensor  $M_3(B,B,B)$  admits an orthogonal decomposition (32), which is the merit we need in order to apply the tensor power method for identifying  $\widehat{\mu_i}$ , for  $i=1,\ldots,k$ . We denote  $M_3(B,B,B)=\widehat{M}_3$ . The tensor power method is given by the following iteration

$$\theta_{t+1} \leftarrow \frac{\widehat{M}_3(:, \theta_t, \theta_t)}{\|\widehat{M}_3(:, \theta_t, \theta_t)\|} \tag{33}$$

starting from an initial random vector  $\theta_0$  on the unit sphere  $\mathcal{S}^k$ . It can be proved that  $\theta_t$  will converge to a certain eigenvector  $\widehat{\mu}_i$  of  $\widehat{M}_3$ . Once we have an estimate of  $\widehat{\mu}_i$ , we can identify  $w_i$  by

$$\frac{1}{\sqrt{w_i}} = \widehat{M}_3(\widehat{\mu_i}, \widehat{\mu_i}, \widehat{\mu_i}) \tag{34}$$

Now we want to find another  $\widehat{\mu_j}$  different from  $\widehat{\mu_i}$ . For this purpose, we need to deflate  $\widehat{\mu_i}$  from  $\widehat{M_3}$ . Let  $\mathcal{I}$  be the index set such that  $i \in \mathcal{I}$  if and only if  $(\widehat{\mu_i}, w_i)$  have been identified. The deflation is defined by

$$\widehat{M}_3 \leftarrow \widehat{M}_3 - \sum_{i \in \mathcal{I}} \frac{1}{\sqrt{w_i}} \widehat{\mu_i} \otimes \widehat{\mu_i} \otimes \widehat{\mu_i}$$
 (35)

Please see [1] for the details of orthogonal tensor decomposition and the tensor power method.

#### 3.3 Recipe

In summary, our recipe using the method of moments are as follows:

- 1. Compute the empirical moments explicitly  $\widetilde{M}_1 = \widetilde{\mathbb{E}}[X]$  and  $\widetilde{\mathbb{E}}[X \otimes X]$ .
- 2. Identify  $\sigma^2$  by extracting the smallest eigenvalue of  $\widetilde{\mathbb{E}}[X \otimes X] \widetilde{M}_1 \otimes \widetilde{M}_1$ .
- 3. Form  $M_2$  explicitly by (19), and do the thin eigendecomposition (23) to extract the whitening matrix B in (24).
- 4. Start with  $\mathcal{I} = \emptyset$ . For i = 1, ..., k, do the tensor power iteration (33) using the deflated version (35) until converge (or maximum number of iterations met). We can estimate  $w_i$  by (34). Let  $\mathcal{I} = \mathcal{I} \cup i$ .

Note because in the tensor power iteration, only the action  $\widehat{M}_3(:, \theta_t, \theta_t)$  is needed, we don't need to explicitly form  $\widehat{M}_3$ . Instead, from (21), we have

$$\widehat{M}_{3}(:,\theta_{t},\theta_{t}) = \mathbb{E}[B^{T}X(\theta_{t}^{T}B^{T}X)^{2}] -$$

$$\sigma^{2} \sum_{j=1}^{d} \left(B^{T}M_{1}(\theta_{t}^{T}B^{T}e_{j})^{2} + 2B^{T}e_{j}(\theta_{t}^{T}B^{T}e_{j})(\theta_{t}^{T}B^{T}M_{1})\right)$$
(36)

5. Recover  $\mu_i$  from  $\widehat{\mu_i}$  by (26).

## 4 More general Gaussians

# **4.1** Differing $\sigma_i^2$ for $i = 1, \dots, k$

The method presented above can be straightforwardly extended to the case where each mixture component has as different variance parameter  $\sigma_i^2$ , with some tweaks to the form of the observed moments  $M_2$  and  $M_3$ . Please see [2] for the details.

## 4.2 General covariance matrices $\Sigma_i$

Intuitively, when we have general covariance matrices  $\Sigma_i$  for  $i=1,\ldots,k$ , we have many more parameters to estimate (each  $\Sigma_i$  have  $\frac{d(d+1)}{2}$  entries) than the case of spherical Gaussians. It turns out we need the 4th and 6th order moments in order to approximately recover  $\Sigma_i$  (with the assumption that  $d=O(k^2)$ ). The algorithm is much more complicated and non-trivial to implement, please see [3] for the details.

#### References

[1] A. Anandkumar and R. Ge and D. Hsu and S. M. Kakade and M. Telgarsky, Tensor decompositions for learning latent variable models. *Journal of Machine Learning Research*, Vol. 15, Issue 1, pp. 2773-2832, January 2014.

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- [3] R. Ge and Q. Huang and S. M. Kakade, Learning mixtures of Gaussians in high dimensions, *Proceedings of the forty-seventh annual ACM symposium on Theory of computing*, pp. 761-770, June, 2015.