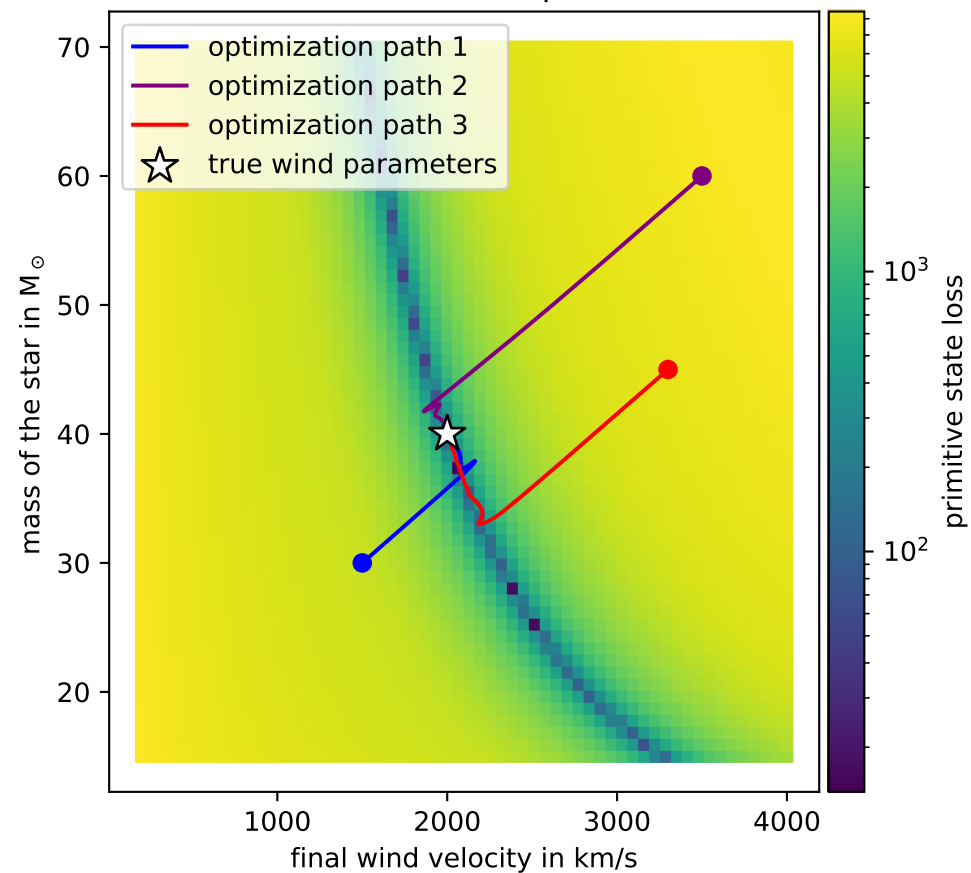


loss landscape



primitive state loss convergence

