

2023010747 21-23  
线性代数作业9

$$1. (1) P = \begin{bmatrix} 0 & 4 & 0 \\ 1 & 8 & 0 \\ -\frac{1}{4} & 4 & 1 \end{bmatrix} \quad J = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\frac{dx(t)}{dt} = Ax(t) \text{ 的解为 } Pe^{Jt}\vec{c}$$

$$\text{即为 } C_1 e^t \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} + C_2 e^t \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} + t \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} + C_3 e^t \begin{pmatrix} 0 \\ 4 \\ -1 \end{pmatrix}$$

$$(2) P = \begin{bmatrix} -1 & -\frac{1}{2} & 0 \\ 1 & 0 & -1 \\ 0 & 0 & 1 \end{bmatrix} \quad J = \begin{bmatrix} 2 & 1 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 4 \end{bmatrix}$$

解为  $Pe^{Jt}\vec{c}$

$$\text{即为 } C_1 e^{4t} \begin{pmatrix} 0 \\ -1 \\ 1 \end{pmatrix} + C_2 \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix} e^{2t} + C_3 \begin{pmatrix} -1 \\ 1 \\ 0 \end{pmatrix} + \begin{pmatrix} -\frac{1}{2} \\ 0 \\ 0 \end{pmatrix} e^{2t}$$

$$2. e^{iA} = I + (iA) + \frac{(iA)^2}{2} + \frac{(iA)^3}{3!} + \dots$$

$$e^{-iA} = I + (-iA) + \frac{(-iA)^2}{2} + \frac{(-iA)^3}{3!} + \dots$$

$$\text{因此 } \frac{1}{2}(e^{iA} + e^{-iA}) = I + \frac{(iA)^2}{2} + \frac{(iA)^4}{4!} + \frac{(iA)^6}{6!} + \dots = I - \frac{A^2}{2} + \frac{A^4}{4!} - \frac{A^6}{6!} + \dots = \cos A$$

$$\frac{1}{2i}(e^{iA} - e^{-iA}) = \frac{1}{2i}(iA + \frac{(iA)^3}{3!} + \frac{(iA)^5}{5!} + \dots) = A - \frac{A^3}{3!} + \frac{A^5}{5!} - \dots = \sin A$$

$$\sin^2 A + \cos^2 A = \frac{1}{4}(e^{2iA} + 2I + e^{-2iA}) - \frac{1}{4}(e^{2iA} - 2I + e^{-2iA}) = I$$

$$3. f(z) = \sin(e^z) \quad f(I) = \sin(e^I), \quad \text{又 } f(I) = \begin{pmatrix} \sin e^c & & \\ & \ddots & \\ & & \sin e^c \end{pmatrix} = (\sin e^c)I \Rightarrow \sin(e^{cI}) = (\sin e^c)I$$

$$\text{令 } f(z) = \cos(e^z) \text{ 则 } \cos(e^{cI}) = (\cos e^c)I$$

同理

$$4. \text{ 验证知 } (a\vec{\alpha} + b\vec{\gamma}, \vec{\beta}) = a(\vec{\alpha}, \vec{\beta}) + b(\vec{\gamma}, \vec{\beta})$$

$$\text{又 } (\vec{\alpha}, \vec{\beta}) = (a_1, a_2) \begin{pmatrix} 1 & -1 \\ -1 & 2 \end{pmatrix} \begin{pmatrix} b_1 \\ b_2 \end{pmatrix} \text{ 其中 } \begin{pmatrix} 1 & -1 \\ -1 & 2 \end{pmatrix} \text{ 正定, 故 } f \text{ 为内积.}$$

$$5. \text{ 设 } \vec{\beta} = a\vec{\alpha}_1 + b\vec{\alpha}_2 = \begin{pmatrix} a-b \\ bi \\ ai+b \end{pmatrix}$$

$$\vec{\beta} \perp \vec{\alpha}_1 \Rightarrow a-b - i(ai+b) = 0 \Rightarrow a = \frac{i+1}{2}b$$

$$\text{又 } |\vec{\beta}| = 1 \Rightarrow (a-b)^2 + (bi)^2 + (ai+b)^2 = 1. \text{ 解得 } \begin{cases} a = \frac{\sqrt{2}(i+1)}{4} \\ b = \frac{\sqrt{2}}{2} \end{cases}$$

$$\text{因此 } \vec{\beta} = \begin{pmatrix} \frac{\sqrt{2}(i-1)}{4} \\ \frac{\sqrt{2}i}{2} \\ \frac{\sqrt{2}(i+1)}{4} \end{pmatrix}$$

$$6. |\vec{\alpha} + \vec{\beta}|^2 + |\vec{\alpha} - \vec{\beta}|^2 = (\vec{\alpha} + \vec{\beta}, \vec{\alpha} + \vec{\beta}) + (\vec{\alpha} - \vec{\beta}, \vec{\alpha} - \vec{\beta}) = (\vec{\alpha}, \vec{\alpha}) + (\vec{\alpha}, \vec{\beta}) + (\vec{\beta}, \vec{\alpha}) + (\vec{\beta}, \vec{\beta}) + (\vec{\alpha}, \vec{\alpha}) - (\vec{\beta}, \vec{\alpha}) - (\vec{\alpha}, \vec{\beta}) + (\vec{\beta}, \vec{\beta}) \\ = 2|\vec{\alpha}|^2 + 2|\vec{\beta}|^2$$

$$7. \text{ 设 } \vec{\alpha} = x_1 \vec{e}_1 + \dots + x_n \vec{e}_n$$

$$\vec{\beta} = y_1 \vec{e}_1 + \dots + y_n \vec{e}_n$$

$$(\vec{\alpha} - \vec{\beta}, \vec{\alpha} - \vec{\beta}) = \sum_{i=1}^n (x_i - y_i)(\vec{\alpha} - \vec{\beta}, \vec{e}_i) = 0 \Rightarrow \vec{\alpha} - \vec{\beta} = 0 \Rightarrow \vec{\alpha} = \vec{\beta}$$

$$8. \text{ 设 } \vec{\alpha} = x_1 \vec{e}_1 + \dots + x_n \vec{e}_n, \text{ 由 } (\vec{\alpha}, \vec{v}_i) = c_i \text{ 知 } \begin{cases} (\vec{v}_1, \vec{v}_1)x_1 + \dots + (\vec{v}_n, \vec{v}_1)x_n = c_1 \\ (\vec{v}_1, \vec{v}_2)x_1 + \dots + (\vec{v}_n, \vec{v}_2)x_n = c_2 \\ \vdots \\ (\vec{v}_1, \vec{v}_n)x_1 + \dots + (\vec{v}_n, \vec{v}_n)x_n = c_n \end{cases} \Rightarrow \begin{pmatrix} (\vec{v}_1, \vec{v}_1) & \dots & (\vec{v}_n, \vec{v}_1) \\ (\vec{v}_1, \vec{v}_2) & \dots & (\vec{v}_n, \vec{v}_2) \\ \vdots & & \vdots \\ (\vec{v}_1, \vec{v}_n) & \dots & (\vec{v}_n, \vec{v}_n) \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix} = \begin{pmatrix} c_1 \\ c_2 \\ \vdots \\ c_n \end{pmatrix}$$

$$\text{令 } A = (\vec{v}_1, \dots, \vec{v}_n), \text{ 则 } A^T A \vec{x} = \vec{c}$$

$$\Rightarrow \vec{x} = (A^T A)^{-1} \vec{c}$$

因此  $\vec{\alpha}$  存在且唯一