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HW11 202301074]
 Problem II. 1 . X = [x, x2]
                                                                                         \chi B = \begin{bmatrix} x_1 & x_2 \\ x_3 & x_4 \end{bmatrix} \begin{bmatrix} 0 & 0 \\ N & NM \end{bmatrix} = \begin{bmatrix} x_{2N} & x_{2NM} \\ x_{4N} & x_{4NM} \end{bmatrix}
                                                                                          \forall \mathbf{X} = \begin{bmatrix} \mathbf{v} & \mathbf{0} \\ \mathbf{v} & \mathbf{0} \end{bmatrix} \begin{bmatrix} \mathbf{x}^2 & \mathbf{x}^4 \end{bmatrix} = \begin{bmatrix} \mathbf{v} \mathbf{x}^1 & \mathbf{v} \mathbf{x}^7 \\ \mathbf{v} \mathbf{v}^2 & \mathbf{v} \mathbf{v}^4 \end{bmatrix}
                                                                                          XB=AX → { x, N = MNX,

X+N = NX,

X+N = MX x

XNM=MNX x

XNM=NX x

let Xz=M. X,=I X+=I and we can satisfy
                                                                                         x = \begin{bmatrix} I & M \\ X_3 & I \end{bmatrix} let X_3 = 0. then x = \begin{bmatrix} I & M \\ 0 & I \end{bmatrix} is also invertible
                                                                     2. A=[ '] B=[ -i]
                                                                                        X = \begin{bmatrix} a & b \\ c & d \end{bmatrix}
AX = \begin{bmatrix} 1 \\ 1 \end{bmatrix} \begin{bmatrix} a & b \\ c & d \end{bmatrix} = \begin{bmatrix} c & d \\ a & b \end{bmatrix}
AX = \begin{bmatrix} 1 \\ 1 \end{bmatrix} \begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} a & b \\ a & b \end{bmatrix} = \begin{bmatrix} c & d \\ a & b \end{bmatrix}
AX = \begin{bmatrix} 1 \\ 1 \end{bmatrix} \begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} a & b \\ c & d \end{bmatrix} = \begin{bmatrix} c & d \\ a & b \end{bmatrix}
AX = \begin{bmatrix} 1 \\ 1 \end{bmatrix} \begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} c & b \\ a & d \end{bmatrix} \begin{bmatrix} c & b \\ d & -ci \end{bmatrix}
AX = \begin{bmatrix} 1 \\ 1 \end{bmatrix} \begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} c & d \\ d & -ci \end{bmatrix}
AX = \begin{bmatrix} 1 \\ 1 \end{bmatrix} \begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} c & d \\ c & d \end{bmatrix} \begin{bmatrix} c & d \\ c & d \end{bmatrix} \begin{bmatrix} c & d \\ c & d \end{bmatrix}
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AX = \begin{bmatrix} 1 \\ 1 \end{bmatrix} \begin{bmatrix} c & d \\ c \end{bmatrix}
AX = \begin{bmatrix} 1 
                                                                       3. A= [ 1 2 3 ] B= [ 1 1 ]
                                                                                      Ax = \begin{bmatrix} 1 & 2 \\ 1 & 3 \end{bmatrix} \begin{bmatrix} 9 & a & b \\ d & h & C \\ e & f & i \end{bmatrix} = \begin{bmatrix} 9 + 2d + 3e & a + 2t + 3f & b + 3c + 23i \\ d + 3e & h + 3f & c + 3i \\ e & f & i \end{bmatrix} \Rightarrow \begin{cases} d = e - f = 0 \\ g = 2 \\ h = 5i \\ a = 2c + 3i \end{cases}
xB = \begin{bmatrix} 3 & a & b \\ 3 & h & C \end{bmatrix} \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix} = \begin{bmatrix} 3 & 9 + a & a + b \\ d & d & h & h + C \end{bmatrix}
                                                                                           xB = [ ] ab [ ] [ ] ] = [ ] 9 9 th arb | d dh hrc | e f fri
                                                                         4. A = \begin{bmatrix} 4 & -2 \\ 2 & -1 \end{bmatrix} B = \begin{bmatrix} 2 \\ 1 \end{bmatrix} X = \begin{bmatrix} A & b \\ c & d \end{bmatrix}
                                                                                    5. A = [4m -2m] B = [2m m]
                                                                                           X = \begin{bmatrix} I & 2I \\ I & 3I \end{bmatrix} and X is invertible
                                                                              6. A = \begin{bmatrix} M & -N \\ N & M \end{bmatrix} B = \begin{bmatrix} M + iN \\ M - iN \end{bmatrix}
                                                                                              X = \begin{bmatrix} I & I \\ -il & iI \end{bmatrix} and X is invertible
                                                                            7. A = \begin{bmatrix} 2J_1 & M \\ 3J_3 \end{bmatrix} B = \begin{bmatrix} 2J_1 \\ 3J_3 \end{bmatrix}
                                                                                                      X = \begin{bmatrix} I_2 & MI_3 \\ O & I_3 \end{bmatrix} and X is invertible
Problem 11.2 1. let B=[n] and we know that Ax=nx
                                                                                    so X is an eigenvector of A
                                                                       2. if VE Ran(x) XW=V
                                                                                                        Axw=Av > XBw=Av > X(Bw)=Av
                                                                                                  SO AV & Ran(X)
                                                                         3. We use mothematical induction to prove A"x=XB"
                                                                                              A'x=xB' is true. suppose A*x=xB* is true
                                                                                              then A^{x+1}x = A(A^xx) = A \times B^x = (Ax) B^x = (xB)B^x = xB^{x+1} is true
                                                                                              therefore we know A^{n}x=xB^{m} is true for all n\in Z^{\dagger}
                                                                                                      since polynomials are just linear combinations of powers
                                                                                                    thus p(A) x = x p(B)
                                                                              4. if B is diagonalizable, B= XBDBX81 PA(B) = XBPA(Do)X81
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since A.B has no common eigenvalue. thus PalDo) diagonal entries are non-zeto thus PalDo is invertible if B is not diagonalizable. we just pick diagonalizable matrices Bn such that B= lim Bn

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so Pa(B) = lim Pa(Bn) is also invertible
                     PAIA) X = X PAIB). from Cayley-Hamilton Theorem. PAIA) = 0
                     thus * Pa(B) = 0, since Pa(B) is invertible. so X=0
Problem 11.3 1. for arbitrary X.Y.
                       L(x+Y) = AK+Y) -(x+Y)B = Ax-xB+ AY-YB = L(x) + L(Y)
                       L(kx) = Akx - kxB = K(Ax-xB) = kL(x)
                 so L is a linear map
              2. if A.B has no eigenvalue
                     then if L(x)=0. from Problem 11.2.4. L(x)=0 => Ax=XB => x=0
                   so Kev(2) = 10], therefore it's trivial
              3. if Ax,-x,B=C and Ax2-x2B=C
                  then A(x1-x2)= (x1-x2)B コ x1-x2=0 コ x1=x2.
                  so we know that L is injective
                  since L: V > V. so L is bijective
                  so the solution to Ax-xB=C exists and unique
Problem 11.4 1. if B is not diagonal lets say B=[:t] has t+0 on (1,9) entry
                  elABej = ait
                                   eł BAej = ajt
                  Since A has distinct diagonal entries. Qi+Qj. So (i,j) entry of AB and BA is not the same, thus AB+BA
                  therefore. B must be diagonal
               2. A has distinct eigenvalues, so A can be diagonalizable.
                   A=XDX', and D has distinct diagonal entries
                   STINCE AB=BA SO XDX B= BXDX = DX BX = X BXD
                   from previous problem . we know that x'bx is also diagonal
                   so both XAX and X'BX are diagonal
              3. A = xDx^{-1} B = xD'x^{-1} A has distinct eigenvalues
                   X is the combination (concat) of all eigenvectors of A and B = XD'X^{-1}
                   thus all eigenvectors of A are eigenvectors of B
                                                                    B = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \quad B = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \quad B \text{ has eigenvector } \begin{bmatrix} 1 \\ 1 \end{bmatrix} \text{ that is not eigenvector of } A
              4. A = \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix} A = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}
               5. A = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} B = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} and B is not diagonalizable
               6. Av= AV ⇒ BAV = BAV → ABV = ABV → A(BU) = A(BV)
                   thus Bu is also an eigenvector of A
Problem 11.5 1. if It is an eigenvalue of A
                  then n^{x}=0 \Rightarrow n=0
                so if A is nxn. then A has eigenvalue 0 with n algebraic multiplicity
                 det(A)=0°=0. so A is non-invertible
              2. Ax=v \( \Rightarrow \) all eigenvalues of A are 0 \( \Rightarrow \) PA(x)=(1) A^
                     if PAIX)=+1)"A". since PA(A)=0 . thus +1)"A"=0 => A"=0
                     if A^{n}=0. A^{n}=0 \Rightarrow A=0. so all eigenvalues ove O
                      so Ak=v ≥> all eigenvalues of A ave 0 ≥> A^=0
               3. A=UTU-1 let D be the diagonal matrix taking all the diagonal entries of T
                   T-D is an upper triangular matrix and diagonal entries are 0. so all eigenvalues are 0
                   (U(T-D)U-1) = U(T-D) U-1=0 => U(T-D)U-1 is nilpotent.
                   and UDU" is a normal matrix, so A = UDU"+ ULT-DIV" is the sum of a normal matrix and a nilpotent matrix
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