Linear algebra HWS 2023010747

3. A is a nxn matrix its diagnol entries remain the same after the transpose, therefor tr (A)=tr (AT)

4. $u = \begin{bmatrix} a_1 \\ a_n \end{bmatrix}$, $u^T = [a_1 \cdots a_n]$ $uu^T = \begin{bmatrix} a_1^* & a_1a_1 & a_2a_1 \\ a_1a_1 & a_2a_2 & a_3a_4 \\ a_1a_1 & a_2a_2 & a_3a_4 \end{bmatrix}$ $tr(uu^T) = \sum_{i=1}^n a_i^2 \cdot since$ we know u is a unit vector therefore we already have $\sum_{i=1}^n a_i^2 \cdot 1 \cdot so$ tr(uu^T) = 1

 $S. \ A^TB = \begin{bmatrix} a_1 & a_2 \\ a_2 & a_4 \end{bmatrix} \begin{bmatrix} b_1 & b_2 \\ b_3 & b_4 \end{bmatrix} = \begin{bmatrix} a_1b_1 + a_2b_3 & \cdots \\ \cdots & a_1b_1 + a_4b_4 \end{bmatrix}$ $AB^T = \begin{bmatrix} a_1 & a_2 \\ a_2 & a_4 \end{bmatrix} \begin{bmatrix} b_1 & b_2 \\ b_2 & b_4 \end{bmatrix} = \begin{bmatrix} a_1b_1 + a_2b_2 & \cdots \\ \cdots & a_1b_2 + a_1b_4 \end{bmatrix}$ $So \ tr(A^TB) = tr(AB^T) = a_1b_1 + a_2b_2 + a_3b_3 + a_4b_4 = \sum_{i=1}^4 a_ib_i$

6. assum
$$V = \begin{bmatrix} A_1 \\ \vdots \\ A_n \end{bmatrix}$$
 $W^T = \begin{bmatrix} b_1 & b_2 \cdots b_n \end{bmatrix}$ $VW^T = \begin{bmatrix} A_1b_1 & a_1b_2 & A_2b_n \\ a_1b_1 & a_2b_2 & \cdots & a_nb_n \\ a_n^T & a_n^T & a_n^T & a_n^T \\ a_n^T & a_n^T & a_n^T & a_n^T \end{bmatrix}$ $ty(vw^T) = \sum_{i=1}^n A_ib_i$. $W^T v = \begin{bmatrix} b_1 & \cdots & b_n \end{bmatrix} \begin{bmatrix} a_1 \\ \vdots \\ a_n \end{bmatrix} = \begin{bmatrix} \sum_{i=1}^n a_ib_i \end{bmatrix}$ so $ty(vw^T) = ty(w^Tv)$

 $T. \quad A = \begin{bmatrix} a_1 & a_2 \cdots a_n \end{bmatrix} \quad B = \begin{bmatrix} b_1^T \\ \vdots \\ b_1^T \end{bmatrix}$

 $tv(AB) = \sum_{i=1}^{n} e_{i}^{T} ABe_{i} = \sum_{i=1}^{n} e_{i}^{T} A(e_{i}e_{i}^{T})Be_{i} = \sum_{i=1}^{n} e_{i}^{T} a_{i}b_{i}^{T}e_{i} = tv(a_{i}b_{i}^{T}) \quad F_{rom} \text{ Problem S.I.b. we know } tv(b_{i}b_{i}^{T}) = tv(b_{i}^{T}a_{i}) = \sum_{i=1}^{n} b_{i}^{T} a_{i} = tv(b_{i}^{T}a_{i}) \quad So \quad tv(AB) = tv(BA)$

8. From the first question we know trace is linear, so triab-BA) = triab)-triba)=0 but $tr(I_2 = n \neq 0$. So AB-BA cannot be the identity matrix

- 2. identity matrix I after permutation is PI. since I = [...,]. the number of fixed elements is just how many I's remain on the diagonal, which is tr(PI), PI=P. so the number of fixed elements is tr(P)
- 3. From Problem 5.1.7 we know tr(P.P.) = tr(P.P.). according to the last question, we know they have the same number of fixed points

Problem 5.3 1. fev then -fev, fiffiev. fiff) is a function: R > 0 which is continuous thus V is not a vector space

3. this is a vector space with dimension 3, a basis can be \$113,51.23,51.2,333

4. this is a vector space with dimension 2 a basis can be $\begin{cases} 0 & 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{cases}$, $\begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$, $\begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$, $\begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$, $\begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$, $\begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$, $\begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$, $\begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$, $\begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$, $\begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$, $\begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$, $\begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$, $\begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$, $\begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$, $\begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$, $\begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$, $\begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$, $\begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$, $\begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$, $\begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$, $\begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$, $\begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$, $\begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$, $\begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$, $\begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$, $\begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$, $\begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$, $\begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$, $\begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$, $\begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$, $\begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$, $\begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$, $\begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$, $\begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$, $\begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$, $\begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$, $\begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$, $\begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$, $\begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$, $\begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$, $\begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$, $\begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$, $\begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$, $\begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$, $\begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$, $\begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$

5. this is a vector space with dimension 2 a basis can be $\left\{ \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \right\}$

6. this is a vector space with dimension \geq a basis can be $\left\{ \begin{bmatrix} 2 & 9 & 4 \\ 7 & 5 & 4 \\ 6 & 1 & 8 \end{bmatrix}, \begin{bmatrix} 2 & 7 & 6 \\ 9 & 5 & 1 \\ 4 & 3 & 8 \end{bmatrix}, \begin{bmatrix} 8 & 3 & 4 \\ 1 & 5 & 9 \\ 6 & 7 & 2 \end{bmatrix} \right\}$

the left side is a upper triangle matrix and the diagonal entries are non-zero, thus A is invertible

2. if ex. ex. ex is dependent, then the vows of A is dependent so A is not bijective thus A is not invertible which forms a contradiction so ex. ex. ex is linearly independent

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3. Suppose the coordinates of f are \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}. f(x) = x_1 \mathcal{E} + x_2 \mathcal{E}^{3x} + x_3 \mathcal{E}^{3x} = A \begin{bmatrix} f(0) \\ f(1) \\ f(2) \end{bmatrix} = A \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}. \begin{bmatrix} x_1 \\ x_3 \\ x_3 \end{bmatrix} = A^{-1} \begin{bmatrix} f(0) \\ f(1) \\ f(2) \end{bmatrix}
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Problem S.S 1. suppose Li= fp.+tv.:teR), Lz=fp.+tv.:teR}

 $\lambda_1, \lambda_2 \in V/W \Rightarrow V_1=VV_2$ so $\lambda_1+\lambda_2=\int p_1+p_2+\int (V+1)V_2: t\in \mathbb{R}^3$, $(V+1)V_2/V_2\Rightarrow \lambda_1+\lambda_2$ is payallel to $\lambda_2\Rightarrow \lambda_1+\lambda_2=\int p_1+p_2+\int (V+1)V_2/V_2\Rightarrow \lambda_1+\lambda_2=\int p_2+\lambda_1+\lambda_2=\int p_1+\lambda_2=\int p_2+\lambda_1+\lambda_2=\int p_1+\lambda_2=\int p_2+\lambda_1+\lambda_2=\int p_2+\lambda_2=\int p_2+$

- 2. K(L+Lx) = {X(p+px)+t K(4+1) Vx: ter} XL+ Kh = {Kp+tK+Vx+Kp+tKVx: ter} thus K(L+Lx)=KL+KL
- 3. W is the zero vector" because w+L=L
- 4. We assume W is in the direction of v = [x,y,z), x,y,z cannot all be zero. Without loss of generality, we assume $Z \neq 0$ for L = S(1.0.0) + tv: $t \in R$. Lie V/w, we put L_1 into the basis, we can easily verify that (0,1,0) is not in S(1) + tx, ty, tz). $t \in R$. Lie V/w so we put L_2 into the basis then for arbitrary L = S(0,1,0) + tv: $t \in R$. Lev/w, we have $L = S(0,-\frac{CX}{2},b,-\frac{CY}{2},0) + tv$: $t' \in R$ and $t' \in R$. Lev/w, we have $L = S(0,-\frac{CX}{2},b,-\frac{CY}{2},0) + tv$: $t' \in R$ as a basis and the dimension of $L = S(0,-\frac{CX}{2},b,-\frac{CY}{2},0) + tv$: $t' \in R$ is a basis and the dimension of $L = S(0,-\frac{CX}{2},b,-\frac{CY}{2},0) + tv$: $t' \in R$ is a basis and the dimension of $L = S(0,-\frac{CX}{2},b,-\frac{CY}{2},0) + tv$.

Problem 5.b 1. Yes. we assume for finitely many polynomials, the maximum of the degree of polynomial is n

we choose $f(x) = x^{n+1}$. if f(x) is in the span, then $f(x) = a_1 f(x) + a_2 f(x) + \dots + a_m f_m(x) \Rightarrow |f(x)| \leq (|a_1| + \dots + |a_m|) (|x|^n + |x|^{n-1} + \dots + |x| + 1)$ $|a_1| + \dots + |a_m| = M$, then $|x|^{n+1} \leq M \cdot \frac{|x|^{n+1}}{|x|-1} \leq M \cdot \frac{|x|^{n+1}}{|x|-1}$ if $x \geq M + 10$, we get $|x|^{n+1} > M \cdot \frac{|x|^{n+1}}{|x|-1}$ which forms a contradiction therefore f(x) is not in the span

- 2. Yes. for fur. girs & W firs = pin. hirs girs = pins. two kfirs + (girs) = (khirs) + (trix). pirs. so kfirs + (girs) & W. thrus W is a subspace
- 3. [+,1x] = 1+1x+ p(x) q(x): q0x e v} [+xx] = 1+xx+ p(x)q(x): q0xe v}

4. if the degree of time > 2. we can use $p(x) = x^2 + 3x + 2$ and q(x) accordingly to reduce its degree let's assume the degree of time is n. $t(x) = ax^m + a_1x^{m-1} + \cdots$ choose $q(x) - ax^{m-2}$ and we can eliminate x^m and get t'(x) whose degree < tous proceed the process similarly and we can get a polynomial whose degree is less than 2

we put $[t'(x) = 1] = 11 + p(x) q(x) : q(x) \in V$ into the basis. but we cannot express $x^2 + 4x + 2$ because it's $\{x + p(x) \cdot q(x) : q(x) \in R\}$ so we put [t'(x) = x] into the basis, then for polynomials whose degree < 1 are in the span. for those degree > 2. Similar as above. we can use $p(x) \cdot q(x)$ to reduce its degree below 2, so it's also in the span.