Peiqi Liu

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EDUCATION

New York University

New York, NY

Bachelors in Honors Computer Science and Mathematics; GPA: 3.96/4.00

Sep 2020 - Dec 2023

PUBLICATIONS

Peiqi Liu, Yaswanth Orru, Jay Vakil, Chris Paxton, Nur Muhammad Mahi Shafiullah, and Lerrel Pinto. Ok-robot: What really matters in integrating open-knowledge models for robotics, 2024

AWARDS & ACHIEVEMENTS

Summa cum laude Honors GPA falls within the top 5% of the previous year's graduating class.

Highest honor in Computer Science GPA greater than 3.65 and Completing an Honors Thesis.

Dean's Undergraduate Research Grant: \$1000 Awarded for conducting prominent research projects.

Research Experience

NYU CILVR, Grail Lab

New York, NY

Undergraduate Researcher

May 2023 - Now, Research Assistant

- Worked on robotics, computer vision, and deep learning project "OK Robot" under the supervision of Prof. Lerrel Pinto that invented a modularized zero shot open vocabulary mobile robot manipulation system.
- Used a voxel-based method to distill vision language features of RGBD images into a semantic memory and designed an A* and SLAM based navigation stack to use semantic memory for open vocabulary navigation.
- Used zero shot grasping model such as AnyGrasp, ContactGraspNet to generate grasps for stretch Robot to pick up objects and filtered grasps by open vocabulary segmentation models such as LangSAM.

NYU CILVR New York, NY

Undergraduate Researcher

Jan 2023 - May 2023, Research Assistant

- Worked on a computer vision and deep learning research project at NYU CILVR Lab with Prof. Mengye Ren that trained a self supervised computer vision model on images from humans' point of view such as SayCam.
- Trained vision representational models by classifying images to video segments they are from and evaluated the models by linear probing on benchmarks such as ImageNet, Toybox.

NYU CILVR New York, NY

 $Under graduate\ Researcher$

Sep 2022 – Mar 2023, Research Assistant

- Worked on a image denoising research project that trained neural network to denoise microscopy images.
- Pretrained a supervised image denoising model on large synthesized image denoising dataset and finetuned it with self supervised method such as N2S, Neighbor2Neighbor.

Work Experience

NYU CILVR New York, NY

Research Assistant

April 2022 - Aug 2022, Part-time

- Worked on a Robotics project Machine Common Sense under supervision of Prof. Rob Fergus where we designed object detection based heuristic policies for agents in Ai2thor simulator to complete different tasks.
- Completed support relations task (predict whether an object at the edge of the table will fall), ramp task (find a ball in a multilevel space), and tool use task (use the tool to poke the ball out from obstalces)

Yahoo New York, NY

Software Development Internship

May 2022 - Aug 2022, Full-time

- Maintained a Yahoo's internal JavaScript dictionary written in TypeScript, Node, Express, React and added new features and fix bugs by writing TypeScript and defining corresponding TypeScript interface.
- Fetched Json data using YQL (Yahoo Query Language) from Vespa database.

SKILLS

AI & Robotics: Python, PyTorch, ROS, ROS2, Machine Learning, Deep Learning, Matplotlib, Numpy, Pandas Software Development: Java, TypeScript, JavaScript, Node, CSS, HTML, React, Linux, Maven, Git, MySQL, C