In [2]:

```
########## HW1-1
from PIL import Image
imgname1 = r'C:\Users\apple\OneDrive\桌面\影像\HW1\laptop_left.png'
img1 = Image.open(imgname1)
imgname2 = r'C:\Users\apple\OneDrive\桌面\影像\HW1\laptop_right.png'
img2 = Image.open(imgname2)
w1 , h1 = img1.size ##200/356
w2 , h2 = img2.size ##280/356
new_w = w1+w2
new_h = h1
new_img = Image.new('RGBA',(new_w,new_h))
new_img.paste(img1,(0,0))
new_img.paste(img2,(w1,0))
new_img.save('new.png')
```

In [13]:

```
######## HW1-2
from PIL import Image
import math
im name = r'C:\Users\apple\OneDrive\桌面\影像\HW1\new.png'
im = Image.open(im_name)
# 計算旋轉後圖片的大小
theta = math.radians(15)
w, h = im.size
new_w = round(abs(w * math.cos(theta)) + abs(h * math.sin(theta)))
new_h = round(abs(h * math.cos(theta)) + abs(w * math.sin(theta)))
new_im = Image.new("RGB", (new_w, new_h), color=(255, 255, 255))
# 計算圖片的中心點
cx, cy = w // 2, h // 2
# 計算旋轉矩陣
cos_theta = math.cos(theta)
sin_theta = math.sin(theta)
rotation_matrix = ((cos_theta, sin_theta), (-sin_theta, cos_theta))
pixels = im.load()
new_pixels = new_im.load()
for i in range(new_w):
    for j in range(new_h):
       # 計算原始圖片上對應的坐標
       x, y = i - new_w // 2, j - new_h // 2
       new_x = round(x * cos_theta + y * sin_theta) + cx
       new_y = round(-x * sin_theta + y * cos_theta) + cy
       # 檢查像素是否超出圖片範圍
       if new_x >= 0 and new_x < w and new_y >= 0 and new_y < h:
           # 設置新圖片的像素值
           new_pixels[i, j] = pixels[new_x, new_y]
new_im.save('rotate.png')
```

In [11]:

```
########## HW1-3
lena_name = r'C:\Users\apple\OneDrive\桌面\影像\HW1\lena.bmp'
lena = Image.open(lena_name)
w , h = lena.size #[512,512]
new_w, new_h = 1024, 1024
hw3 = Image.new("RGB", (new_w, new_h), color=(255, 255, 255))
#縮放比例
sx = new w / w
sy = new_h / h
pixels = lena.load()
new_pixels = hw3.load()
for i in range(new_w):
   for j in range(new_h):
       # 計算對應的原始圖像的坐標
       x = i / sx
       y = j / sy
       # 計算四個最近的像素的坐標
       x1, y1 = int(x), int(y)
       x2, y2 = x1 + 1, y1 + 1
       # 計算插值權重
       wx = x - x1
       wy = y - y1
       try:
           r1, g1, b1 = pixels[x1, y1]
           r2, g2, b2 = pixels[x2, y1]
           r3, g3, b3 = pixels[x1, y2]
           r4, g4, b4 = pixels[x2, y2]
       except IndexError:
           # 如果超出圖像範圍,則將像素設置為白色
           r1, g1, b1 = r2, g2, b2 = r3, g3, b3 = r4, g4, b4 = 255, 255, 255
       # 計算插值後的像素值
       r = int((1 - wx) * (1 - wy) * r1 + wx * (1 - wy) * r2 + (1 - wx) * wy * r3 + wx
       g = int((1 - wx) * (1 - wy) * g1 + wx * (1 - wy) * g2 + (1 - wx) * wy * g3 + wx
       b = int((1 - wx) * (1 - wy) * b1 + wx * (1 - wy) * b2 + (1 - wx) * wy * b3 + wx
       # 設置新圖像的像素值
       new_pixels[i, j] = (r, g, b)
hw3.save('lena2.bmp')
```

In [4]:

Out[4]:

(104, 53)