

3.5 Depth-First Search and Breadth-First Search

The term “exhaustive search” can also be applied to two very important algorithms that systematically process all vertices and edges of a graph. These two traversal algorithms are *depth-first search (DFS)* and *breadth-first search (BFS)*. These algorithms have proved to be very useful for many applications involving graphs in artificial intelligence and operations research. In addition, they are indispensable for efficient investigation of fundamental properties of graphs such as connectivity and cycle presence.

Depth-First Search

It is also very useful to accompany a depth-first search traversal by constructing the so-called *depth-first search forest*. The starting vertex of the traversal serves as the root of the first tree in such a forest. Whenever a new unvisited vertex is reached for the first time, it is attached as a child to the vertex from which it is being reached. Such an edge is called a *tree edge* because the set of all such edges forms a forest. The algorithm may also encounter an edge leading to a previously visited vertex other than its immediate predecessor (i.e., its parent in the tree).

Such an edge is called a *back edge* because it connects a vertex to its ancestor, other than the parent, in the depth-first search forest. Figure 3.10 provides an example of a depth-first search traversal, with the traversal stack and corresponding depth-first search forest shown as well.

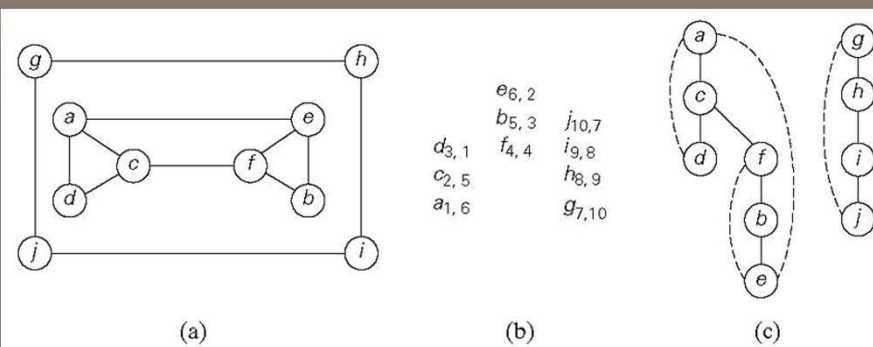


FIGURE 3.10 Example of a DFS traversal. (a) Graph. (b) Traversal's stack (the first subscript number indicates the order in which a vertex is visited, i.e., pushed onto the stack; the second one indicates the order in which it becomes a dead-end, i.e., popped off the stack). (c) DFS forest with the tree and back edges shown with solid and dashed lines, respectively.

ALGORITHM *DFS*(*G*)

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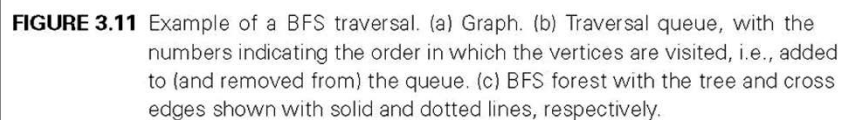
//Implements a depth-first search traversal of a given graph
//Input: Graph  $G = V, E$ 
//Output: Graph  $G$  with its vertices marked with consecutive
        integers
// in the order they are first encountered by the DFS traversal
    mark each vertex in  $V$  with 0 as a mark of being “unvisited”
    count  $\leftarrow$  0
    for each vertex  $v$  in  $V$  do
        if  $v$  is marked with 0
            dfs( $v$ )

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dfs( $v$ )
//visits recursively all the unvisited vertices connected to
    vertex  $v$ 
//by a path and numbers them in the order they are
    encountered
//via global variable count
    count  $\leftarrow$  count + 1; mark  $v$  with count
    for each vertex  $w$  in  $V$  adjacent to  $v$  do
        if  $w$  is marked with 0
            dfs( $w$ )

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ALGORITHM *BFS*(*G*)

//Implements a breadth-first search traversal of a given graph

//Input: Graph $G = V, E$

//Output: Graph G with its vertices marked with consecutive integers

// in the order they are visited by the BFS traversal

mark each vertex in V with 0 as a mark of being “unvisited”

$count \leftarrow 0$

for each vertex v in V do

 if v is marked with 0

bfs(v)

bfs(v)

//visits all the unvisited vertices connected to vertex v

//by a path and numbers them in the order they are visited

//via global variable *count*

$count \leftarrow count + 1$; mark v with *count* and initialize a queue with v

while the queue is not empty do

 for each vertex w in V adjacent to the front vertex do

 if w is marked with 0

$count \leftarrow count + 1$; mark w with *count*

 add w to the queue

 remove the front vertex from the queue

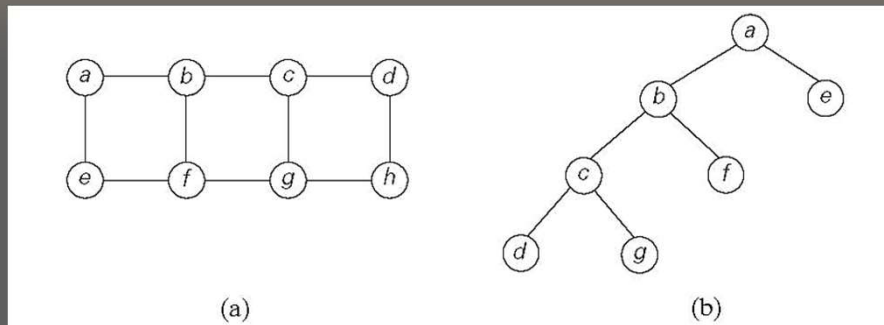


FIGURE 3.12 Illustration of the BFS-based algorithm for finding a minimum-edge path. (a) Graph. (b) Part of its BFS tree that identifies the minimum-edge path from *a* to *g*.

TABLE 3.1 Main facts about depth-first search (DFS) and breadth-first search (BFS)

	DFS	BFS
Data structure	a stack	a queue
Number of vertex orderings	two orderings	one ordering
Edge types (undirected graphs)	tree and back edges	tree and cross edges
Applications	connectivity, acyclicity, articulation points	connectivity, acyclicity, minimum-edge paths
Efficiency for adjacency matrix	$\Theta(V ^2)$	$\Theta(V ^2)$
Efficiency for adjacency lists	$\Theta(V + E)$	$\Theta(V + E)$