
Technical University of Crete
School of Electrical and Computer Engineering
Course: **Convex Optimization**

Exercise 3

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100/1000 points

In this exercise, we shall solve simple (but important) optimization problems by explicitly solving the KKT conditions. **In all cases, start with a drawing of the problem.** We shall also use the projected gradient method.

1. (10) Compute the projection of $\mathbf{x}_0 \in \mathbb{R}^n$ onto the set $\mathbf{B}(\mathbf{0}, r) := \{\mathbf{x} \in \mathbb{R}^n \mid \|\mathbf{x}\|_2 \leq r\}$.
 - (a) Draw a scheme of the problem.
 - (b) Write down the optimization problem you must solve, in terms of **differentiable** functions.
 - (c) Write down the KKT conditions, in terms of the optimal parameters \mathbf{x}_* and λ_* .
 - (d) Consider the case $\lambda_* > 0$. What is the conclusion?
 - (e) Consider the case $\lambda_* = 0$. What is the conclusion?
2. (10) Repeat the steps of the previous question and compute the projection of $\mathbf{x}_0 \in \mathbb{R}^n$ onto the set $\mathbf{B}(\mathbf{y}, r) := \{\mathbf{x} \in \mathbb{R}^n \mid \|\mathbf{x} - \mathbf{y}\|_2 \leq r\}$ (for given $\mathbf{y} \in \mathbb{R}^n$ and $r \in \mathbb{R}_{++}$).
3. (10) Let $\mathbf{a} \in \mathbb{R}^n$. Compute the projection of $\mathbf{x}_0 \in \mathbb{R}^n$ onto set $\mathbb{S} := \{\mathbf{x} \in \mathbb{R}^n \mid \mathbf{a} \leq \mathbf{x}\}$.
4. Let $\mathbf{0} \neq \mathbf{a} \in \mathbb{R}^n$, $b \in \mathbb{R}$ and consider the problem

$$(P) \quad \min_{\mathbf{x}} f_0(\mathbf{x}) := \frac{1}{2} \|\mathbf{x}\|_2^2, \text{ subject to } \mathbf{x} \in \mathbb{H} := \{\mathbf{x} \in \mathbb{R}^n \mid \mathbf{a}^T \mathbf{x} = b\}. \quad (1)$$

- (a) (10) Write and solve the KKT for problem (P).
- (b) (10) Compute the solution of problem (P) using the projected gradient descent method

$$\mathbf{x}_{k+1} = \mathbf{P}_{\mathbb{H}} \left(\mathbf{x}_k - \frac{1}{L} \nabla f_0(\mathbf{x}_k) \right), \quad (2)$$

where $L := \max(\text{eig}(\nabla^2 f_0(\mathbf{x})))$. What do you observe?

5. Let $\mathbf{A} \in \mathbb{R}^{p \times n}$, with $\text{rank}(\mathbf{A}) = p$, and $\mathbf{b} \in \mathbb{R}^p$.

- (a) (10) Find the distance of a point $\mathbf{x}_0 \in \mathbb{R}^n$ from the set $\mathbb{S} := \{\mathbf{x} \in \mathbb{R}^n \mid \mathbf{Ax} = \mathbf{b}\}$ (you must compute the projection of \mathbf{x}_0 onto \mathbb{S}).
- (b) Let the $(n \times n)$ positive definite matrix $\mathbf{P} = \mathbf{P}^T \succ \mathbf{0}$, $\mathbf{q} \in \mathbb{R}^n$ and

$$f_0(\mathbf{x}) := \frac{1}{2} \mathbf{x}^T \mathbf{P} \mathbf{x} + \mathbf{q}^T \mathbf{x}.$$

Consider the problem

$$(Q) \quad \min_{\mathbf{x} \in \mathbb{S}} f_0(\mathbf{x}). \tag{3}$$

- i. Solve problem (Q) using `cvx`.
- ii. (10) Write the KKT for problem (Q) and compute the optimal solution by solving them using `matlab` (no `cvx`).
- iii. (30) Compute the optimal solution via the projected gradient method

$$\mathbf{x}_{k+1} = \mathbf{P}_{\mathbb{S}} \left(\mathbf{x}_k - \frac{1}{L} \nabla f_0(\mathbf{x}_k) \right), \tag{4}$$

where $L := \max(\text{eig}(\nabla^2 f_0(\mathbf{x})))$.