As mentioned previously, wavelets are important in image processing. Keeping in mind this applications we introduce here "separable" multiresolutions (or wavelets), that is multiresolutions in R2 detained as products of 1-dimensional resolutions.

A first attempt, given a wavelet orthonormal basis 3 4 mx macz of 22 (TR) would be to consider the products in L2 (TR2):

\[
 \ \(\mathbb{H}_{11}, \mathbb{K}_1 \) \\
 \ \(\mathbb{H}_{11}, \mathbb{K}_2 \) \\
 \ \(\mathbb{H}_{11}, \mathbb{M}_2 \) \\
 \ \(\mathbb{K}_1, \mathbb{K}_2 \) \\
 \ \(\mathbb{K}_1, \mathbb{K}_2 \) \\
 \ \(\mathbb{K}_2, \mathbb{K}_2 \)
 \[
 \ \mathbb{K}_2, \mathbb{K}_2 \]

These functions mix information at two different seales 2^m, 2^m, along the axes x, xr. This is not convenient, we would like to have the same scale in all directions. However, this construction can be slightly modified to provide another separable wavelet lossis whose elements are products of functions delated at the same xale. These multi-polition approximations have important applications in computer vision, where they are used to process images at different levels of detail.

Separable multiresolutions:

As in dimension d=1, the notion of resolution is formalised with orthogonal projections on spaces of various sizes. The approximation of f(x1, x2) at the resolution n is defined as the orthogonal projection of f on a space Vi that is included in L2(TR2). The space Vi is the set of all approximations at the resolution n. When the resolution

decreases, the size of Vi decreases as well. The formal definition of a MRA is an in dimension 1: Where \le L2 (1/22) with the properties previously lited. We consider the particular case of separable multiresolutions. Given a multiresolution 3 Vn quere in L2(R), a separable 2- dimensional multiresolution is composed of the tensor product spaces $V_n^2 = V_n \otimes V_n$. Then $f \in V_u^2 \in L^2(\mathbb{R}^2)$ if it has the form f(x1, x2) = E cm fm(xi)gm(x2) fm,gm eVn, Z/cm/2 co. Then 3 V2 FREK is a multiresolution of L2(P2). Lat 4 be (so that I think KER is an the scaling function of 3 Valace Vn² = Vn ⊗ Vn, then system orthonormal basis of Vn. Since K= (K1, K2) € 度² n ∈ 是 Ynix (x) := Yn, x, (x1) Yn, K2 (x2) = 2" 4(2"x1-K1) 4 (2"X2-K2) is an orthonormal basis of Vn. Notice that the saling function here is just $\varphi(x_1, x_2) := \varphi(x_i) \, \varphi(x_2)$. Example: Piecewise approximation (Haar). Let Vn be the approximation space of functions that are constant on interval, LZ"K,Z",K], KER The 2- dimensional scaling function is 4(x1, x2) = 2 (0,1) (x1) 2 (0,1) (x1) $=\mathcal{X}_{[0,1)\times[0,1)}(x_1,x_2)$

Given a MRA 3V" YNER of L2(R2) as before let Wh 12.2 denote the corresponding detail space; that is, Wi is the orthogonal complement of Vn in Vn+1: Vn @ Wh = Vn+1

Theorem: Let Y be the scaling function of a MRA $3V_n Y_n \in \mathbb{Z}$ in $L^2(\mathbb{R})$ and let Y denote the associated wavelet (which generates the corresponding wavelet basis) Define $Y^4(x) = Y(x_1) Y(x_2)$ $X = (X_1, X_2)$ $Y^2(x) = Y(x_1) Y(x_1)$ $Y(x_1)$ $Y(x_2)$

and denote, for $K_1, K_2 \in \mathbb{Z}$ and j=1,2,3, $n \in \mathbb{Z}$ $\psi_{R,K}^{\dagger} (X_1, X_2) = 2^n \psi_{S} (2^n X_1 - K_1, 2^n X_2 - K_2).$

The family I Ynin, Ynin, Ynin I kette is an orthonormal basis of Wn, and therefore IYnin, Ynin, Ynin, Ynin I nett is an orthonormal basis of L2 (TR2)

Proof: Since by definition $V_{n+1} = V_n \oplus W_n$, we have $V_{n+1} = (V_n \otimes V_n) \oplus W_n^2$

Also $V_{n+2} = (V_n \oplus W_n) \otimes (V_n \oplus W_n) = V_n^2 \oplus (W_n \otimes V_n) \oplus (V_n \otimes W_n) \oplus (W_n \otimes W_n)$ and therefore

Whi = (Wh & Vn) & (Vn & Wn) & (Wh & Vn)

Then: LY2 is a basis of Wn & Wn I have is a basis of Vn & Wn & Wn & Wn & Ynin'r is a basis of Wn & Wn & Wn & Ynin'r is a basis of Wn & Wn & &

The three wavelets of the theorem extract image details at different scales and orientations. Notice also that $\hat{Y}^1(5...52) = \hat{Y}(5.) \hat{Y}(52)$ $\hat{Y}^2(5...52) = \hat{Y}(5.) \hat{Y}(52)$

Sometimes 4' is called 4' (horizontal) because each 42 is called 4' (vertical)

43 is called 4' (diagonal)

of the subspaces favour, details in those directions.

\$\hat{\psi}^3 (\z_1,\z_2) = \P(\z_1) \P(\z_2)

Example: (Shannon aproximation). Let 3 Vn (mere be the MRA of Exercise 2, with 4 given by 4(5)=2(5).

You will (hopefully) see that 4(3) is, up to a constant of modulus 1, the function XEINJ E12.163(3). The two demensional basis explained above paves the Fourier plane with dilated rectangles

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