

2nd set of exercises

Association rules and the A-priori algorithm

Association Rule learning is a rule based machine learning method which is used to discover interesting relationships hidden in large data-sets. These rules do not necessarily extract users preference, but rather find relationships between set of elements present in different entries in data-sets. Association Rule Mining is sometimes referred to as “Market Basket Analysis”.

Running the script: “Python3 main.py”

Data preprocessing

At first we need to create our sets. In our occasion we will analyse imdb ratings and how each users rated a movie. These will be our “baskets”. The *CreateMovieBaskets* function does exactly this thing having an input file of the ratings in a csv format. The function iterates over the csv as it creates and finally returns the *user_baskets* list. A second function named *ReadMovies* reads a file that contains all movies as single items with their information, converts it into a pandas dataframe and returns it for use.

The A-priori algorithm

The first step in generation of association rules is to get all the frequent items of a set. This cannot be done with a brute force approach. There are some techniques that use memory loading such as the 1-dimensional triangular matrix or the hash table approach. The triangular matrix stores each counter of a pair in the position of $a[k]$ where $k = (i - 1)(n - \frac{i}{2} + j - 1)$. In result the pair counters are stored lexicographically.

The hash table counts triples for every basket we have. In contrast with the triangular matrix the hash method does not need to count nothing if the counter of a pairs is zero. Bellow we can see two snippets of these memory techniques.

```

01. # space needed 2*n^2
02.
03. triangular_matrix = [0]*(2*no_of_movies ** 2)
04.
05. for basket in user_baskets:
06.
07.     list_of_pairs = itertools.combinations(basket, 2)
08.
09.     for pair in list_of_pairs:
10.
11.         i = pair[0]
12.         j = pair[1]
13.
14.         if i < j:
15.
16.             # store the pair with i < j as a lower triangular matrix
17.             # with a dimension array
18.
19.             k = (i-1) * (no_of_movies - i / 2) + j - 1
20.
21.             # float to int
22.             k = int(k)
23.
24.             # update the counter
25.             triangular_matrix[k] += 1

```

Triangular Matrix

```

01. hash_table = {}
02.
03. for basket in user_baskets:
04.
05.     # pairs of three
06.     list_of_pairs = itertools.combinations(basket, 3)
07.
08.     for pair in list_of_pairs:
09.
10.         # if exists in the hash table counter + 1, else create the entry
11.         # this way we dont need to store zeros, opposed to the triangular matrix
12.
13.         try:
14.
15.             hash_table.update({pair: hash_table[pair] + 1})
16.
17.         except KeyError:
18.
19.             hash_table.update({pair: 1})

```

Hash table

The A-priori principle helps us with making this search efficient. The main principle that holds is that all subsets of a frequent item set must also be frequent. This allows us to prune all the supersets of an item set which does not satisfy the minimum threshold condition for the *support* (= the fraction of the number of occurrences of all items in a set with the total number of the item sets). It helps us identify the rules worth considering.

The A-priori starts by generating singletons, pairs of two, pairs of three, etc until there are no bigger common pairs of common items while keeping only those that have a support of a certain threshold. Bellow we can see a snippet.

```

01. items_to_pair = []
02.
03.     # use a counter, .index() can return a list of items with the same occurrence
04.     index_counter = 0
05.
06.     for item in counter_of_items:
07.
08.         index_counter += 1
09.
10.         if item > 0:
11.
12.             try:
13.
14.                 index = counter_of_items.index(index_counter)
15.
16.                 pair = movies_basket[index]
17.
18.                 # compute frequency for every singleton or pair of two, three etc
19.
20.                 if frequency_ap(pair, user_baskets) > min_frequency:
21.                     items_to_pair.append(pair)
22.
23.             except ValueError:
24.                 pass

```

Computing with items to pair

Creating association rules

Once the frequent item sets are generated, identifying rules out of them is comparatively easy. From a list of all possible candidate rules, we aim to identify rules that fall above a minimum confidence level. Below we can see a snippet and how the metrics are computed.

```

01. for item in itemset:
02.
03.     if len(item) > 1:
04.
05.         returned_set_of_rules = k_subset(item, 2)
06.
07.         set_of_rules = [list(x) for x in returned_set_of_rules]
08.
09.         for rule in set_of_rules:
10.
11.             append_flag = False
12.
13.             left_side = [rule[0]]
14.             right_side = [rule[1]]
15.
16.             items_of_the_rule = left_side + right_side
17.
18.             frequency_of_rule = frequency(items_of_the_rule, user_baskets)
19.
20.             frequency_of_left = frequency(left_side, user_baskets)
21.
22.             frequency_of_right = frequency(right_side, user_baskets)
23.
24.             confidence_of_rule = frequency_of_rule / frequency_of_left
25.
26.             lift_of_rule = confidence_of_rule / frequency_of_right

```

Rules generation

Results

Bellow we can see the available options and the results each one of them generates.

Parameters:

$min_conf = 0.1$, $min_lift = 3$, $max_lift = 6$, $min_length = 2$

```
*****
* Main script started *
*****

Crunching the data \
Done!

#####
(a) List ALL discovered rules           : [format: a]
(b) List all rules containing a BAG of movies: : [format:
in their <ITEMSET|HYPOTHESIS|CONCLUSION> : b,<i,h,c>,<comma-sep. movie IDs>]
(c) COMPARE rules with <CONFIDENCE,LIFT> : [format: c]
(h) Print the HISTOGRAM of <CONFIDENCE|LIFT > : [format: h,<c,l >]
(m) Show details of a MOVIE           : [format: m,<movie ID>]
(r) Show a particular RULE            : [format: r,<rule ID>]
(s) SORT rules by increasing <CONFIDENCE|LIFT > : [format: s,<c,l >]
(v) Visualise association rules of top 10 : [format: v]
(e) EXIT                             : [format: e]
#####
```

Main options

Presenting the discovered rules

```
Please enter an option:a
rule          itemset  ... lift rule ID
0      [(136,)]->[(131,)] [131, 136] ... 3.130499 0
1      [(131,)]->[(785,)] [131, 785] ... 3.048614 1
2      [(18,)]->[(131,)] [131, 18] ... 3.577713 2
3      [(295,)]->[(131,)] [131, 295] ... 3.322162 3
4      [(131,)]->[(44,)] [131, 44] ... 4.485294 4
5      [(176,)]->[(131,)] [131, 176] ... 3.079944 5
6      [(311,)]->[(131,)] [131, 311] ... 3.074597 6
7      [(131,)]->[(326,)] [131, 326] ... 3.722755 7
8      [(455,)]->[(131,)] [131, 455] ... 3.992520 8
9      [(131,)]->[(217,)] [131, 217] ... 3.068955 9
10     [(483,)]->[(131,)] [131, 483] ... 3.808533 10
11     [(485,)]->[(131,)] [131, 485] ... 4.086849 11
12     [(379,)]->[(131,)] [131, 379] ... 3.904250 12
13     [(134,)]->[(260,)] [260, 134] ... 3.655750 13
```

Presenting discovered rules of movie 156 that exists in the item set of rules

```
Choose another option to continue:b,i,156
rule          itemset  ... lift rule ID
27     [(134,)]->[(156,)] [134, 156] ... 3.331311 27
87     [(297,)]->[(156,)] [156, 297] ... 3.167821 87
88     [(176,)]->[(156,)] [156, 176] ... 3.125776 88
89     [(253,)]->[(156,)] [156, 253] ... 3.397277 89
168    [(134,)]->[(176, 156)] [134, 176, 156] ... 4.037952 168
169    [(134, 156)]->[(176,)] [134, 176, 156] ... 3.788820 169
170    [(134, 176)]->[(156,)] [134, 176, 156] ... 4.154056 170
177    [(307, 156)]->[(134,)] [134, 307, 156] ... 4.935275 177
178    [(134, 307)]->[(156,)] [134, 307, 156] ... 3.680019 178
179    [(134, 156)]->[(307,)] [134, 307, 156] ... 4.401154 179
186    [(156, 253)]->[(134,)] [134, 156, 253] ... 4.418246 186
187    [(134, 156)]->[(253,)] [134, 156, 253] ... 4.505736 187
188    [(134, 253)]->[(156,)] [134, 156, 253] ... 4.128744 188
```

Presenting discovered rules of movie 156 that exists in the hypothesis of rules

Choose another option to continue: **b,h,156**

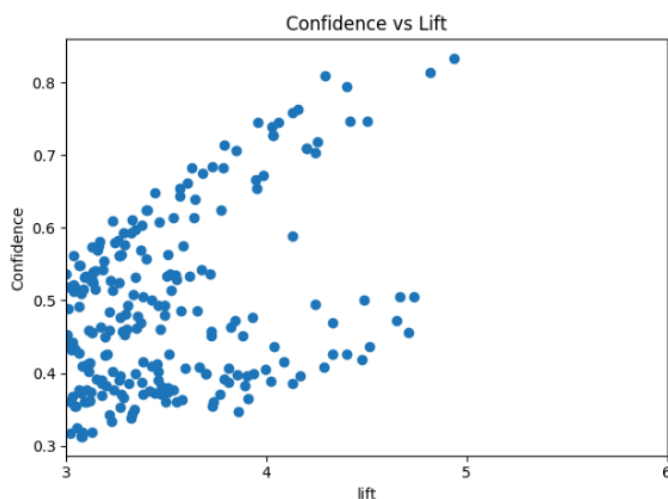
	rule	itemset	...	lift	rule ID
169	$[(134, 156)] \rightarrow [(176,)]$	[134, 176, 156]	...	3.788820	169
177	$[(307, 156)] \rightarrow [(134,)]$	[134, 307, 156]	...	4.935275	177
179	$[(134, 156)] \rightarrow [(307,)]$	[134, 307, 156]	...	4.401154	179
186	$[(156, 253)] \rightarrow [(134,)]$	[134, 156, 253]	...	4.418246	186
187	$[(134, 156)] \rightarrow [(253,)]$	[134, 156, 253]	...	4.505736	187
191	$[(156, 287)] \rightarrow [(134,)]$	[134, 156, 287]	...	4.199470	191
204	$[(156, 253)] \rightarrow [(176,)]$	[176, 156, 253]	...	4.293996	204
207	$[(156, 287)] \rightarrow [(176,)]$	[176, 156, 287]	...	3.954150	207
215	$[(156, 253)] \rightarrow [(307,)]$	[307, 156, 253]	...	3.784993	215
216	$[(156, 287)] \rightarrow [(307,)]$	[307, 156, 287]	...	4.033058	216
224	$[(156, 287)] \rightarrow [(253,)]$	[156, 253, 287]	...	3.953195	224

Presenting discovered rules of movie 156 that exists in the conclusion of rules

Choose another option to continue: **b,c,156**

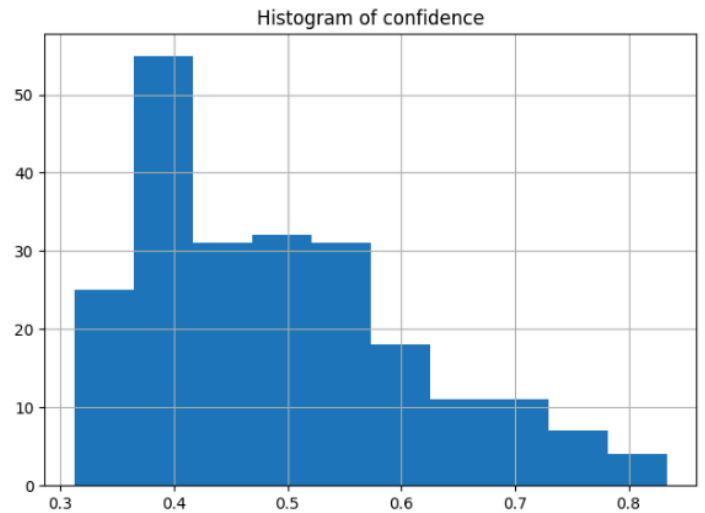
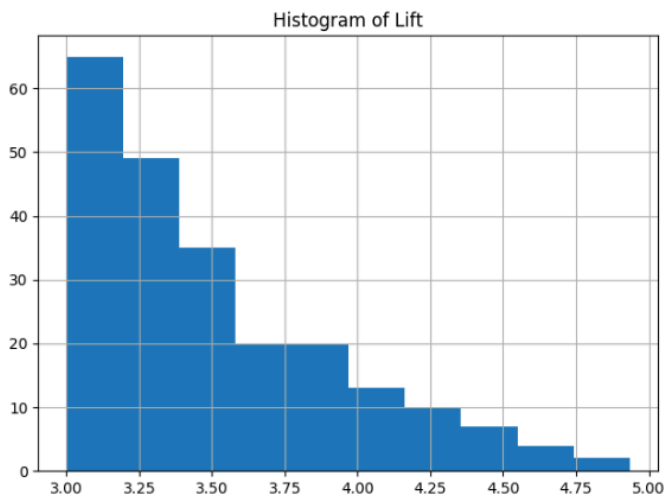
	rule	itemset	...	lift	rule ID
27	$[(134,)] \rightarrow [(156,)]$	[134, 156]	...	3.331311	27
87	$[(297,)] \rightarrow [(156,)]$	[156, 297]	...	3.167821	87
88	$[(176,)] \rightarrow [(156,)]$	[156, 176]	...	3.125776	88
89	$[(253,)] \rightarrow [(156,)]$	[156, 253]	...	3.397277	89
168	$[(134,)] \rightarrow [(176, 156)]$	[134, 176, 156]	...	4.037952	168
170	$[(134, 176)] \rightarrow [(156,)]$	[134, 176, 156]	...	4.154056	170
178	$[(134, 307)] \rightarrow [(156,)]$	[134, 307, 156]	...	3.680019	178
188	$[(134, 253)] \rightarrow [(156,)]$	[134, 156, 253]	...	4.128744	188
189	$[(134, 287)] \rightarrow [(156,)]$	[134, 156, 287]	...	3.726504	189
190	$[(287,)] \rightarrow [(134, 156)]$	[134, 156, 287]	...	3.496473	190
195	$[(176,)] \rightarrow [(307, 156)]$	[176, 307, 156]	...	3.889855	195
196	$[(176, 307)] \rightarrow [(156,)]$	[176, 307, 156]	...	4.061743	196
197	$[(307,)] \rightarrow [(176, 156)]$	[176, 307, 156]	...	3.696970	197

Comparing rules with Confidence and Lift



We can clearly see that as the lift is getting bigger the number of items are getting smaller. Even though that some items remain approximately at the same level the confidence of the rest is clearly higher.

Histograms of Confidence and Lift



A small number of items have a high Lift and Confidence number, that means, a small number of rules are interesting.
Exactly what we want.

Showing movie information

```
Choose another option to continue:m,156
  movieId      title      genres  index
156      185 Net, The (1995) Action|Crime|Thriller    156
| Selected results were presented |
```

Showing rules information

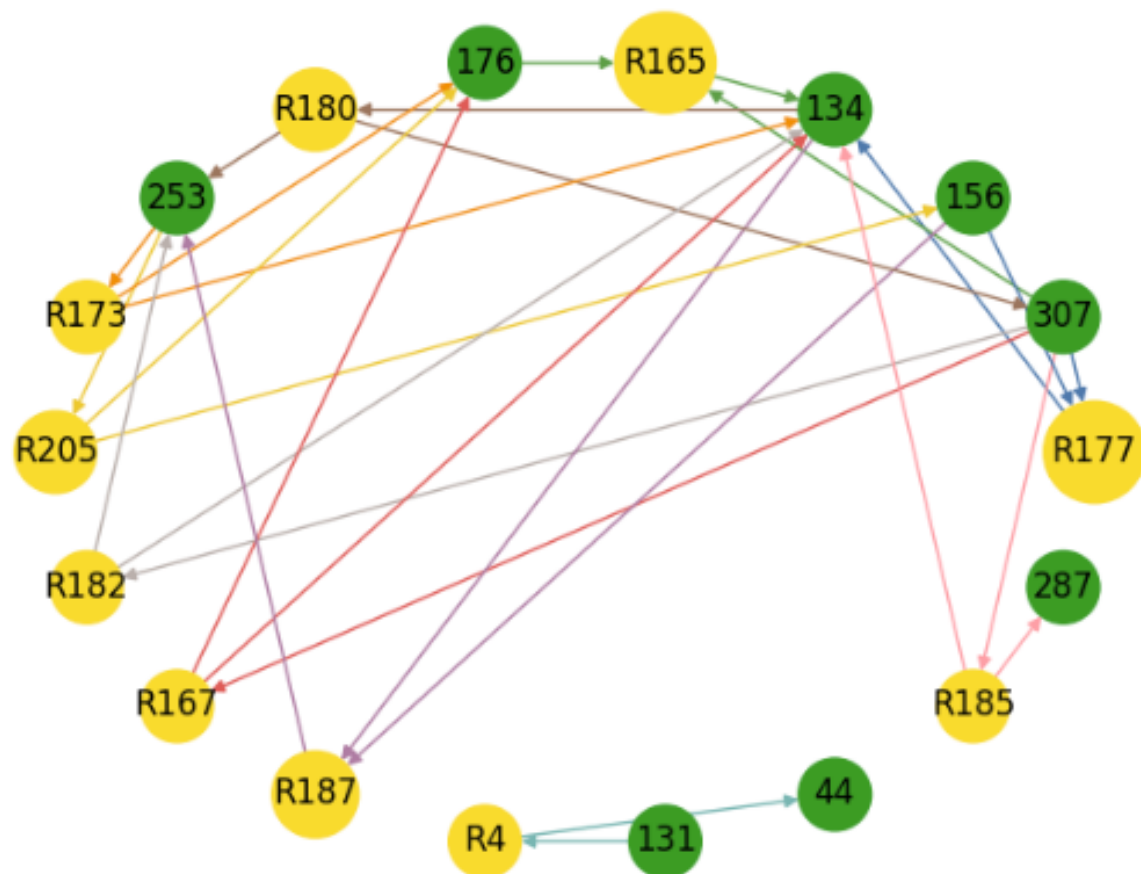
```
Choose another option to continue:r,5
  rule      itemset  frequency  confidence      lift  rule ID
5  [(176,)]->[(131,)] [131, 176]   0.059016    0.313043  3.079944      5
| Selected results were presented |
```

Sorting according to lift or confidence

Choose another option to continue: **s, l**

	rule	itemset	...	lift	rule ID
147	[(455,)]->[(217,)]	[455, 217]	...	3.000931	147
128	[(311,)]->[(249,)]	[311, 249]	...	3.004416	128
153	[(839,)]->[(1404,)]	[839, 1404]	...	3.009753	153
78	[(18,)]->[(92,)]	[18, 92]	...	3.010790	78
37	[(903,)]->[(2982,)]	[903, 2982]	...	3.017504	37
83	[(84,)]->[(20,)]	[20, 84]	...	3.018994	83
102	[(839,)]->[(2982,)]	[2982, 839]	...	3.020300	102
60	[(15,)]->[(311,)]	[15, 311]	...	3.022104	60

Graph relation between the movies and the rules. Node rule is bigger if it has bigger confidence thus being more important and notable.



The A-priori algorithm in a stream of item sets.

This concept applies to a uniform reservoir sampling. In situations that we have a live stream of data, in our case baskets, we want to sample this data with an equal probability, thus a uniform probability. This is achieved with the reservoir sampling. At the beginning the first n baskets fill the available place of the memory, after this is done a random number is drawn with a range from zero to the current iteration. If the number is below n then the n^{th} item will be replaced with the new item that came from the stream. If it is higher the new item will be discarded. In our implementation we have two options. Return the current common pairs the priori algorithm found if there is a change in the sample or after the end of the stream take a second pass and return the common pairs it found. The second script provides this in an option menu.

Note: the second script also provides the triangular and hash methods.

Running the script: “Python3 sampled_apriori_and_memory_techniques.py”

```
*****
* Second script started *
*****

Crunching the data |
Done!
(t): Compute triangular matrix and save to file
(h): Compute hash table and save to file
(a,c): Run the apriori-stream and display every change in the stream
(a,s): Run the apriori-stream and display the final results with a second pass
(e): Exit
Please enter an option:a,s
-----
stream ended
common pairs:
[(1, 9), (1, 18)]
-----
| Action completed |
-----
Choose another option to continue:
```

Running example 1


```
Choose another option to continue:a,c
Sample changed...
Current common items: [1, 2, 5, 6, 9, 10, 18]
Sample changed...
Current common items: [1, 2, 5, 6, 9, 10, 18, 20, 24, 31]
Sample changed...
Current common items: [1, 2, 5, 6, 9, 10, 18, 20, 24, 31]
Sample changed...
Current common items: [1, 2, 5, 6, 9, 10, 18, 20, 24, 31]
Sample changed...
Current common items: [1, 2, 5, 6, 9, 10, 18, 20, 24, 31]
Sample changed...
Current common items: [1, 2, 5, 6, 9, 10, 18, 20, 24, 32]
Sample changed...
Current common items: [1, 2, 5, 6, 9, 10, 18, 20, 24, 32]
Sample changed...
Current common items: [1, 2, 5, 6, 9, 10, 18, 20, 31]
Sample changed...
Current common items: [1, 2, 5, 6, 9, 10, 18, 20, 24]
```

Running example 2

Notes:

- 1) Association rules are saved in a csv file after discovering them.
- 2) Item sets are stored in a txt file after discovering them.
- 3) Sampled A-priori, triangular matrix and hash table results are stored in a pickle file. Pickle serializes a single object at a time, and reads back a single object, the pickled data is recorded in sequence on the file.
- 4) The scripts provide basic input handling for wrong inputs and catches most of the wrong arguments.