

Complete Instantiation for Quantified Formulas in SMT

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Satisfiability Modulo Theories (SMT)

$$a > 3, (a = b \vee a = b + 1), f(a) = 0, f(b) = 1$$

Many Applications

- Dynamic symbolic execution (DART)
- Extended static checking
- Test-case generation
- Bounded model checking (BMC)
- Equivalence checking
- ...

What is a Theory?

A theory T is a set of sentences.

F is satisfiable modulo T
iff

$T \cup F$ is satisfiable.

Theory: Examples

- Array Theory:

$$\forall a, i, v: \text{read}(\text{write}(a, i, v), i) = v$$

$$\forall a, i, v: i = j \vee \text{read}(\text{write}(a, i, v), j) = \text{read}(a, j)$$

- Linear Arithmetic
- Bit-vectors
- Inductive datatypes
- ...

SMT: Example

$$a > 3, (a = b \vee a = b + 1), f(a) = 0, f(b) = 1$$

f,g,h	Uninterpreted functions
a,b,c	Uninterpreted constants
+, -, <, ≤, 0, 1, ...	Interpreted symbols

SMT: Example

$$a > 3, (a = b \vee a = b + 1), f(a) = 0, f(b) = 1$$

Model/Structure:

$$a \rightarrow 4$$

$$b \rightarrow 3$$

$$f \rightarrow \{ 4 \rightarrow 0, 3 \rightarrow 1, \dots \}$$

SMT: Example

$$a > 3, (a = b \vee a = b + 1), f(a) = 0, f(b) = 1$$

Model M:

$$M(a) = 4$$

$$M(b) = 3$$

$$M(f) = \{ 4 \rightarrow 0, 3 \rightarrow 1, \dots \}$$

SMT Solvers

Many SMT Solvers:

- Barcelogic, Beaver, Boolector,
- CVC3, MathSAT, OpenSMT,
- Sateen, Yices, **Z3**, ...

They are very efficient for **quantifier-free formulas**.

Many applications need quantifiers

- Modeling the runtime

$\forall h, o, f:$

$\text{IsHeap}(h) \wedge o \neq \text{null} \wedge \text{read}(h, o, \text{alloc}) = t$

\Rightarrow

$\text{read}(h, o, f) = \text{null} \vee \text{read}(h, \text{read}(h, o, f), \text{alloc}) = t$

Many applications need quantifiers

- Modeling the runtime
- User provided assertions

$$\forall i,j: i \leq j \Rightarrow \text{read}(a,i) \leq \text{read}(b,j)$$

Many applications need quantifiers

- Modeling the runtime
- User provided assertions
- Unsupported theories

$$\forall x: p(x,x)$$

$$\forall x,y,z: p(x,y), p(y,z) \Rightarrow p(x,z)$$

$$\forall x,y: p(x,y), p(y,x) \Rightarrow x = y$$

Many applications need quantifiers

- Modeling the runtime
- User provided assertions
- Unsupported theories
- Solver must be fast in satisfiable instances.



We want to find bugs!

Many Approaches

- Superposition Calculus + SMT.
- Instantiation Based Methods
 - Implemented on top of “regular” SMT solvers.
 - Heuristic quantifier instantiation (E-Matching).
 - **Complete quantifier instantiation.**

Instantiation Based Methods: Related work

- Bernays-Schönfinkel class.
- Stratified Many-Sorted Logic.
- **Array Property Fragment.**
- Local theory extensions.

Simplifying Assumption: CNF

$$\forall x_1, x_2: \neg p(x_1, x_2) \vee f(x_1) = f(x_2) + 1,$$
$$p(a, b), a < b + 1$$

Simplifying Assumption: CNF

$$\neg p(x_1, x_2) \vee f(x_1) = f(x_2) + 1,$$
$$p(a, b), a < b + 1$$

Essentially uninterpreted fragment

- Variables appear only as arguments of uninterpreted symbols.

$$f(g(x_1) + a) < g(x_1) \vee h(f(x_1), x_2) = 0$$



$$f(x_1 + x_2) \leq f(x_1) + f(x_2)$$



Basic Idea

Given a set of formulas F ,
build an equisatisfiable set of quantifier-free formulas F^*

“Domain” of f is the set of ground terms A_f
 $t \in A_f$ if there is a ground term $f(t)$

Suppose

1. We have a clause $C[f(x)]$ containing $f(x)$.
2. We have $f(t)$.



Instantiate x with t : $C[f(t)]$.

Example

F

$$\begin{aligned}g(x_1, x_2) &= 0 \vee h(x_2) = 0, \\g(f(x_1), b) + 1 &\leq f(x_1), \\h(c) &= 1, \\f(a) &= 0\end{aligned}$$

F*

Example

F

$g(x_1, x_2) = 0 \vee h(x_2) = 0,$
 $g(f(x_1), b) + 1 \leq f(x_1),$
 $h(c) = 1,$
 $f(a) = 0$



F*

$h(c) = 1,$
 $f(a) = 0$

Copy quantifier-free formulas

“Domains”:

$A_f: \{ a \}$

$A_g: \{ \}$

$A_h: \{ c \}$

Example

F

$g(x_1, x_2) = 0 \vee h(x_2) = 0,$
 $g(f(x_1), b) + 1 \leq f(\mathbf{x}_1),$
 $h(c) = 1,$
 $f(a) = 0$



F*

$h(c) = 1,$
 $f(\mathbf{a}) = 0,$

“Domains”:

$A_f : \{ \mathbf{a} \}$

$A_g : \{ \}$

$A_h : \{ c \}$

Example

F

$$\begin{aligned}g(x_1, x_2) &= 0 \vee h(x_2) = 0, \\g(f(x_1), b) + 1 &\leq f(x_1), \\h(c) &= 1, \\f(a) &= 0\end{aligned}$$



F*

$$\begin{aligned}h(c) &= 1, \\f(a) &= 0, \\g(f(a), b) + 1 &\leq f(a)\end{aligned}$$

“Domains”:

$$A_f : \{ a \}$$

$$A_g : \{ [f(a), b] \}$$

$$A_h : \{ c \}$$

Example

F

$$\begin{aligned} g(\mathbf{x}_1, \mathbf{x}_2) &= 0 \vee h(\mathbf{x}_2) = 0, \\ g(f(\mathbf{x}_1), \mathbf{b}) + 1 &\leq f(\mathbf{x}_1), \\ h(\mathbf{c}) &= 1, \\ f(\mathbf{a}) &= 0 \end{aligned}$$



F*

$$\begin{aligned} h(\mathbf{c}) &= 1, \\ f(\mathbf{a}) &= 0, \\ g(\mathbf{f}(\mathbf{a}), \mathbf{b}) + 1 &\leq f(\mathbf{a}), \end{aligned}$$

“Domains”:

$$A_f : \{ \mathbf{a} \}$$

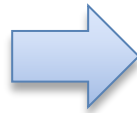
$$A_g : \{ [\mathbf{f}(\mathbf{a}), \mathbf{b}] \}$$

$$A_h : \{ \mathbf{c} \}$$

Example

F

$$\begin{aligned}g(x_1, x_2) &= 0 \vee h(x_2) = 0, \\g(f(x_1), b) + 1 &\leq f(x_1), \\h(c) &= 1, \\f(a) &= 0\end{aligned}$$



F*

$$\begin{aligned}h(c) &= 1, \\f(a) &= 0, \\g(f(a), b) + 1 &\leq f(a), \\g(f(a), b) &= 0 \vee h(b) = 0\end{aligned}$$

“Domains”:

$$A_f : \{ a \}$$

$$A_g : \{ [f(a), b] \}$$

$$A_h : \{ c, \textcolor{red}{b} \}$$

Example

F

$g(\mathbf{x}_1, x_2) = 0 \vee h(\mathbf{x}_2) = 0,$
 $g(f(x_1), b) + 1 \leq f(x_1),$
 $h(c) = 1,$
 $f(a) = 0$



F*

$h(\mathbf{c}) = 1,$
 $f(a) = 0,$
 $g(\mathbf{f(a)}, b) + 1 \leq f(a),$
 $g(f(a), b) = 0 \vee h(b) = 0$

“Domains”:

$A_f : \{ a \}$

$A_g : \{ [\mathbf{f(a)}, b] \}$

$A_h : \{ \mathbf{c}, b \}$

Example

F

$$\begin{aligned}g(x_1, x_2) &= 0 \vee h(x_2) = 0, \\g(f(x_1), b) + 1 &\leq f(x_1), \\h(c) &= 1, \\f(a) &= 0\end{aligned}$$



F*

$$\begin{aligned}h(c) &= 1, \\f(a) &= 0, \\g(f(a), b) + 1 &\leq f(a), \\g(f(a), b) &= 0 \vee h(b) = 0, \\g(f(a), c) &= 0 \vee h(c) = 0\end{aligned}$$

“Domains”:

$$A_f : \{ a \}$$

$$A_g : \{ [f(a), b], [f(a), c] \}$$

$$A_h : \{ c, b \}$$

Example

F

$g(x_1, x_2) = 0 \vee h(x_2) = 0,$
 $g(f(x_1), b) + 1 \leq f(x_1),$
 $h(c) = 1,$
 $f(a) = 0$



F*

$h(c) = 1,$
 $f(a) = 0,$
 $g(f(a), b) + 1 \leq f(a),$
 $g(f(a), b) = 0 \vee h(b) = 0,$
 $g(f(a), c) = 0 \vee h(c) = 0$



M

$a \rightarrow 2, b \rightarrow 2, c \rightarrow 3$
 $f \rightarrow \{ 2 \rightarrow 0, \dots \}$
 $h \rightarrow \{ 2 \rightarrow 0, 3 \rightarrow 1, \dots \}$
 $g \rightarrow \{ [0, 2] \rightarrow -1, [0, 3] \rightarrow 0, \dots \}$

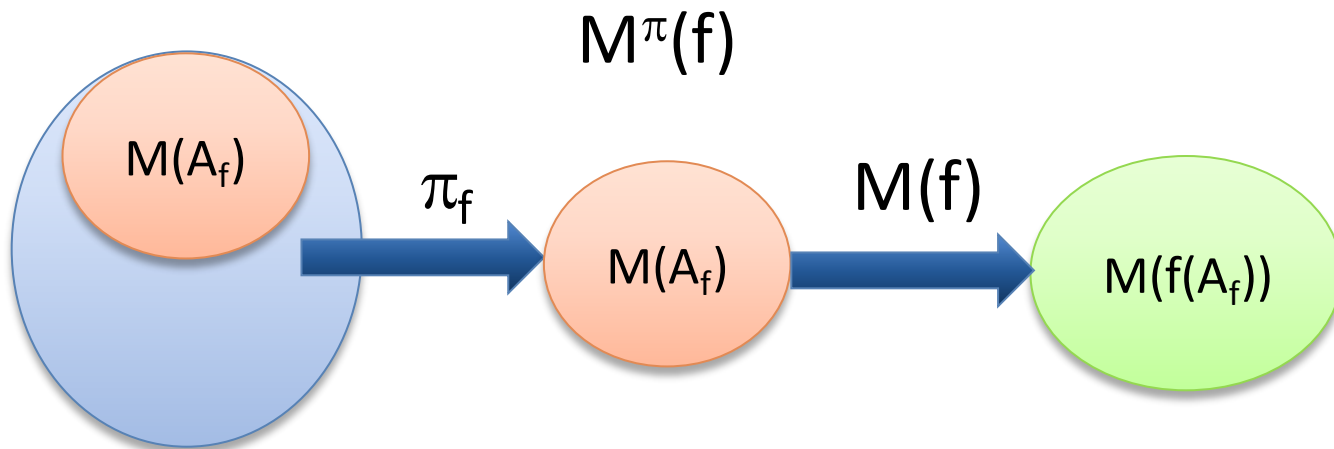
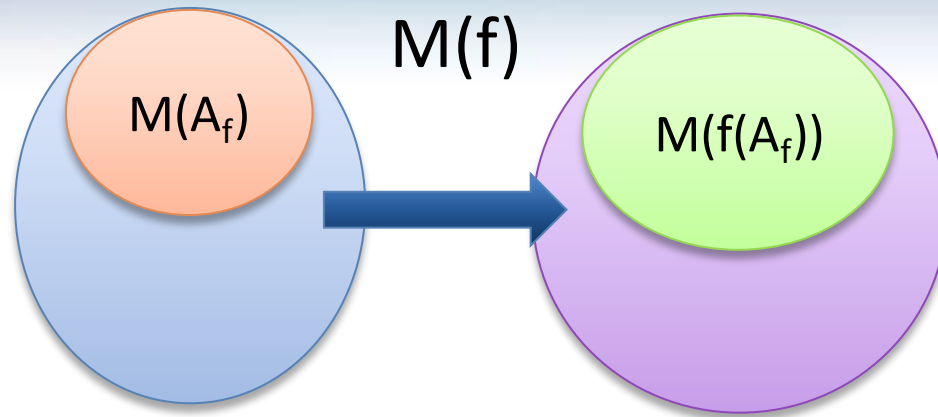
Basic Idea (cont.)

Given a model M for F^* ,
Build a model M^π for F

Define a projection function π_f s.t.
range of π_f is $M(A_f)$, and
 $\pi_f(v) = v$ if $v \in M(A_f)$

Then,
 $M^\pi(f)(v) = M(f)(\pi_f(v))$

Basic Idea (cont.)



Basic Idea (cont.)

Given a model M for F^* ,
Build a model M^π for F

In our example, we have: $h(b)$ and $h(c)$
 $\rightarrow A_h = \{ b, c \}$, and $M(A_h) = \{ 2, 3 \}$

$$\pi_h = \{ 2 \rightarrow 2, 3 \rightarrow 3, \text{ else } \rightarrow 3 \}$$

$$\begin{array}{ccc} M(h) & & M^\pi(h) \\ \{ 2 \rightarrow 0, 3 \rightarrow 1, \dots \} & \longrightarrow & \{ 2 \rightarrow 0, 3 \rightarrow 1, \text{ else } \rightarrow 1 \} \end{array}$$

$$M^\pi(h) = \lambda x. \text{ if}(x=2, 0, 1)$$

Example

F

$g(x_1, x_2) = 0 \vee h(x_2) = 0,$
 $g(f(x_1), b) + 1 \leq f(x_1),$
 $h(c) = 1,$
 $f(a) = 0$



F*

$h(c) = 1,$
 $f(a) = 0,$
 $g(f(a), b) + 1 \leq f(a),$
 $g(f(a), b) = 0 \vee h(b) = 0,$
 $g(f(a), c) = 0 \vee h(c) = 0$



M^π

$a \rightarrow 2, b \rightarrow 2, c \rightarrow 3$
 $f \rightarrow \lambda x. 2$
 $h \rightarrow \lambda x. \text{if}(x=2, 0, 1)$
 $g \rightarrow \lambda x, y. \text{if}(x=0 \wedge y=2, -1, 0)$



M

$a \rightarrow 2, b \rightarrow 2, c \rightarrow 3$
 $f \rightarrow \{ 2 \rightarrow 0, \dots \}$
 $h \rightarrow \{ 2 \rightarrow 0, 3 \rightarrow 1, \dots \}$
 $g \rightarrow \{ [0, 2] \rightarrow -1, [0, 3] \rightarrow 0, \dots \}$

Example: Model Checking

M^π

$a \rightarrow 2, b \rightarrow 2, c \rightarrow 3$

$f \rightarrow \lambda x. 2$

$h \rightarrow \lambda x. \text{if}(x=2, 0, 1)$

$g \rightarrow \lambda x, y. \text{if}(x=0 \wedge y=2, -1, 0)$

Does M^π satisfies?

$\forall x_1, x_2 : g(x_1, x_2) = 0 \vee h(x_2) = 0$



$\forall x_1, x_2 : \text{if}(x_1=0 \wedge x_2=2, -1, 0) = 0 \vee \text{if}(x_2=2, 0, 1) = 0$ **is valid**



$\exists x_1, x_2 : \text{if}(x_1=0 \wedge x_2=2, -1, 0) \neq 0 \wedge \text{if}(x_2=2, 0, 1) \neq 0$ **is unsat**



$\text{if}(s_1=0 \wedge s_2=2, -1, 0) \neq 0 \wedge \text{if}(s_2=2, 0, 1) \neq 0$ **is unsat**

Why does it work?

Suppose M^π does not satisfy $C[f(x)]$.

Then for some value v ,
 $M^\pi\{x \rightarrow v\}$ falsifies $C[f(x)]$.

$M^\pi\{x \rightarrow \pi_f(v)\}$ also falsifies $C[f(x)]$.

But, there is a term $t \in A_f$ s.t. $M(t) = \pi_f(v)$
Moreover, we instantiated $C[f(x)]$ with t .

So, M must not satisfy $C[f(t)]$.

Contradiction: M is a model for F^* .

Refinement 1: Lazy construction

- F^* may be very big (or infinite).
- Lazy-construction
 - Build F^* incrementally, F^* is the limit of the sequence
$$F^0 \subset F^1 \subset \dots \subset F^k \subset \dots$$
 - If F^k is unsat then F is unsat.
 - If F^k is sat, then build (candidate) M^π
 - If M^π satisfies all quantifiers in F then return sat.

Refinement 2: Model-based instantiation

Suppose M^π does not satisfy a clause $C[f(x)]$ in F .

Add an instance $C[f(t)]$ which “blocks” this spurious model.

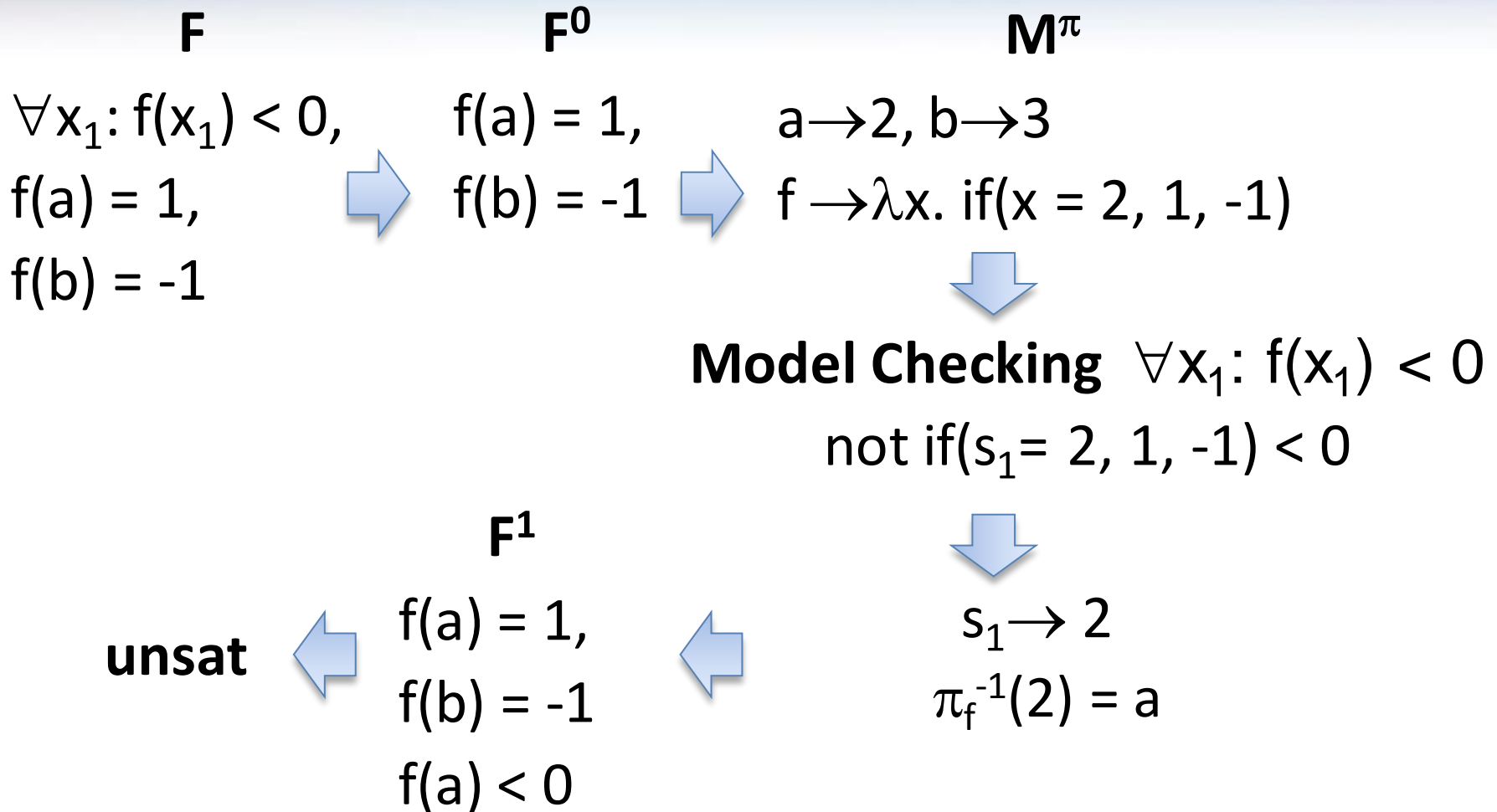
Issue: how to find t ?

Use model checking,

and the “inverse” mapping π_f^{-1} from values to terms (in A_f).

$$\pi_f^{-1}(v) = t \quad \text{if} \quad M^\pi(t) = \pi_f(v)$$

Model-based instantiation: Example



Infinite F^*

- Is our procedure refutationally complete?
- FOL Compactness

A set of sentences is unsatisfiable
iff
it contains an unsatisfiable **finite** subset.
- A theory **T** is a set of sentences, then
apply compactness to $F^* \cup T$

Infinite F^* : Example

F

$\forall x_1: f(x_1) < f(f(x_1)),$

$\forall x_1: f(x_1) < a,$

$1 < f(0).$

Unsatisfiable

F^*

$f(0) < f(f(0)), f(f(0)) < f(f(f(0))), \dots$

$f(0) < a, f(f(0)) < a, \dots$

$1 < f(0)$

Every finite subset
of F^* is satisfiable.

Infinite F^* : What is wrong?

- Theory of linear arithmetic T_Z is the set of all first-order sentences that are true in the standard structure Z .
- T_Z has non-standard models.
- F and F^* are satisfiable in a non-standard model.
- Alternative: a theory is a class of structures.
- Compactness does not hold.
- F and F^* are still equisatisfiable.

Δ_F and Set Constraints

Given a clause $C_k[x_1, \dots, x_n]$

Let

$S_{k,i}$ be the set of ground terms used to instantiate x_i in clause $C_k[x_1, \dots, x_n]$

How to characterize $S_{k,i}$?

F j-th argument of f in C_k	Δ_F system of set constraints
a ground term t	$t \in A_{f,j}$
$t[x_1, \dots, x_n]$	$t[S_{k,1}, \dots, S_{k,n}] \subseteq A_{f,j}$
x_i	$S_{k,i} = A_{f,j}$

Δ_F : Example

F

$g(x_1, x_2) = 0 \vee h(x_2) = 0,$
 $g(f(x_1), b) + 1 \leq f(x_1),$
 $h(c) = 1,$
 $f(a) = 0$



Δ_F

$S_{1,1} = A_{g,1}, S_{1,2} = A_{g,2}, S_{1,2} = A_{h,1}$
 $S_{2,1} = A_{f,1}, f(S_{2,1}) \subseteq A_{g,1}, b \in A_{g,2}$
 $c \in A_{h,1}$
 $a \in A_{f,1}$



Δ_F : least solution

Use Δ_F to generate F^*



$S_{1,1} = \{ f(a) \}, S_{1,2} = \{ b, c \}$
 $S_{2,1} = \{ a \}$

Complexity

- Δ_F is **stratified** then the least solution (and F^*) is finite

$t[S_{k,1}, \dots, S_{k,n}] \subseteq A_{f,j}$	$\text{level}(S_{k,i}) < \text{level}(A_{f,j})$
$S_{k,i} = A_{f,j}$	$\text{level}(S_{k,i}) = \text{level}(A_{f,j})$

- New decidable fragment: NEXPTIME-Hard.
- The least solution of Δ_F is exponential in the worst case.
 $a \in S_1, b \in S_1, f_1(S_1, S_1) \subseteq S_2, \dots, f_n(S_n, S_n) \subseteq S_{n+1}$
- F^* can be doubly exponential in the size of F .

Extensions

- Arithmetical literals: π_f must be monotonic.

Literal of C_k	Δ_F
$\neg(x_i \leq x_j)$	$S_{k,i} = S_{k,j}$
$\neg(x_i \leq t), \neg(t \leq x_i)$	$t \in S_{k,i}$
$x_i = t$	$\{t+1, t-1\} \subseteq S_{k,i}$

- Offsets:

j-th argument of f in C_k	Δ_F
$x_i + r$	$S_{k,i} + r \subseteq A_{f,j}$ $A_{f,j} + (-r) \subseteq S_{k,i}$

Extensions: Example

Shifting

$$\neg(0 \leq x_1) \vee \neg(x_1 \leq n) \vee f(x_1) = g(x_1+2)$$

More Extensions

- Many-sorted logic
- Pseudo-Macros

$$0 \leq g(x_1) \vee f(g(x_1)) = x_1,$$

$$0 \leq g(x_1) \vee h(g(x_1)) = 2x_1,$$

$$g(a) < 0$$

Conclusion

- SMT solvers usually return **unsat** or **unknown** for quantified SMT formulas.
- Z3 was the only SMT-solver in SMT-COMP'08 to correctly answer satisfiable quantified formulas.
- New decidable fragments.
- Model-based instantiation and Model checking.
- Conditions for refutationally complete procedures.
- Future work: more efficient model checking techniques.

Thank you!